

Lecture 18  
Thur. 3.01 - Mon 3.05.2012

*Lagrangian and Hamiltonian dynamics:  
Living with duality in GCC cells and vectors Part III.*

*(Ch. 12 of Unit 1)*

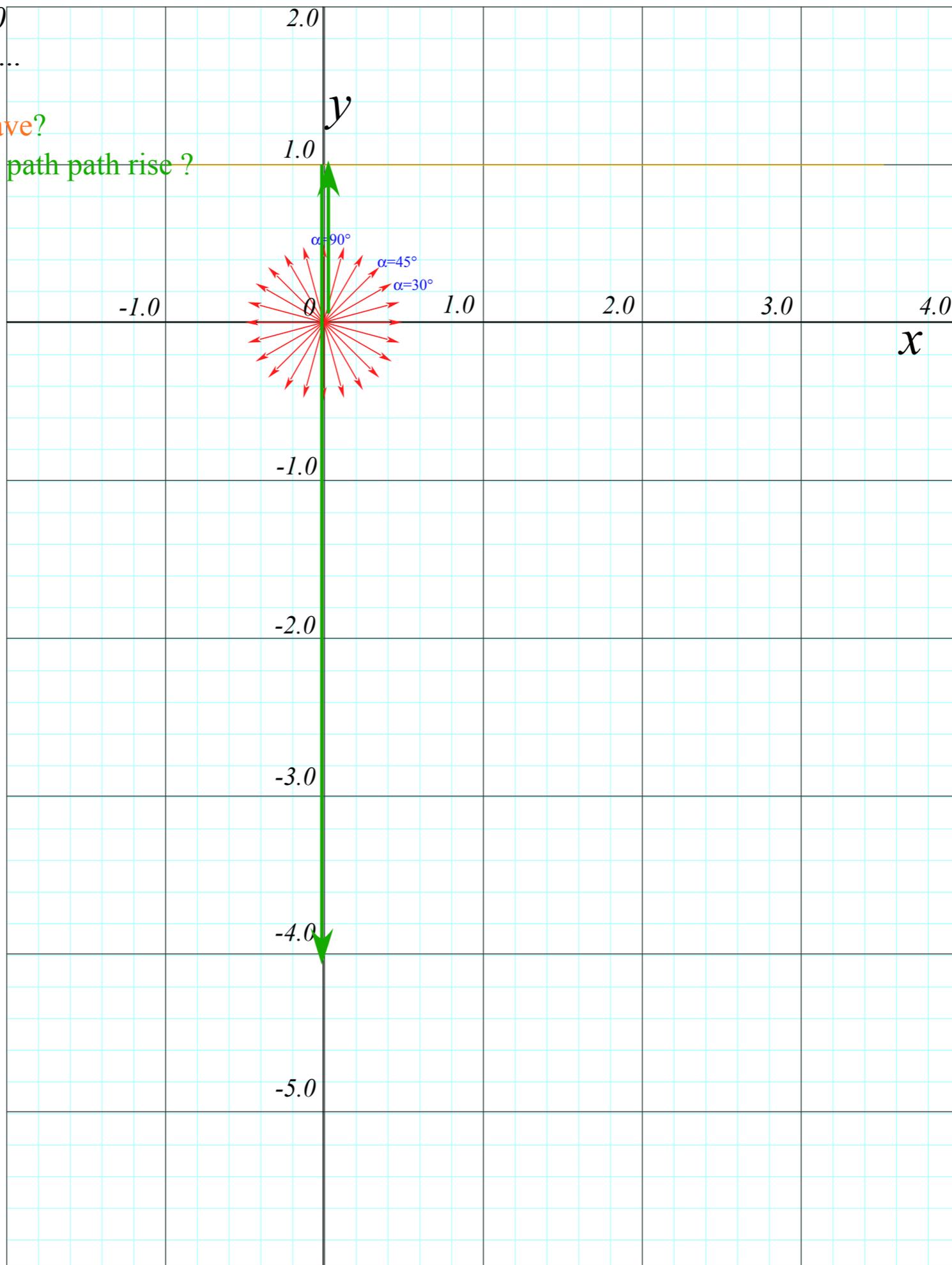
0. *Discussion of trajectory-contact-envelope problems/midterm exam* ← Topic for 3.01.2012
2. *Examples of Hamiltonian dynamics and phase plots*  
*1D Pendulum and phase plot (Simulation)*  
*Phase control (Simulation)* ← Topics for 3.05.2012
3. *Exploring phase space and Lagrangian mechanics more deeply*  
*A weird “derivation” of Lagrange’s equations*  
*Poincare identity and Action*  
*How Classicists might have “derived” quantum equations*  
*Huygen’s contact transformations enforce minimum action*  
*How to do quantum mechanics if you only know classical mechanics*

Say  $\alpha=90^\circ$  path rises to 1.0  
then drops. When at  $y=1.0$ ...

Q1. ...where is its focus?

Q2. ...where is the **blast wave**?

Q3. ...how high can  $\alpha=45^\circ$  path rise ?



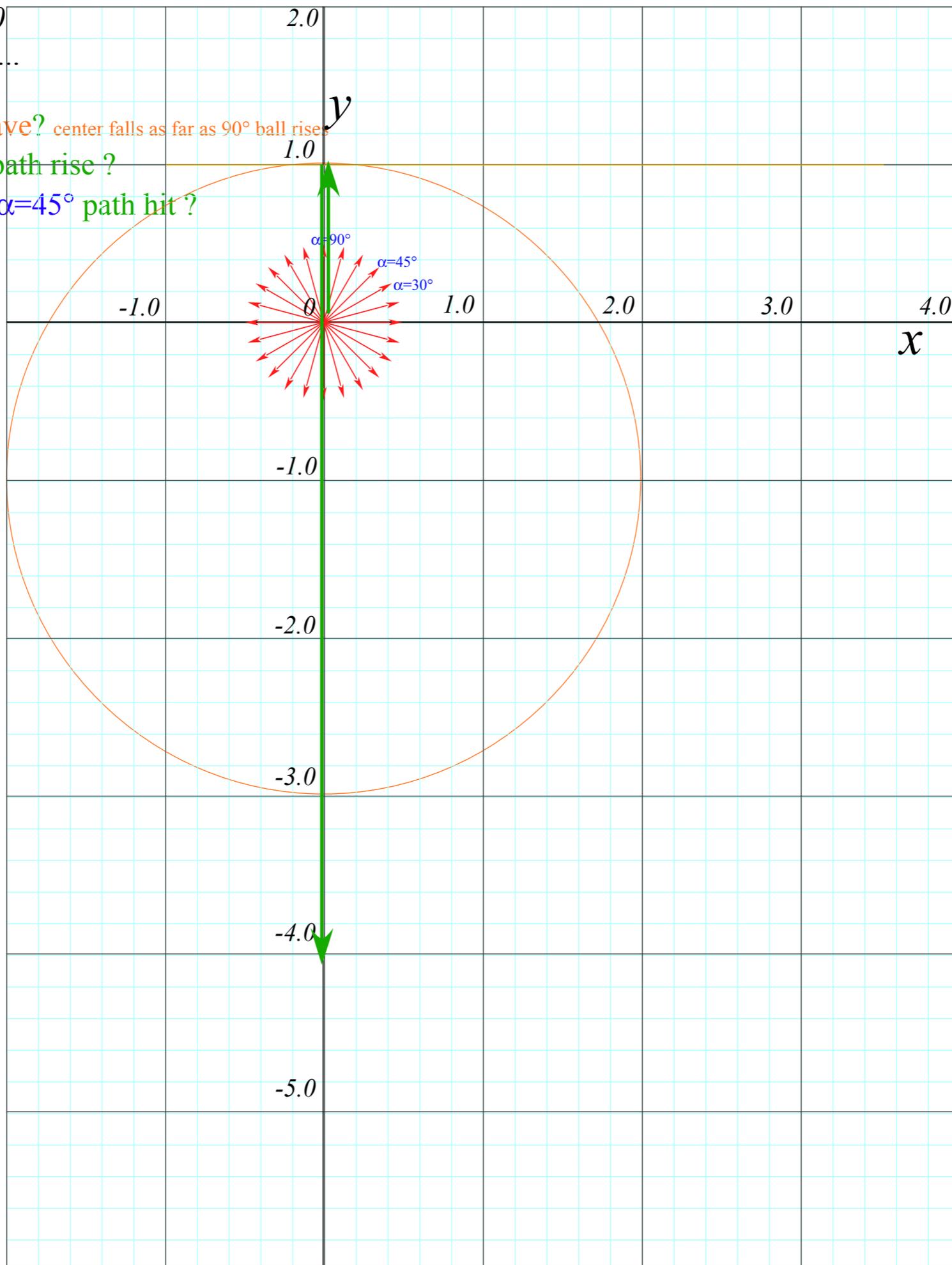
Say  $\alpha=90^\circ$  path rises to 1.0  
then drops. When at  $y=1.0$ ...

Q1. ...where is its focus?

Q2. ...where is the **blast wave**? center falls as far as  $90^\circ$  ball rise...

Q3. How high can  $\alpha=45^\circ$  path rise?

Q4. Where on  $x$ -axis does  $\alpha=45^\circ$  path hit?



Say  $\alpha=90^\circ$  path rises to 1.0 then drops. When at  $y=1.0$ ...

Q1. ...where is its focus?

Q2. ...where is the **blast wave**? center falls as far as  $90^\circ$  ball rise

Q3. How high can  $\alpha=45^\circ$  path rise? 1/2 as high

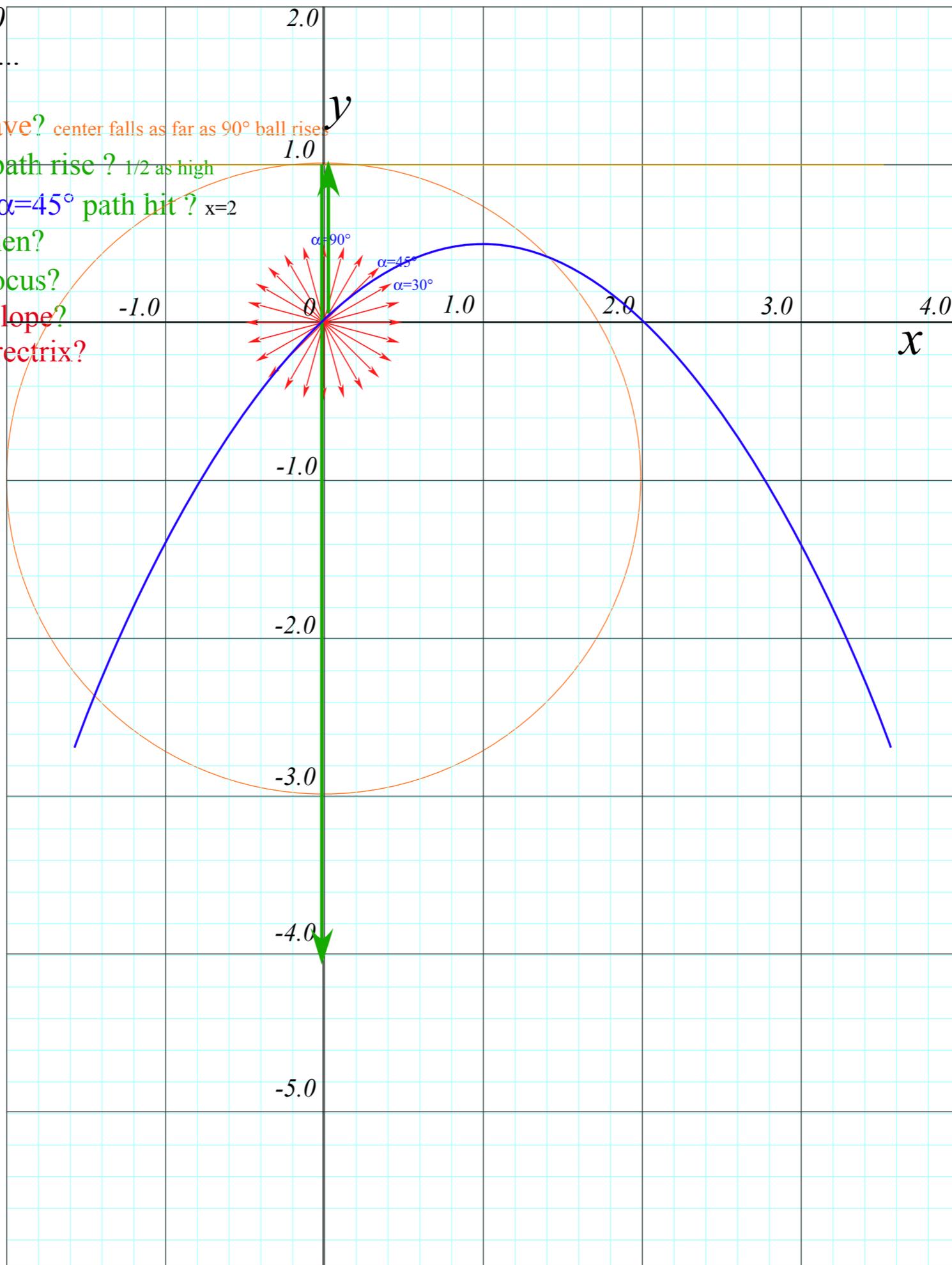
Q4. Where on  $x$ -axis does  $\alpha=45^\circ$  path hit?  $x=2$

Q5. Where is **blast wave** then?

Q6. Where is  $\alpha=45^\circ$  path focus?

Q7. Guess for **all-path envelope**?

and its focus? directrix?



Say  $\alpha=90^\circ$  path rises to 1.0  
 then drops. When at  $y=1.0$ ...

Q1. ...where is its focus?

Q2. ...where is the **blast wave**? center falls as far as  $90^\circ$  ball rises

Q3. How high can  $\alpha=45^\circ$  path rise? 1/2 as high

Q4. Where on  $x$ -axis does  $\alpha=45^\circ$  path hit?  $x=2$

Q5. Where is **blast wave** then? centered on  $45^\circ$  normal

Q6 Where is  $\alpha=45^\circ$  path focus?  $x=1, y=0$

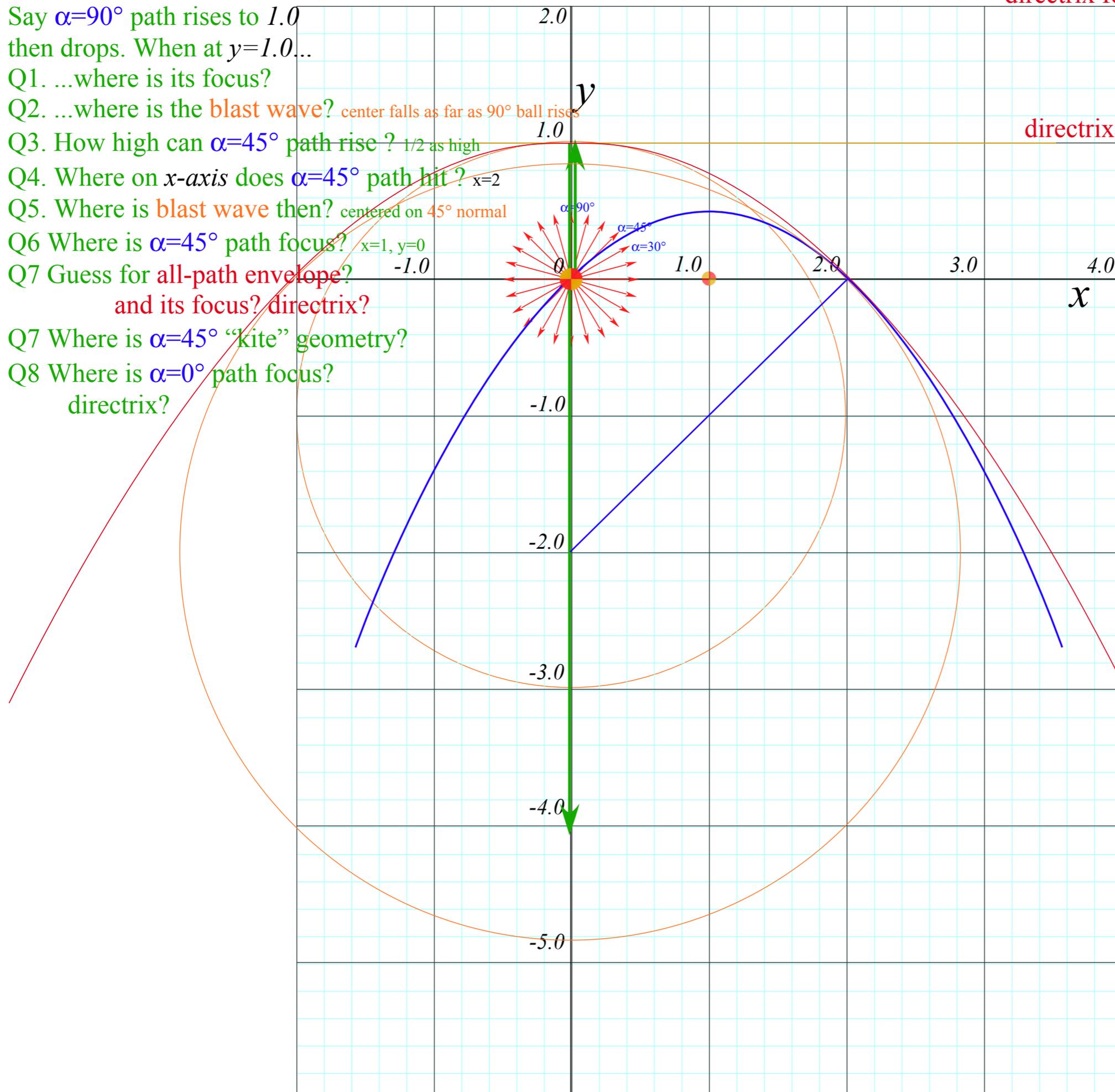
Q7 Guess for **all-path envelope**?

and its focus? directrix?

Q7 Where is  $\alpha=45^\circ$  "kite" geometry?

Q8 Where is  $\alpha=0^\circ$  path focus?

directrix?



directrix for all-path envelope

directrix for  $\alpha=90^\circ$  and  $45^\circ$

Say  $\alpha=90^\circ$  path rises to 1.0 then drops. When at  $y=1.0$ ...

Q1. ...where is its focus?

Q2. ...where is the blast wave? center falls as far as  $90^\circ$  ball rises

Q3. How high can  $\alpha=45^\circ$  path rise? 1/2 as high

Q4. Where on  $x$ -axis does  $\alpha=45^\circ$  path hit?  $x=2$

Q5. Where is blast wave then? centered on  $45^\circ$  normal

Q6 Where is  $\alpha=45^\circ$  path focus?  $x=1, y=0$

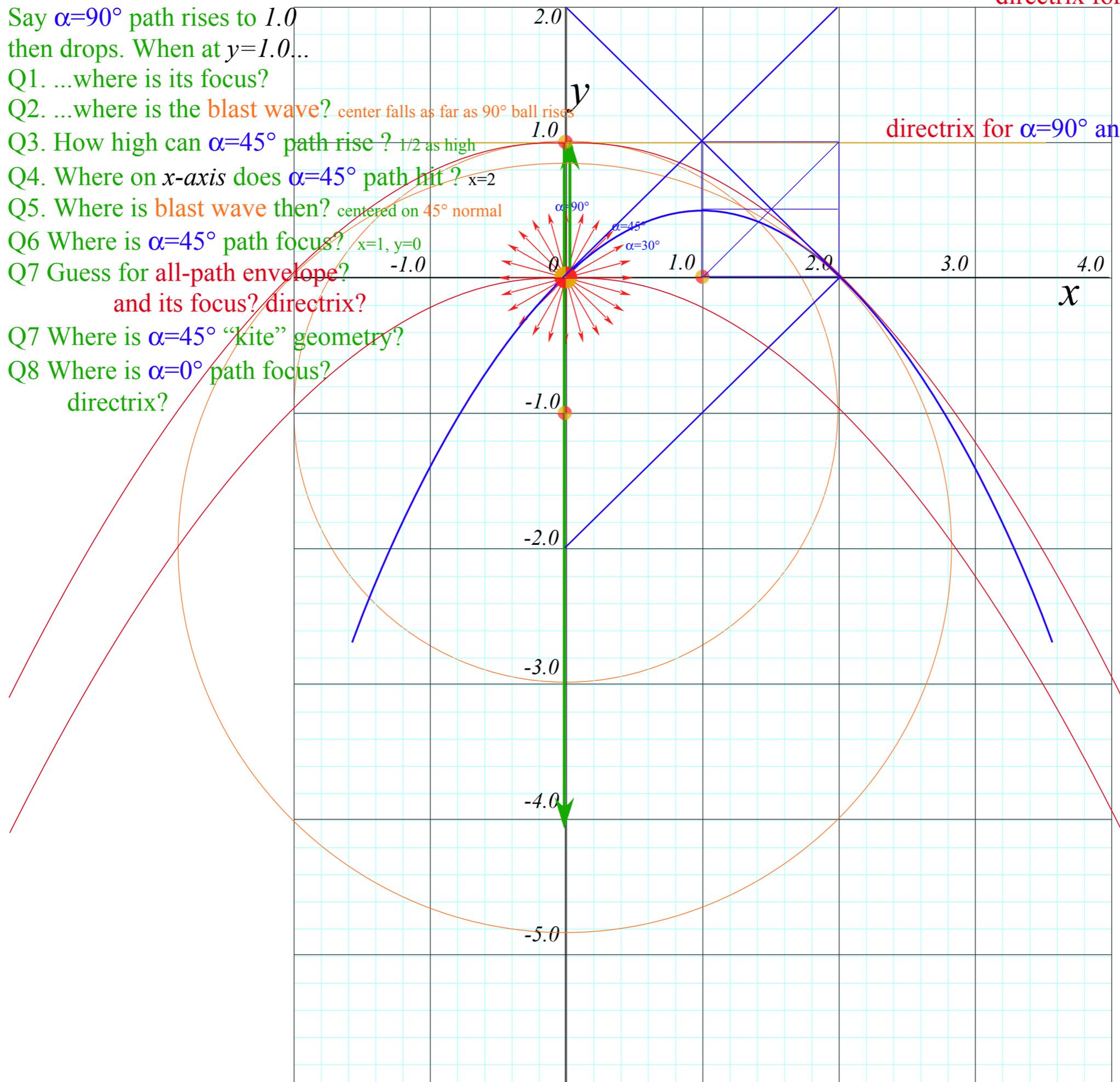
Q7 Guess for all-path envelope? and its focus? directrix?

Q7 Where is  $\alpha=45^\circ$  "kite" geometry?

Q8 Where is  $\alpha=0^\circ$  path focus? directrix?

directrix for all-path envelope

directrix for  $\alpha=90^\circ$  and  $45^\circ$  and  $0^\circ$



Say  $\alpha=90^\circ$  path rises to 1.0 then drops. When at  $y=1.0$ ...

Q1. ...where is its focus?

Q2. ...where is the blast wave? center falls as far as  $90^\circ$  ball rises

Q3. How high can  $\alpha=45^\circ$  path rise? 1/2 as high

Q4. Where on  $x$ -axis does  $\alpha=45^\circ$  path lift?  $x=2$

Q5. Where is blast wave then? centered on  $45^\circ$  normal

Q6 Where is  $\alpha=45^\circ$  path focus?  $x=1, y=0$

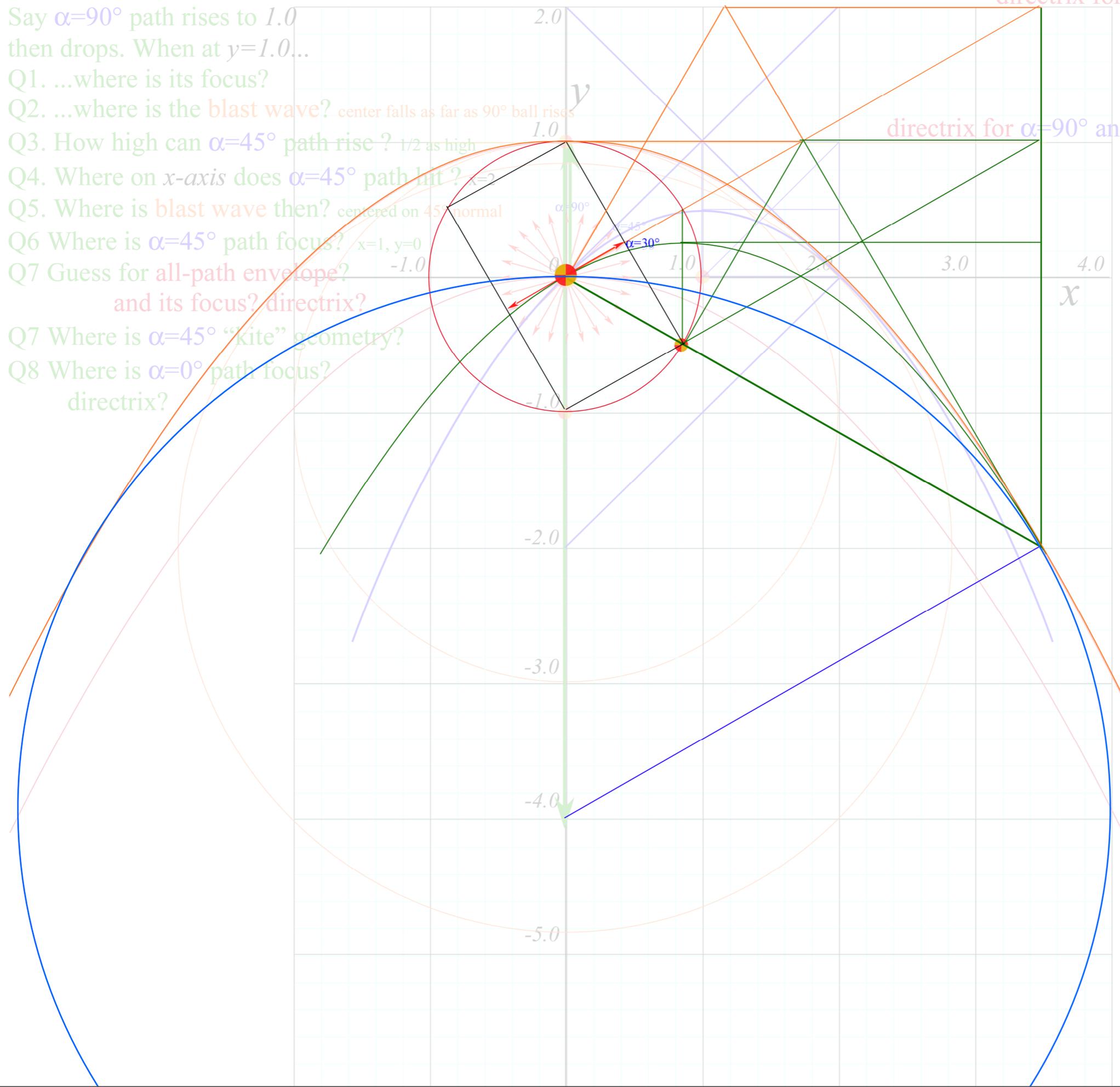
Q7 Guess for all-path envelope?

and its focus? directrix?

Q7 Where is  $\alpha=45^\circ$  "kite" geometry?

Q8 Where is  $\alpha=0^\circ$  path focus?

directrix?



directrix for all-path envelope

directrix for  $\alpha=90^\circ$  and  $45^\circ$  and  $0^\circ$

$x$

$y$

$\alpha=90^\circ$

$\alpha=45^\circ$

$\alpha=30^\circ$

centered on  $45^\circ$  normal

$x=1, y=0$

$x=2$

$x=1$

$x=2$

$x=3$

$x=4$

$y=1$

$y=2$

$y=3$

$y=4$

$y=5$

$y=6$

$y=7$

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$y=9$

$y=10$

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$y=113$

$y=114$

$y=115$

$y=116$

$y=117$

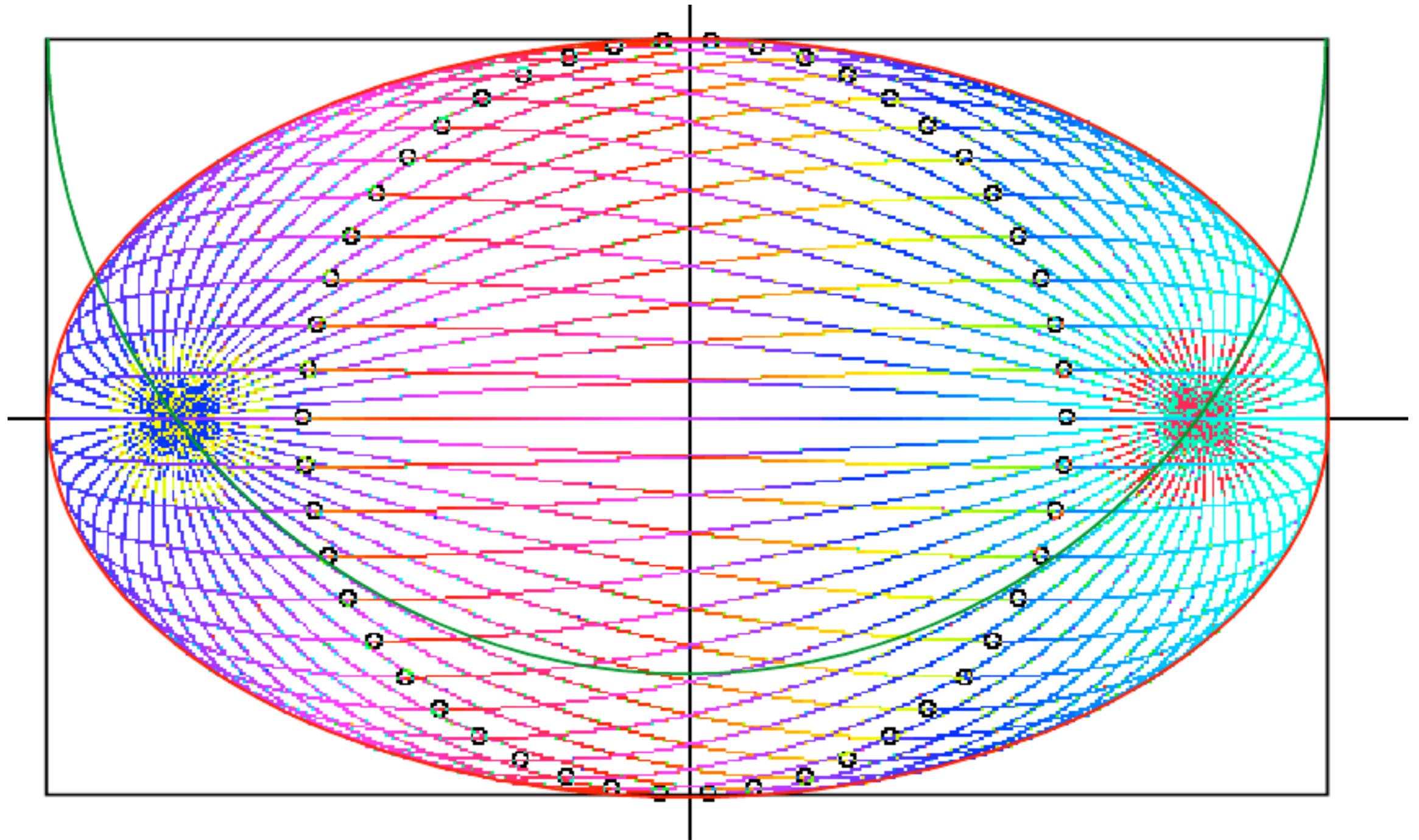
$y=118$

$y=119$

$y=120$



# *Exploding-starlet elliptical envelope and contacting elliptical trajectories*

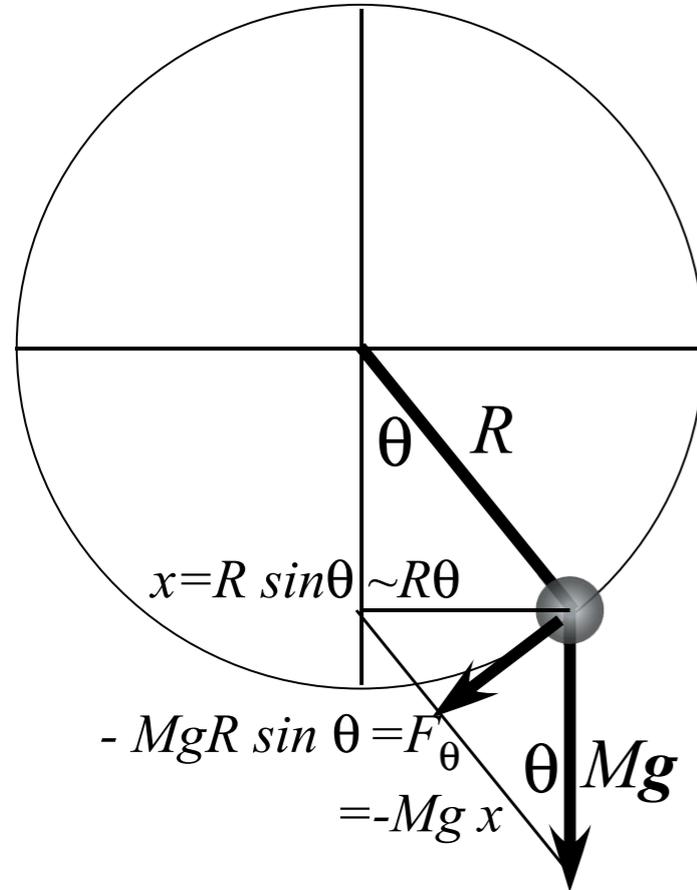


## *2. Examples of Hamiltonian dynamics and phase plots*

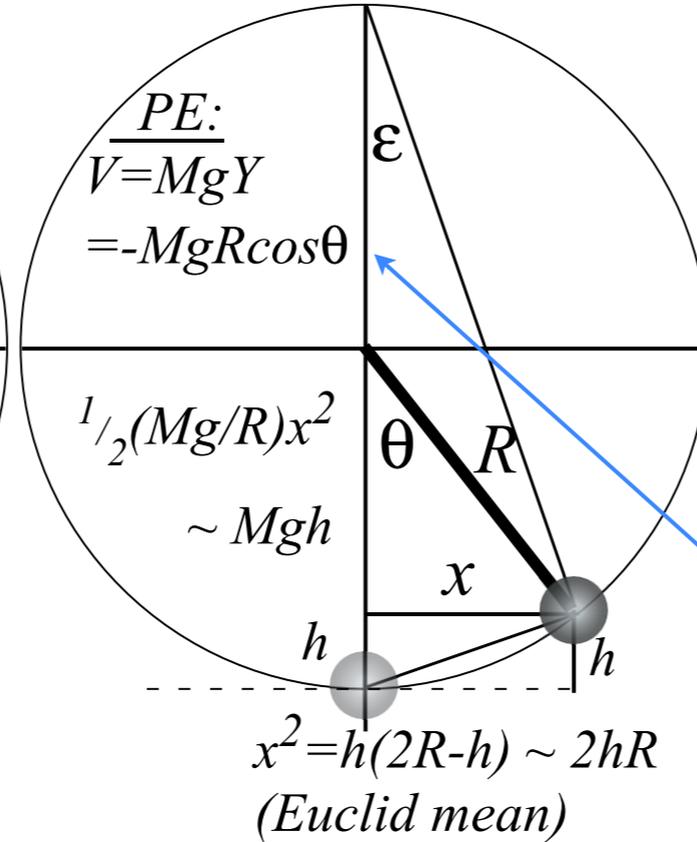
 *1D Pendulum and phase plot (Simulation)*  
*Phase space control (Simulation)*

# 1D Pendulum and phase plot

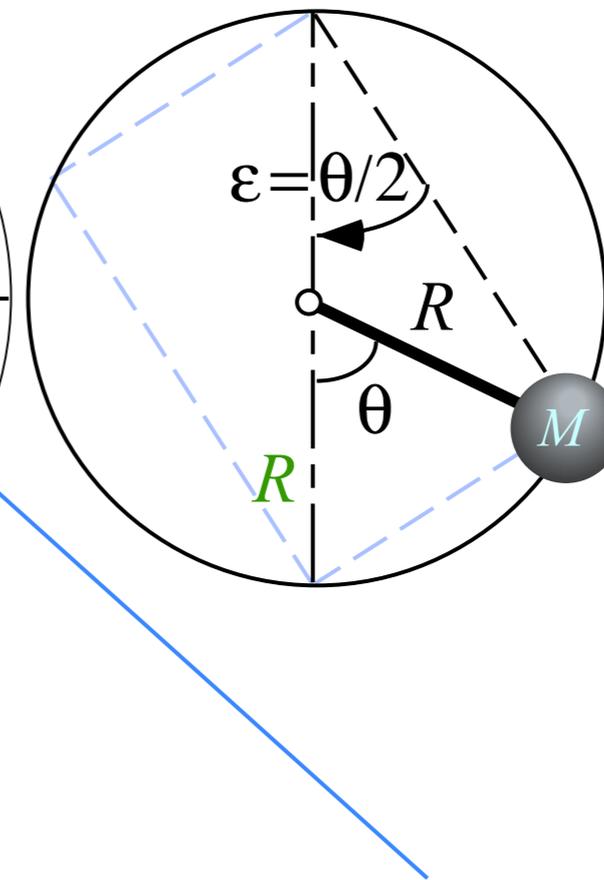
(a) Force geometry



(b) Energy geometry



(c) Time geometry

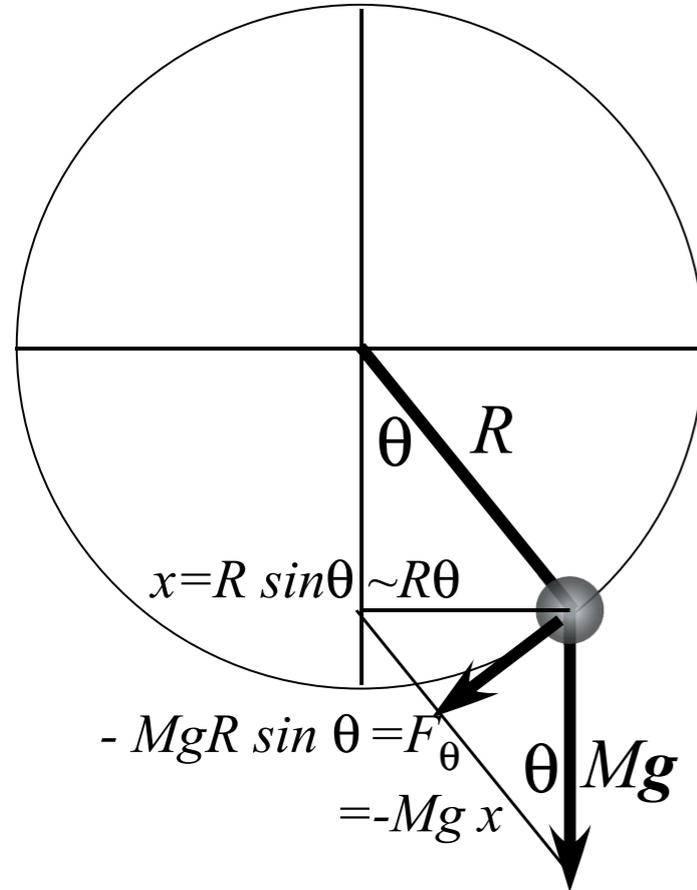


Lagrangian function  $L = KE - PE = T - U$  where potential energy is  $U(\theta) = -MgR \cos \theta$

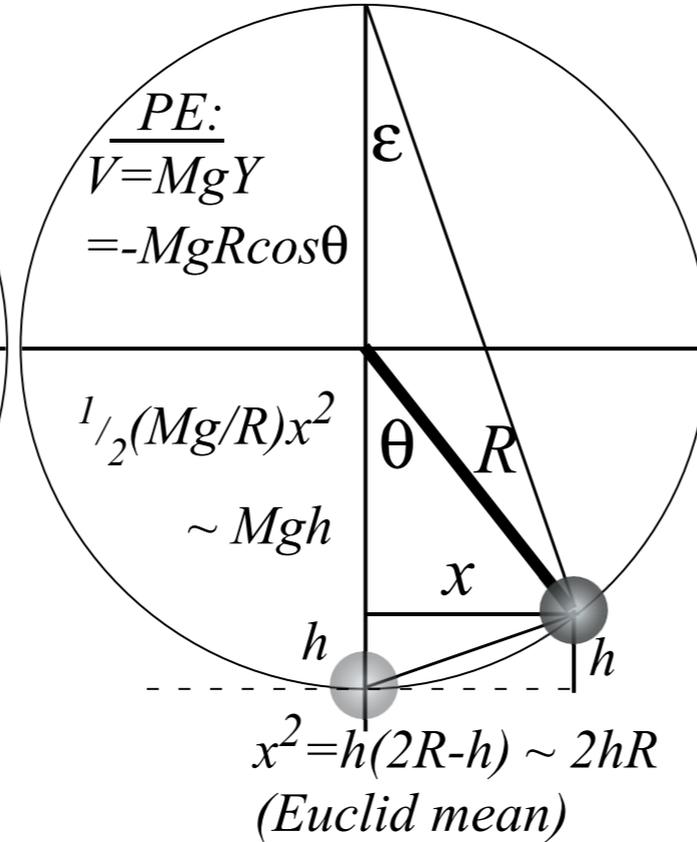
$$L(\dot{\theta}, \theta) = \frac{1}{2} I \dot{\theta}^2 - U(\theta) = \frac{1}{2} I \dot{\theta}^2 + MgR \cos \theta$$

# 1D Pendulum and phase plot

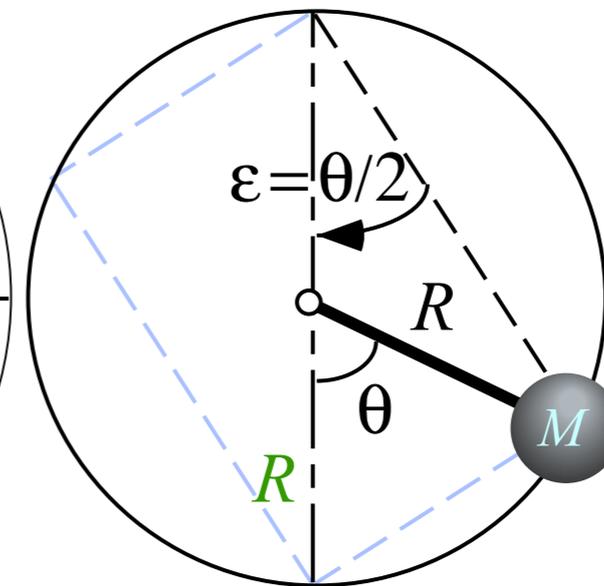
(a) Force geometry



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*Lagrangian function*  $L = KE - PE = T - U$  where potential energy is  $U(\theta) = -MgR \cos \theta$

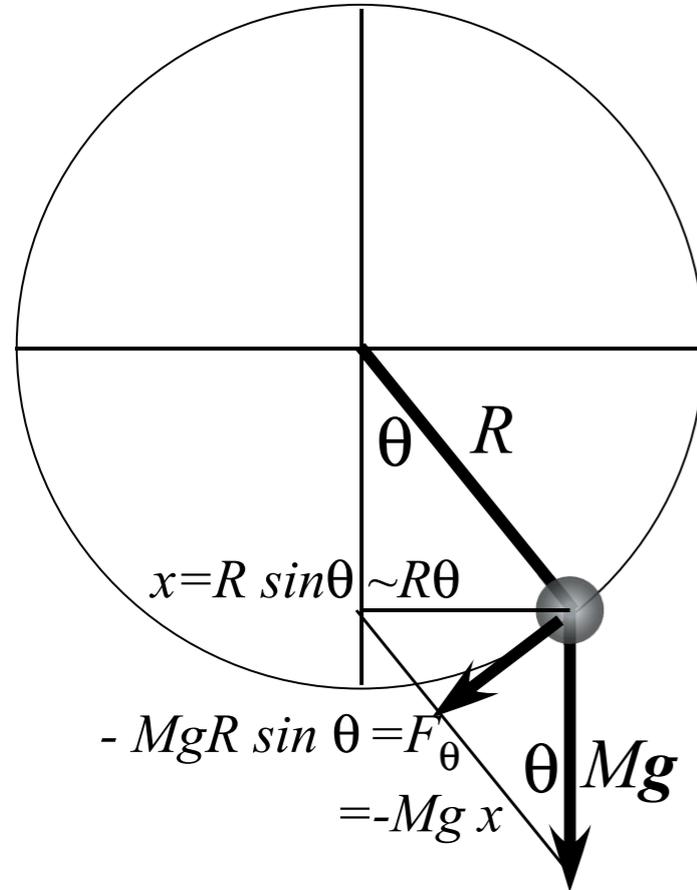
$$L(\dot{\theta}, \theta) = \frac{1}{2} I \dot{\theta}^2 - U(\theta) = \frac{1}{2} I \dot{\theta}^2 + MgR \cos \theta$$

*Hamiltonian function*  $H = KE + PE = T + U$  where potential energy is  $U(\theta) = -MgR \cos \theta$

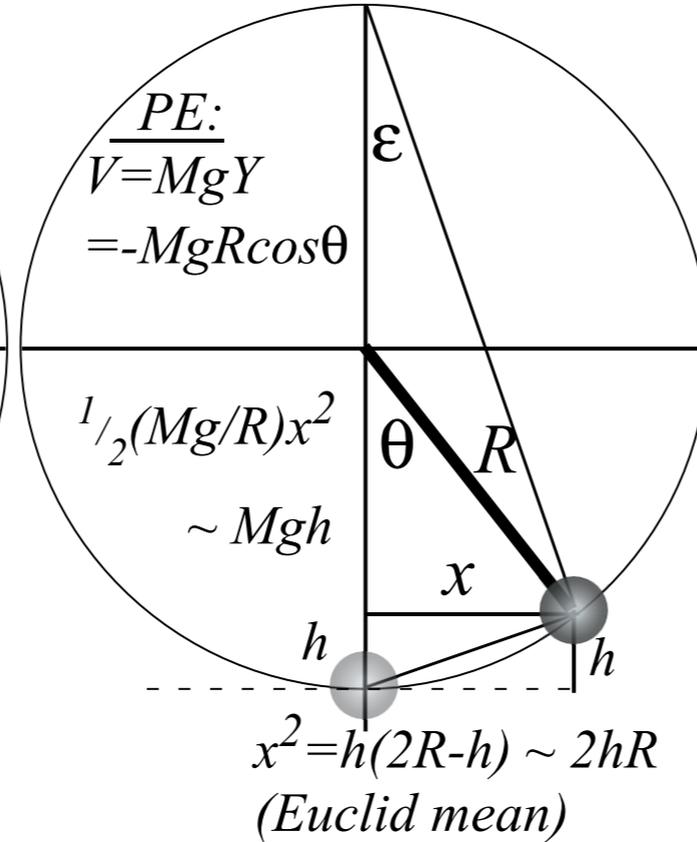
$$H(p_\theta, \theta) = \frac{1}{2I} p_\theta^2 + U(\theta) = \frac{1}{2I} p_\theta^2 - MgR \cos \theta = E = \text{const.}$$

# 1D Pendulum and phase plot

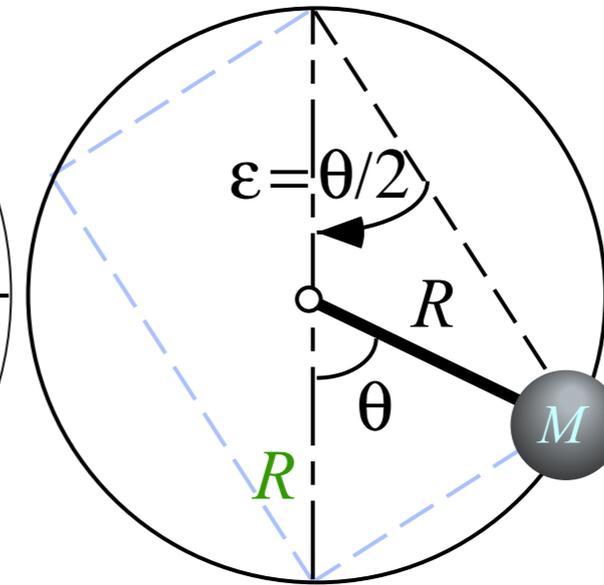
(a) Force geometry



(b) Energy geometry



(c) Time geometry



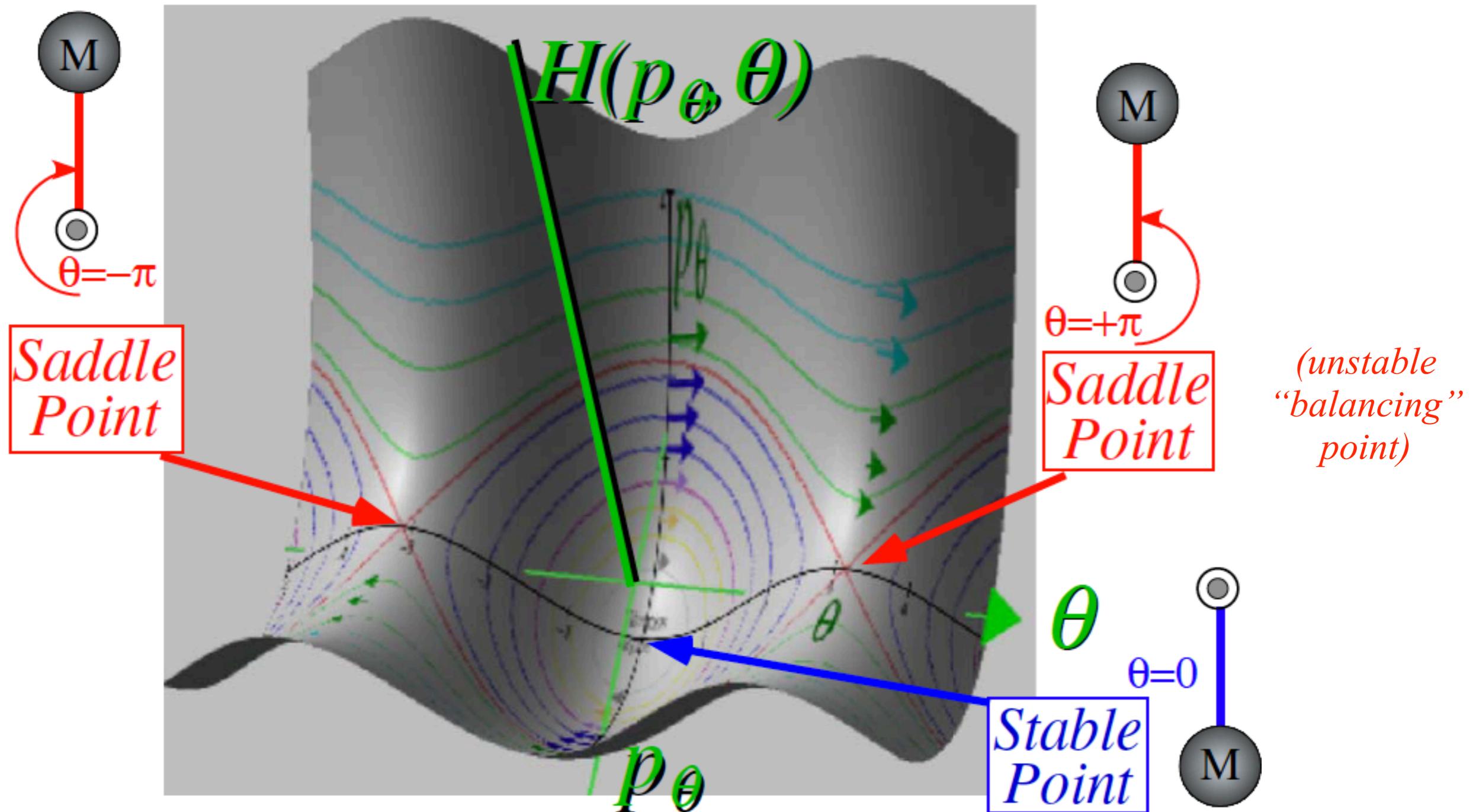
Lagrangian function  $L = KE - PE = T - U$  where potential energy is  $U(\theta) = -MgR \cos \theta$

$$L(\dot{\theta}, \theta) = \frac{1}{2} I \dot{\theta}^2 - U(\theta) = \frac{1}{2} I \dot{\theta}^2 + MgR \cos \theta$$

Hamiltonian function  $H = KE + PE = T + U$  where potential energy is  $U(\theta) = -MgR \cos \theta$

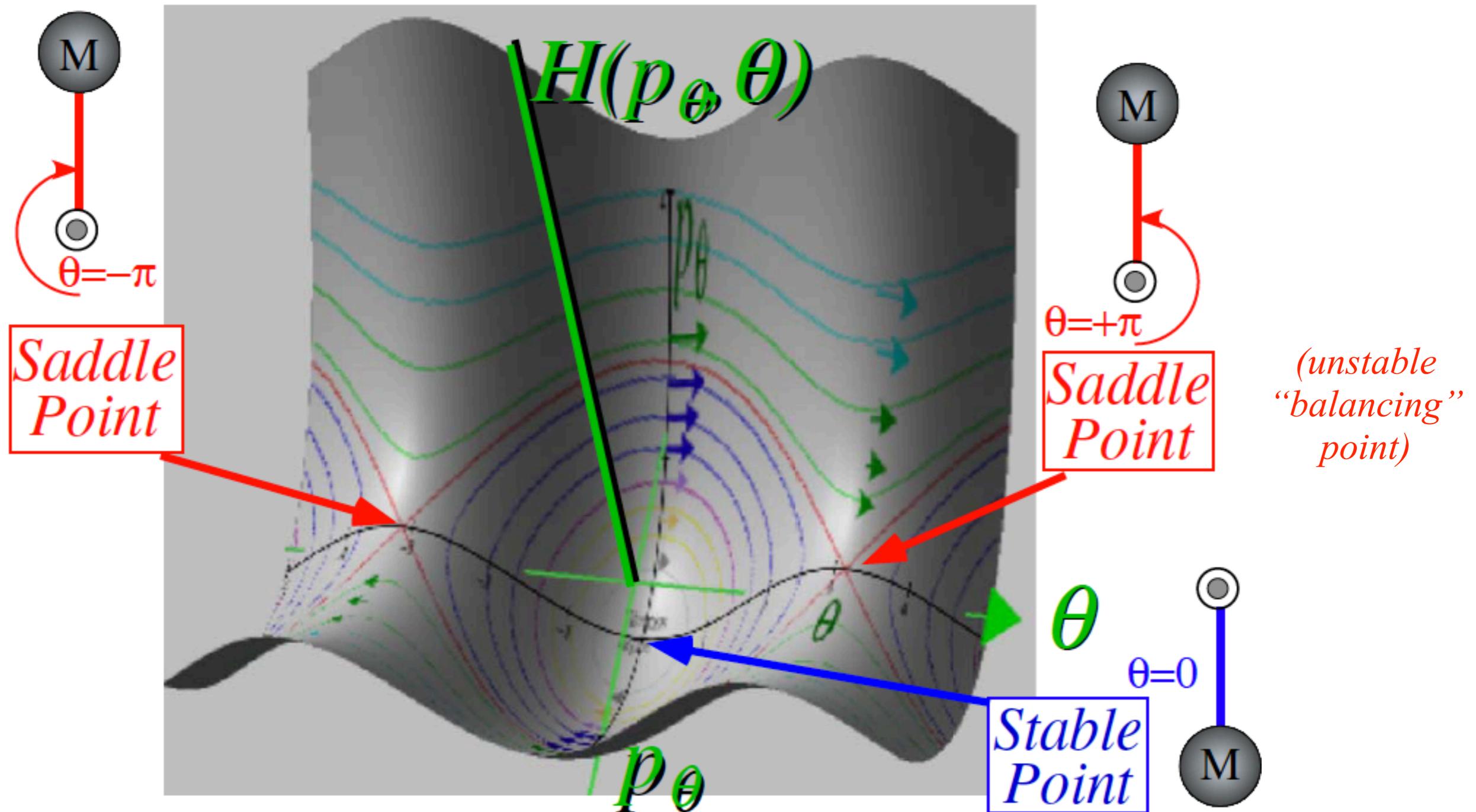
$$H(p_\theta, \theta) = \frac{1}{2I} p_\theta^2 + U(\theta) = \frac{1}{2I} p_\theta^2 - MgR \cos \theta = E = \text{const.}$$

implies:  $p_\theta = \sqrt{2I(E + MgR \cos \theta)}$



Example of plot of Hamilton for 1D-solid pendulum in its Phase Space  $(\theta, p_\theta)$

$$H(p_\theta, \theta) = E = \frac{1}{2I} p_\theta^2 - MgR \cos \theta, \quad \text{or:} \quad p_\theta = \sqrt{2I(E + MgR \cos \theta)}$$



Example of plot of Hamilton for 1D-solid pendulum in its Phase Space  $(\theta, p_\theta)$

$$H(p_\theta, \theta) = E = \frac{1}{2I} p_\theta^2 - MgR \cos \theta, \quad \text{or: } p_\theta = \sqrt{2I(E + MgR \cos \theta)}$$

Funny way to look at Hamilton's equations:

$$\begin{pmatrix} \dot{q} \\ \dot{p} \end{pmatrix} = \begin{pmatrix} \partial_p H \\ -\partial_q H \end{pmatrix} = \mathbf{e}_H \times (-\nabla H) = (\text{H-axis}) \times (\text{fall line}), \quad \text{where: } \begin{cases} (\text{H-axis}) = \mathbf{e}_H = \mathbf{e}_q \times \mathbf{e}_p \\ (\text{fall line}) = -\nabla H \end{cases}$$

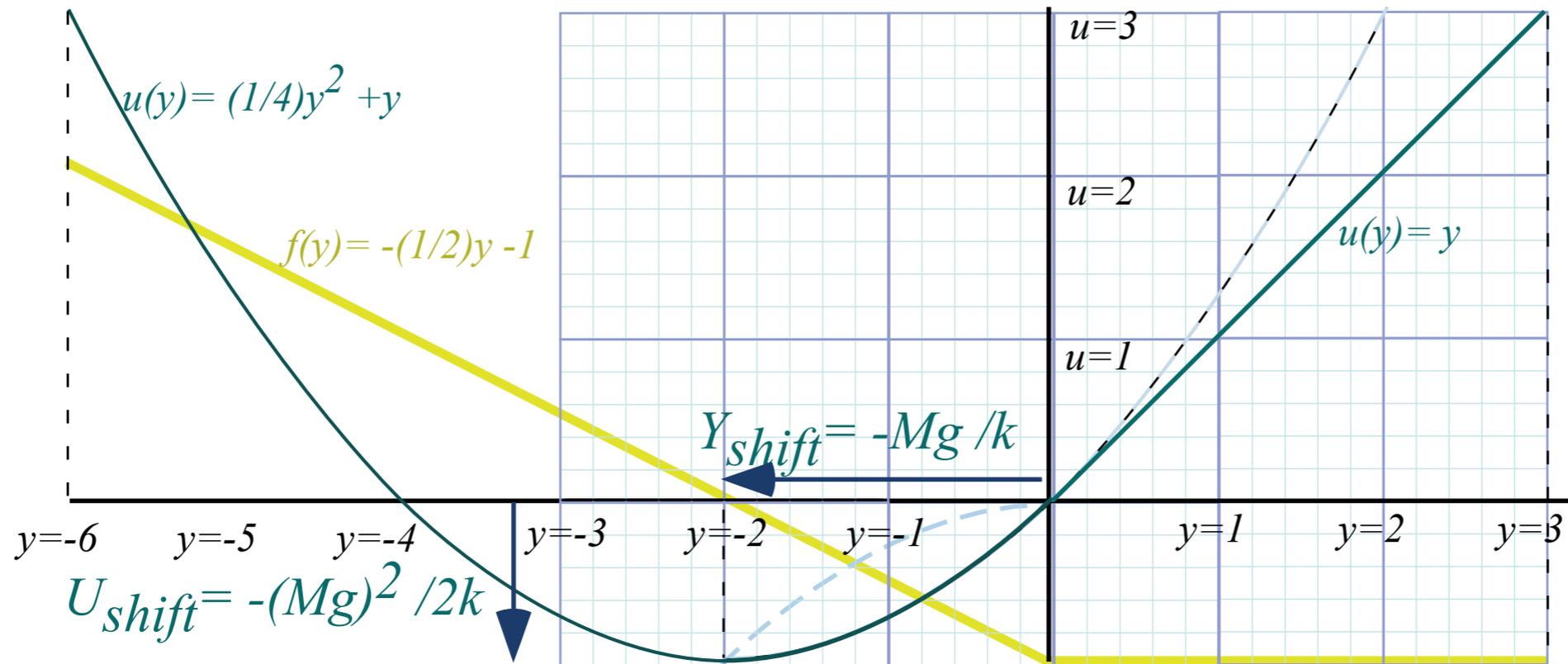
## *2. Examples of Hamiltonian dynamics and phase plots*

*1D Pendulum and phase plot (Simulation)*

 ***Phase control (Simulation)***

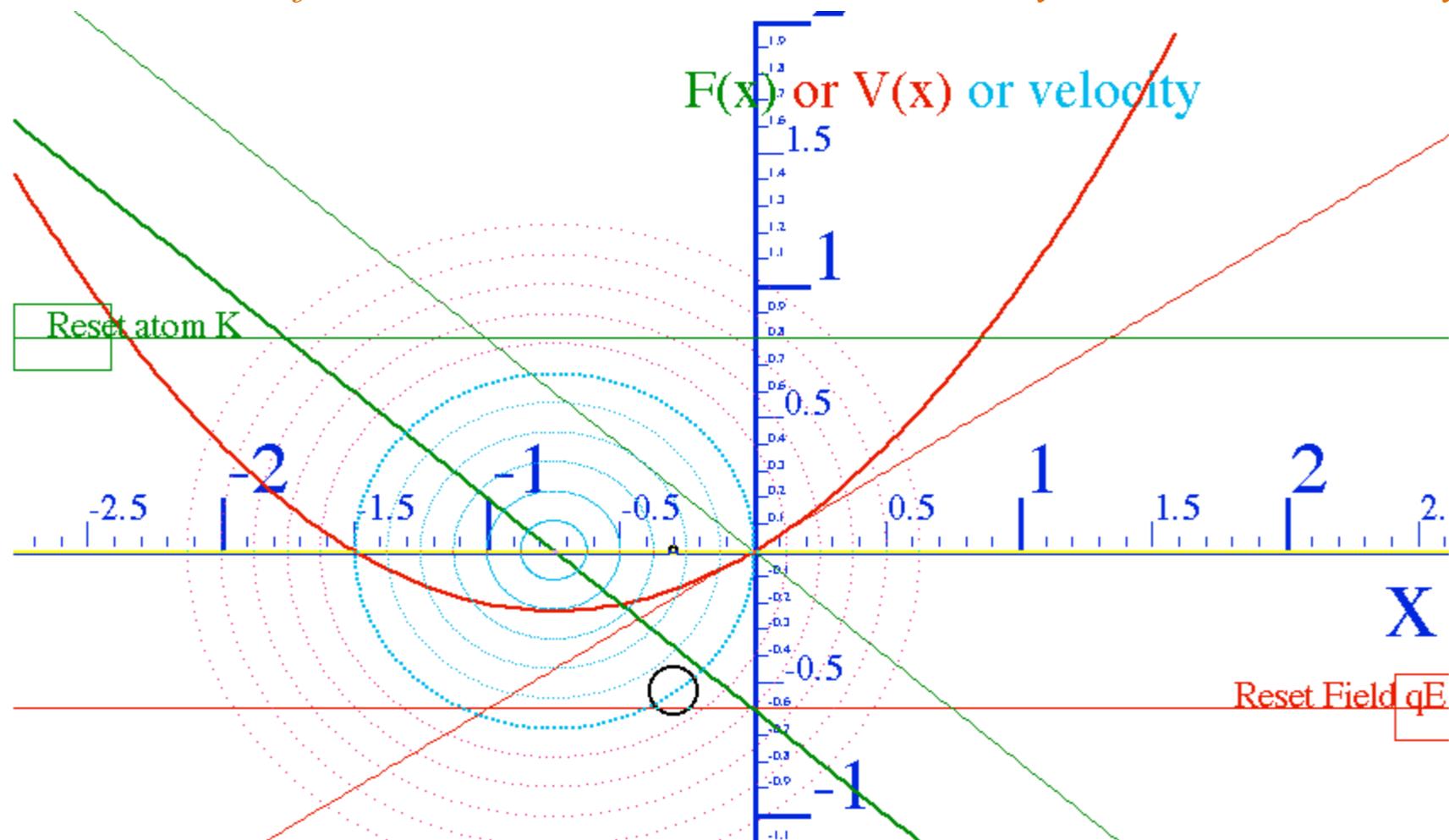
$$F(Y) = -kY - Mg$$

$$U(Y) = (1/2)kY^2 + MgY$$



Unit 1  
Fig. 7.4

*Simulation of atomic classical (or semi-classical) dynamics under varying phase control*



### *3. Exploring phase space and Lagrangian mechanics more deeply*

 *A weird “derivation” of Lagrange’s equations*

*Poincare identity and Action*

*How Classicists might have “derived” quantum equations*

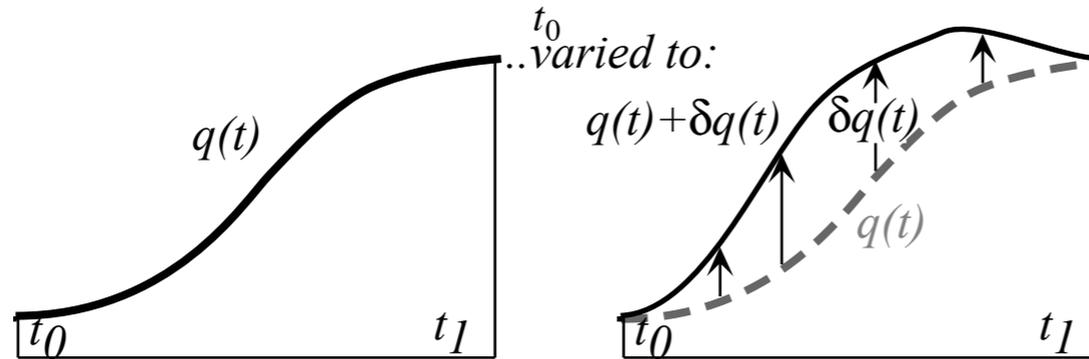
*Huygen’s contact transformations enforce minimum action*

*How to do quantum mechanics if you only know classical mechanics*

## A strange "derivation" of Lagrange's equations by Calculus of Variation

Variational calculus finds extreme (minimum or maximum) values to entire integrals

*Minimize (or maximize):*  $S(q) = \int_{t_0}^{t_1} dt L(q(t), \dot{q}(t), t).$



An arbitrary but small variation function  $\delta q(t)$  is allowed at every point  $t$  in the figure along the curve except at the end points  $t_0$  and  $t_1$ . There we demand it not vary at all. (1)

$$\delta q(t_0) = 0 = \delta q(t_1) \quad (1)$$

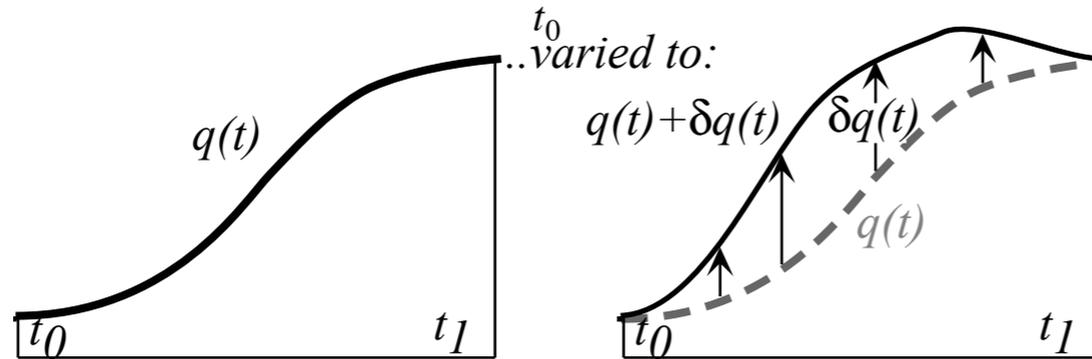
*1st order  $L(q + \delta q)$  approximate:*

$$S(q + \delta q) = \int_{t_0}^{t_1} dt \left[ L(q, \dot{q}, t) + \frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} \right] \quad \text{where: } \delta \dot{q} = \frac{d}{dt} \delta q$$

# A weird "derivation" of Lagrange's equations

Variational calculus finds extreme (minimum or maximum) values to entire integrals

$$S(q) = \int_{t_0}^{t_1} dt L(q(t), \dot{q}(t), t).$$



An arbitrary but small variation function  $\delta q(t)$  is allowed at every point  $t$  in the figure along the curve except at the end points  $t_0$  and  $t_1$ . There we demand it not vary at all. (1)

*1st order  $L(q+\delta q)$  approximate:*  $\delta q(t_0) = 0 = \delta q(t_1)$  (1)

$$S(q + \delta q) = \int_{t_0}^{t_1} dt \left[ L(q, \dot{q}, t) + \frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} \right] \text{ where: } \delta \dot{q} = \frac{d}{dt} \delta q$$

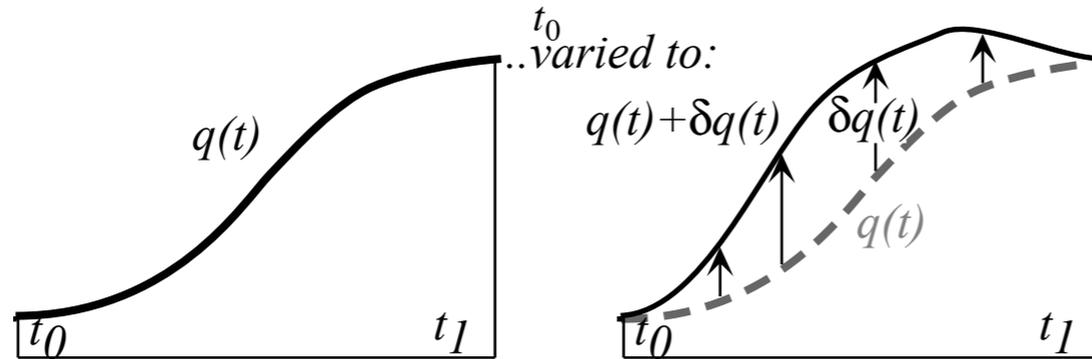
Replace  $\frac{\partial L}{\partial \dot{q}} \delta \dot{q}$  with  $\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \delta q \right) - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \delta q$

*Diagrammatic derivation of the replacement:*  $u \cdot \frac{dv}{dt} = \frac{d}{dt}(uv) - \frac{du}{dt}v$

# A weird "derivation" of Lagrange's equations

Variational calculus finds extreme (minimum or maximum) values to entire integrals

$$S(q) = \int_{t_0}^{t_1} dt L(q(t), \dot{q}(t), t).$$



An arbitrary but small variation function  $\delta q(t)$  is allowed at every point  $t$  in the figure along the curve except at the end points  $t_0$  and  $t_1$ . There we demand it not vary at all. (1)

*1st order  $L(q+\delta q)$  approximate:*  $\delta q(t_0) = 0 = \delta q(t_1)$  (1)

$$S(q + \delta q) = \int_{t_0}^{t_1} dt \left[ L(q, \dot{q}, t) + \frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} \right] \text{ where: } \delta \dot{q} = \frac{d}{dt} \delta q$$

Replace  $\frac{\partial L}{\partial \dot{q}} \delta \dot{q}$  with  $\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \delta q \right) - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \delta q$

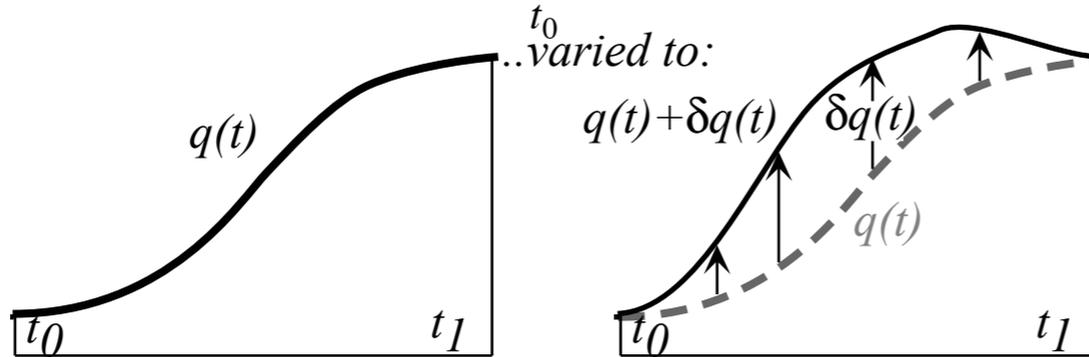
$$S(q + \delta q) = \int_{t_0}^{t_1} dt \left[ L(q, \dot{q}, t) + \frac{\partial L}{\partial q} \delta q - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \delta q \right] + \int_{t_0}^{t_1} dt \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \delta q \right)$$

*Handwritten notes:*  $u \cdot \frac{dv}{dt} = \frac{d}{dt}(uv) - \frac{du}{dt}v$

# A weird "derivation" of Lagrange's equations

Variational calculus finds extreme (minimum or maximum) values to entire integrals

$$S(q) = \int_{t_0}^{t_1} dt L(q(t), \dot{q}(t), t).$$



An arbitrary but small variation function  $\delta q(t)$  is allowed at every point  $t$  in the figure along the curve except at the end points  $t_0$  and  $t_1$ . There we demand it not vary at all. (1)

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$$S(q + \delta q) = \int_{t_0}^{t_1} dt \left[ L(q, \dot{q}, t) + \frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} \right] \text{ where: } \delta \dot{q} = \frac{d}{dt} \delta q$$

Replace  $\frac{\partial L}{\partial \dot{q}} \delta \dot{q}$  with  $\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \delta q \right) - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \delta q$

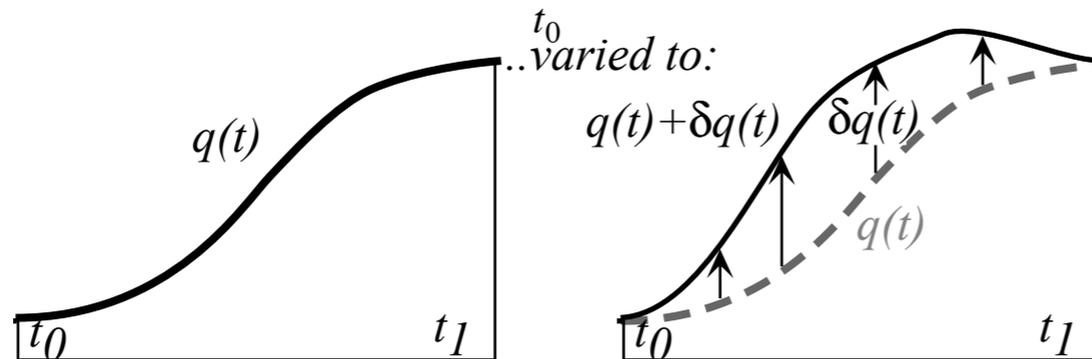
$$S(q + \delta q) = \int_{t_0}^{t_1} dt \left[ L(q, \dot{q}, t) + \frac{\partial L}{\partial q} \delta q - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \delta q \right] + \int_{t_0}^{t_1} dt \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \delta q \right)$$

$$= \int_{t_0}^{t_1} dt L(q, \dot{q}, t) + \int_{t_0}^{t_1} dt \left[ \frac{\partial L}{\partial q} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \right] \delta q + \left( \frac{\partial L}{\partial \dot{q}} \delta q \right) \Big|_{t_0}^{t_1}$$

# A weird "derivation" of Lagrange's equations

Variational calculus finds extreme (minimum or maximum) values to entire integrals

$$S(q) = \int_{t_0}^{t_1} dt L(q(t), \dot{q}(t), t).$$



An arbitrary but small variation function  $\delta q(t)$  is allowed at every point  $t$  in the figure along the curve except at the end points  $t_0$  and  $t_1$ . There we demand it not vary at all. (1)

1st order  $L(q + \delta q)$  approximate:  $\delta q(t_0) = 0 = \delta q(t_1)$  (1)

$$S(q + \delta q) = \int_{t_0}^{t_1} dt \left[ L(q, \dot{q}, t) + \frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} \right] \text{ where: } \delta \dot{q} = \frac{d}{dt} \delta q$$

Replace  $\frac{\partial L}{\partial \dot{q}} \delta \dot{q}$  with  $\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \delta q \right) - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \delta q$

$$S(q + \delta q) = \int_{t_0}^{t_1} dt \left[ L(q, \dot{q}, t) + \frac{\partial L}{\partial q} \delta q - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \delta q \right] + \int_{t_0}^{t_1} dt \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \delta q \right)$$

$$= \int_{t_0}^{t_1} dt L(q, \dot{q}, t) + \int_{t_0}^{t_1} dt \left[ \frac{\partial L}{\partial q} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \right] \delta q + \left. \left( \frac{\partial L}{\partial \dot{q}} \delta q \right) \right|_{t_0}^{t_1}$$

Third term vanishes by (1). This leaves first order variation:  $\delta S = S(q + \delta q) - S(q) = \int_{t_0}^{t_1} dt \left[ \frac{\partial L}{\partial q} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \right] \delta q$

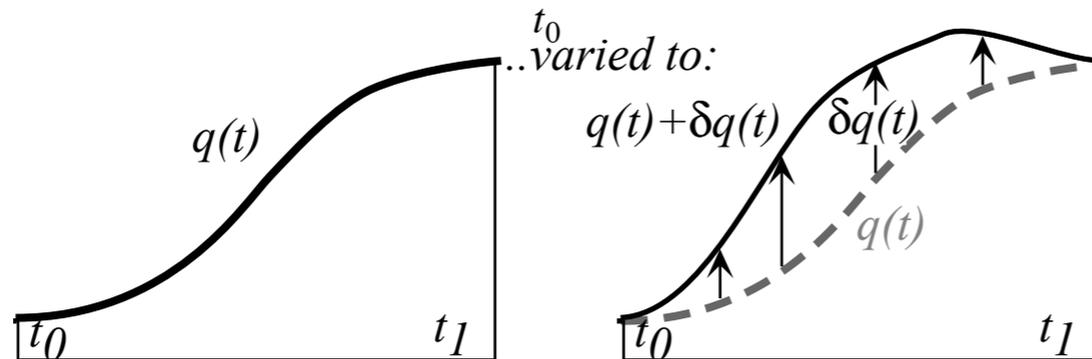
Extreme value (actually *minimum* value) of  $S(q)$  occurs *if and only if* Lagrange equation is satisfied!

$$\delta S = 0 \Rightarrow \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) - \frac{\partial L}{\partial q} = 0 \quad \text{Euler-Lagrange equation(s)}$$

# A weird "derivation" of Lagrange's equations

Variational calculus finds extreme (minimum or maximum) values to entire integrals

$$S(q) = \int_{t_0}^{t_1} dt L(q(t), \dot{q}(t), t).$$



An arbitrary but small variation function  $\delta q(t)$  is allowed at every point  $t$  in the figure along the curve except at the end points  $t_0$  and  $t_1$ . There we demand it not vary at all. (1)

1st order  $L(q + \delta q)$  approximate:  $\delta q(t_0) = 0 = \delta q(t_1)$  (1)

$$S(q + \delta q) = \int_{t_0}^{t_1} dt \left[ L(q, \dot{q}, t) + \frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} \right] \text{ where: } \delta \dot{q} = \frac{d}{dt} \delta q$$

Replace  $\frac{\partial L}{\partial \dot{q}} \delta \dot{q}$  with  $\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \delta q \right) - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \delta q$

$$S(q + \delta q) = \int_{t_0}^{t_1} dt \left[ L(q, \dot{q}, t) + \frac{\partial L}{\partial q} \delta q - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \delta q \right] + \int_{t_0}^{t_1} dt \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \delta q \right)$$

$$= \int_{t_0}^{t_1} dt L(q, \dot{q}, t) + \int_{t_0}^{t_1} dt \left[ \frac{\partial L}{\partial q} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) \right] \delta q + \left. \left( \frac{\partial L}{\partial \dot{q}} \delta q \right) \right|_{t_0}^{t_1}$$

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But, WHY is nature so inclined to fly JUST SO as to minimize the Lagrangian  $L = T - U$ ???

### *3. Exploring phase space and Lagrangian mechanics more deeply*

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*Huygen’s contact transformations enforce minimum action*

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## Legendre-Poincare identity and Action

Legendre transform  $L(\mathbf{v}) = \mathbf{p} \cdot \mathbf{v} - H(\mathbf{p})$  becomes *Poincare's invariant differential* if  $dt$  is cleared.

$$L \cdot dt = \mathbf{p} \cdot \mathbf{v} \cdot dt - H \cdot dt = \mathbf{p} \cdot d\mathbf{r} - H \cdot dt \quad \left( \mathbf{v} = \frac{d\mathbf{r}}{dt} \text{ implies: } \mathbf{v} \cdot dt = d\mathbf{r} \right)$$

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This is the time differential  $dS$  of *action*  $S = \int L \cdot dt$  whose time derivative is rate  $L$  of *quantum phase*.

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Unit 2 shows *DeBroglie law*  $\mathbf{p} = \hbar \mathbf{k}$  and *Planck law*  $H = \hbar \omega$  make *quantum plane wave phase*  $\Phi$ :

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Q: When is the *Action*-differential  $dS$  integrable?

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Similar to conditions for integrating work differential  $dW = \mathbf{f} \cdot d\mathbf{r}$  to get potential  $W(\mathbf{r})$ . That condition is **no curl allowed**:  $\nabla \times \mathbf{f} = \mathbf{0}$  or  $\partial$ -symmetry of  $W$ :

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These conditions are known as *Jacobi-Hamilton equations*

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# How Jacobi-Hamilton could have “derived” Schrodinger equations

(Given “quantum wave”)

$$\psi(\mathbf{r}, t) = e^{iS/\hbar} = e^{i(\mathbf{p}\cdot\mathbf{r} - H\cdot t)/\hbar} = e^{i(\mathbf{k}\cdot\mathbf{r} - \omega\cdot t)}$$

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$$= (i/\hbar)(-H) \psi(\mathbf{r}, t) \text{ or: } i\hbar \frac{\partial}{\partial t} \psi(\mathbf{r}, t) = H \psi(\mathbf{r}, t)$$

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# Huygen's contact transformations enforce minimum action

Each point  $\mathbf{r}_k$  on a wavefront "broadcasts" in all directions.

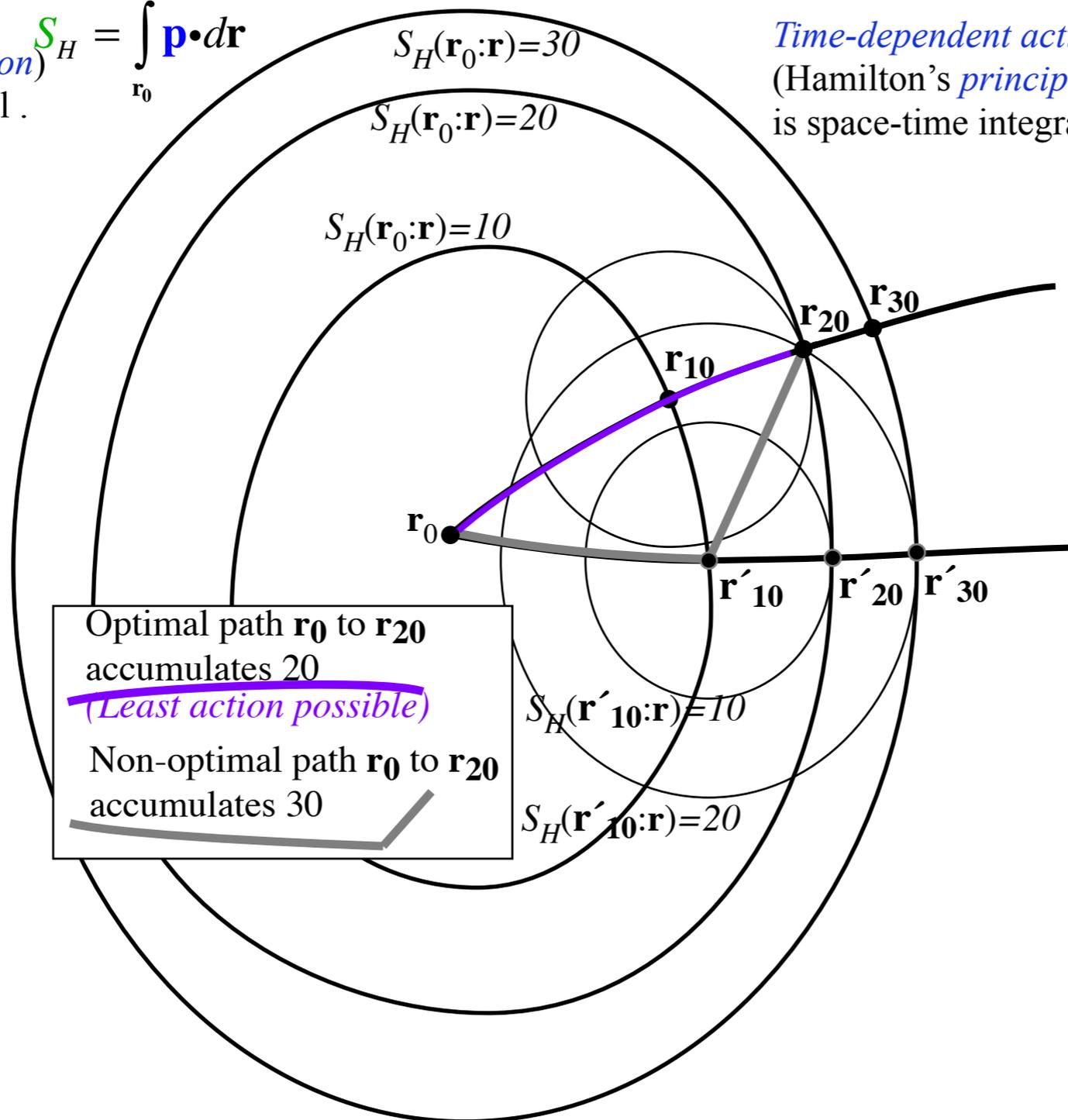
Only **minimum action** path interferes constructively

Time-independent action  
(Hamilton's *reduced action*)  
is a purely spatial integral .

$$S_H = \int_{\mathbf{r}_0}^{\mathbf{r}_1} \mathbf{p} \cdot d\mathbf{r}$$

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$$S_p = \int_{\mathbf{r}_0 t_0}^{\mathbf{r}_1 t_1} (\mathbf{p} \cdot d\mathbf{r} - H \cdot dt)$$



Unit 1  
Fig. 12.12

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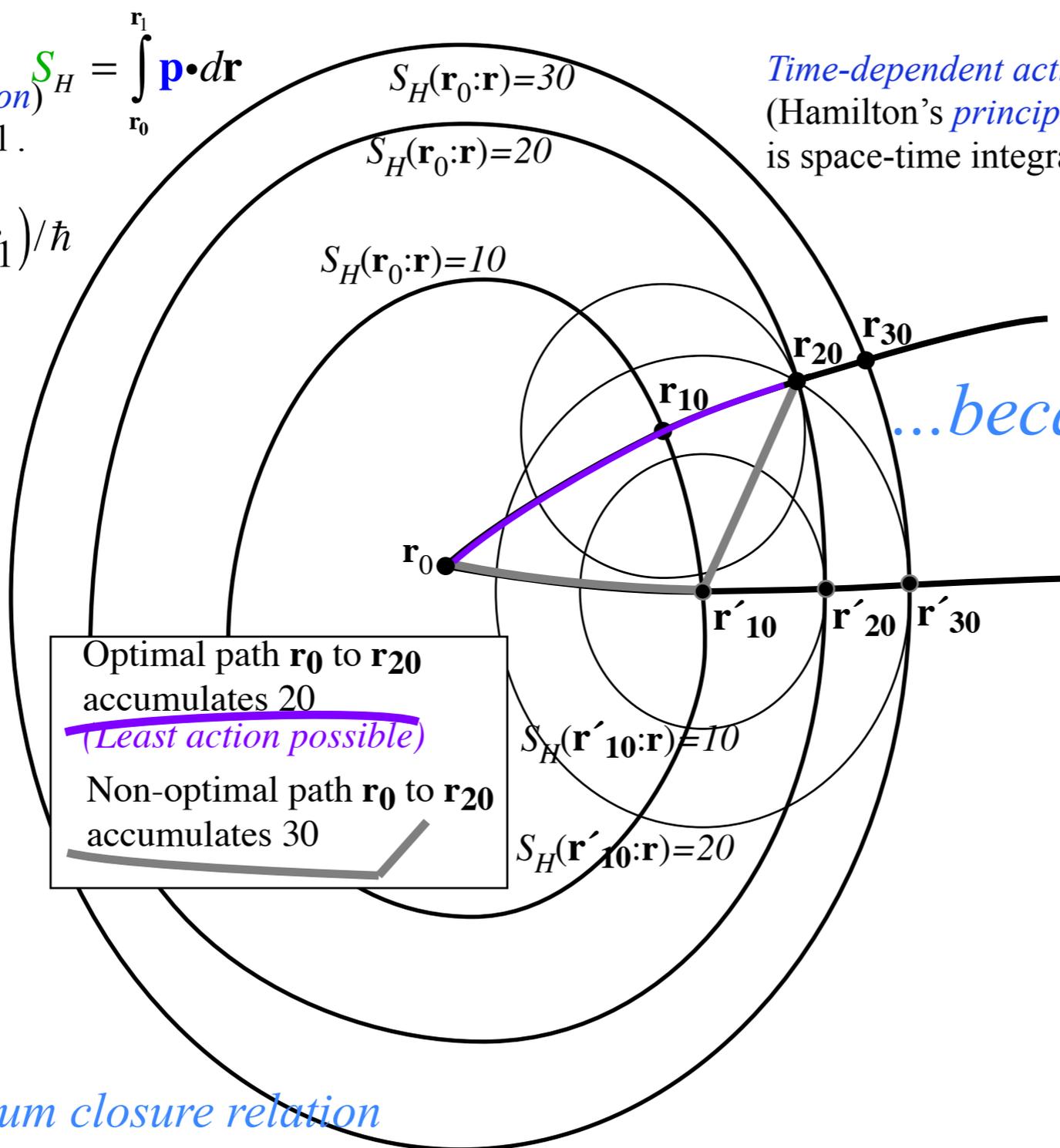
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$$\langle \mathbf{r}_1 | \mathbf{r}_0 \rangle = e^{i S_H(\mathbf{r}_0 : \mathbf{r}_1) / \hbar}$$

$$\langle \mathbf{r}_1, t_1 | \mathbf{r}_0, t_0 \rangle = e^{i S(\mathbf{r}_0, t_0 : \mathbf{r}_1, t_1) / \hbar}$$



...because action is quantum wave phase

Optimal path  $\mathbf{r}_0$  to  $\mathbf{r}_{20}$  accumulates 20  
 (Least action possible)  
 Non-optimal path  $\mathbf{r}_0$  to  $\mathbf{r}_{20}$  accumulates 30

Unit 1  
Fig. 12.12

## Feynman's path-sum closure relation

$$\sum_{\mathbf{r}'} \langle \mathbf{r}_1 | \mathbf{r}' \rangle \langle \mathbf{r}' | \mathbf{r}_0 \rangle \equiv \sum_{\mathbf{r}'} e^{i(S_H(\mathbf{r}_0 : \mathbf{r}') + S_H(\mathbf{r}' : \mathbf{r}_1)) / \hbar} = e^{i S_H(\mathbf{r}_0 : \mathbf{r}_1) / \hbar} = \langle \mathbf{r}_1 | \mathbf{r}_0 \rangle$$

### *3. Exploring phase space and Lagrangian mechanics more deeply*

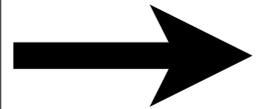
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# How to do quantum mechanics if you only know classical mechanics

*Bohr quantization* requires quantum phase  $S_H/\hbar$  in amplitude to be an integral multiple  $n$  of  $2\pi$  after a closed loop integral  $S_H(\mathbf{r}_0:\mathbf{r}_0) = \int_{r_0}^{r_0} \mathbf{p} \cdot d\mathbf{r}$ . The integer  $n$  ( $n = 0, 1, 2, \dots$ ) is a *quantum number*.

$$1 = \langle \mathbf{r}_0 | \mathbf{r}_0 \rangle = e^{i S_H(\mathbf{r}_0:\mathbf{r}_0)/\hbar} = e^{i \Sigma_H/\hbar} = 1 \quad \text{for: } \Sigma_H = 2\pi \hbar n = h n$$

Numerically integrate Hamilton's equations and Lagrangian  $L$ . Color the trajectory according to the current accumulated value of action  $S_H(\mathbf{0} : \mathbf{r})/\hbar$ . Adjust energy to quantized pattern (if closed system\*)

$$S_H(\mathbf{0} : \mathbf{r}) = S_p(\mathbf{0}, 0 : \mathbf{r}, t) + Ht = \int_0^t L dt + Ht .$$

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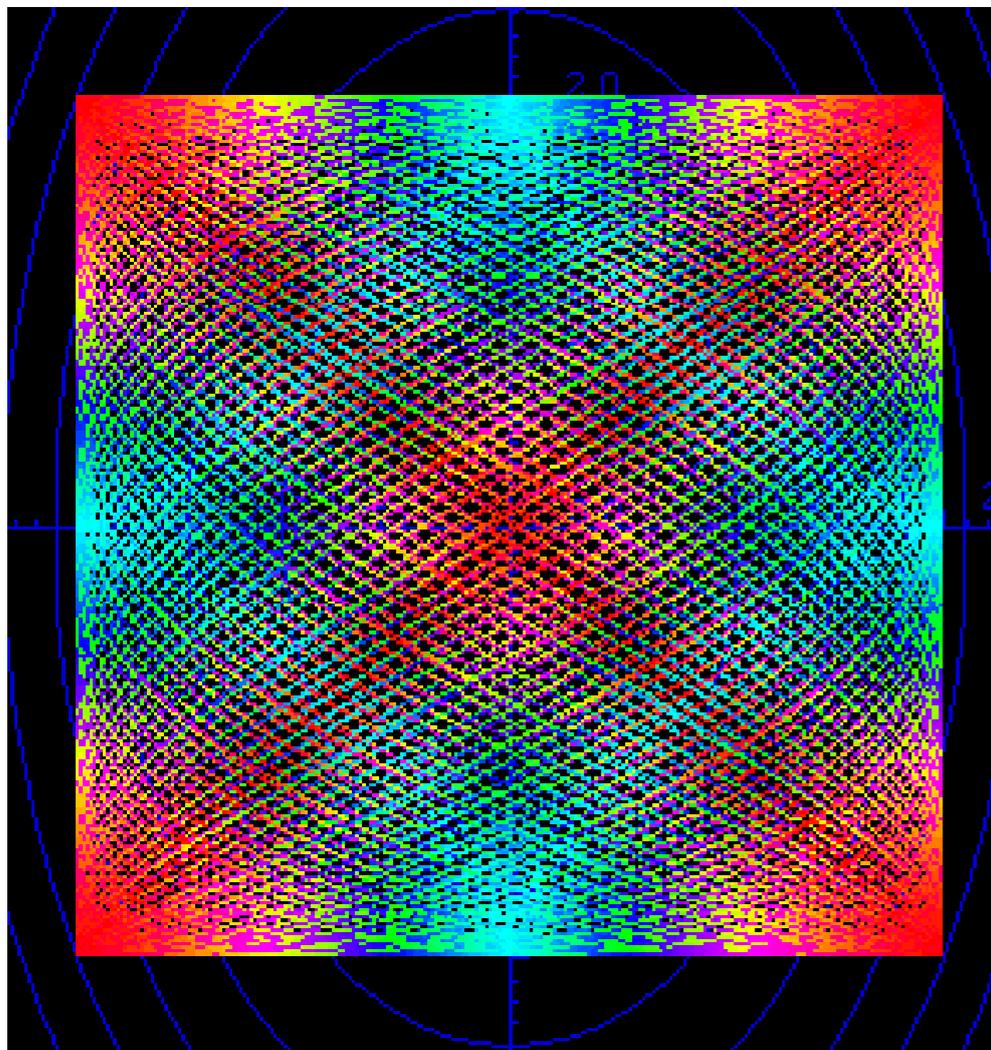
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$0=\text{red}$ ,  $\pi/4=\text{orange}$ ,  $\pi/2=\text{yellow}$ ,  $3\pi/4=\text{green}$ ,  $\pi=\text{cyan}$  (opposite of red),  $5\pi/4=\text{indigo}$ ,  $3\pi/2=\text{blue}$ ,  $7\pi/4=\text{purple}$ , and  $2\pi=\text{red}$  (full color circle).

Interpolating action on a palette of 32 colors is enough precision for low quanta.



Unit 1  
Fig.  
12.13

# How to do quantum mechanics if you only know classical mechanics

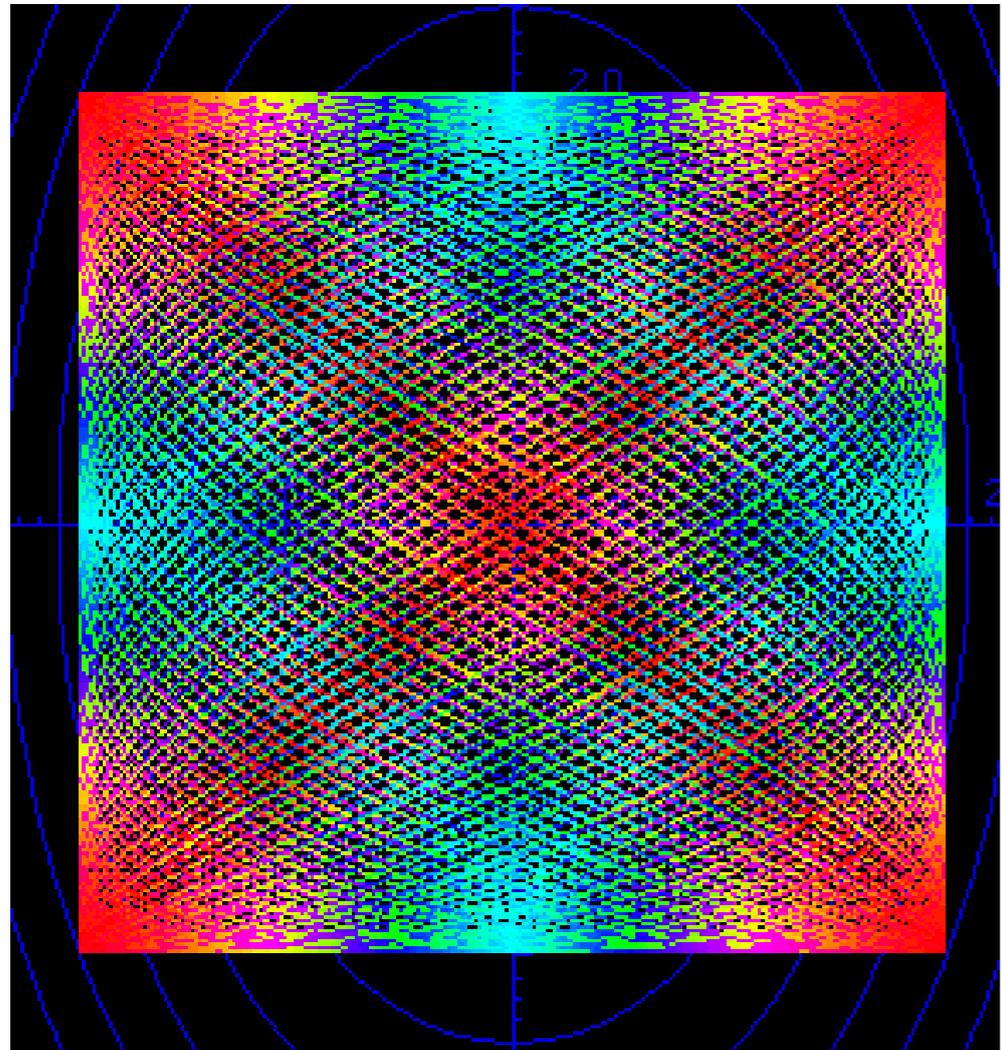
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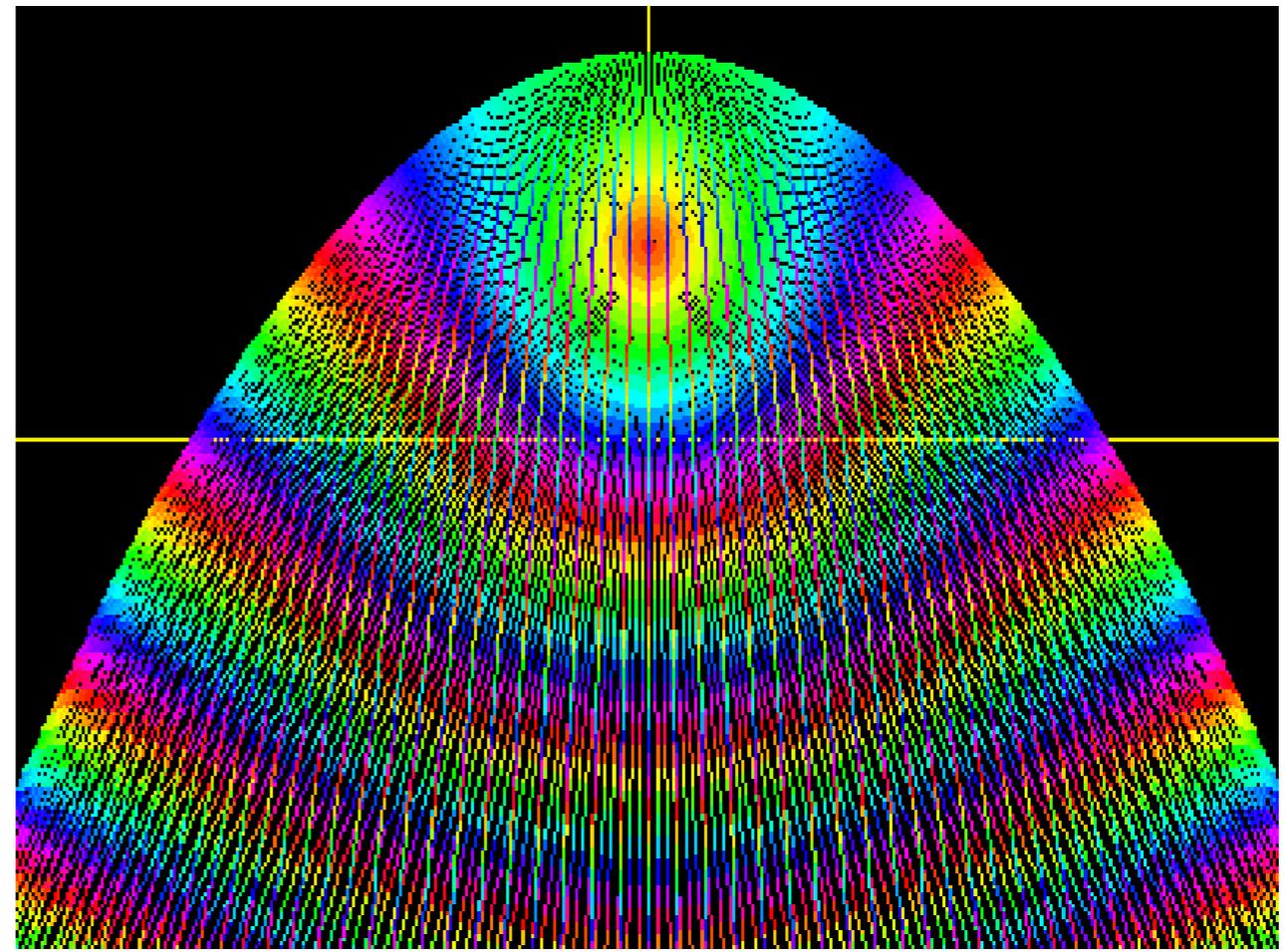
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Unit 1  
Fig.  
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\*open system has continuous energy

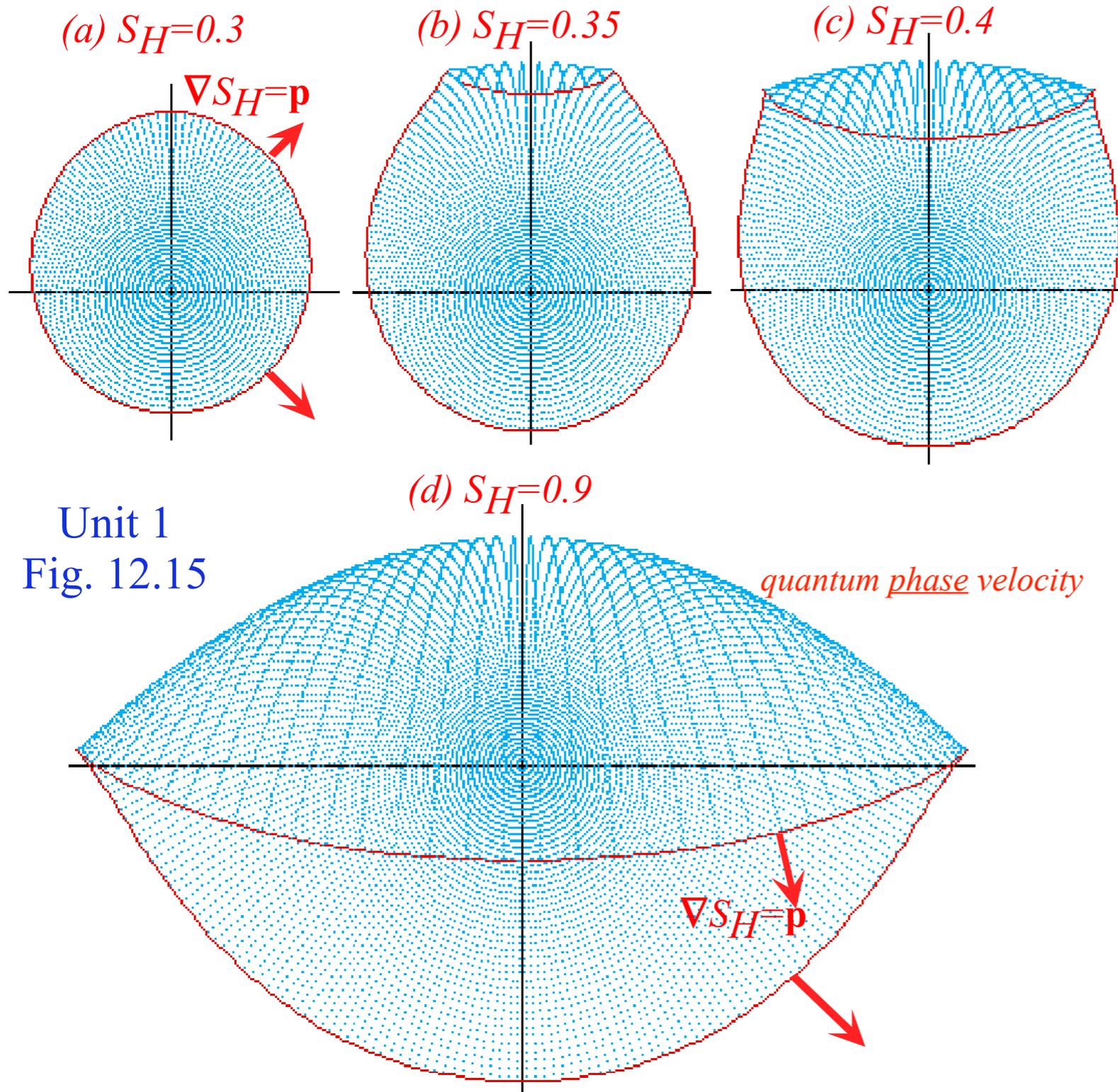


Unit 1  
Fig.  
12.14

A moving wave has a *quantum phase velocity* found by setting  $S = \text{const.}$  or  $dS(0,0:r,t) = 0 = \mathbf{p} \cdot d\mathbf{r} - H dt$ .

$$\mathbf{v}_{\text{phase}} = \frac{d\mathbf{r}}{dt} = \frac{H}{\mathbf{p}} = \frac{\omega}{\mathbf{k}}$$

*Quantum "phase wavefronts"*



Unit 1  
Fig. 12.15

A moving wave has a *quantum phase velocity* found by setting  $S=const.$  or  $dS(0,0:r,t)=0=\mathbf{p}\cdot d\mathbf{r}-Hdt.$

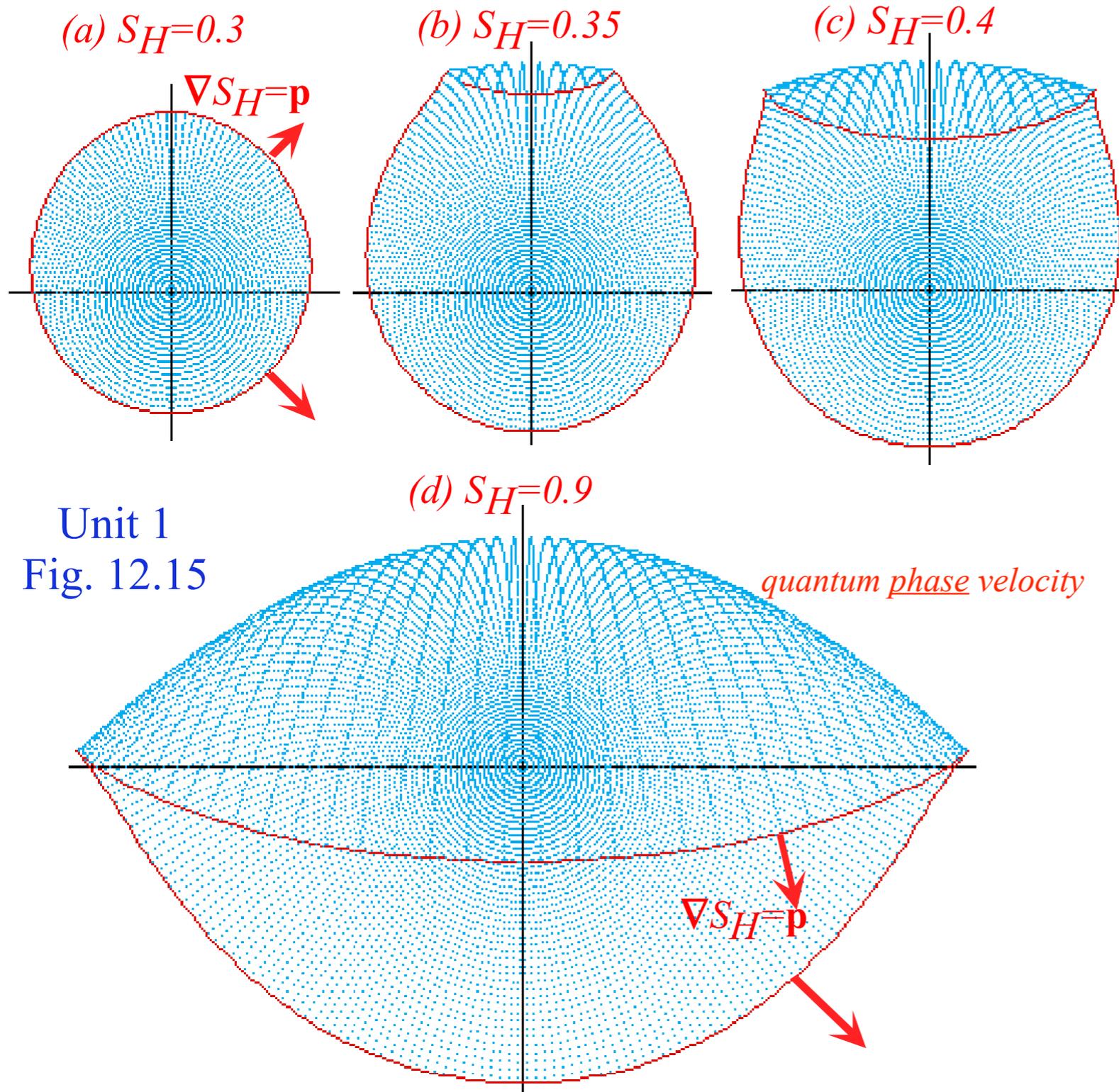
$$\mathbf{V}_{phase} = \frac{d\mathbf{r}}{dt} = \frac{H}{\mathbf{p}} = \frac{\omega}{\mathbf{k}}$$

This is quite the opposite of classical particle velocity which is *quantum group velocity*.

$$\mathbf{V}_{group} = \frac{d\mathbf{r}}{dt} = \dot{\mathbf{r}} = \frac{\partial H}{\partial \mathbf{p}} = \frac{\partial \omega}{\partial \mathbf{k}}$$

Note: This is Hamilton's 1<sup>st</sup> Equation

*Quantum "phase wavefronts"*



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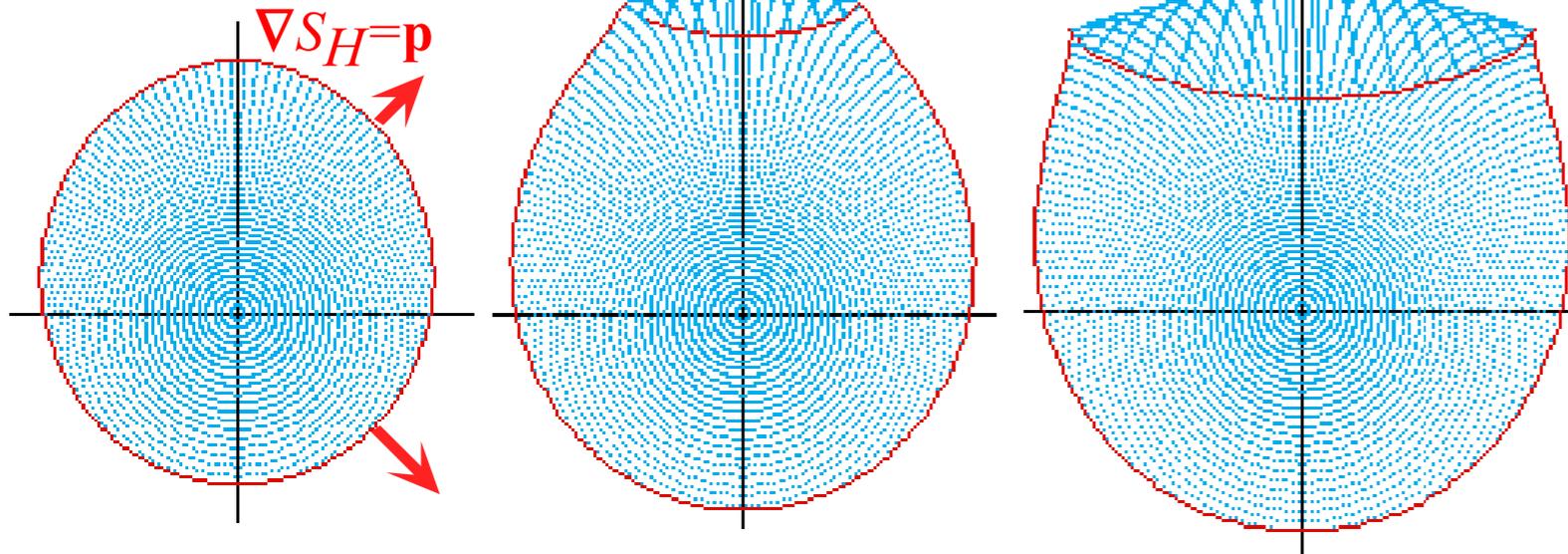
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*Quantum "phase wavefronts"*

(a)  $S_H=0.3$

(b)  $S_H=0.35$

(c)  $S_H=0.4$



(d)  $S_H=0.9$

higher  $V_{phase}$  up here

quantum phase velocity

Unit 1  
Fig. 12.15

lower  $V_{phase}$  down here

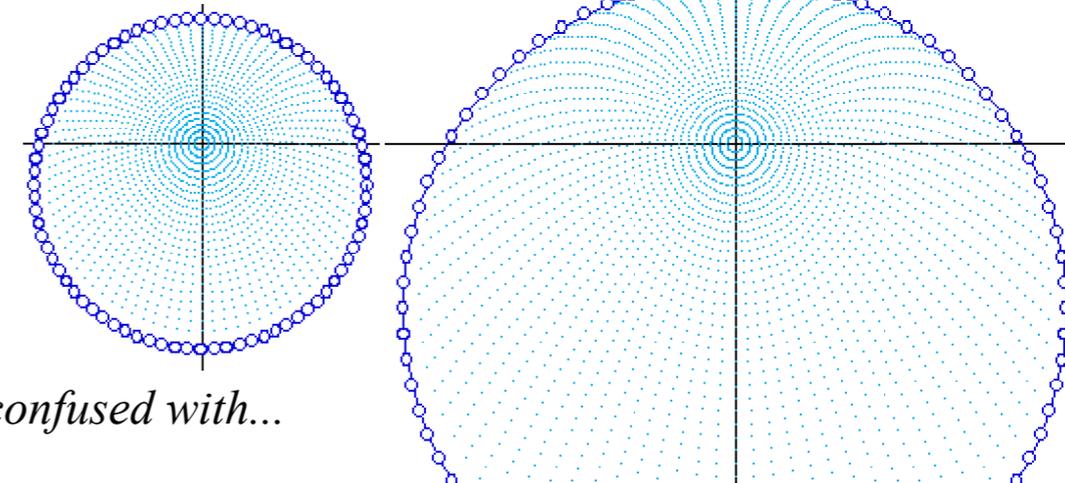
$\nabla S_H = \mathbf{p}$

...not to be confused with...

*Classical "blast wavefronts"*

(a)  $T=0.4$

(b)  $T=1.0$



...quantum group velocity...  
that is classical particle velocity

(c)  $T=2.3$

lower  $V_{group}$  up here

higher  $V_{group}$  down here

