

Lecture 21

Wed. 11.06.2019

Introduction to coupled oscillation and eigenmodes

(Ch. 2-4 of Unit 4)

2D harmonic oscillator equations

Lagrangian and matrix forms and Reciprocity symmetry

2D harmonic oscillator equation eigensolutions

Geometric method

Matrix-algebraic eigensolutions with example $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

Secular equation

Hamilton-Cayley equation and projectors

Idempotent projectors (how eigenvalues \Rightarrow eigenvectors)

Operator orthonormality and Completeness (Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

Spectral Decompositions

Functional spectral decomposition

Orthonormality vs. Completeness vis-a`-vis Operator vs. State

Lagrange functional interpolation formula

Diagonalizing Transformations (D-Ttran) from projectors

2D-HO eigensolution example with bilateral (B-Type) symmetry

Mixed mode beat dynamics and fixed $\pi/2$ phase

2D-HO eigensolution example with asymmetric (A-Type) symmetry

Initial state projection, mixed mode beat dynamics with variable phase



This Lecture's Reference Link Listing

[Web Resources - front page](#)

[UAF Physics UTube channel](#)

[Wiki on Pafnuty Chebyshev](#)

[Nobelprize.org](#)

[2005 Physics Award](#)

BoxIt Web Simulations:

[A-Type w/Cosine](#), [A-Type w/Freq ratios](#),

[AB-Type w/Cosine](#), [AB-Type 2:1 Freq ratio](#)

OscillIt Web Simulations:

[Default/Generic](#), [Weakly Damped #18](#),

Forced : [Way below resonance](#), [On resonance](#)

[Way above resonance](#), [Underdamped](#)

[Complex Response Plot](#)

Coult Web Simulations:

[Stark-Coulomb : Bound-state motion in parabolic coordinates](#)

[Molecular Ion : Bound-state motion in hyperbolic coordinates](#)

[Synchrotron Motion](#), [Synchrotron Motion #2](#)

[Mechanical Analog to EM Motion \(YouTube video\)](#)

[iBall demo - Quasi-periodicity \(YouTube video\)](#)

Trebuchet Web Simulations:

[Default/Generic URL](#), [Montezuma's Revenge](#), [Seige of Kenilworth](#),
["Flinger"](#),

[Position Space \(Course\)](#), [Position Space \(Fine\)](#)

[Wacky Waving Solid Metal Arm Flailing Chaos Pendulum - Scooba_ Steeve-yt-2015](#)

[Triple Double-Pendulum - Cohen-yt-2008](#)

[Punkin Chunkin - TheArmchairCritic-2011](#)

[Jersey Team Claims Title in Punkin Chunkin - sussexcountyonline-1999](#)

[Shooting range for medieval siege weapons. Anybody knows? - twcenter.net/forums](#)

[The Trebuchet - Chevedden-SciAm-1995](#)

[NOVA Builds a Trebuchet](#)

Recent Articles of Interest:

[Quantum Supremacy Using a Programmable Superconducting Processor - Arute-n-2019](#)

[This Indestructible NASA Camera Revealed Hidden Patterns on Jupiter - seeker-yt-2019](#)

[What did NASA's New Horizons discover around Pluto? - Astrum-yt-2018](#)

[Synthetic Chiral Light for Efficient Control of Chiral Light-Matter Interaction - Ayuso-np-2019](#)

[Quantum Computing for Computer Scientists - Helwer-mr-yt-2018](#), Slides

[Quantum Computing and Workforce, Curriculum, and App Devel - Roetteler-MS-2019](#)

[A Semi-Classical Approach to the Calculation of Highly Excited Rotational Energies for ...](#)

[Asymmetric-Top Molecules - Schmiedt-pccp-2017](#)

[Quantum Chaos - An Introduction - Stockmann-cup-2006](#), Review by E. Heller

[Tunable and broadband coherent perfect absorption by ultrathin blk phos metasurfaces - Guo-josab-2019](#)

[Vortex Detection in Vector Fields Using Geometric Algebra - Pollock-aaca-2013.pdf](#)

[Quantum Theory for the Computer Age](#)

[Principles of Symmetry, Dynamics, and Spectroscopy](#)

[Classical Mechanics with a Bang!](#)

[Modern Physics and its Classical Foundations](#)

Lectures #12 through #21

In reverse order

[2017 Group Theory for QM](#)

[2018 Adv CM](#)

[2018 AMOP](#)

[2019 Advanced Mechanics](#)

Pirelli Relativity Challenge (Introduction level) - Visualizing Waves:

[Using Earth as a clock](#),

[Tesla's AC Phasors](#) ,

[Phasors using complex numbers](#).

[CM wBang Unit 1 - Chapter 10, pdf_page=135](#)

[Calculus of exponentials, logarithms, and complex fields](#),

[RelaWavity Web Simulation - Unit Circle and Hyperbola \(Mixed labeling\)](#)

[Smith Chart, Invented by Phillip H. Smith \(1905-1987\)](#)

Select, exciting, and related Research

[Springer handbook on Molecular Symmetry and Dynamics - Ch_32 - Molecular Symmetry](#)

[AMOP Ch 0 Space-Time Symmetry - 2019](#)

[Seminar at Rochester Institute of Optics, Auxiliary slides, June 19, 2018](#)

[Clifford Algebra And The Projective Model Of Homogeneous Metric Spaces - Foundations - Sokolov-x-2013](#)

[Geometric Algebra 3 - Complex Numbers - MacDonald-yt-2015](#)

[Biquaternion -Complexified Quaternion- Roots of -1 - Sangwine-x-2015](#)

[An Introduction to Clifford Algebras and Spinors - Vaz-Rocha-op-2016](#)

[Unified View on Complex Numbers and Quaternions- Bongardt-wcmms-2015](#)

[Complex Functions and the Cauchy-Riemann Equations - complex2 - Friedman-columbia-2019](#)

[An sp-hybridized Molecular Carbon Allotrope- cyclo-18-carbon - Kaiser-s-2019](#)

[An Atomic-Scale View of Cyclocarbon Synthesis - Maier-s-2019](#)

[Discovery Of Topological Weyl Fermion Lines And Drumhead Surface States in a Room Temperature Magnet - Belopolski-s-2019](#)

["Weyl"ing away Time-reversal Symmetry - Neto-s-2019](#)

[Non-Abelian Band Topology in Noninteracting Metals - Wu-s-2019](#)

[What Industry Can Teach Academia - Mao-s-2019](#)

[RoVib- quantum state resolution of the C60 fullerene - Changala-Ye-s-2019 \(Alt\)](#)

[A Degenerate Fermi Gas of Polar molecules - DeMarco-s-2019](#)

An assist from Physics Girl (YouTube Channel):

[How to Make VORTEX RINGS in a Pool](#)

[Crazy pool vortex - pg-yt-2014](#)

[Fun with Vortex Rings in the Pool - pg-yt-2014](#)

Excerpts (Page 44-47 in Preliminary Draft) from the [Geometric Algebra- A Guided Tour through Space and Time - Reimer-www-2019](#)

Running Reference Link Listing

Lectures #11 through #7

In reverse order

Eric J Heller Gallery:

[Main portal](#), [Consonance and Dissonance II](#), [Bessel 21](#), [Chladni](#)

[The Semiclassical Way to Molecular Spectroscopy - Heller-acs-1981](#)
[Quantum dynamical tunneling in bound states - Davis-Heller-jcp-1981](#)

[Pendulum Web Simulation](#)

[Cycloidulum Web Simulation](#)

Links to previous lecture: [Page=74](#), [Page=75](#), [Page=79](#)

[Pendulum Web Sim](#)

[Cycloidulum Web Sim](#)

JerkIt Web Simulations: [Basic/Generic](#); [Inverted](#), [FVPlot](#)

[CMwithBang Lecture 8, page=20](#)

[WWW.sciencenewsforstudents.org: Cassini - Saturnian polar vortex](#)

“RelaWavity” Web Simulations:

[2-CW laser wave](#), [Lagrangian vs Hamiltonian](#),

[Physical Terms Lagrangian L\(u\) vs Hamiltonian H\(p\)](#)

[CoulIt Web Simulation of the Volcanoes of Io](#)

[BohrIt Multi-Panel Plot:](#)

[Relativistically shifted Time-Space plots of 2 CW light waves](#)

BoxIt Web Simulations:

[Generic/Default](#)

[Most Basic A-Type](#)

[Basic A-Type w/reference lines](#)

[Basic A-Type A-Type with Potential energy](#)

[A-Type with Potential energy and Stokes Plot](#)

[A-Type w/3 time rates of change](#)

[A-Type w/3 time rates of change with Stokes Plot](#)

[B-Type \(A=1.0, B=-0.05, C=0.0, D=1.0\)](#)

RelaWavity Web Elliptical Motion Simulations:

[Orbits with b/a=0.125](#)

[Orbits with b/a=0.5](#)

[Orbits with b/a=0.7](#)

[Exegesis with b/a=0.125](#)

[Exegesis with b/a=0.5](#)

[Exegesis with b/a=0.7](#)

[Contact Ellipsometry](#)

CoulIt Web Simulations:

[Basic/Generic](#)

[Exploding Starlet](#)

[Volcanoes of Io \(Color Quantized\)](#)

JerkIt Web Simulations:

[Basic/Generic](#)

[Catcher in the Eye - IHO with Linear Hooke perturbation - Force-potential-Velocity Plot](#)

OscillatorPE Web Simulation:

[Coulomb-Newton-Inverse Square](#),

[Hooke-Isotropic Harmonic](#),

[Pendulum-Circular Constraint](#)

[AMOP Ch 0 Space-Time Symmetry - 2019](#)

[Seminar at Rochester Institute of Optics, Aux. slides-2018](#)

[NASA Astronomy Picture of the Day -](#)

[Io: The Prometheus Plume \(Just Image\)](#)

[NASA Galileo - Io's Alien Volcanoes](#)

[New Horizons - Volcanic Eruption Plume on Jupiter's moon IO](#)

[NASA Galileo - A Hawaiian-Style Volcano on Io](#)

[Pirelli Site: Phasors animation](#)

[CMwithBang Lecture #6, page=70 \(9.10.18\)](#)

Select, exciting, and related Research & Articles of Interest:

[Burning a hole in reality—design for a new laser may be powerful enough to pierce space-time - Sumner-KOS-2019](#)

[Trampoline mirror may push laser pulse through fabric of the Universe - Lee-ArsTechnica-2019](#)

[Achieving Extreme Light Intensities using Optically Curved Relativistic Plasma Mirrors - Vincenti-prl-2019](#)

[A Soft Matter Computer for Soft Robots - Garrad-sr-2019](#)

[Correlated Insulator Behaviour at Half-Filling in Magic-Angle Graphene Superlattices - cao-n-2018](#)

[Sorting ultracold atoms in a three-dimensional optical lattice in a realization of Maxwell's Demon - Kumar-n-2018](#)

[Synthetic three-dimensional atomic structures assembled atom by atom - Barredo-n-2018](#)

Older ones:

[Wave-particle duality of C60 molecules - Arndt-ltn-1999](#)

[Optical Vortex Knots - One Photon At A Time - Tempone-Wiltshire-Sr-2018](#)

[Baryon Deceleration by Strong Chromofields in Ultrarelativistic](#)

[Nuclear Collisions - Mishustin-PhysRevC-2007, APS Link & Abstract](#)

[Hadronic Molecules - Guo-x-2017](#)

[Hidden-charm pentaquark and tetraquark states - Chen-pr-2016](#)

Running Reference Link Listing

Lectures #6 through #1

In reverse order

[RelaWavity Web Simulation: Contact Ellipsometry](#)

[BoxIt Web Simulation: Elliptical Motion \(A-Type\)](#)

[CMwBang Course: Site Title Page](#)

[Pirelli Relativity Challenge: Describing Wave Motion With Complex Phasors](#)

[UAF Physics UTube channel](#)

[Velocity Amplification in Collision Experiments Involving Superballs - Harter, 1971](#)

[MIT OpenCourseWare: High School/Physics/Impulse and Momentum](#)

[Hubble Site: Supernova - SN 1987A](#)

BounceIt Web Animation - Scenarios:

[49:1 y vs t, 49:1 V2 vs V1, 1:500:1 - 1D Gas Model w/ faux restorative force \(Cool\),](#)

[1:500:1 - 1D Gas \(Warm\), 1:500:1 - 1D Gas Model \(Cool, Zoomed in\),](#)

[Farey Sequence - Wolfram](#)

[Fractions - Ford-AMM-1938](#)

Monstermash BounceIt Animations:

[1000:1 - V2 vs V1, 1000:1 with t vs x - Minkowski Plot](#)

[Quantum Revivals of Morse Oscillators and Farey-Ford Geometry - Li-Harter-2013](#)

[Quantum Revivals of Morse Oscillators and Farey-Ford Geometry - Li-Harter-cpl-2015](#)

[Quant. Revivals of Morse Oscillators and Farey-Ford Geom. - Harter-Li-CPL-2015 \(Publ.\)](#)

[Velocity Amplification in Collision Experiments Involving Superballs-Harter-1971](#)

WaveIt Web Animation - Scenarios:

[Quantum Carpet, Quantum Carpet wMBars,](#)

[Quantum Carpet BCar, Quantum Carpet BCar wMBars](#)

[Wave Node Dynamics and Revival Symmetry in Quantum Rotors - Harter-JMS-2001](#)

[Wave Node Dynamics and Revival Symmetry in Quantum Rotors - Harter-jms-2001 \(Publ.\)](#)

[AJP article on superball dynamics](#)

[AAPT Summer Reading List](#)

[Scitation.org - AIP publications](#)

[HarterSoft Youtube Channel](#)

BounceIt Web Animation - Scenarios:

[Generic Scenario: 2-Balls dropped no Gravity \(7:1\) - V vs V Plot \(Power=4\)](#)

[1-Ball dropped w/Gravity=0.5 w/Potential Plot: Power=1, Power=4](#)

[7:1 - V vs V Plot: Power=1](#)

[3-Ball Stack \(10:3:1\) w/Newton plot \(y vs t\) - Power=4](#)

[3-Ball Stack \(10:3:1\) w/Newton plot \(y vs t\) - Power=1](#)

[3-Ball Stack \(10:3:1\) w/Newton plot \(y vs t\) - Power=1 w/Gaps](#)

[4-Ball Stack \(27:9:3:1\) w/Newton plot \(y vs t\) - Power=4](#)

[4-Newton's Balls \(1:1:1:1\) w/Newtonian plot \(y vs t\) - Power=4 w/Gaps](#)

[6-Ball Totally Inelastic \(1:1:1:1:1:1\) w/Gaps: Newtonian plot \(t vs x\), V6 vs V5 plot](#)

[5-Ball Totally Inelastic Pile-up w/ 5-Stationary-Balls - Minkowski plot \(t vs x1\) w/Gaps](#)

[1-Ball Totally Inelastic Pile-up w/ 5-Stationary-Balls - Vx2 vs Vx1 plot w/Gaps](#)

BounceIt Dual plots

$m_1:m_2 = 3:1$

[v2 vs v1 and V2 vs V1, \(v1, v2\)=\(1, 0.1\), \(v1, v2\)=\(1, 0\)](#)

[y2 vs y1 plots: \(v1, v2\)=\(1, 0.1\), \(v1, v2\)=\(1, 0\), \(v1, v2\)=\(1, -1\)](#)

[Estrangian plot V2 vs V1: \(v1, v2\)=\(0, 1\), \(v1, v2\)=\(1, -1\)](#)

$m_1:m_2 = 4:1$

[v2 vs v1, y2 vs y1](#)

$m_1:m_2 = 100:1$, (v1, v2)=(1, 0): V2 vs V1 Estrangian plot, y2 vs y1 plot

[With g=0 and 70:10 mass ratio](#)

[With non zero g, velocity dependent damping and mass ratio of 70:35](#)

[M1=49, M2=1 with Newtonian time plot](#)

[M1=49, M2=1 with V2 vs V1 plot](#)

[Example with friction](#)

[Low force constant with drag displaying a Pass-thru, Fall-Thru, Bounce-Off](#)

[m1:m2= 3:1 and \(v1, v2\) = \(1, 0\) Comparison with Estrangian](#)

X2 paper: [Velocity Amplification in Collision Experiments Involving Superballs - Harter, et. al. 1971 \(pdf\)](#)

Car Collision Web Simulator: <https://modphys.hosted.uark.edu/markup/CMMotionWeb.html>

Superball Collision Web Simulator: <https://modphys.hosted.uark.edu/markup/BounceItWeb.html>; with Scenarios: [1007](#)

[BounceIt web simulation with g=0 and 70:10 mass ratio](#)

[With non zero g, velocity dependent damping and mass ratio of 70:35](#)

Elastic Collision Dual Panel Space vs Space: [Space vs Time \(Newton\)](#), [Time vs. Space\(Minkowski\)](#)

Inelastic Collision Dual Panel Space vs Space: [Space vs Time \(Newton\)](#), [Time vs. Space\(Minkowski\)](#)

Matrix Collision Simulator: [M1=49, M2=1 V2 vs V1 plot](#) <<Under Construction>>

More Advanced QM and classical references will soon be available through our: [Mechanics References Page](#)

(Now in Development)

➔ *2D harmonic oscillator equations*
Lagrangian and matrix forms and Reciprocity symmetry



2D harmonic oscillator equation eigensolutions
Geometric method

Matrix-algebraic eigensolutions with example $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

Secular equation

Hamilton-Cayley equation and projectors

Idempotent projectors (how eigenvalues \Rightarrow eigenvectors)

Operator orthonormality and Completeness (Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

Spectral Decompositions

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Mixed mode beat dynamics and fixed $\pi/2$ phase

2D-HO eigensolution example with asymmetric (A-Type) symmetry

Initial state projection, mixed mode beat dynamics with variable phase

2D harmonic oscillators

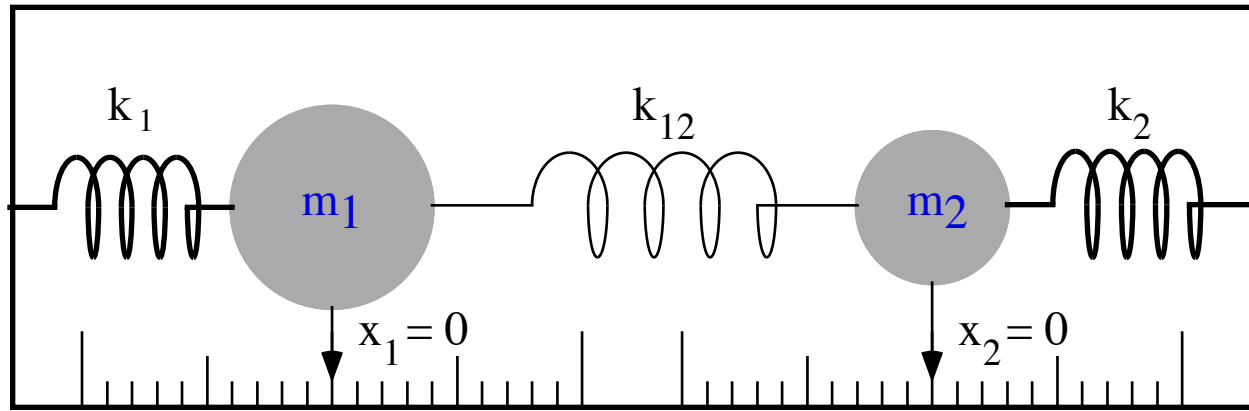


Fig. 3.3.1 Two 1-dimensional coupled oscillators

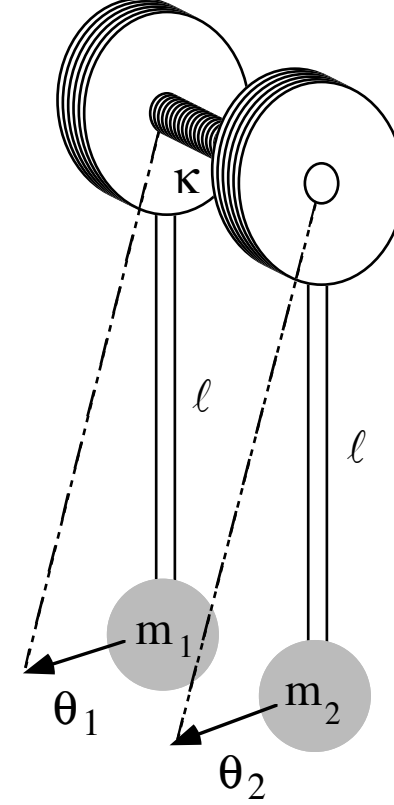
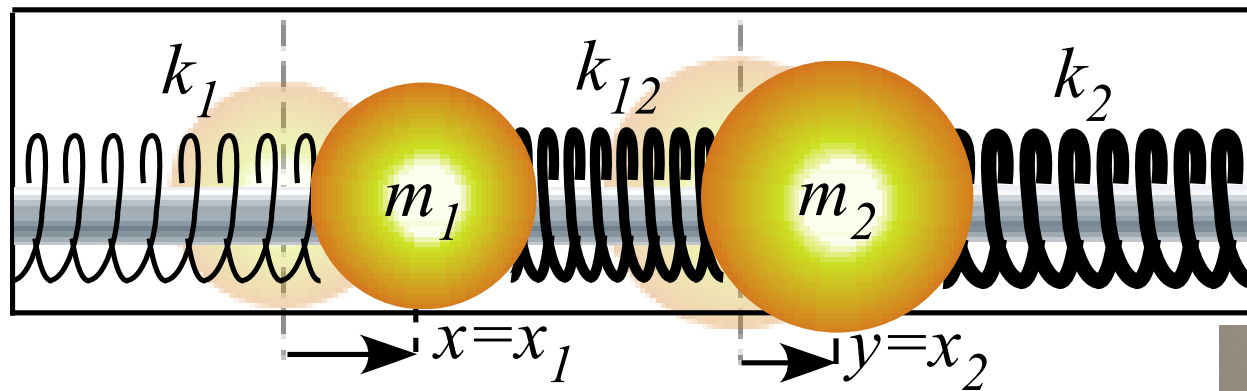


Fig. 3.3.2 Coupled pendulums

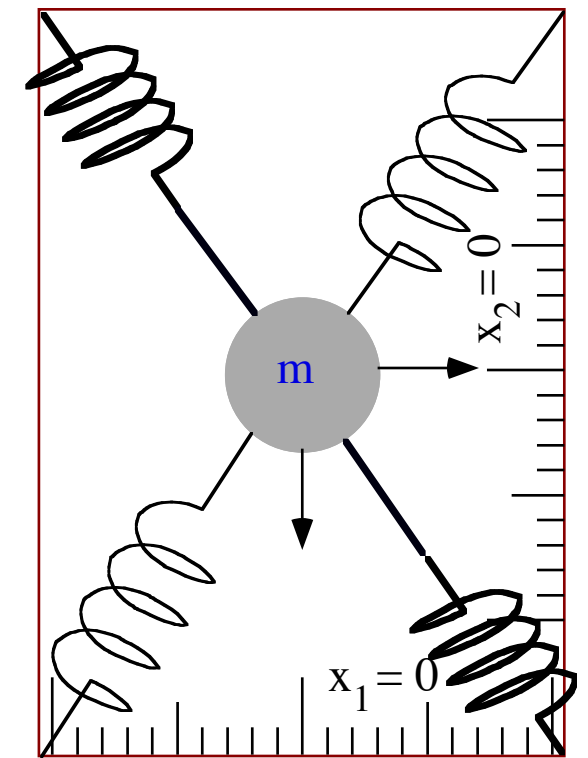


Fig. 3.3.3 One 2-dimensional coupled oscillator



2D harmonic oscillator energy

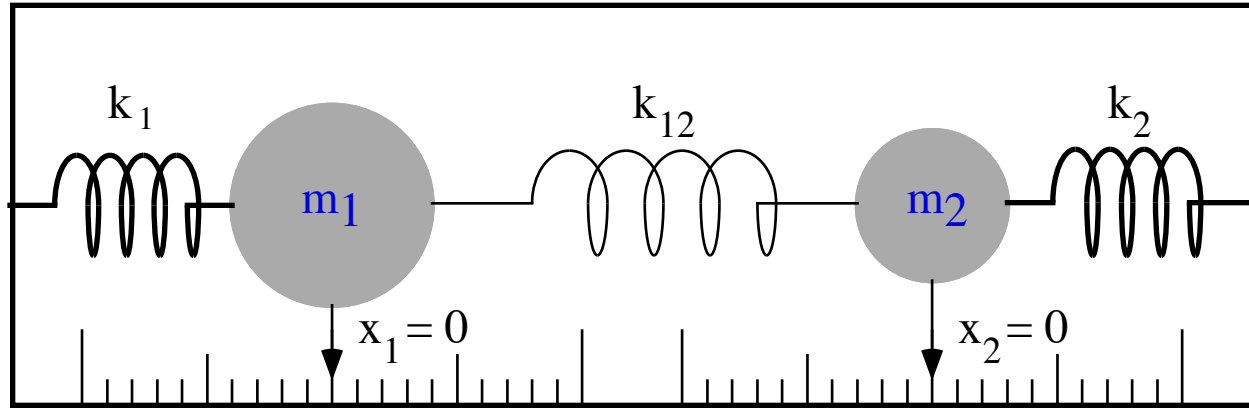


Fig. 3.3.1 Two 1-dimensional coupled oscillators

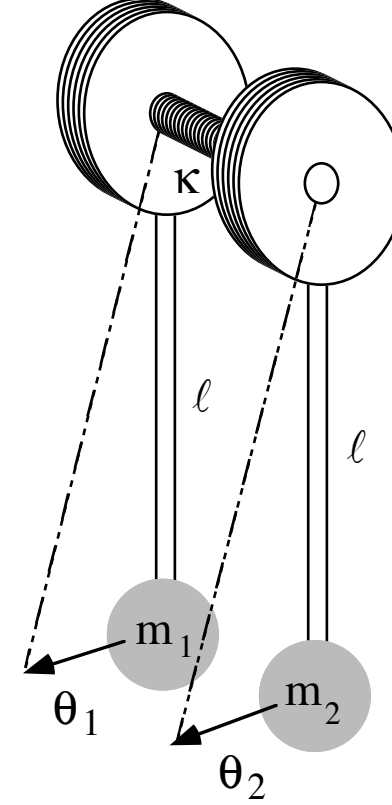
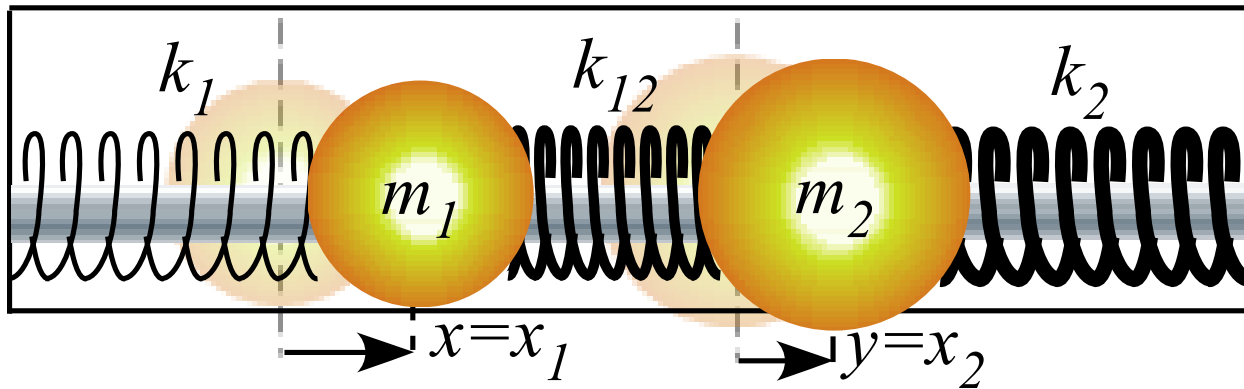


Fig. 3.3.2 Coupled pendulums

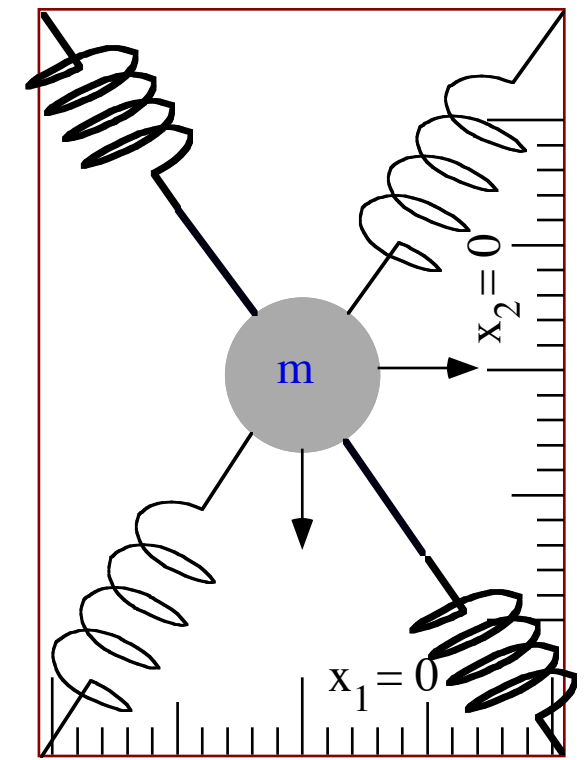


Fig. 3.3.3 One 2-dimensional coupled oscillator

2D HO kinetic energy $T(v_1, v_2)$

$$T = \frac{1}{2} m_1 \dot{x}_1^2 + \frac{1}{2} m_2 \dot{x}_2^2$$

2D harmonic oscillator energy

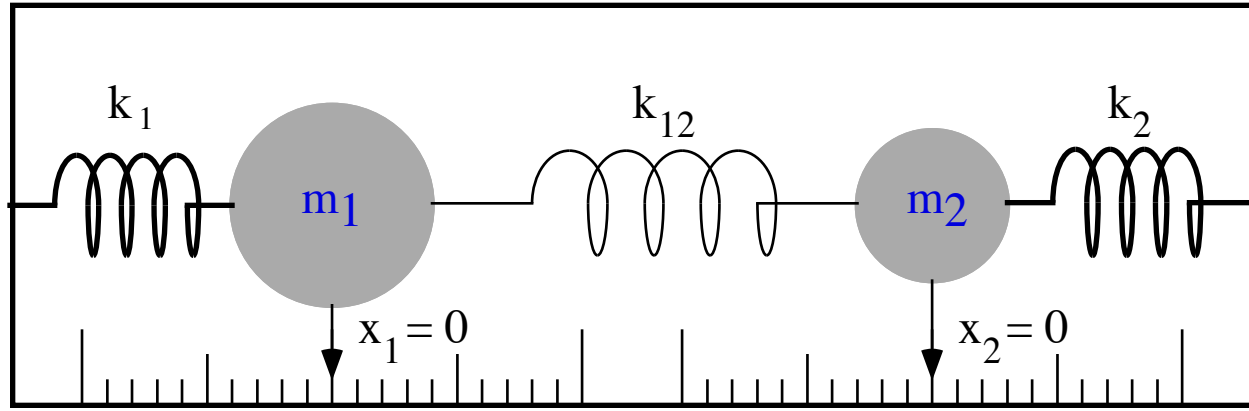


Fig. 3.3.1 Two 1-dimensional coupled oscillators

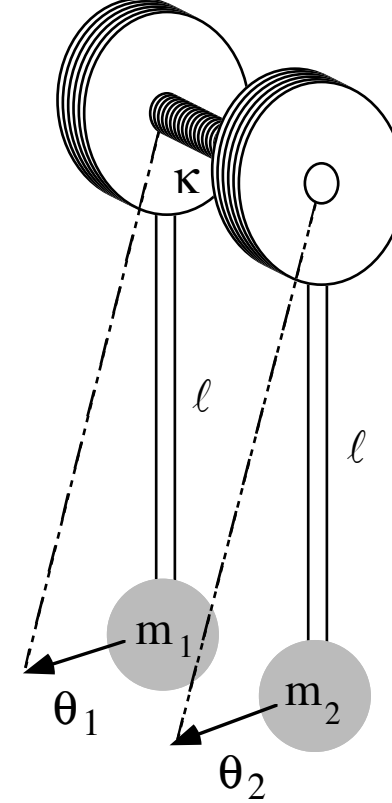
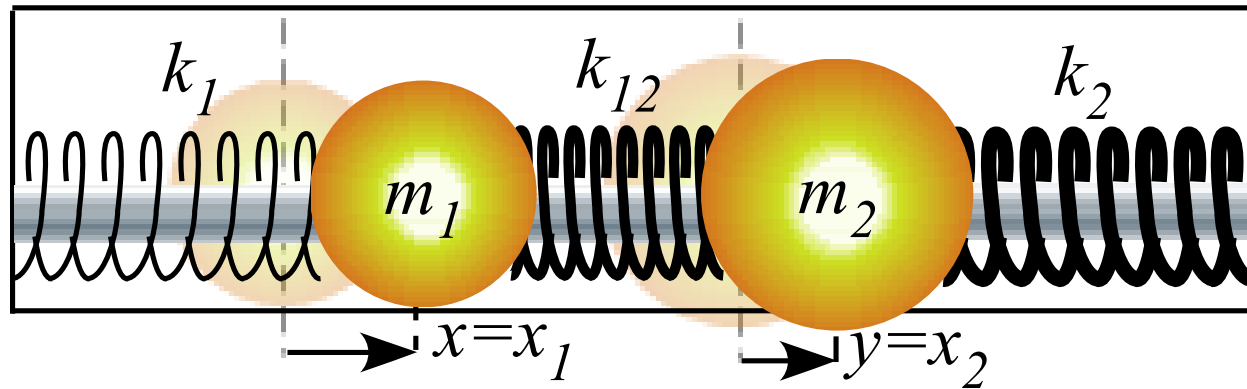


Fig. 3.3.2 Coupled pendulums

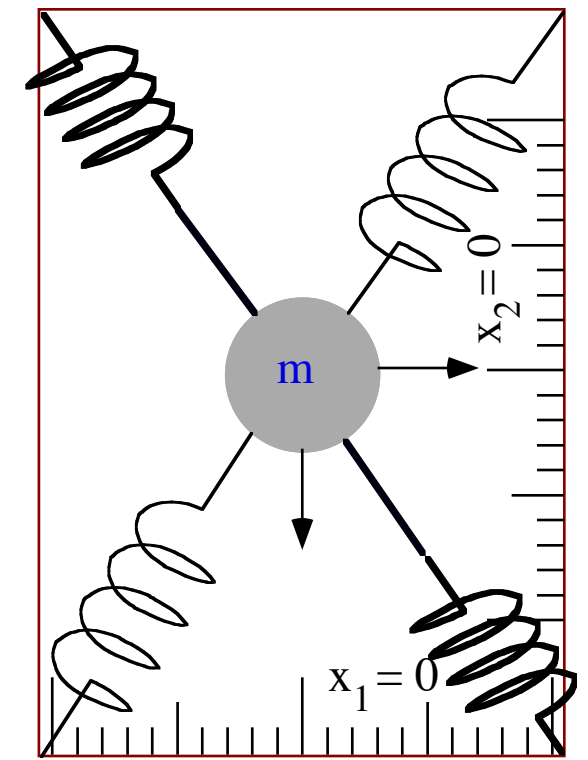


Fig. 3.3.3 One 2-dimensional coupled oscillator

2D HO kinetic energy $T(v_1, v_2)$

$$T = \frac{1}{2} m_1 \dot{x}_1^2 + \frac{1}{2} m_2 \dot{x}_2^2$$

2D HO potential energy $V(x_1, x_2)$

$$\begin{aligned} V &= \frac{1}{2} k_1 x_1^2 + \frac{1}{2} k_2 x_2^2 + \frac{1}{2} k_{12} (x_1 - x_2)^2 \\ &= \frac{1}{2} (k_1 + k_{12}) x_1^2 - k_{12} x_1 x_2 + \frac{1}{2} (k_2 + k_{12}) x_2^2 \end{aligned}$$

Lagrangian $L=T-V$

2D harmonic oscillator equations

➔ *Lagrangian and matrix forms and Reciprocity symmetry*



2D harmonic oscillator equation eigensolutions

Geometric method

Matrix-algebraic eigensolutions with example $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

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Hamilton-Cayley equation and projectors

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Initial state projection, mixed mode beat dynamics with variable phase

2D harmonic oscillator equations

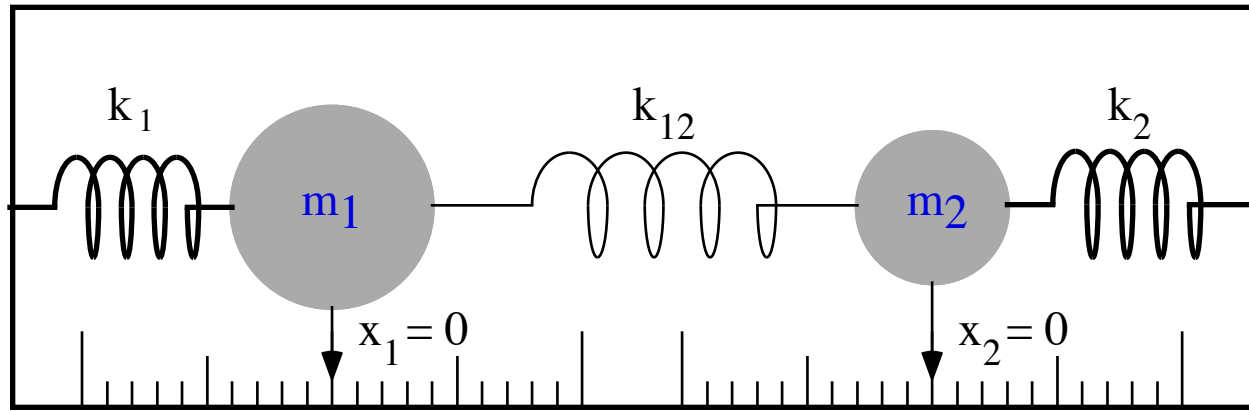


Fig. 3.3.1 Two 1-dimensional coupled oscillators

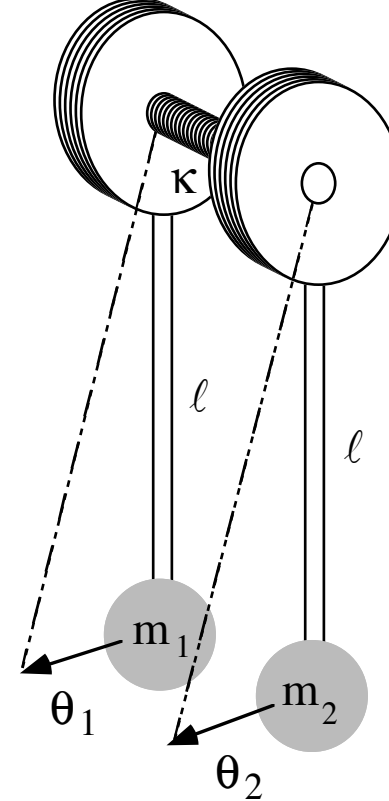
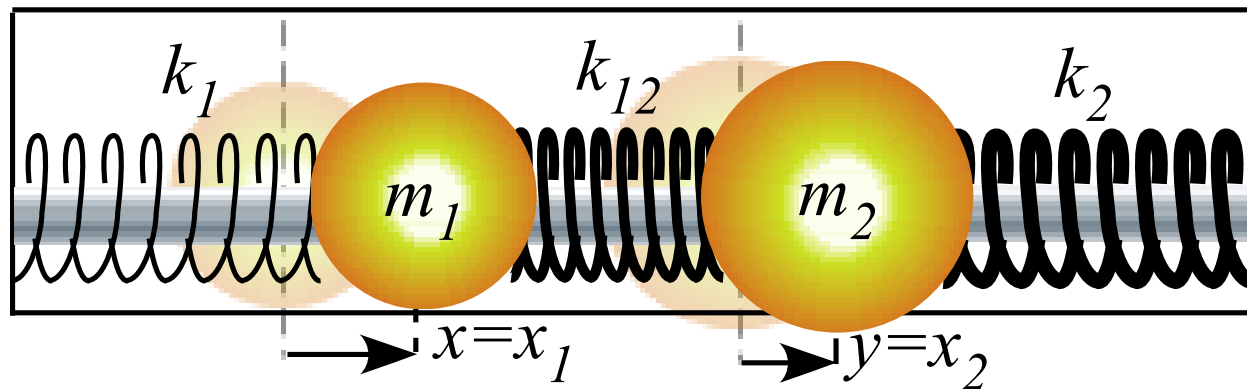


Fig. 3.3.2 Coupled pendulums

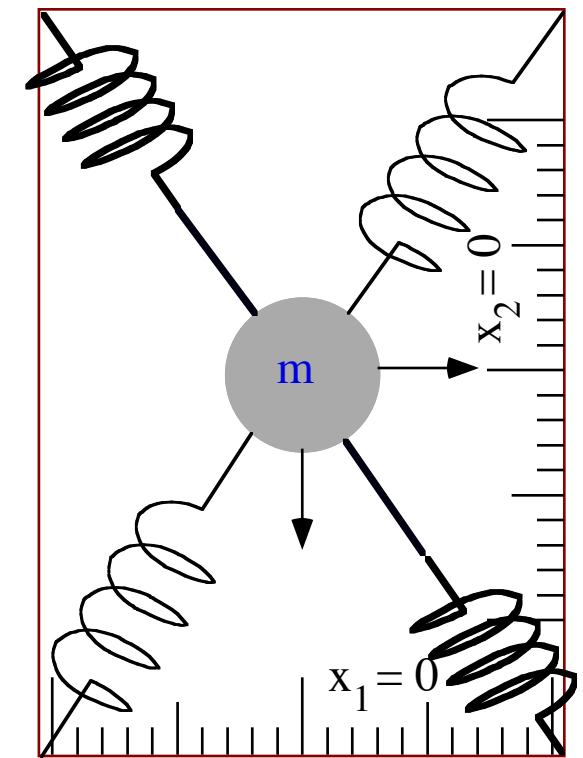


Fig. 3.3.3 One 2-dimensional coupled oscillator

2D HO kinetic energy $T(v_1, v_2)$

$$T = \frac{1}{2} m_1 \dot{x}_1^2 + \frac{1}{2} m_2 \dot{x}_2^2$$

2D HO potential energy $V(x_1, x_2)$

$$\begin{aligned} V &= \frac{1}{2} k_1 x_1^2 + \frac{1}{2} k_2 x_2^2 + \frac{1}{2} k_{12} (x_1 - x_2)^2 \\ &= \frac{1}{2} (k_1 + k_{12}) x_1^2 - k_{12} x_1 x_2 + \frac{1}{2} (k_2 + k_{12}) x_2^2 \end{aligned}$$

Lagrangian $L=T-V$

2D HO Lagrange equations

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_1} \right) = m_1 \ddot{x}_1 = F_1 = - \frac{\partial V}{\partial x_1} = - (k_1 + k_{12}) x_1 + k_{12} x_2$$

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_2} \right) = m_2 \ddot{x}_2 = F_2 = - \frac{\partial V}{\partial x_2} = k_{12} x_1 - (k_2 + k_{12}) x_2$$

2D harmonic oscillator equations

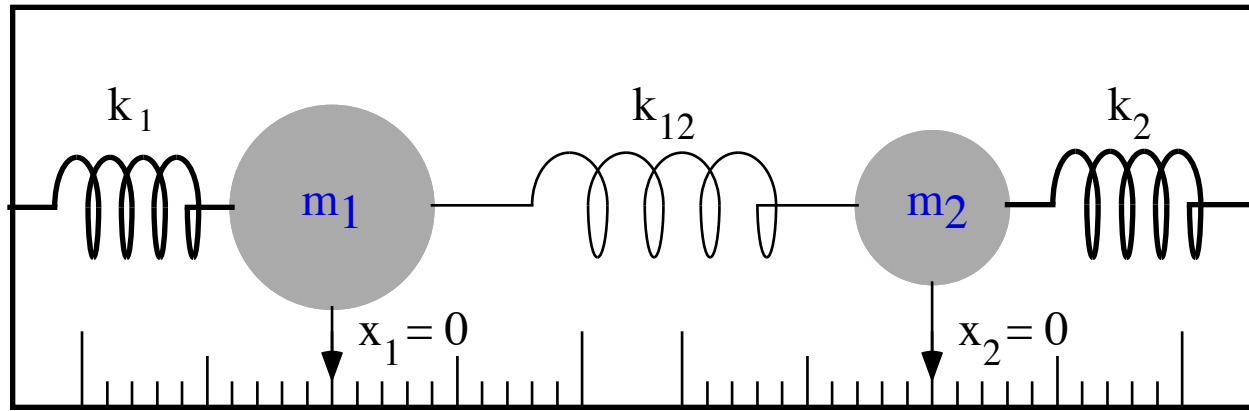


Fig. 3.3.1 Two 1-dimensional coupled oscillators

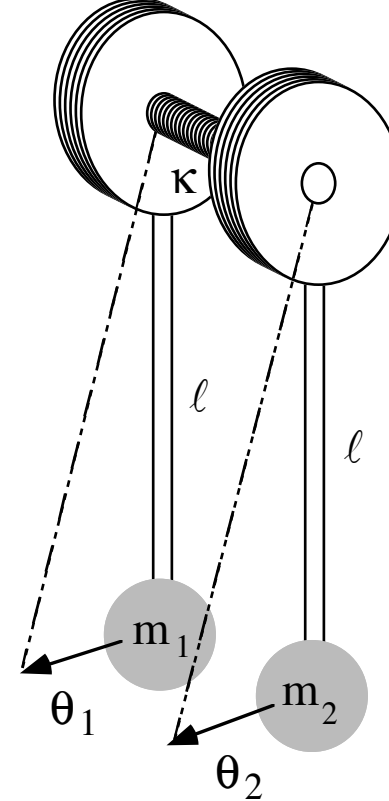
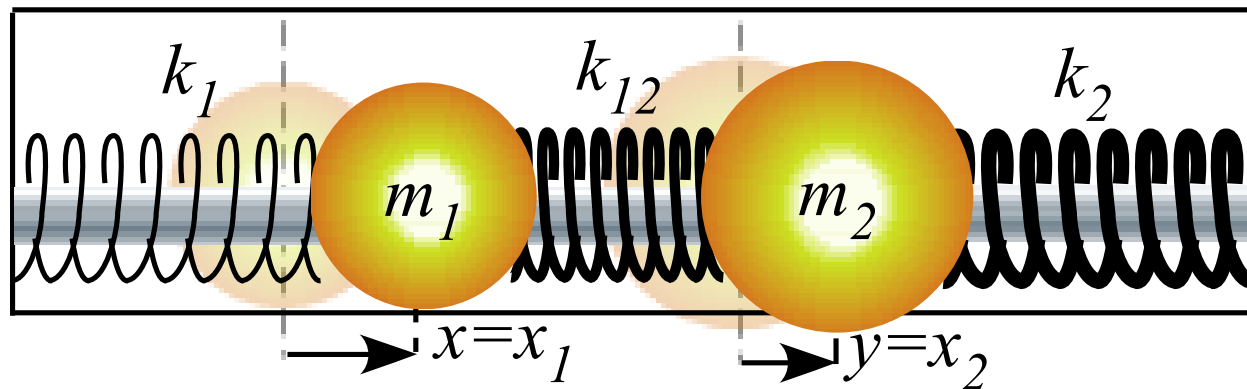


Fig. 3.3.2 Coupled pendulums

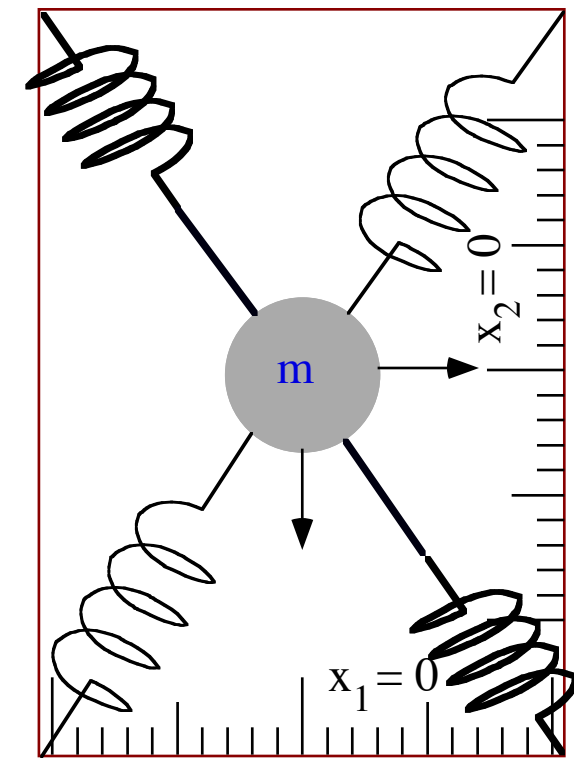


Fig. 3.3.3 One 2-dimensional coupled oscillator

2D HO kinetic energy $T(v_1, v_2)$

$$T = \frac{1}{2} m_1 \dot{x}_1^2 + \frac{1}{2} m_2 \dot{x}_2^2$$

2D HO potential energy $V(x_1, x_2)$

$$V = \frac{1}{2} k_1 x_1^2 + \frac{1}{2} k_2 x_2^2 + \frac{1}{2} k_{12} (x_1 - x_2)^2$$

$$= \frac{1}{2} (k_1 + k_{12}) x_1^2 - k_{12} x_1 x_2 + \frac{1}{2} (k_2 + k_{12}) x_2^2$$

Lagrangian $L=T-V$

2D HO Lagrange equations

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_1} \right) = m_1 \ddot{x}_1 = F_1 = - \frac{\partial V}{\partial x_1} = - (k_1 + k_{12}) x_1 + k_{12} x_2$$

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_2} \right) = m_2 \ddot{x}_2 = F_2 = - \frac{\partial V}{\partial x_2} = k_{12} x_1 - (k_2 + k_{12}) x_2$$

2D HO Matrix operator equations

$$\begin{pmatrix} m_1 & 0 \\ 0 & m_2 \end{pmatrix} \begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix} = - \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

2D harmonic oscillator equations

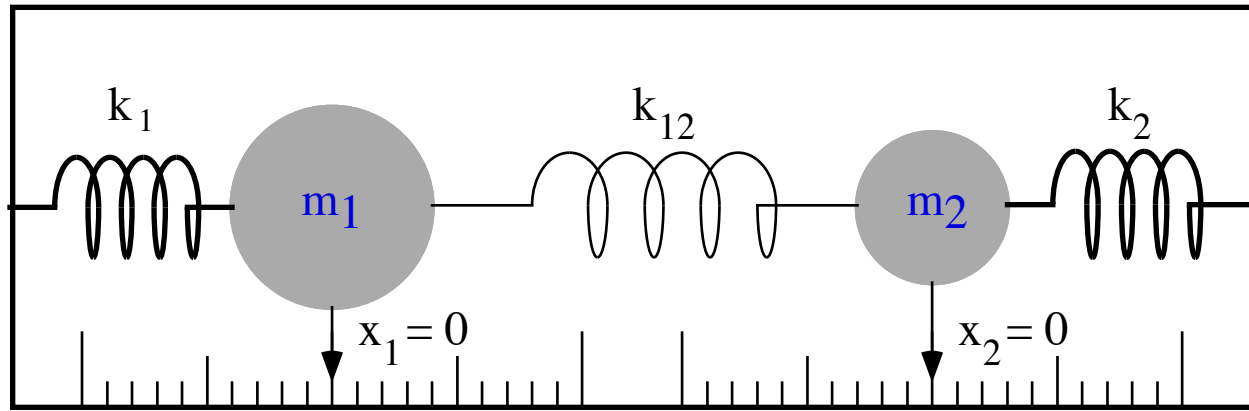


Fig. 3.3.1 Two 1-dimensional coupled oscillators

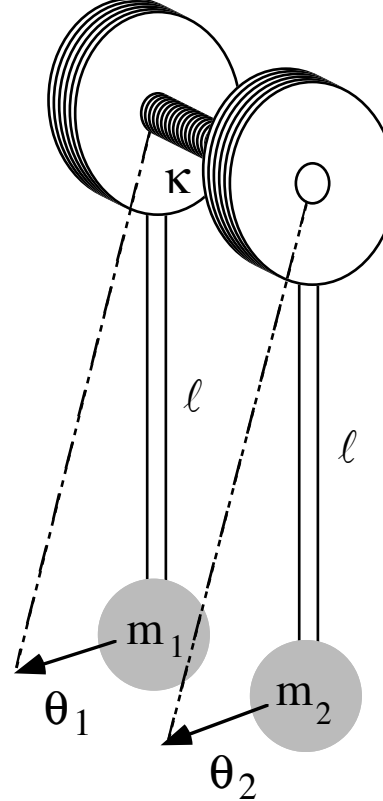
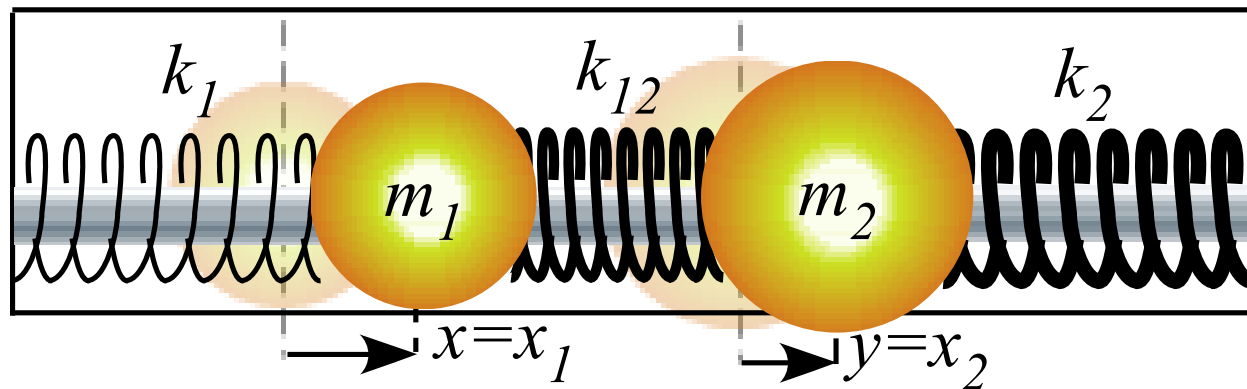


Fig. 3.3.2 Coupled pendulums

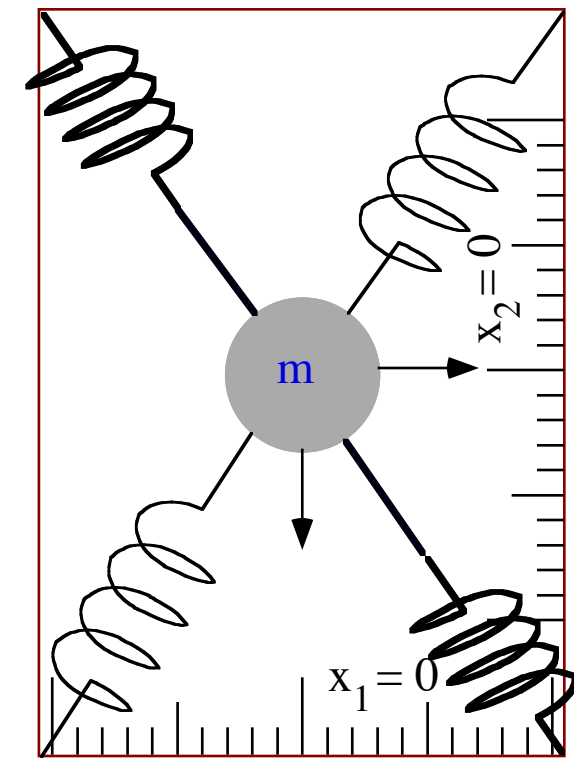


Fig. 3.3.3 One 2-dimensional coupled oscillator

2D HO kinetic energy $T(v_1, v_2)$

$$T = \frac{1}{2} m_1 \dot{x}_1^2 + \frac{1}{2} m_2 \dot{x}_2^2$$

2D HO potential energy $V(x_1, x_2)$

$$V = \frac{1}{2} k_1 x_1^2 + \frac{1}{2} k_2 x_2^2 + \frac{1}{2} k_{12} (x_1 - x_2)^2$$

$$= \frac{1}{2} (k_1 + k_{12}) x_1^2 - k_{12} x_1 x_2 + \frac{1}{2} (k_2 + k_{12}) x_2^2$$

Lagrangian $L=T-V$

2D HO Lagrange equations

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_1} \right) = m_1 \ddot{x}_1 = F_1 = - \frac{\partial V}{\partial x_1} = - (k_1 + k_{12}) x_1 + k_{12} x_2$$

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_2} \right) = m_2 \ddot{x}_2 = F_2 = - \frac{\partial V}{\partial x_2} = k_{12} x_1 - (k_2 + k_{12}) x_2$$

2D HO Matrix operator equations

$$\begin{pmatrix} m_1 & 0 \\ 0 & m_2 \end{pmatrix} \begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix} = - \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

Matrix operator notation:

$$\mathbf{M} \cdot |\ddot{\mathbf{x}}\rangle = - \mathbf{K} \cdot |\mathbf{x}\rangle$$

2D harmonic oscillator equations

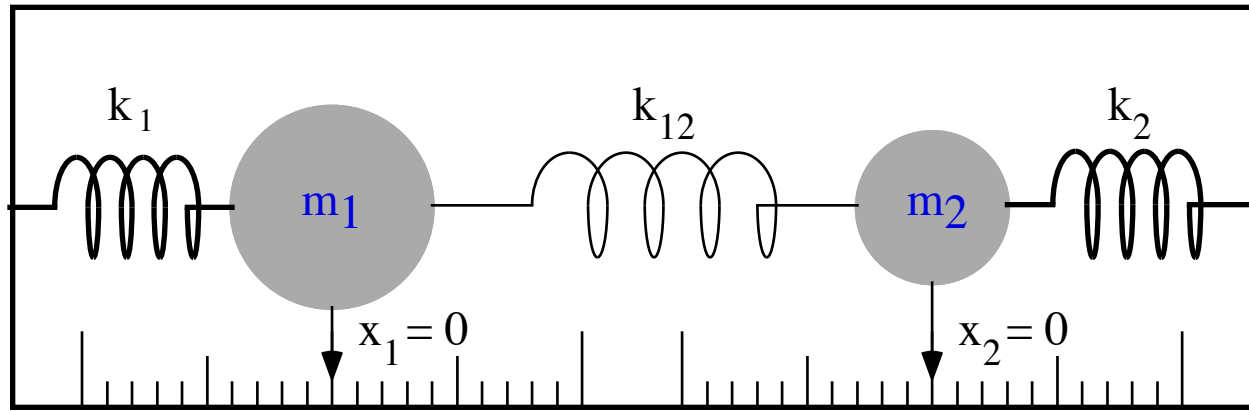


Fig. 3.3.1 Two 1-dimensional coupled oscillators

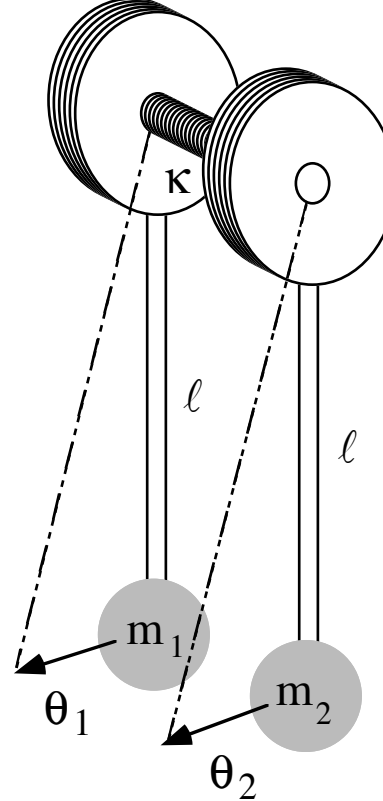
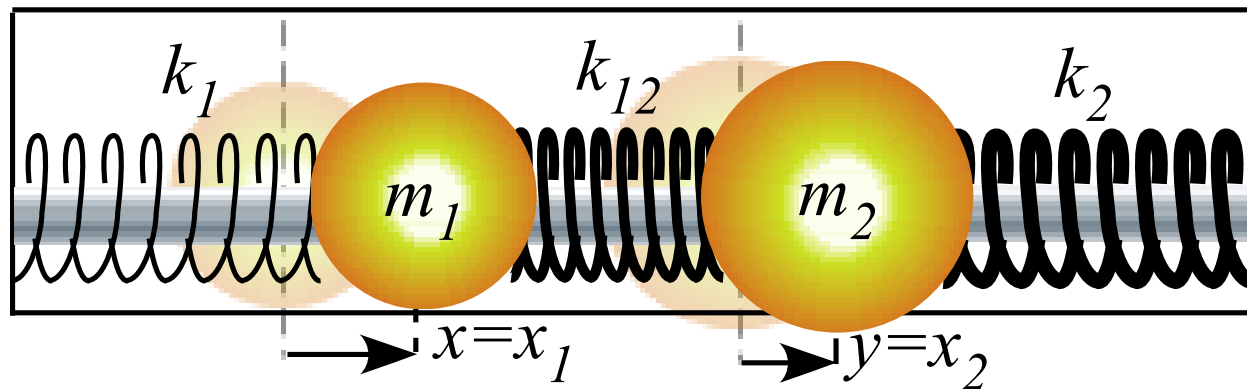


Fig. 3.3.2 Coupled pendulums

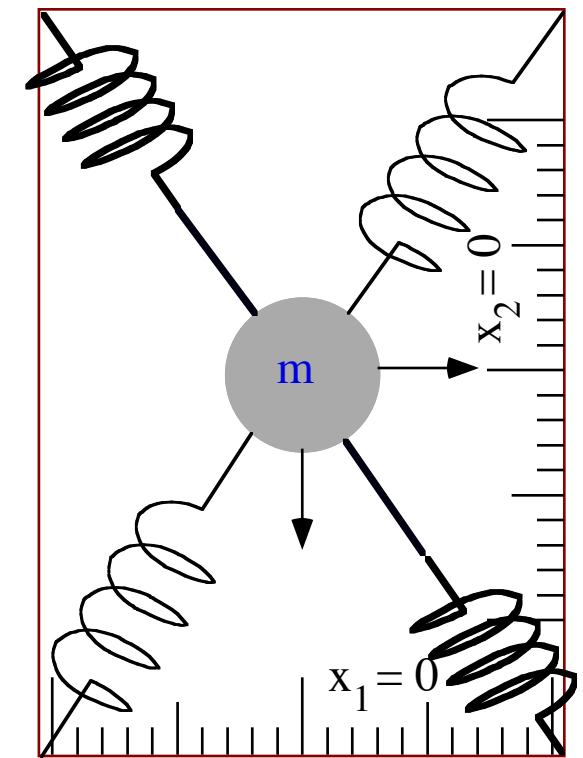


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$$T = \frac{1}{2} m_1 \dot{x}_1^2 + \frac{1}{2} m_2 \dot{x}_2^2$$

$$= \frac{1}{2} \langle \dot{\mathbf{x}} | \mathbf{M} | \dot{\mathbf{x}} \rangle$$

2D HO potential energy $V(x_1, x_2)$

$$V = \frac{1}{2} (k_1 + k_{12}) x_1^2 - k_{12} x_1 x_2 + \frac{1}{2} (k_2 + k_{12}) x_2^2$$

$$= \frac{1}{2} \langle \mathbf{x} | \mathbf{K} | \mathbf{x} \rangle$$

Lagrangian $L=T-V$

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2D HO Matrix operator equations

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Matrix operator notation:

$$\mathbf{M} \cdot | \ddot{\mathbf{x}} \rangle = - \mathbf{K} \cdot | \mathbf{x} \rangle$$

2D harmonic oscillator equations

Lagrangian and matrix forms and Reciprocity symmetry  

2D harmonic oscillator equation eigensolutions

Geometric method

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Matrix equations and reciprocity symmetry

General form of 2D-HO equation of motion has force matrix components: $\kappa_{11} = k_1 + k_{12}$, $\kappa_{22} = k_2 + k_{12}$

$$\begin{pmatrix} F_1 \\ F_2 \end{pmatrix} = \begin{pmatrix} m_1 \ddot{x}_1 \\ m_2 \ddot{x}_2 \end{pmatrix} = - \begin{pmatrix} \kappa_{11} & \kappa_{12} \\ \kappa_{21} & \kappa_{22} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

Off-diagonal force constants satisfy *Reciprocity Relations*: $-\kappa_{12} = k_{12} = \frac{\partial F_1}{\partial x_2} = -\frac{\partial^2 V}{\partial x_2 \partial x_1} = -\frac{\partial^2 V}{\partial x_1 \partial x_2} = \frac{\partial F_2}{\partial x_1} = k_{21} = -\kappa_{21}$

Rescaling and symmetrization

Each coordinate (x_1, x_2) is rescaled $(q_1 = s_1 x_1, q_2 = s_2 x_2)$ to symmetrize mass factors on \ddot{q}_j -terms.

$$\begin{aligned} -\frac{m_1}{s_1} \ddot{q}_1 &= \kappa_{11} \frac{q_1}{s_1} + \kappa_{12} \frac{q_2}{s_2} & -\ddot{q}_1 &= \frac{\kappa_{11}}{m_1} q_1 + \frac{\kappa_{12} s_1}{m_1 s_2} q_2 \equiv \mathbf{K}_{11} q_1 + \mathbf{K}_{12} q_2 \\ -\frac{m_2}{s_2} \ddot{q}_2 &= \kappa_{12} \frac{q_1}{s_1} + \kappa_{22} \frac{q_2}{s_2} & -\ddot{q}_2 &= \frac{\kappa_{12} s_2}{m_2 s_1} q_1 + \frac{\kappa_{22}}{m_2} q_2 \equiv \mathbf{K}_{21} q_1 + \mathbf{K}_{22} q_2 \end{aligned}$$

New constants K_{ij} have pseudo-reciprocity symmetry for a special scale factor ratio: $\frac{s_2}{s_1} = \sqrt{\frac{m_2}{m_1}}$

$$\mathbf{K}_{21} = \frac{\kappa_{12} s_2}{m_2 s_1} = \mathbf{K}_{12} = \frac{\kappa_{12} s_1}{m_1 s_2} = \frac{-k_{12}}{\sqrt{m_1 m_2}}$$

Diagonal constants K_{jj} are not affected by scaling. To be equal requires: $\frac{\kappa_{11}}{m_1} = \frac{\kappa_{22}}{m_2}$ or: $\frac{\kappa_{11}}{\kappa_{22}} = \frac{m_1}{m_2}$

$$\mathbf{K}_{11} = \frac{\kappa_{11}}{m_1} = \frac{k_1 + k_{12}}{m_1} \quad \mathbf{K}_{22} = \frac{\kappa_{22}}{m_2} = \frac{k_2 + k_{12}}{m_2}$$

Caution is advised since such forced symmetry may give modes with imaginary frequency.

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2D harmonic oscillator equation solutions

1. May rewrite equation $\mathbf{M} \cdot |\ddot{\mathbf{x}}\rangle = -\mathbf{K} \cdot |\mathbf{x}\rangle$ in acceleration matrix form: $|\ddot{\mathbf{x}}\rangle = -\mathbf{A}|\mathbf{x}\rangle$ where: $\mathbf{A} = \mathbf{M}^{-1} \cdot \mathbf{K}$

$$\begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix} = - \begin{pmatrix} m_1 & 0 \\ 0 & m_2 \end{pmatrix}^{-1} \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = - \begin{pmatrix} \frac{k_1 + k_{12}}{m_1} & \frac{-k_{12}}{m_1} \\ \frac{-k_{12}}{m_2} & \frac{k_2 + k_{12}}{m_2} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

2. Need to find *eigenvectors* $|\mathbf{e}_1\rangle, |\mathbf{e}_2\rangle, \dots$ of acceleration matrix such that: $\mathbf{A}|\mathbf{e}_n\rangle = \varepsilon_n|\mathbf{e}_n\rangle = \omega_n^2|\mathbf{e}_n\rangle$

Then equations decouple to: $|\ddot{\mathbf{e}}_n\rangle = -\mathbf{A}|\mathbf{e}_n\rangle = -\varepsilon_n|\mathbf{e}_n\rangle = -\omega_n^2|\mathbf{e}_n\rangle$ where ε_n is an *eigenvalue*

and ω_n is an *eigenfrequency*

2D harmonic oscillator equation solutions

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Then equations decouple to: $|\ddot{\mathbf{e}}_n\rangle = -\mathbf{A}|\mathbf{e}_n\rangle = -\varepsilon_n|\mathbf{e}_n\rangle = -\omega_n^2|\mathbf{e}_n\rangle$ where ε_n is an *eigenvalue*

and ω_n is an *eigenfrequency*

To introduce eigensolutions we take a simple case of unit masses ($m_1=1=m_2$)

So equation of motion is simply: $|\ddot{\mathbf{x}}\rangle = -\mathbf{K}|\mathbf{x}\rangle$

Eigenvectors $|\mathbf{x}\rangle = |\mathbf{e}_n\rangle$ are in special directions where $|\ddot{\mathbf{x}}\rangle = -\mathbf{K}|\mathbf{x}\rangle$ is in same direction as $|\mathbf{x}\rangle$

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➔ *Geometric method*



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$$V = \frac{1}{2}(k_1 + k_{12})x_1^2 - k_{12}x_1x_2 + \frac{1}{2}(k_2 + k_{12})x_2^2 = \frac{1}{2}\langle \mathbf{x} | \mathbf{K} | \mathbf{x} \rangle = \frac{1}{2}\mathbf{x} \cdot \mathbf{K} \cdot \mathbf{x} = \begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

(a) PE Contours

(if any)
 What direction $|\mathbf{x}\rangle = |\mathbf{e}_n\rangle$
 is the same as $\mathbf{K}|\mathbf{x}\rangle$??
 Not most directions!

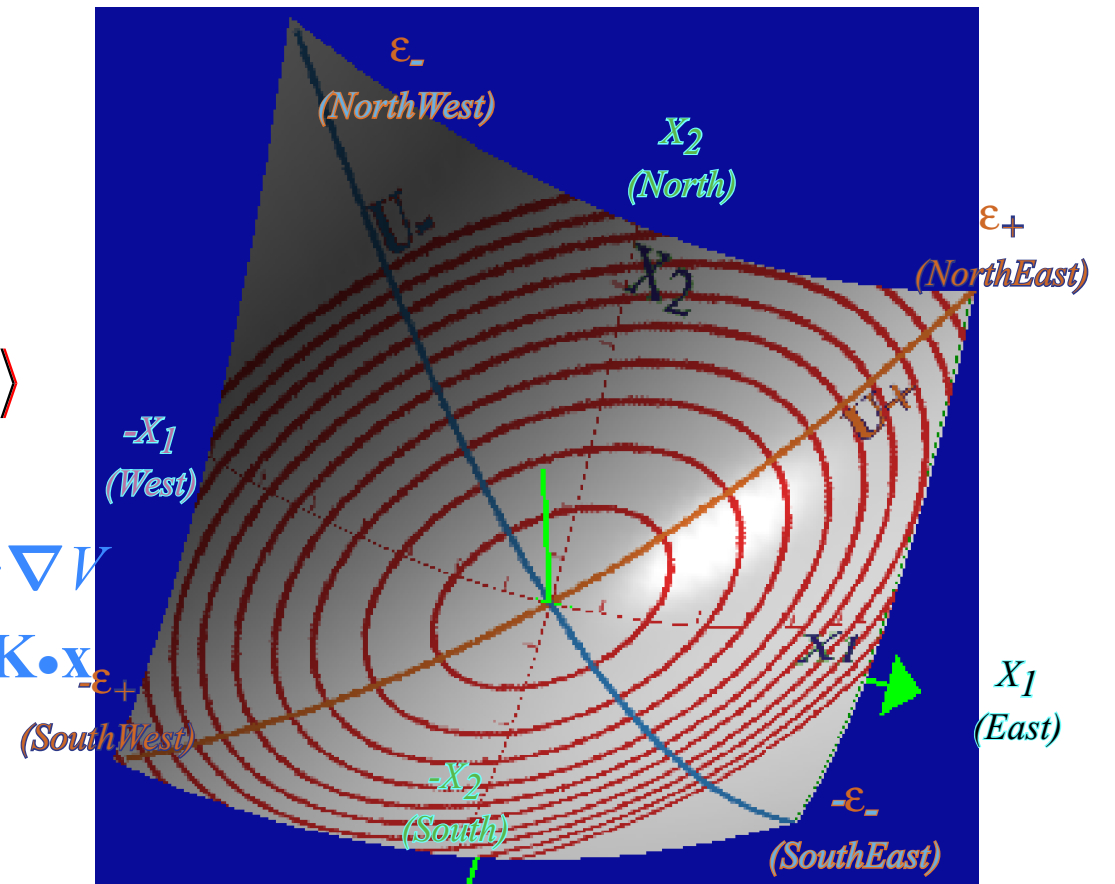
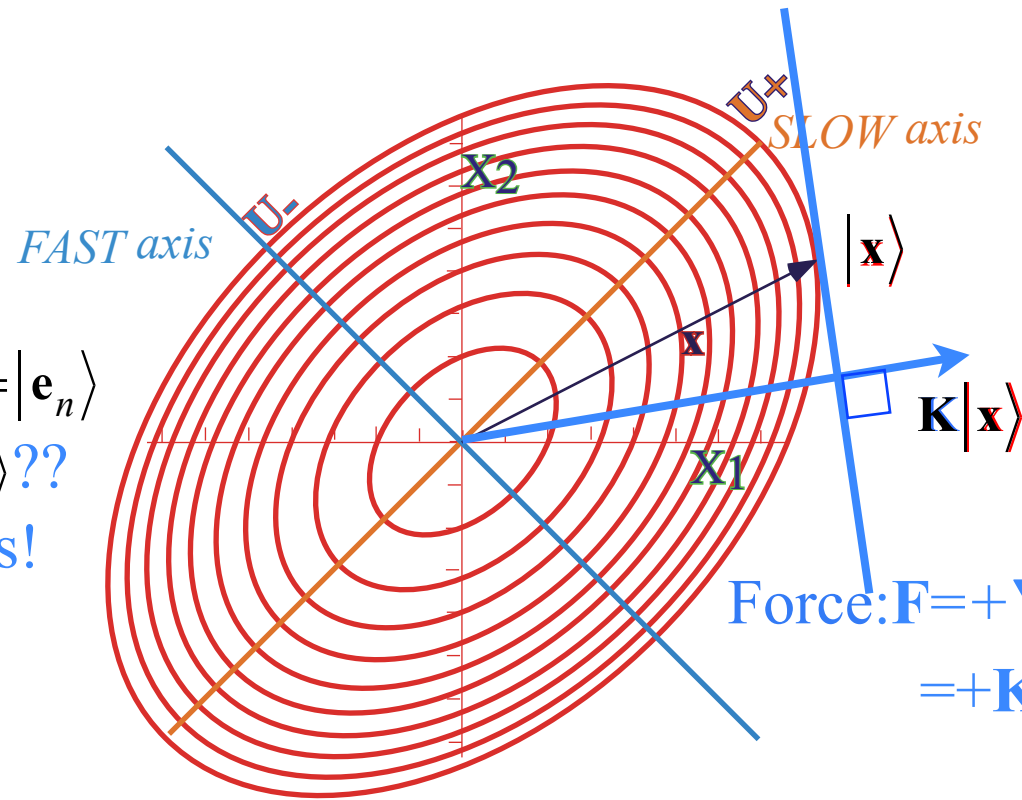


Fig. 3.3.4 Plot of potential function $V(x_1, x_2)$ showing elliptical $V(x_1, x_2) = \text{const.}$ level curves.

2D HO potential energy $V(x_1, x_2)$ quadratic form defines layers of elliptical V -contours

$$V = \frac{1}{2}(k_1 + k_{12})x_1^2 - k_{12}x_1x_2 + \frac{1}{2}(k_2 + k_{12})x_2^2 = \frac{1}{2}\langle \mathbf{x} | \mathbf{K} | \mathbf{x} \rangle = \frac{1}{2}\mathbf{x} \cdot \mathbf{K} \cdot \mathbf{x} = \begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

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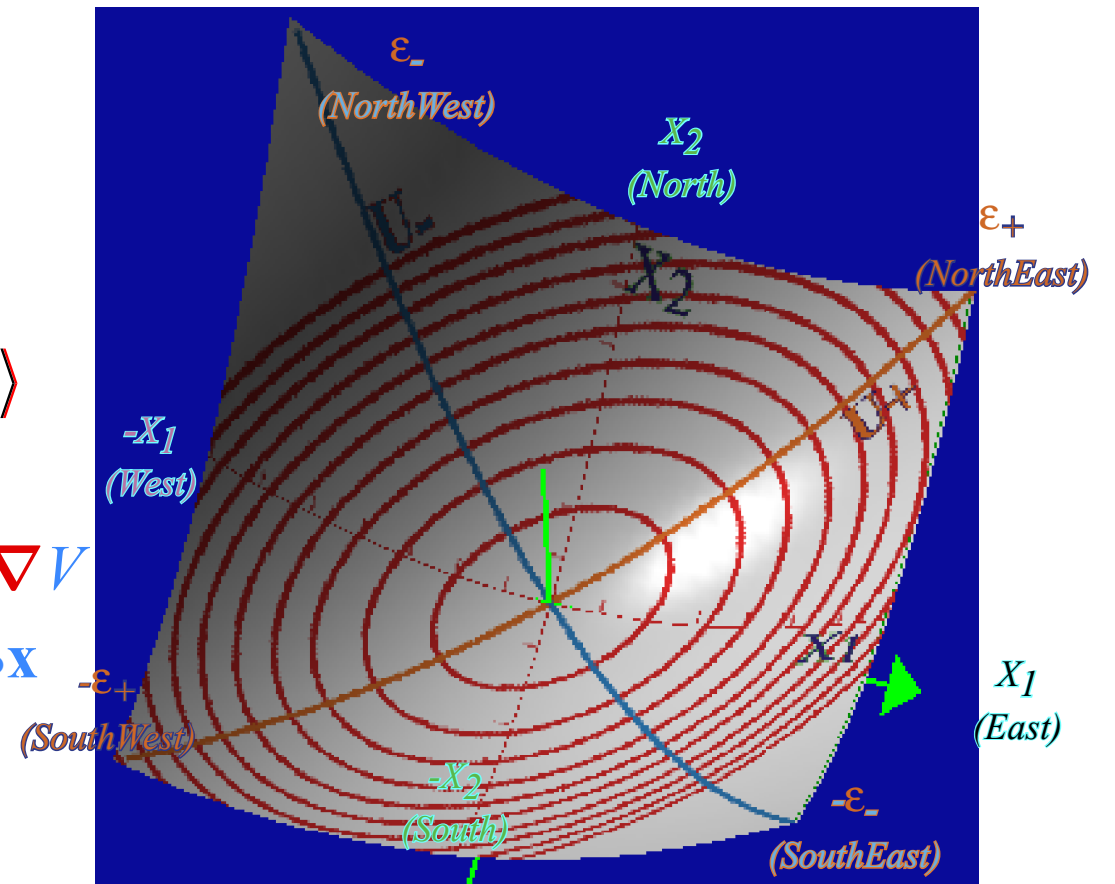
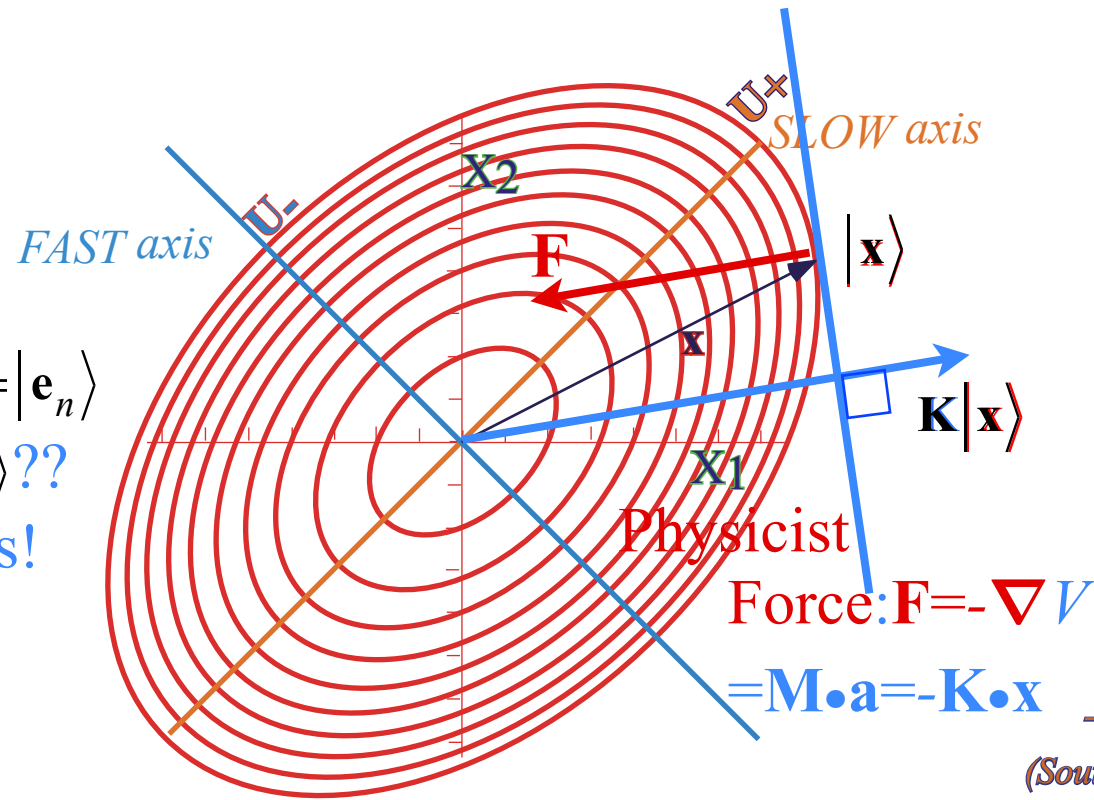
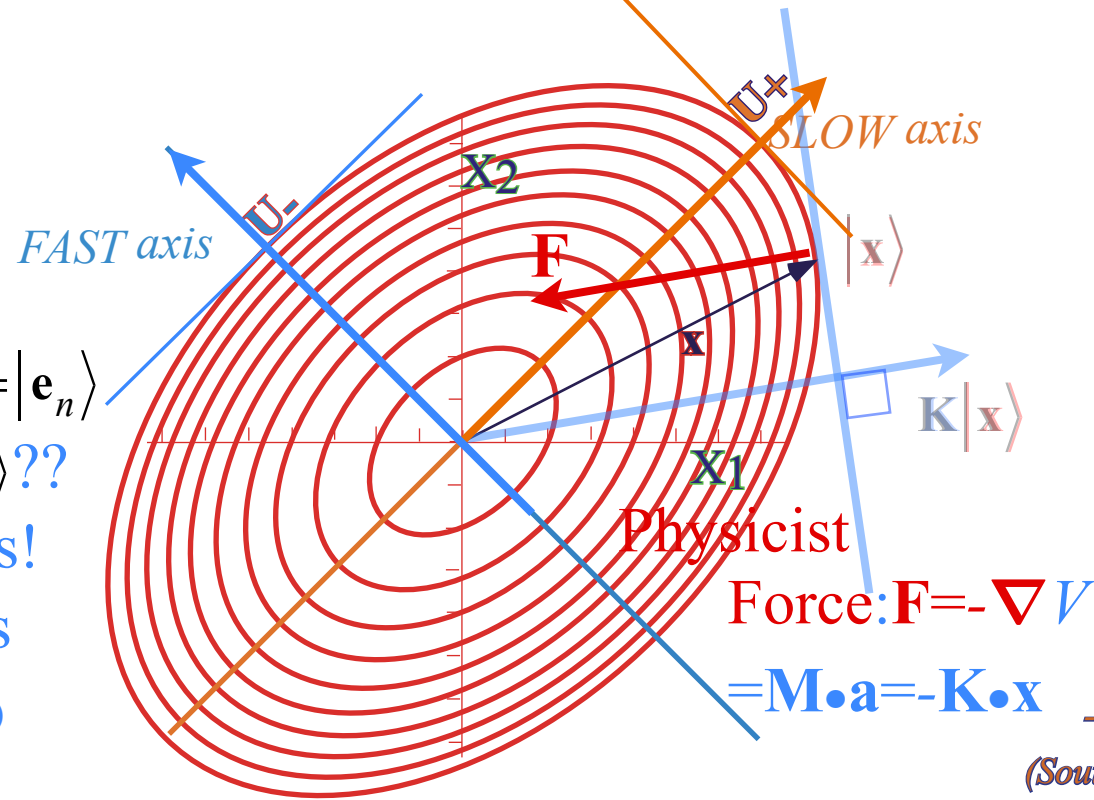


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(a) PE Contours



(if any)

What direction $|\mathbf{x}\rangle = |\mathbf{e}_n\rangle$ is the same as $\mathbf{K}|\mathbf{x}\rangle$??

Not most directions!

Only extremal axes

work. (major or minor axes)

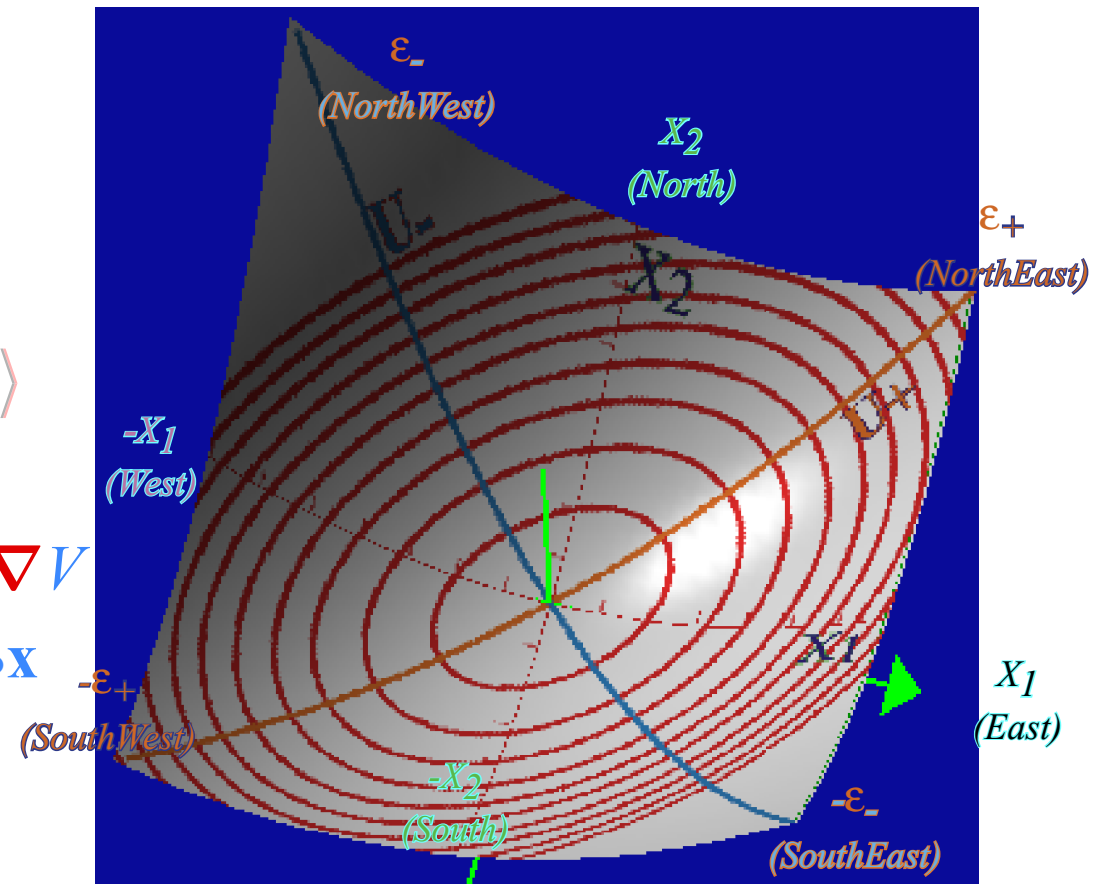
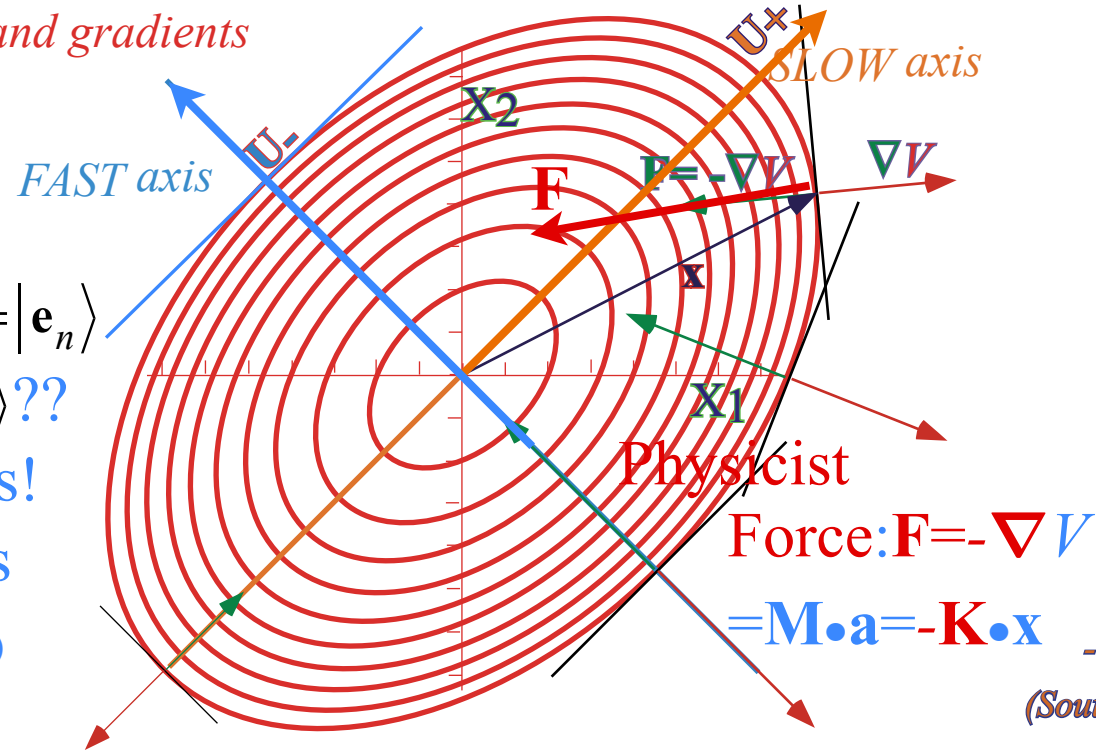


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2D HO potential energy $V(x_1, x_2)$ quadratic form defines layers of elliptical V -contours (Here: $k_1 = k = k_2$)

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(a) PE Contours and gradients



(if any)

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work. (major or minor axes)

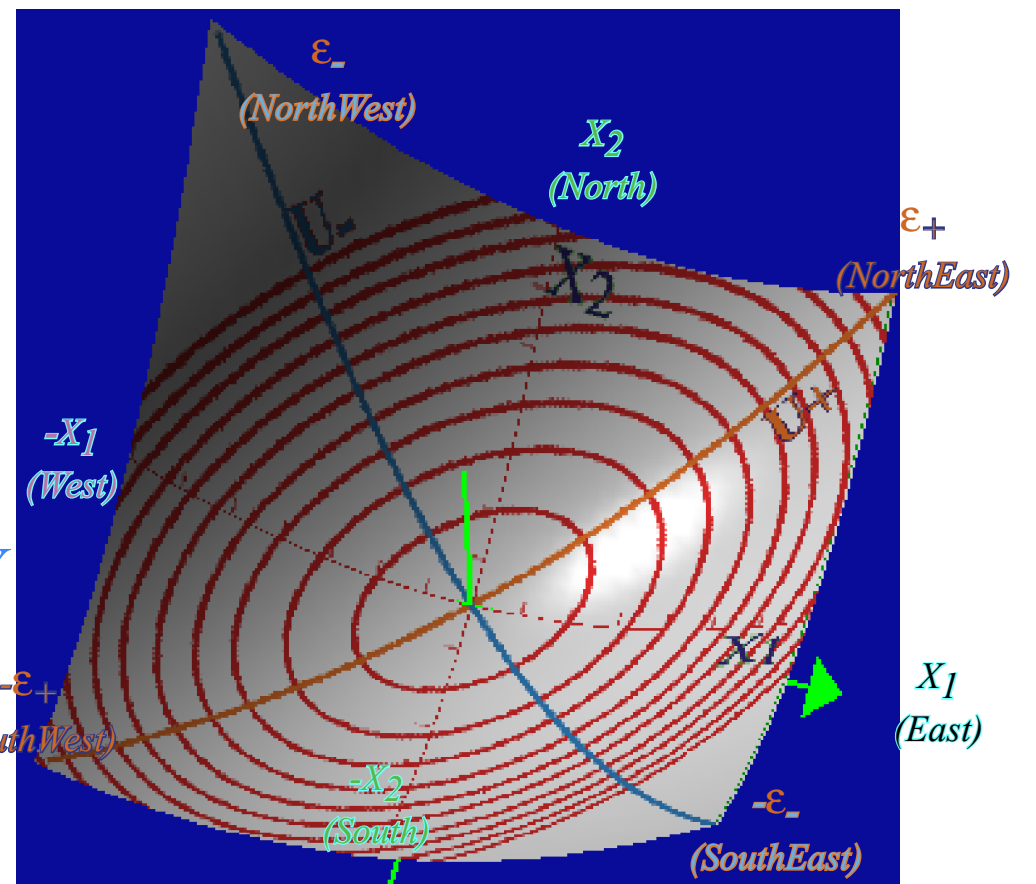
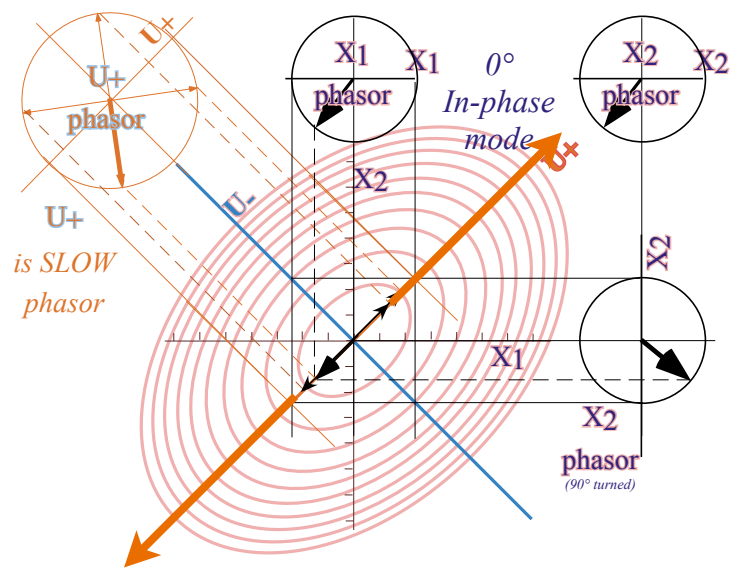
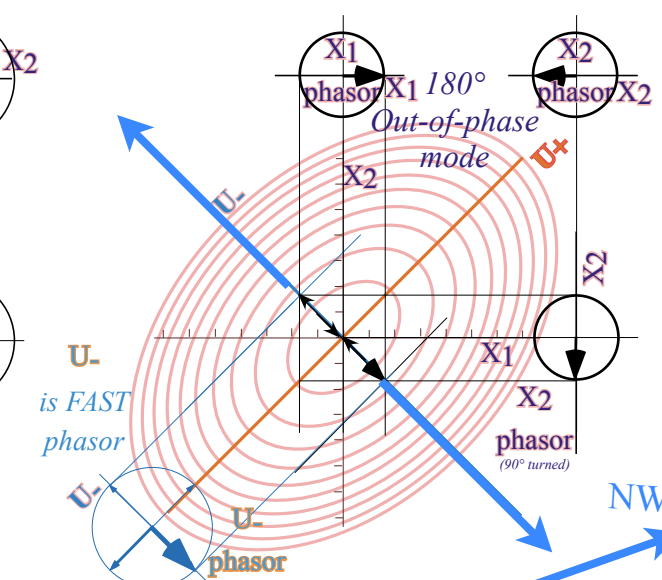


Fig. 3.3.4 Plot of potential function $V(x_1, x_2)$ showing elliptical $V(x_1, x_2) = \text{const.}$ level curves.

(b) Symmetric $U+$ Coordinate SLOW Mode



(c) Anti-symmetric $U-$ Coordinate FAST Mode



With Bilateral symmetry ($k_1 = k = k_2$) the extremal axes lie at $\pm 45^\circ$

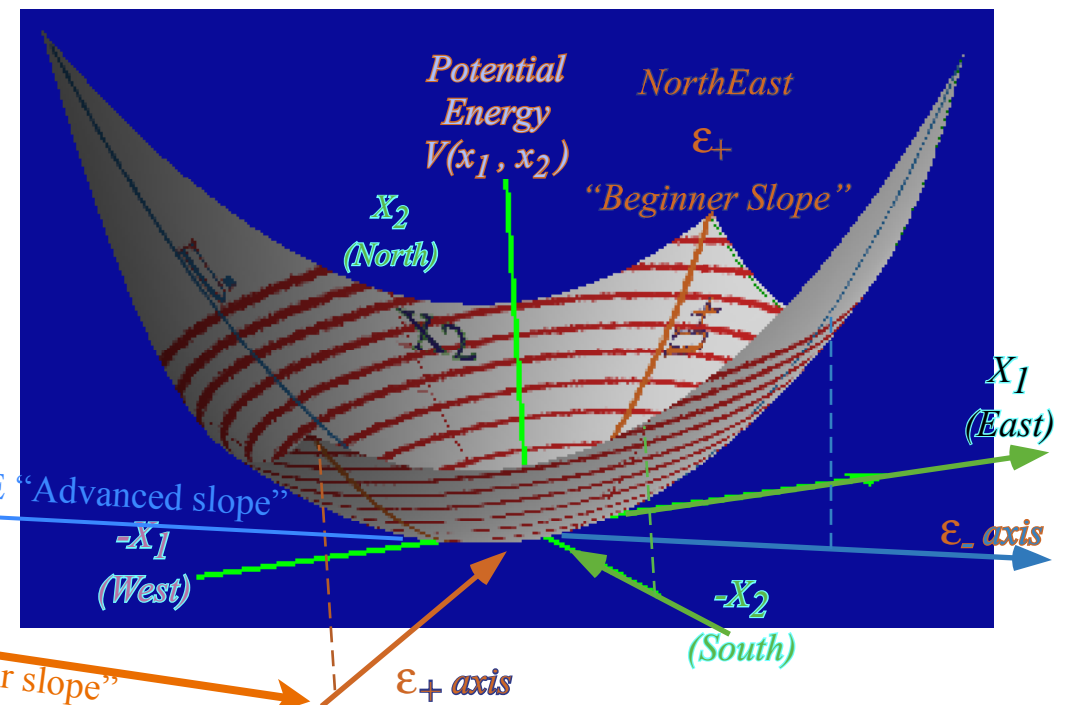
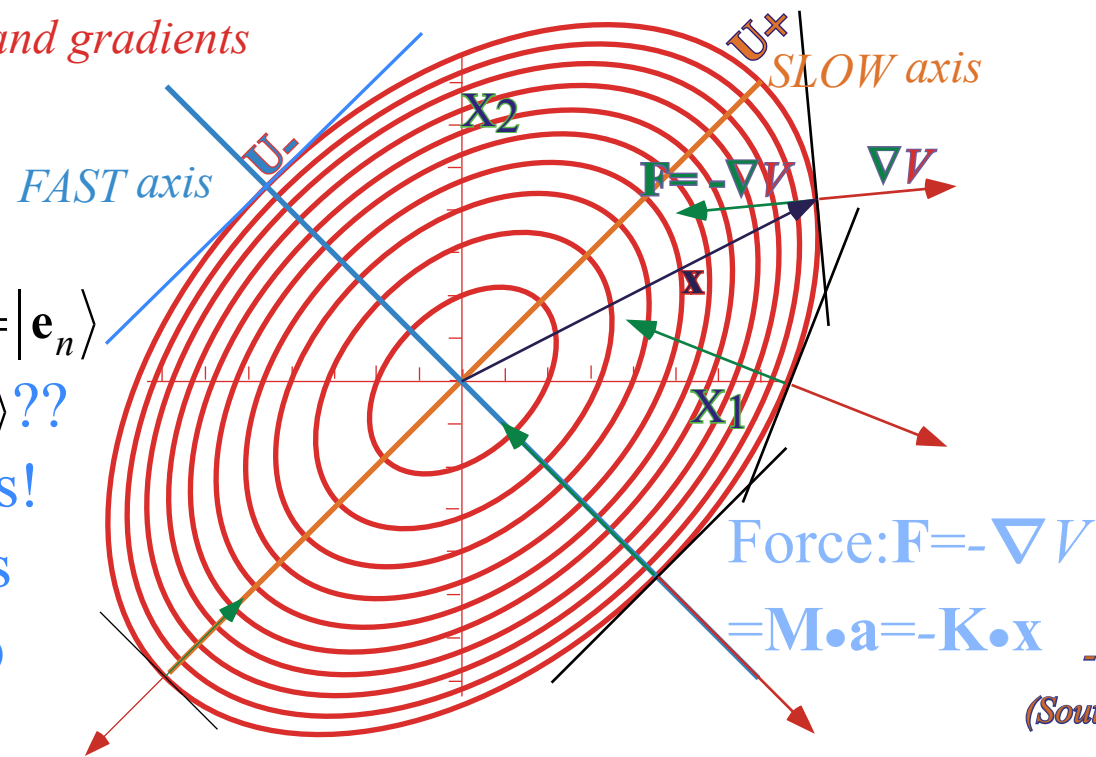


Fig. 3.3.5 Topography lines of potential function $V(x_1, x_2)$ and orthogonal ϵ_+ and ϵ_- normal mode slopes

2D HO potential energy $V(x_1, x_2)$ quadratic form defines layers of elliptical V -contours (Here: $k_1 = k = k_2$)

$$V = \frac{1}{2}(k + k_{12})x_1^2 - k_{12}x_1x_2 + \frac{1}{2}(k + k_{12})x_2^2 = \frac{1}{2}\langle \mathbf{x} | \mathbf{K} | \mathbf{x} \rangle = \frac{1}{2}\mathbf{x} \cdot \mathbf{K} \cdot \mathbf{x} = \begin{pmatrix} x_1 & x_2 \end{pmatrix} \begin{pmatrix} k + k_{12} & -k_{12} \\ -k_{12} & k + k_{12} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

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(if any)

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Only extremal axes

work. (major or minor axes)

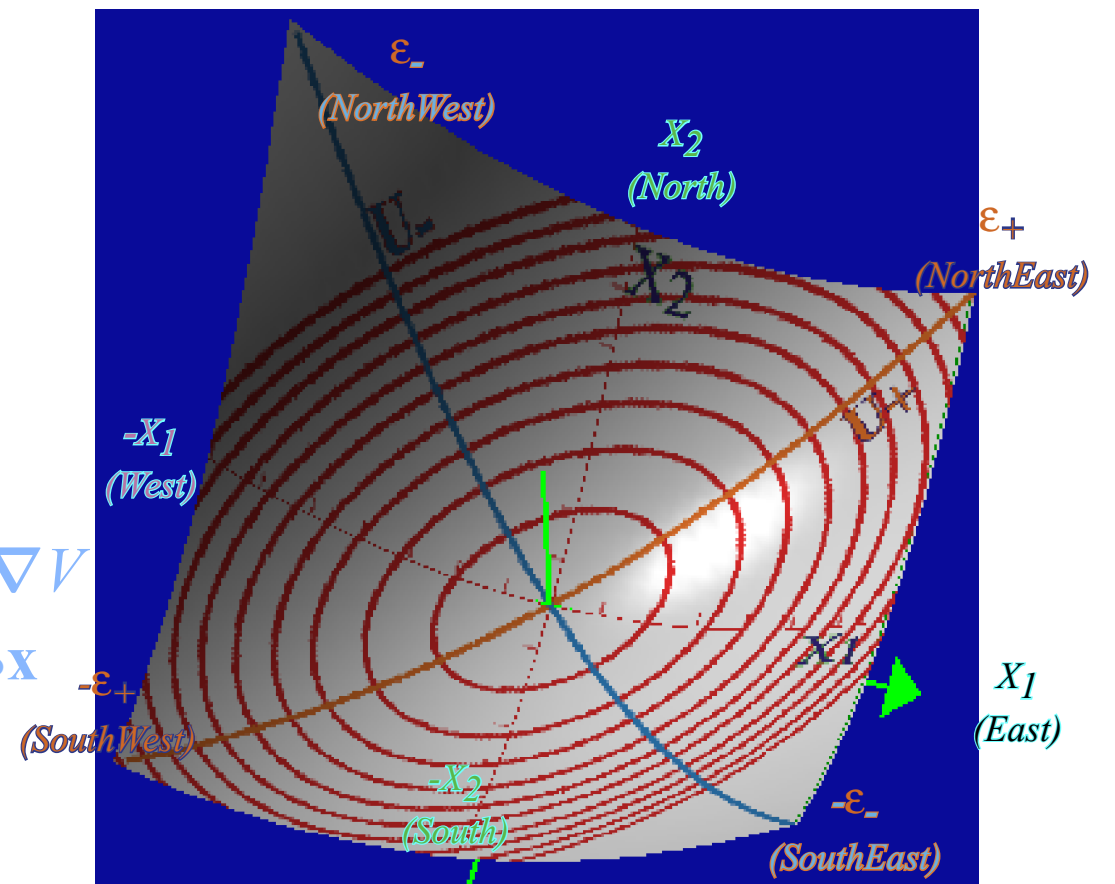
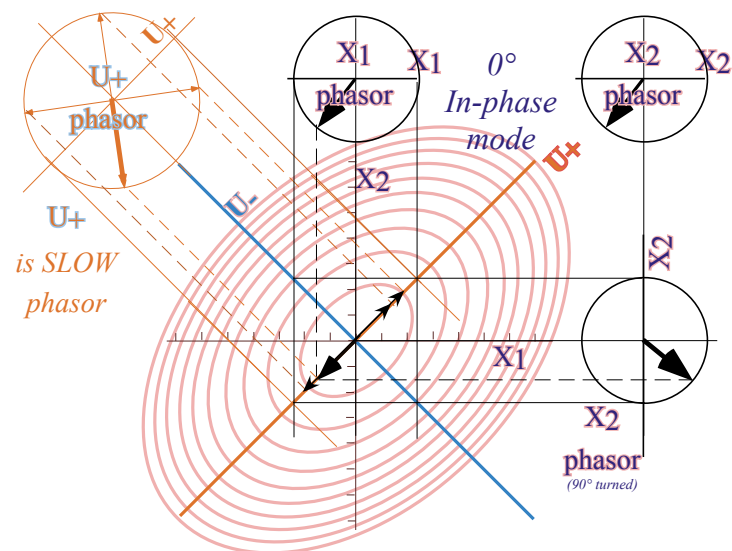
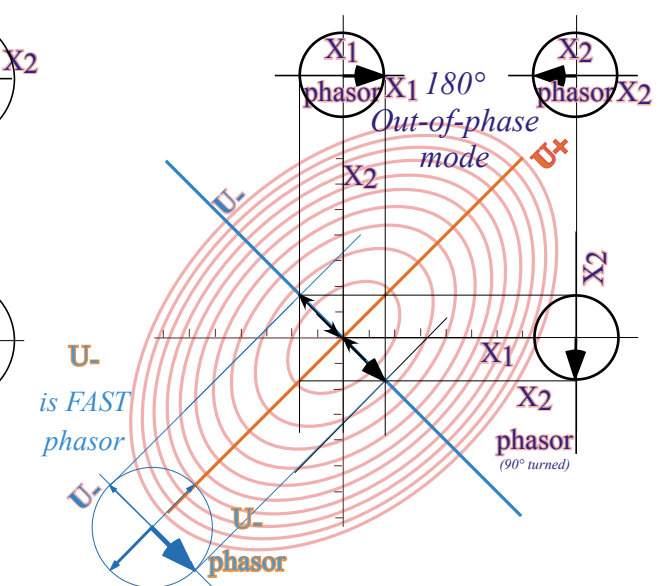


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BoxIt (Beating) Web Simulation (A=1, B=-0.1, C=0, D=1) with Comparison Cosine wave (T=2π)

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Matrix-algebraic method for finding eigenvector and eigenvalues *With example matrix* $\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

An *eigenvector* $|\varepsilon_k\rangle$ of \mathbf{M} is in a direction that is left unchanged by \mathbf{M} .

$$\mathbf{M}|\varepsilon_k\rangle = \varepsilon_k|\varepsilon_k\rangle, \text{ or: } (\mathbf{M} - \varepsilon_k\mathbf{1})|\varepsilon_k\rangle = \mathbf{0}$$

$$\mathbf{M}|\varepsilon\rangle = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \varepsilon \begin{pmatrix} x \\ y \end{pmatrix} \text{ or: } \begin{pmatrix} 4-\varepsilon & 1 \\ 3 & 2-\varepsilon \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

ε_k is *eigenvalue* associated with eigenvector $|\varepsilon_k\rangle$ direction.

A change of basis to $\{|\varepsilon_1\rangle, |\varepsilon_2\rangle, \dots, |\varepsilon_n\rangle\}$ called *diagonalization* gives

$$\begin{pmatrix} \langle \varepsilon_1 | \mathbf{M} | \varepsilon_1 \rangle & \langle \varepsilon_1 | \mathbf{M} | \varepsilon_2 \rangle & \dots & \langle \varepsilon_1 | \mathbf{M} | \varepsilon_n \rangle \\ \langle \varepsilon_2 | \mathbf{M} | \varepsilon_1 \rangle & \langle \varepsilon_2 | \mathbf{M} | \varepsilon_2 \rangle & \dots & \langle \varepsilon_2 | \mathbf{M} | \varepsilon_n \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \varepsilon_n | \mathbf{M} | \varepsilon_1 \rangle & \langle \varepsilon_n | \mathbf{M} | \varepsilon_2 \rangle & \dots & \langle \varepsilon_n | \mathbf{M} | \varepsilon_n \rangle \end{pmatrix} = \begin{pmatrix} \varepsilon_1 & 0 & \dots & 0 \\ 0 & \varepsilon_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \varepsilon_n \end{pmatrix}$$

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➔ *Secular equation*



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$$0 = (4-\epsilon)(2-\epsilon) - 1 \cdot 3 = 8 - 6\epsilon + \epsilon^2 - 3 = \epsilon^2 - 6\epsilon + 5$$

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Obviously true if \mathbf{M} has diagonal form. (But, that's circular logic. Faith needed!)

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Obviously true if \mathbf{M} has diagonal form. (But, that's circular logic. Faith needed!)

Replace j^{th} HC-factor by $(\mathbf{1})$ to make *projection operators*

$$\begin{aligned} \mathbf{p}_1 &= (\mathbf{1})(\mathbf{M} - \epsilon_2\mathbf{1}) \dots (\mathbf{M} - \epsilon_n\mathbf{1}) \\ \mathbf{p}_2 &= (\mathbf{M} - \epsilon_1\mathbf{1})(\mathbf{1}) \dots (\mathbf{M} - \epsilon_n\mathbf{1}) \\ &\vdots \\ \mathbf{p}_n &= (\mathbf{M} - \epsilon_1\mathbf{1})(\mathbf{M} - \epsilon_2\mathbf{1}) \dots (\mathbf{1}) \end{aligned}$$

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$$\mathbf{p}_2 = (\mathbf{M} - 1\mathbf{1})(\mathbf{1}) = \begin{pmatrix} 4-1 & 1 \\ 3 & 2-1 \end{pmatrix} = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$$

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Replace j^{th} HC-factor by $(\mathbf{1})$ to make *projection operators* $\mathbf{p}_k = \prod_{j \neq k} (\mathbf{M} - \epsilon_j \mathbf{1})$

$$\mathbf{p}_1 = (\mathbf{1})(\mathbf{M} - \epsilon_2 \mathbf{1}) \dots (\mathbf{M} - \epsilon_n \mathbf{1})$$

$$\mathbf{p}_2 = (\mathbf{M} - \epsilon_1 \mathbf{1})(\mathbf{1}) \dots (\mathbf{M} - \epsilon_n \mathbf{1}) \quad (\text{Assume distinct e-values here: Non-degeneracy clause})$$

$$\vdots \quad \epsilon_j \neq \epsilon_k \neq \dots$$

$$\mathbf{p}_n = (\mathbf{M} - \epsilon_1 \mathbf{1})(\mathbf{M} - \epsilon_2 \mathbf{1}) \dots (\mathbf{1})$$

Each \mathbf{p}_k contains *eigen-bra-kets* since: $(\mathbf{M} - \epsilon_k \mathbf{1})\mathbf{p}_k = \mathbf{0}$ or: $\mathbf{M}\mathbf{p}_k = \epsilon_k \mathbf{p}_k = \mathbf{p}_k \mathbf{M}$.

$$\mathbf{M}|\epsilon\rangle = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \epsilon \begin{pmatrix} x \\ y \end{pmatrix} \text{ or: } \begin{pmatrix} 4 - \epsilon & 1 \\ 3 & 2 - \epsilon \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Trying to solve by Kramer's inversion: (A fool's errand!)

$$x = \frac{\det \begin{pmatrix} 0 & 1 \\ 0 & 2 - \epsilon \end{pmatrix}}{\det \begin{pmatrix} 4 - \epsilon & 1 \\ 3 & 2 - \epsilon \end{pmatrix}} \quad \text{and} \quad y = \frac{\det \begin{pmatrix} 4 - \epsilon & 0 \\ 3 & 0 \end{pmatrix}}{\det \begin{pmatrix} 4 - \epsilon & 1 \\ 3 & 2 - \epsilon \end{pmatrix}}$$

Only possible non-zero $\{x, y\}$ if denominator is zero, too!

$$0 = \det|\mathbf{M} - \epsilon \cdot \mathbf{1}| = \det \left[\begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} - \epsilon \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right] = \det \begin{pmatrix} 4 - \epsilon & 1 \\ 3 & 2 - \epsilon \end{pmatrix}$$

$$0 = (4 - \epsilon)(2 - \epsilon) - 1 \cdot 3 = 8 - 6\epsilon + \epsilon^2 - 3 = \epsilon^2 - 6\epsilon + 5$$

$$0 = \epsilon^2 - \text{Trace}(\mathbf{M})\epsilon + \det(\mathbf{M}) = \epsilon^2 - 6\epsilon + 5$$

$$0 = (\epsilon - 1)(\epsilon - 5) \text{ so let: } \epsilon_1 = 1 \text{ and: } \epsilon_2 = 5$$

$$0 = \mathbf{M}^2 - 6\mathbf{M} + 5\mathbf{1} = (\mathbf{M} - 1 \cdot \mathbf{1})(\mathbf{M} - 5 \cdot \mathbf{1})$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}^2 - 6 \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} + 5 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\mathbf{p}_1 = (\mathbf{1})(\mathbf{M} - 5 \cdot \mathbf{1}) = \begin{pmatrix} 4 - 5 & 1 \\ 3 & 2 - 5 \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix}$$

$$\mathbf{p}_2 = (\mathbf{M} - 1 \cdot \mathbf{1})(\mathbf{1}) = \begin{pmatrix} 4 - 1 & 1 \\ 3 & 2 - 1 \end{pmatrix} = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$$

$$\mathbf{M}\mathbf{p}_1 = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \cdot \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} = 1 \cdot \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} = 1 \cdot \mathbf{p}_1$$

$$\mathbf{M}\mathbf{p}_2 = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \cdot \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = 5 \cdot \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = 5 \cdot \mathbf{p}_2$$

Matrix-algebraic method for finding eigenvector and eigenvalues With example matrix $\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

An *eigenvector* $|\epsilon_k\rangle$ of \mathbf{M} is in a direction that is left unchanged by \mathbf{M} .

$$\mathbf{M}|\epsilon_k\rangle = \epsilon_k|\epsilon_k\rangle, \text{ or: } (\mathbf{M} - \epsilon_k \mathbf{1})|\epsilon_k\rangle = \mathbf{0}$$

ϵ_k is *eigenvalue* associated with eigenvector $|\epsilon_k\rangle$ direction.

A change of basis to $\{|\epsilon_1\rangle, |\epsilon_2\rangle, \dots, |\epsilon_n\rangle\}$ called *diagonalization* gives

$$\begin{pmatrix} \langle \epsilon_1 | \mathbf{M} | \epsilon_1 \rangle & \langle \epsilon_1 | \mathbf{M} | \epsilon_2 \rangle & \dots & \langle \epsilon_1 | \mathbf{M} | \epsilon_n \rangle \\ \langle \epsilon_2 | \mathbf{M} | \epsilon_1 \rangle & \langle \epsilon_2 | \mathbf{M} | \epsilon_2 \rangle & \dots & \langle \epsilon_2 | \mathbf{M} | \epsilon_n \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \epsilon_n | \mathbf{M} | \epsilon_1 \rangle & \langle \epsilon_n | \mathbf{M} | \epsilon_2 \rangle & \dots & \langle \epsilon_n | \mathbf{M} | \epsilon_n \rangle \end{pmatrix} = \begin{pmatrix} \epsilon_1 & 0 & \dots & 0 \\ 0 & \epsilon_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \epsilon_n \end{pmatrix}$$

First step in finding eigenvalues: Solve *secular equation*

$$\det|\mathbf{M} - \epsilon \mathbf{1}| = 0 = (-1)^n (\epsilon^n + a_1 \epsilon^{n-1} + a_2 \epsilon^{n-2} + \dots + a_{n-1} \epsilon + a_n)$$

where:

$$a_1 = -\text{Trace} \mathbf{M}, \dots, a_k = (-1)^k \sum \text{diagonal k-by-k minors of } \mathbf{M}, \dots, a_n = (-1)^n \det|\mathbf{M}|$$

Secular equation has n -factors, one for each eigenvalue.

$$\det|\mathbf{M} - \epsilon \mathbf{1}| = 0 = (-1)^n (\epsilon - \epsilon_1)(\epsilon - \epsilon_2) \dots (\epsilon - \epsilon_n)$$

Each ϵ replaced by \mathbf{M} and each ϵ_k by $\epsilon_k \mathbf{1}$ gives *Hamilton-Cayley* matrix equation.

$$\mathbf{0} = (\mathbf{M} - \epsilon_1 \mathbf{1})(\mathbf{M} - \epsilon_2 \mathbf{1}) \dots (\mathbf{M} - \epsilon_n \mathbf{1})$$

Obviously true if \mathbf{M} has diagonal form. (But, that's circular logic. Faith needed!)

Replace j^{th} HC-factor by $(\mathbf{1})$ to make *projection operators* $\mathbf{p}_k = \prod_{j \neq k} (\mathbf{M} - \epsilon_j \mathbf{1})$

$$\begin{aligned} \mathbf{p}_1 &= (\mathbf{1})(\mathbf{M} - \epsilon_2 \mathbf{1}) \dots (\mathbf{M} - \epsilon_n \mathbf{1}) \\ \mathbf{p}_2 &= (\mathbf{M} - \epsilon_1 \mathbf{1})(\mathbf{1}) \dots (\mathbf{M} - \epsilon_n \mathbf{1}) \\ &\vdots \\ \mathbf{p}_n &= (\mathbf{M} - \epsilon_1 \mathbf{1})(\mathbf{M} - \epsilon_2 \mathbf{1}) \dots (\mathbf{1}) \end{aligned} \quad \begin{array}{l} \text{(Assume distinct e-values here: Non-degeneracy clause)} \\ \epsilon_j \neq \epsilon_k \neq \dots \end{array}$$

Each \mathbf{p}_k contains *eigen-bra-kets* since: $(\mathbf{M} - \epsilon_k \mathbf{1})\mathbf{p}_k = \mathbf{0}$ or: $\mathbf{M}\mathbf{p}_k = \epsilon_k \mathbf{p}_k = \mathbf{p}_k \mathbf{M}$.

Notice \mathbf{p}_k commutes with \mathbf{M} ,...

since $\mathbf{M}^1, \mathbf{M}^2, \dots$ commute with \mathbf{M} .

$$\mathbf{M}|\epsilon\rangle = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \epsilon \begin{pmatrix} x \\ y \end{pmatrix} \text{ or: } \begin{pmatrix} 4 - \epsilon & 1 \\ 3 & 2 - \epsilon \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Trying to solve by Kramer's inversion: (A fool's errand!)

$$x = \frac{\det \begin{pmatrix} 0 & 1 \\ 0 & 2 - \epsilon \end{pmatrix}}{\det \begin{pmatrix} 4 - \epsilon & 1 \\ 3 & 2 - \epsilon \end{pmatrix}} \quad \text{and} \quad y = \frac{\det \begin{pmatrix} 4 - \epsilon & 0 \\ 3 & 0 \end{pmatrix}}{\det \begin{pmatrix} 4 - \epsilon & 1 \\ 3 & 2 - \epsilon \end{pmatrix}}$$

Only possible non-zero $\{x, y\}$ if denominator is zero, too!

$$0 = \det|\mathbf{M} - \epsilon \cdot \mathbf{1}| = \det \left[\begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} - \epsilon \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right] = \det \begin{pmatrix} 4 - \epsilon & 1 \\ 3 & 2 - \epsilon \end{pmatrix}$$

$$0 = (4 - \epsilon)(2 - \epsilon) - 1 \cdot 3 = 8 - 6\epsilon + \epsilon^2 - 1 \cdot 3 = \epsilon^2 - 6\epsilon + 5$$

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$$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}^2 - 6 \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} + 5 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\mathbf{p}_1 = (\mathbf{1})(\mathbf{M} - 5 \cdot \mathbf{1}) = \begin{pmatrix} 4 - 5 & 1 \\ 3 & 2 - 5 \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix}$$

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$$\mathbf{M}\mathbf{p}_1 = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \cdot \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} = 1 \cdot \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} = 1 \cdot \mathbf{p}_1$$

$$\mathbf{M}\mathbf{p}_2 = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \cdot \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = 5 \cdot \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = 5 \cdot \mathbf{p}_2$$

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➔ *Idempotent projectors* (↔ *low eigenvalues ⇒ eigenvectors*)

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Matrix-algebraic method for finding eigenvector and eigenvalues : *With example matrix* $\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

$$\mathbf{p}_j \mathbf{p}_k = \mathbf{p}_j \prod_{m \neq k} (\mathbf{M} - \varepsilon_m \mathbf{1}) = \prod_{m \neq k} (\mathbf{p}_j \mathbf{M} - \varepsilon_m \mathbf{p}_j \mathbf{1}) \quad \mathbf{M} \mathbf{p}_k = \varepsilon_k \mathbf{p}_k = \mathbf{p}_k \mathbf{M}$$

Multiplication properties of \mathbf{p}_j :

$$\mathbf{p}_j \mathbf{p}_k = \prod_{m \neq k} (\varepsilon_j \mathbf{p}_j - \varepsilon_m \mathbf{p}_j) = \mathbf{p}_j \prod_{m \neq k} (\varepsilon_j - \varepsilon_m) = \begin{cases} \mathbf{0} & \text{if } j \neq k \\ \mathbf{p}_k \prod_{m \neq k} (\varepsilon_k - \varepsilon_m) & \text{if } j = k \end{cases}$$

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$$\mathbf{p}_1 \mathbf{p}_2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

Matrix-algebraic method for finding eigenvector and eigenvalues : With example matrix $\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

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Last step:

make *Idempotent Projectors*: $\mathbf{P}_k = \frac{\mathbf{p}_k}{\prod_{m \neq k} (\varepsilon_k - \varepsilon_m)} = \frac{\prod_{m \neq k} (\mathbf{M} - \varepsilon_m \mathbf{1})}{\prod_{m \neq k} (\varepsilon_k - \varepsilon_m)}$
(Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

$$\mathbf{P}_1 = \frac{(\mathbf{M} - 5 \cdot \mathbf{1})}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix}$$

$$\mathbf{P}_2 = \frac{(\mathbf{M} - 1 \cdot \mathbf{1})}{(5 - 1)} = \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$$

Matrix-algebraic method for finding eigenvector and eigenvalues : With example matrix $\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

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$$\mathbf{P}_j \mathbf{P}_k = \begin{cases} \mathbf{0} & \text{if } j \neq k \\ \mathbf{P}_k & \text{if } j = k \end{cases} \quad \begin{array}{l} \mathbf{M} \mathbf{p}_k = \varepsilon_k \mathbf{p}_k = \mathbf{p}_k \mathbf{M} \\ \text{implies:} \\ \mathbf{M} \mathbf{P}_k = \varepsilon_k \mathbf{P}_k = \mathbf{P}_k \mathbf{M} \end{array}$$

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$$\mathbf{p}_2 = (\mathbf{M} - 1 \cdot \mathbf{1}) = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$$

(tricky step)

Factoring bra-kets into "Ket-Bras:

$$\mathbf{P}_1 = \frac{(\mathbf{M} - 5 \cdot \mathbf{1})}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} = k_1 \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \end{pmatrix}}{k_1} = |\varepsilon_1\rangle \langle \varepsilon_1|$$

$$\mathbf{P}_2 = \frac{(\mathbf{M} - 1 \cdot \mathbf{1})}{(5 - 1)} = \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = k_2 \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{3}{2} & \frac{1}{2} \end{pmatrix}}{k_2} = |\varepsilon_2\rangle \langle \varepsilon_2|$$

"Gauge" scale factors that only affect plots

Matrix-algebraic method for finding eigenvector and eigenvalues : With example matrix $\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

$$\mathbf{p}_j \mathbf{p}_k = \mathbf{p}_j \prod_{m \neq k} (\mathbf{M} - \epsilon_m \mathbf{1}) = \prod_{m \neq k} (\mathbf{p}_j \mathbf{M} - \epsilon_m \mathbf{p}_j \mathbf{1}) \quad \mathbf{M} \mathbf{p}_k = \epsilon_k \mathbf{p}_k = \mathbf{p}_k \mathbf{M}$$

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(Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

$$\mathbf{P}_j \mathbf{P}_k = \begin{cases} \mathbf{0} & \text{if } j \neq k \\ \mathbf{P}_k & \text{if } j = k \end{cases}$$

$$\mathbf{M} \mathbf{p}_k = \epsilon_k \mathbf{p}_k = \mathbf{p}_k \mathbf{M} \text{ implies: } \mathbf{M} \mathbf{P}_k = \epsilon_k \mathbf{P}_k = \mathbf{P}_k \mathbf{M}$$

$$\mathbf{p}_1 = (\mathbf{M} - 5 \cdot \mathbf{1}) = \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} \quad \mathbf{p}_1 \mathbf{p}_2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

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"Gauge" scale factors that only affect plots

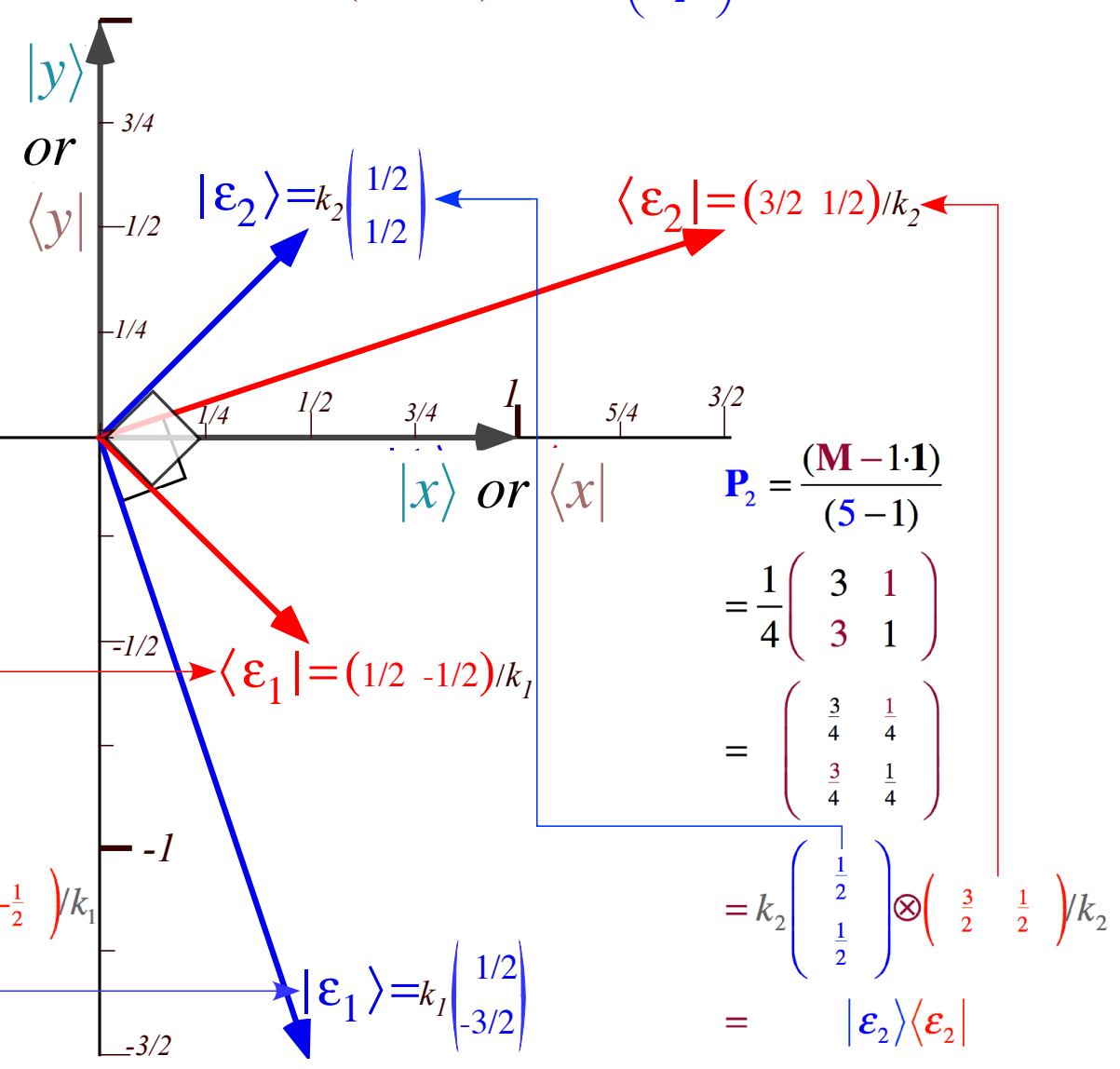
$$\mathbf{P}_2 = \frac{(\mathbf{M} - 1 \cdot \mathbf{1})}{(5 - 1)} = \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = k_2 \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{3}{2} & \frac{1}{2} \end{pmatrix}}{k_2} = |\epsilon_2\rangle \langle \epsilon_2|$$

Eigen-bra-ket projectors of matrix:

$$\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$$

$$\mathbf{P}_1 = \frac{(\mathbf{M} - 5 \cdot \mathbf{1})}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} = \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} = k_1 \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \end{pmatrix}}{k_1} = |\epsilon_1\rangle \langle \epsilon_1|$$

$$\mathbf{P}_2 = \frac{(\mathbf{M} - 1 \cdot \mathbf{1})}{(5 - 1)} = \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix} = k_2 \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{3}{2} & \frac{1}{2} \end{pmatrix}}{k_2} = |\epsilon_2\rangle \langle \epsilon_2|$$



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Orthonormality vs. Completeness vis-a`-vis Operator vs. State

Lagrange functional interpolation formula

2D-HO eigensolution example with bilateral (B-Type) symmetry

Mixed mode beat dynamics and fixed $\pi/2$ phase

2D-HO eigensolution example with asymmetric (A-Type) symmetry

Initial state projection, mixed mode beat dynamics with variable phase

Matrix-algebraic method for finding eigenvector and eigenvalues : With example matrix $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

$$P_j P_k = P_j \prod_{m \neq k} (M - \epsilon_m I) = \prod_{m \neq k} (P_j M - \epsilon_m P_j I) \quad M P_k = \epsilon_k P_k = P_k M$$

Multiplication properties of P_j :

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The P_j are *Mutually Ortho-Normal* as are bra-ket $\langle \epsilon_j |$ and $|\epsilon_j \rangle$ inside P_j 's

Eigen-bra-ket projectors of matrix:
 $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$
 $\begin{pmatrix} \langle \epsilon_1 | \epsilon_1 \rangle & \langle \epsilon_1 | \epsilon_2 \rangle \\ \langle \epsilon_2 | \epsilon_1 \rangle & \langle \epsilon_2 | \epsilon_2 \rangle \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

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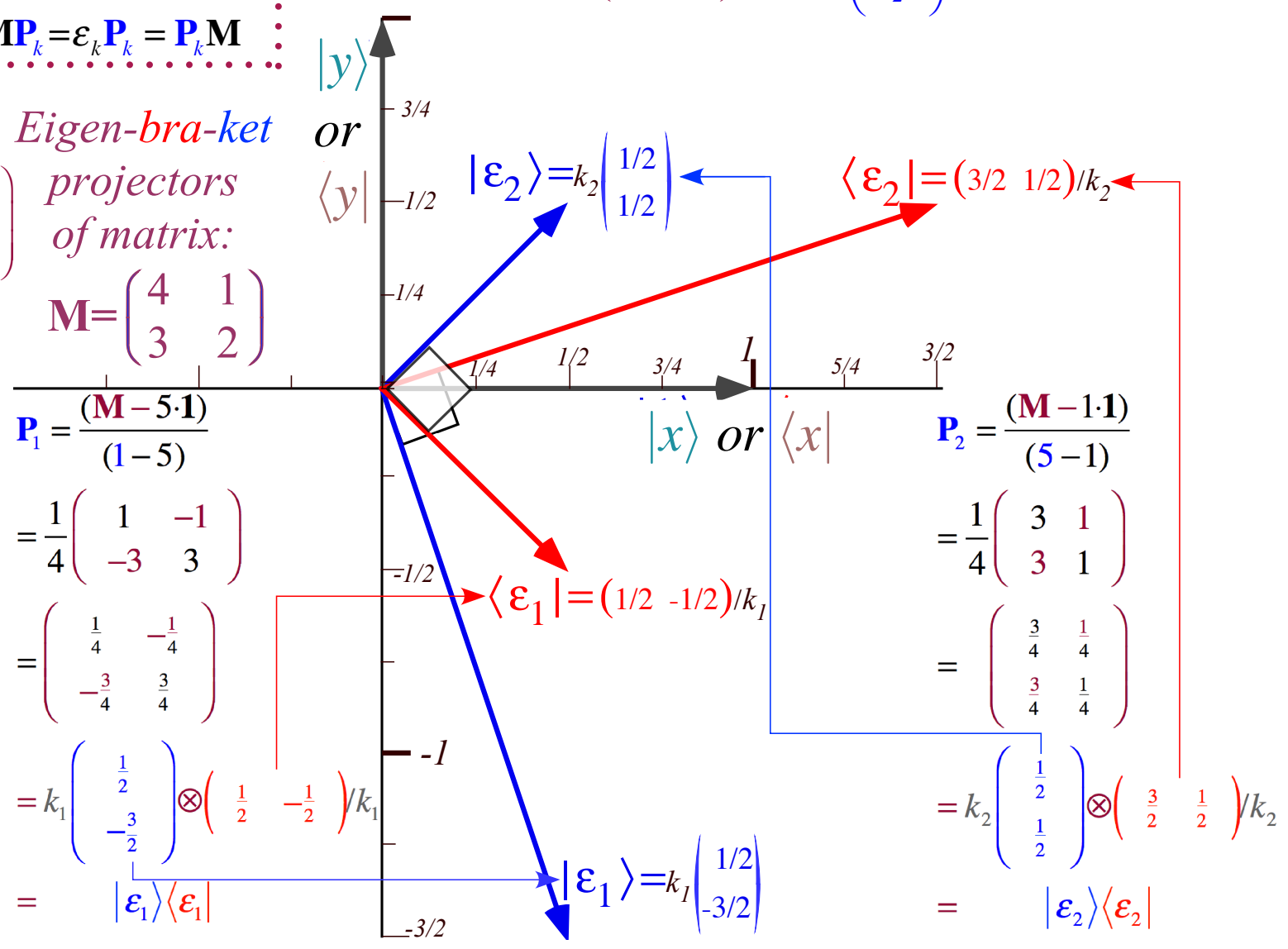
$$P_2 = (M - 1 \cdot I) = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$$

(tricky step)
 Factoring bra-kets into "Ket-Bras:

$$P_1 = \frac{(M - 5 \cdot I)}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} = k_1 \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \end{pmatrix} = |\epsilon_1 \rangle \langle \epsilon_1 |$$

"Gauge" scale factors that only affect plots

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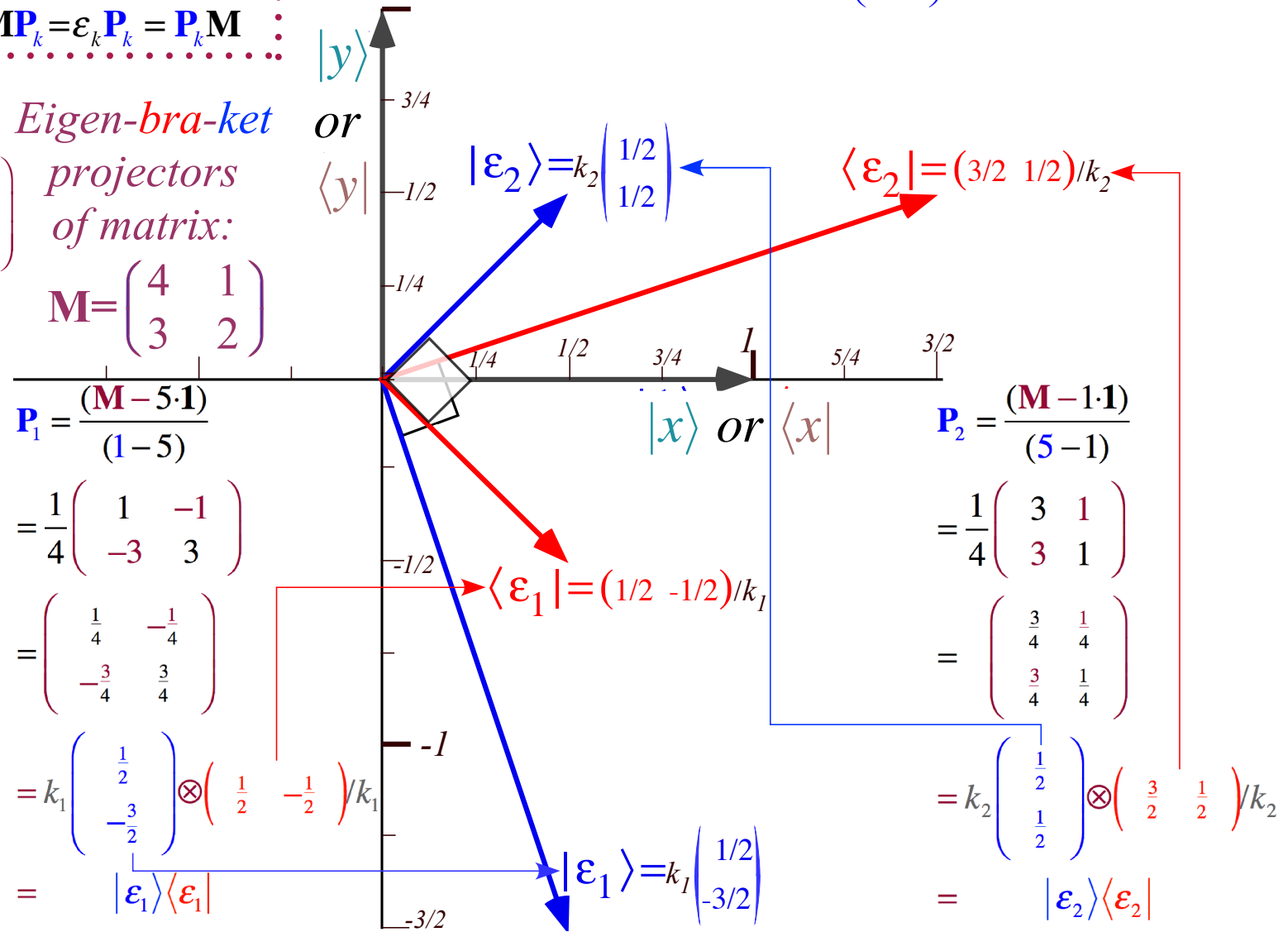
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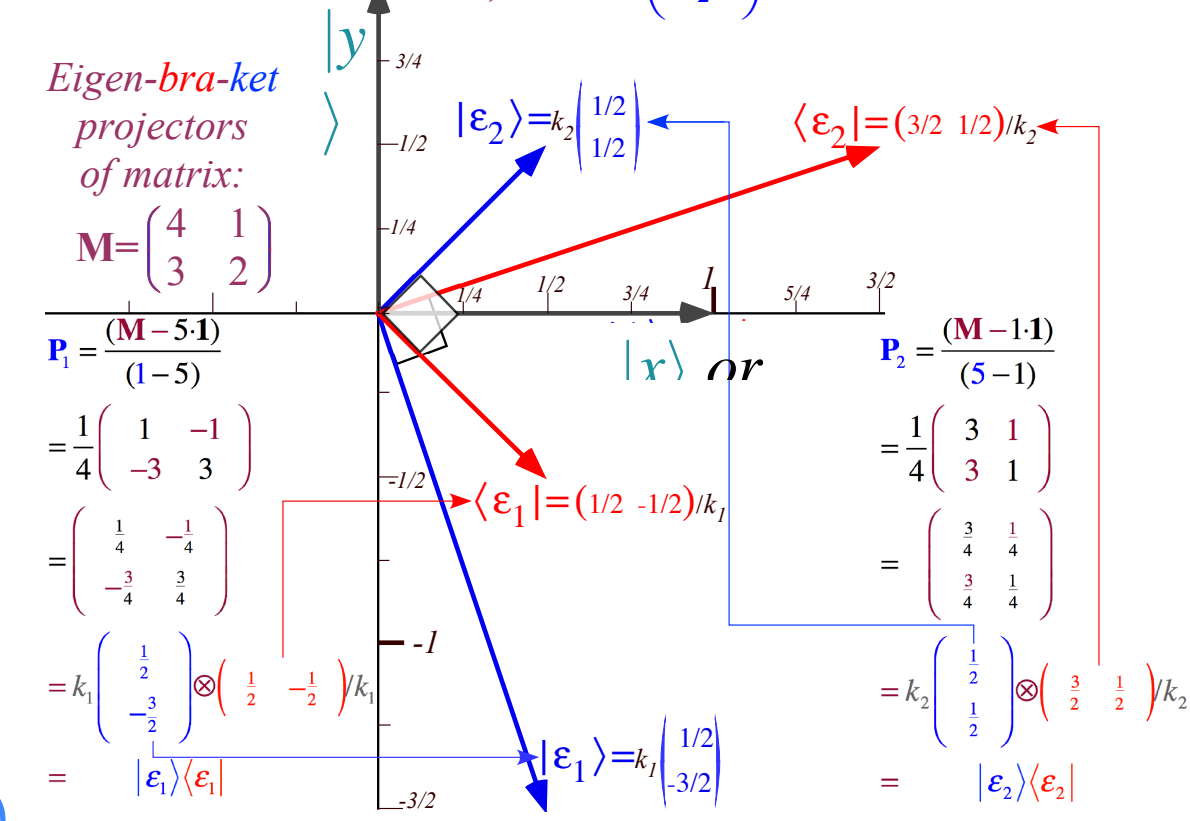
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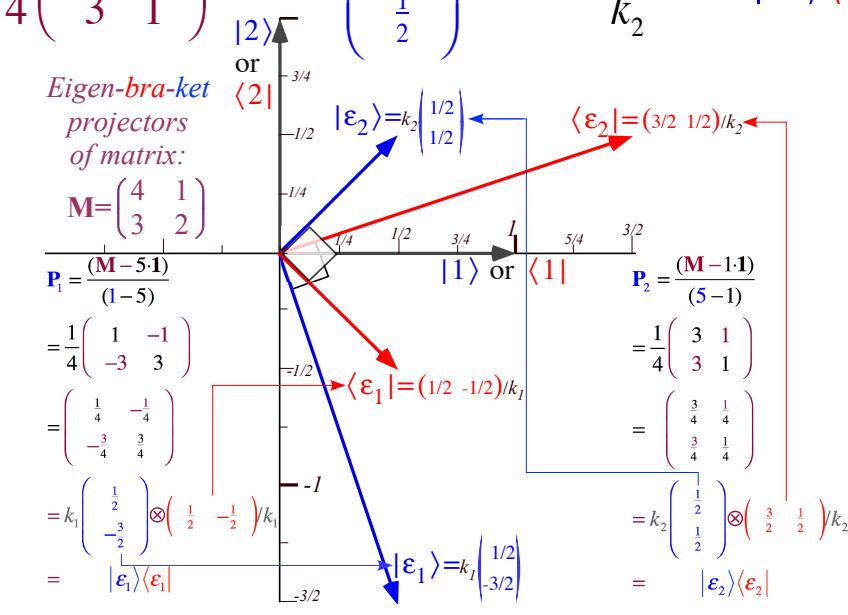
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...and *Functional Spectral Decomposition* of any function $f(\mathbf{M})$ of \mathbf{M}

$$f(\mathbf{M}) = f(\varepsilon_1) \mathbf{P}_1 + f(\varepsilon_2) \mathbf{P}_2 + \dots + f(\varepsilon_n) \mathbf{P}_n$$

Matrix and operator Spectral Decompositions

$$\mathbf{p}_j \mathbf{p}_k = \mathbf{p}_j \prod_{m \neq k} (\mathbf{M} - \varepsilon_m \mathbf{1}) = \prod_{m \neq k} (\mathbf{p}_j \mathbf{M} - \varepsilon_m \mathbf{p}_j \mathbf{1}) \quad \mathbf{M} \mathbf{p}_k = \varepsilon_k \mathbf{p}_k = \mathbf{p}_k \mathbf{M}$$

Multiplication properties of \mathbf{p}_j :

$$\mathbf{p}_j \mathbf{p}_k = \prod_{m \neq k} (\varepsilon_j \mathbf{p}_j - \varepsilon_m \mathbf{p}_j) = \mathbf{p}_j \prod_{m \neq k} (\varepsilon_j - \varepsilon_m) = \begin{cases} \mathbf{0} & \text{if } j \neq k \\ \mathbf{p}_k \prod_{m \neq k} (\varepsilon_k - \varepsilon_m) & \text{if } j = k \end{cases}$$

Last step:

make *Idempotent Projectors*: $\mathbf{P}_k = \frac{\mathbf{p}_k}{\prod_{m \neq k} (\varepsilon_k - \varepsilon_m)} = \frac{\prod_{m \neq k} (\mathbf{M} - \varepsilon_m \mathbf{1})}{\prod_{m \neq k} (\varepsilon_k - \varepsilon_m)}$
(Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

$$\mathbf{P}_j \mathbf{P}_k = \begin{cases} \mathbf{0} & \text{if } j \neq k \\ \mathbf{P}_k & \text{if } j = k \end{cases} \quad \begin{array}{l} \mathbf{M} \mathbf{P}_k = \varepsilon_k \mathbf{P}_k = \mathbf{P}_k \mathbf{M} \\ \text{implies:} \\ \mathbf{M} \mathbf{P}_k = \varepsilon_k \mathbf{P}_k = \mathbf{P}_k \mathbf{M} \end{array}$$

The \mathbf{P}_j are *Mutually Ortho-Normal* as are bra-ket $\langle \varepsilon_j |$ and $|\varepsilon_j \rangle$ inside \mathbf{P}_j 's

$$\begin{pmatrix} \langle \varepsilon_1 | \varepsilon_1 \rangle & \langle \varepsilon_1 | \varepsilon_2 \rangle \\ \langle \varepsilon_2 | \varepsilon_1 \rangle & \langle \varepsilon_2 | \varepsilon_2 \rangle \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

...and the \mathbf{P}_j satisfy a *Completeness Relation*:

$$\mathbf{1} = \mathbf{P}_1 + \mathbf{P}_2 + \dots + \mathbf{P}_n = |\varepsilon_1 \rangle \langle \varepsilon_1 | + |\varepsilon_2 \rangle \langle \varepsilon_2 | + \dots + |\varepsilon_n \rangle \langle \varepsilon_n |$$

$$\mathbf{P}_1 + \mathbf{P}_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = |\varepsilon_1 \rangle \langle \varepsilon_1 | + |\varepsilon_2 \rangle \langle \varepsilon_2 |$$

$$\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = 1\mathbf{P}_1 + 5\mathbf{P}_2 = 1|\varepsilon_1 \rangle \langle \varepsilon_1 | + 5|\varepsilon_2 \rangle \langle \varepsilon_2 | = 1 \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} + 5 \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix}$$

Eigen-operators $\mathbf{M} \mathbf{P}_k = \varepsilon_k \mathbf{P}_k$ then give *Spectral Decomposition* of operator \mathbf{M}

$$\mathbf{M} = \mathbf{M} \mathbf{P}_1 + \mathbf{M} \mathbf{P}_2 + \dots + \mathbf{M} \mathbf{P}_n = \varepsilon_1 \mathbf{P}_1 + \varepsilon_2 \mathbf{P}_2 + \dots + \varepsilon_n \mathbf{P}_n$$

...and *Functional Spectral Decomposition* of any function $f(\mathbf{M})$ of \mathbf{M}

$$f(\mathbf{M}) = f(\varepsilon_1) \mathbf{P}_1 + f(\varepsilon_2) \mathbf{P}_2 + \dots + f(\varepsilon_n) \mathbf{P}_n$$

$$\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$$

$$\mathbf{p}_1 = (\mathbf{M} - 5 \cdot \mathbf{1}) = \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix}$$

$$\mathbf{p}_2 = (\mathbf{M} - 1 \cdot \mathbf{1}) = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$$

$$\mathbf{p}_1 \mathbf{p}_2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

(tricky step)

Factoring bra-kets into "Ket-Bras:

$$\mathbf{P}_1 = \frac{(\mathbf{M} - 5 \cdot \mathbf{1})}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} = k_1 \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \end{pmatrix}}{k_1} = |\varepsilon_1 \rangle \langle \varepsilon_1 |$$

$$\mathbf{P}_2 = \frac{(\mathbf{M} - 1 \cdot \mathbf{1})}{(5 - 1)} = \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = k_2 \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{3}{2} & \frac{1}{2} \end{pmatrix}}{k_2} = |\varepsilon_2 \rangle \langle \varepsilon_2 |$$

Example:

$$\mathbf{M}^{50} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = 1^{50} \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} + 5^{50} \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 1+3 \cdot 5^{50} & 5^{50}-1 \\ 3 \cdot 5^{50}-3 & 5^{50}+3 \end{pmatrix}$$

Matrix and operator Spectral Decompositions

$$\mathbf{p}_j \mathbf{p}_k = \mathbf{p}_j \prod_{m \neq k} (\mathbf{M} - \varepsilon_m \mathbf{1}) = \prod_{m \neq k} (\mathbf{p}_j \mathbf{M} - \varepsilon_m \mathbf{p}_j \mathbf{1}) \quad \mathbf{M} \mathbf{p}_k = \varepsilon_k \mathbf{p}_k = \mathbf{p}_k \mathbf{M}$$

Multiplication properties of \mathbf{p}_j :

$$\mathbf{p}_j \mathbf{p}_k = \prod_{m \neq k} (\varepsilon_j \mathbf{p}_j - \varepsilon_m \mathbf{p}_j) = \mathbf{p}_j \prod_{m \neq k} (\varepsilon_j - \varepsilon_m) = \begin{cases} \mathbf{0} & \text{if } j \neq k \\ \mathbf{p}_k \prod_{m \neq k} (\varepsilon_k - \varepsilon_m) & \text{if } j = k \end{cases}$$

Last step:

make *Idempotent Projectors*: $\mathbf{P}_k = \frac{\mathbf{p}_k}{\prod_{m \neq k} (\varepsilon_k - \varepsilon_m)} = \frac{\prod_{m \neq k} (\mathbf{M} - \varepsilon_m \mathbf{1})}{\prod_{m \neq k} (\varepsilon_k - \varepsilon_m)}$
(Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

$$\mathbf{P}_j \mathbf{P}_k = \begin{cases} \mathbf{0} & \text{if } j \neq k \\ \mathbf{P}_k & \text{if } j = k \end{cases} \quad \begin{array}{l} \mathbf{M} \mathbf{P}_k = \varepsilon_k \mathbf{P}_k = \mathbf{P}_k \mathbf{M} \\ \text{implies:} \\ \mathbf{M} \mathbf{P}_k = \varepsilon_k \mathbf{P}_k = \mathbf{P}_k \mathbf{M} \end{array}$$

The \mathbf{P}_j are *Mutually Ortho-Normal* as are bra-ket $\langle \varepsilon_j |$ and $|\varepsilon_j \rangle$ inside \mathbf{P}_j 's

$$\begin{pmatrix} \langle \varepsilon_1 | \varepsilon_1 \rangle & \langle \varepsilon_1 | \varepsilon_2 \rangle \\ \langle \varepsilon_2 | \varepsilon_1 \rangle & \langle \varepsilon_2 | \varepsilon_2 \rangle \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

...and the \mathbf{P}_j satisfy a *Completeness Relation*:

$$\mathbf{1} = \mathbf{P}_1 + \mathbf{P}_2 + \dots + \mathbf{P}_n = |\varepsilon_1 \rangle \langle \varepsilon_1 | + |\varepsilon_2 \rangle \langle \varepsilon_2 | + \dots + |\varepsilon_n \rangle \langle \varepsilon_n |$$

$$\mathbf{P}_1 + \mathbf{P}_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = |\varepsilon_1 \rangle \langle \varepsilon_1 | + |\varepsilon_2 \rangle \langle \varepsilon_2 |$$

$$\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = 1 \mathbf{P}_1 + 5 \mathbf{P}_2 = 1 |1 \rangle \langle 1| + 5 |2 \rangle \langle 2| = 1 \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} + 5 \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix}$$

Eigen-operators $\mathbf{M} \mathbf{P}_k = \varepsilon_k \mathbf{P}_k$ then give *Spectral Decomposition* of operator \mathbf{M}

$$\mathbf{M} = \mathbf{M} \mathbf{P}_1 + \mathbf{M} \mathbf{P}_2 + \dots + \mathbf{M} \mathbf{P}_n = \varepsilon_1 \mathbf{P}_1 + \varepsilon_2 \mathbf{P}_2 + \dots + \varepsilon_n \mathbf{P}_n$$

...and *Functional Spectral Decomposition* of any function $f(\mathbf{M})$ of \mathbf{M}

$$f(\mathbf{M}) = f(\varepsilon_1) \mathbf{P}_1 + f(\varepsilon_2) \mathbf{P}_2 + \dots + f(\varepsilon_n) \mathbf{P}_n$$

$$\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$$

$$\mathbf{p}_1 = (\mathbf{M} - 5 \cdot \mathbf{1}) = \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix}$$

$$\mathbf{p}_2 = (\mathbf{M} - 1 \cdot \mathbf{1}) = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$$

$$\mathbf{p}_1 \mathbf{p}_2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

(tricky step)

Factoring bra-kets into "Ket-Bras:

$$\mathbf{P}_1 = \frac{(\mathbf{M} - 5 \cdot \mathbf{1})}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} = k_1 \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \end{pmatrix}}{k_1} = |\varepsilon_1 \rangle \langle \varepsilon_1 |$$

$$\mathbf{P}_2 = \frac{(\mathbf{M} - 1 \cdot \mathbf{1})}{(5 - 1)} = \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = k_2 \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{3}{2} & \frac{1}{2} \end{pmatrix}}{k_2} = |\varepsilon_2 \rangle \langle \varepsilon_2 |$$

Examples:

$$\mathbf{M}^{50} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = 1^{50} \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} + 5^{50} \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 1 + 3 \cdot 5^{50} & 5^{50} - 1 \\ 3 \cdot 5^{50} - 3 & 5^{50} + 3 \end{pmatrix}$$

$$\sqrt{\mathbf{M}} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = \pm \sqrt{1} \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} \pm \sqrt{5} \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix}$$

2D harmonic oscillator equations

Lagrangian and matrix forms and Reciprocity symmetry

2D harmonic oscillator equation eigensolutions

Geometric method

Matrix-algebraic eigensolutions with example $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

Secular equation

Hamilton-Cayley equation and projectors

Idempotent projectors (how eigenvalues \Rightarrow eigenvectors)

Operator orthonormality and Completeness (Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

Spectral Decompositions

Functional spectral decomposition

➔ *Orthonormality vs. Completeness vis-a`-vis Operator vs. State* **←**

Lagrange functional interpolation formula

Diagonalizing Transformations (D-Ttran) from projectors

2D-HO eigensolution example with bilateral (B-Type) symmetry

Mixed mode beat dynamics and fixed $\pi/2$ phase

2D-HO eigensolution example with asymmetric (A-Type) symmetry

Initial state projection, mixed mode beat dynamics with variable phase

Orthonormality vs. Completeness

$$\mathbf{P}_j \mathbf{P}_k = \mathbf{P}_j \prod_{m \neq k} (\mathbf{M} - \varepsilon_m \mathbf{1}) = \prod_{m \neq k} (\mathbf{P}_j \mathbf{M} - \varepsilon_m \mathbf{P}_j \mathbf{1})$$

$$\mathbf{M} \mathbf{P}_k = \varepsilon_k \mathbf{P}_k = \mathbf{P}_k \mathbf{M}$$

$$\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$$

Multiplication properties of \mathbf{P}_j :

$$\mathbf{P}_j \mathbf{P}_k = \prod_{m \neq k} (\varepsilon_j \mathbf{P}_j - \varepsilon_m \mathbf{P}_j) = \mathbf{P}_j \prod_{m \neq k} (\varepsilon_j - \varepsilon_m) = \begin{cases} \mathbf{0} & \text{if } j \neq k \\ \mathbf{P}_k \prod_{m \neq k} (\varepsilon_k - \varepsilon_m) & \text{if } j = k \end{cases}$$

$$\mathbf{P}_1 = (\mathbf{M} - 5 \cdot \mathbf{1}) = \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix}$$

$$\mathbf{P}_1 \mathbf{P}_2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\mathbf{P}_2 = (\mathbf{M} - 1 \cdot \mathbf{1}) = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$$

(tricky step)

Last step:

make *Idempotent Projectors*: $\mathbf{P}_k = \frac{\mathbf{P}_k}{\prod_{m \neq k} (\varepsilon_k - \varepsilon_m)} = \frac{\prod_{m \neq k} (\mathbf{M} - \varepsilon_m \mathbf{1})}{\prod_{m \neq k} (\varepsilon_k - \varepsilon_m)}$

(Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

$$\mathbf{P}_j \mathbf{P}_k = \begin{cases} \mathbf{0} & \text{if } j \neq k \\ \mathbf{P}_k & \text{if } j = k \end{cases}$$

$$\begin{aligned} \mathbf{M} \mathbf{P}_k &= \varepsilon_k \mathbf{P}_k = \mathbf{P}_k \mathbf{M} \\ \text{implies:} \\ \mathbf{M} \mathbf{P}_k &= \varepsilon_k \mathbf{P}_k = \mathbf{P}_k \mathbf{M} \end{aligned}$$

Factoring bra-kets into "Ket-Bras:

$$\begin{aligned} \mathbf{P}_1 &= \frac{(\mathbf{M} - 5 \cdot \mathbf{1})}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} = k_1 \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \end{pmatrix}}{k_1} = |\varepsilon_1\rangle \langle \varepsilon_1| \\ \mathbf{P}_2 &= \frac{(\mathbf{M} - 1 \cdot \mathbf{1})}{(5 - 1)} = \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = k_2 \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{3}{2} & \frac{1}{2} \end{pmatrix}}{k_2} = |\varepsilon_2\rangle \langle \varepsilon_2| \end{aligned}$$

"Gauge" scale factors that only affect plots

The \mathbf{P}_j are *Mutually Ortho-Normal* as are bra-ket $\langle \varepsilon_j |$ and $|\varepsilon_j\rangle$ inside \mathbf{P}_j 's

$$\begin{pmatrix} \langle \varepsilon_1 | \varepsilon_1 \rangle & \langle \varepsilon_1 | \varepsilon_2 \rangle \\ \langle \varepsilon_2 | \varepsilon_1 \rangle & \langle \varepsilon_2 | \varepsilon_2 \rangle \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Eigen-bra-ket projectors of matrix:

$$\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$$

...and the \mathbf{P}_j satisfy a *Completeness Relation*:

$$\begin{aligned} \mathbf{1} &= \mathbf{P}_1 + \mathbf{P}_2 + \dots + \mathbf{P}_n \\ &= |\varepsilon_1\rangle \langle \varepsilon_1| + |\varepsilon_2\rangle \langle \varepsilon_2| + \dots + |\varepsilon_n\rangle \langle \varepsilon_n| \end{aligned}$$

$$\begin{aligned} \mathbf{P}_1 + \mathbf{P}_2 &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ &= |\varepsilon_1\rangle \langle \varepsilon_1| + |\varepsilon_2\rangle \langle \varepsilon_2| \end{aligned}$$

$\{|x\rangle, |y\rangle\}$ -orthonormality with $\{|\varepsilon_1\rangle, |\varepsilon_2\rangle\}$ -completeness

$$\langle x | y \rangle = \delta_{x,y} = \langle x | \mathbf{1} | y \rangle = \langle x | \varepsilon_1 \rangle \langle \varepsilon_1 | y \rangle + \langle x | \varepsilon_2 \rangle \langle \varepsilon_2 | y \rangle.$$

$\{|\varepsilon_1\rangle, |\varepsilon_2\rangle\}$ -orthonormality with $\{|x\rangle, |y\rangle\}$ -completeness

$$\langle \varepsilon_i | \varepsilon_j \rangle = \delta_{i,j} = \langle \varepsilon_i | \mathbf{1} | \varepsilon_j \rangle = \langle \varepsilon_i | x \rangle \langle x | \varepsilon_j \rangle + \langle \varepsilon_i | y \rangle \langle y | \varepsilon_j \rangle$$

$$\mathbf{P}_1 = \frac{(\mathbf{M} - 5 \cdot \mathbf{1})}{(1 - 5)}$$

$$= \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix}$$

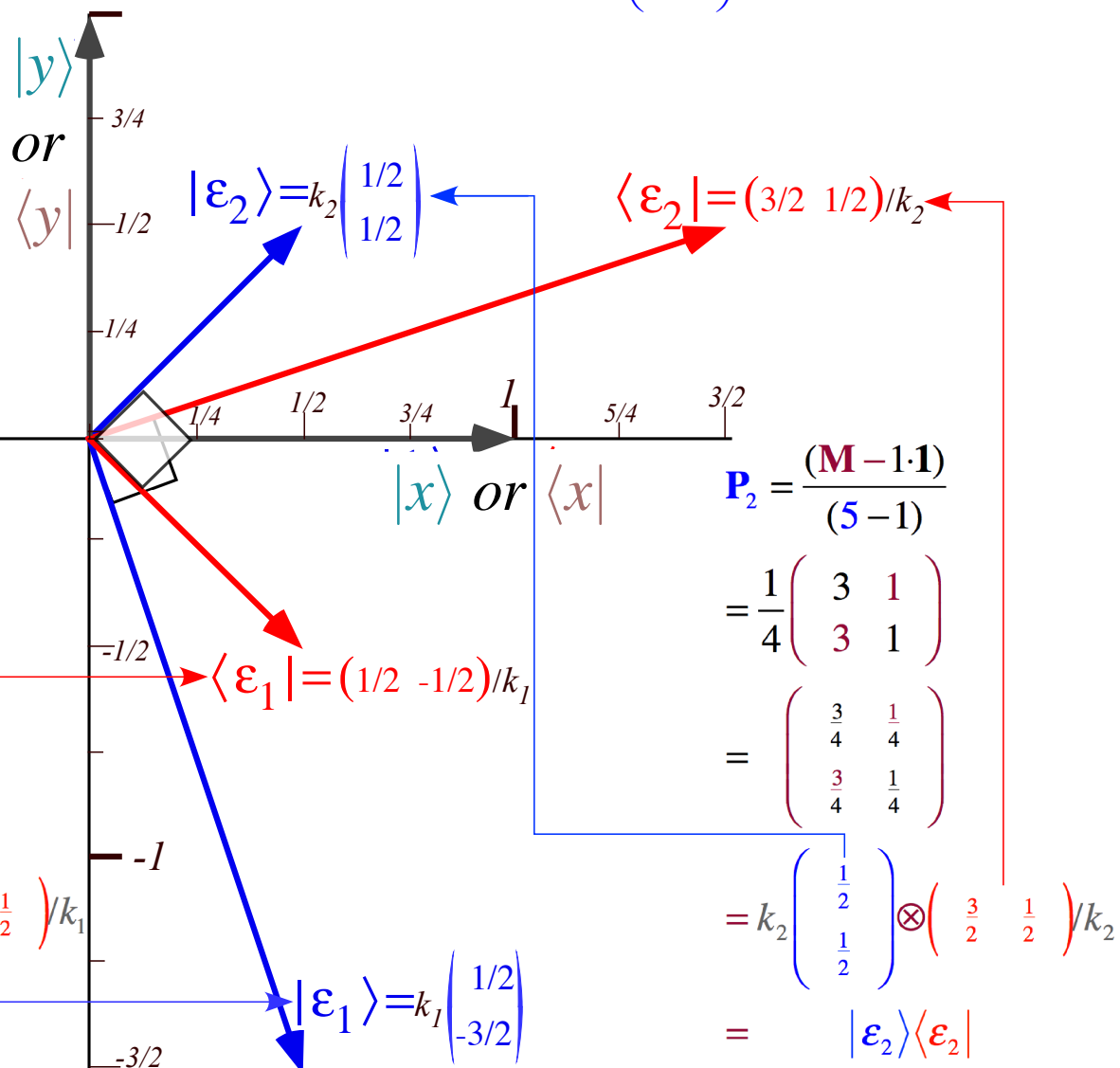
$$= k_1 \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \end{pmatrix}}{k_1} = |\varepsilon_1\rangle \langle \varepsilon_1|$$

$$\mathbf{P}_2 = \frac{(\mathbf{M} - 1 \cdot \mathbf{1})}{(5 - 1)}$$

$$= \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix}$$

$$= k_2 \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{3}{2} & \frac{1}{2} \end{pmatrix}}{k_2} = |\varepsilon_2\rangle \langle \varepsilon_2|$$



Orthonormality vs. Completeness vis-a`-vis Operator vs. State

Operator expressions for orthonormality appear quite different from expressions for completeness.

$$\mathbf{P}_j \mathbf{P}_k = \delta_{jk} \mathbf{P}_k = \begin{cases} \mathbf{0} & \text{if } j \neq k \\ \mathbf{P}_k & \text{if } j = k \end{cases}$$

$$\mathbf{1} = \mathbf{P}_1 + \mathbf{P}_2 + \dots + \mathbf{P}_n$$

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$$|\varepsilon_j\rangle \langle \varepsilon_j | \varepsilon_k\rangle \langle \varepsilon_k| = \delta_{jk} |\varepsilon_k\rangle \langle \varepsilon_k| \quad \text{or:} \quad \langle \varepsilon_j | \varepsilon_k\rangle = \delta_{jk}$$

$$\mathbf{1} = \mathbf{P}_1 + \mathbf{P}_2 + \dots + \mathbf{P}_n$$

$$\mathbf{1} = |\varepsilon_1\rangle \langle \varepsilon_1| + |\varepsilon_2\rangle \langle \varepsilon_2| + \dots + |\varepsilon_n\rangle \langle \varepsilon_n|$$

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$$|\epsilon_j\rangle\langle\epsilon_j|\epsilon_k\rangle\langle\epsilon_k| = \delta_{jk}|\epsilon_k\rangle\langle\epsilon_k| \quad \text{or:} \quad \langle\epsilon_j|\epsilon_k\rangle = \delta_{jk}$$

$$\mathbf{1} = |\epsilon_1\rangle\langle\epsilon_1| + |\epsilon_2\rangle\langle\epsilon_2| + \dots + |\epsilon_n\rangle\langle\epsilon_n|$$

State vector representations of orthonormality are quite **similar** to representations of completeness.

Like 2-sides of the same coin.

$\{|x\rangle, |y\rangle\}$ -orthonormality with $\{|\epsilon_1\rangle, |\epsilon_2\rangle\}$ -completeness

$$\langle x|y\rangle = \delta_{x,y} = \langle x|\mathbf{1}|y\rangle = \langle x|\epsilon_1\rangle\langle\epsilon_1|y\rangle + \langle x|\epsilon_2\rangle\langle\epsilon_2|y\rangle.$$

$\{|\epsilon_1\rangle, |\epsilon_2\rangle\}$ -orthonormality with $\{|x\rangle, |y\rangle\}$ -completeness

$$\langle\epsilon_i|\epsilon_j\rangle = \delta_{i,j} = \langle\epsilon_i|\mathbf{1}|\epsilon_j\rangle = \langle\epsilon_i|x\rangle\langle x|\epsilon_j\rangle + \langle\epsilon_i|y\rangle\langle y|\epsilon_j\rangle$$

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$$|\epsilon_j\rangle \langle \epsilon_j | \epsilon_k\rangle \langle \epsilon_k| = \delta_{jk} |\epsilon_k\rangle \langle \epsilon_k| \quad \text{or:} \quad \langle \epsilon_j | \epsilon_k\rangle = \delta_{jk} \qquad \mathbf{1} = |\epsilon_1\rangle \langle \epsilon_1| + |\epsilon_2\rangle \langle \epsilon_2| + \dots + |\epsilon_n\rangle \langle \epsilon_n|$$

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$$\langle x | y \rangle = \delta(x, y) = \psi_1(x) \psi_1^*(y) + \psi_2(x) \psi_2^*(y) + \dots$$

Dirac δ -function

$\{|\epsilon_1\rangle, |\epsilon_2\rangle\}$ -orthonormality with $\{|x\rangle, |y\rangle\}$ -completeness

$$\langle \epsilon_i | \epsilon_j \rangle = \delta_{i,j} = \langle \epsilon_i | \mathbf{1} | \epsilon_j \rangle = \langle \epsilon_i | x \rangle \langle x | \epsilon_j \rangle + \langle \epsilon_i | y \rangle \langle y | \epsilon_j \rangle$$

However Schrodinger wavefunction notation $\psi(x) = \langle x | \psi \rangle$ shows quite a **difference**...

Orthonormality vs. Completeness vis-a-vis Operator vs. State

Operator expressions for orthonormality appear quite **different** from expressions for completeness.

$$\mathbf{P}_j \mathbf{P}_k = \delta_{jk} \mathbf{P}_k = \begin{cases} \mathbf{0} & \text{if } j \neq k \\ \mathbf{P}_k & \text{if } j = k \end{cases} \quad \mathbf{1} = \mathbf{P}_1 + \mathbf{P}_2 + \dots + \mathbf{P}_n$$

$$|\epsilon_j\rangle \langle \epsilon_j| \epsilon_k\rangle \langle \epsilon_k| = \delta_{jk} |\epsilon_k\rangle \langle \epsilon_k| \quad \text{or:} \quad \langle \epsilon_j | \epsilon_k \rangle = \delta_{jk} \quad \mathbf{1} = |\epsilon_1\rangle \langle \epsilon_1| + |\epsilon_2\rangle \langle \epsilon_2| + \dots + |\epsilon_n\rangle \langle \epsilon_n|$$

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$$\langle x | y \rangle = \delta(x, y) = \psi_1(x) \psi_1^*(y) + \psi_2(x) \psi_2^*(y) + \dots$$

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$\{|\epsilon_1\rangle, |\epsilon_2\rangle\}$ -orthonormality with $\{|x\rangle, |y\rangle\}$ -completeness

$$\langle \epsilon_i | \epsilon_j \rangle = \delta_{i,j} = \langle \epsilon_i | \mathbf{1} | \epsilon_j \rangle = \langle \epsilon_i | x \rangle \langle x | \epsilon_j \rangle + \langle \epsilon_i | y \rangle \langle y | \epsilon_j \rangle$$

$$\langle \epsilon_i | \epsilon_j \rangle = \delta_{i,j} = \dots + \psi_i^*(x) \psi_j(x) + \psi_2(y) \psi_2^*(y) + \dots \rightarrow \int dx \psi_i^*(x) \psi_j(x)$$

However Schrodinger wavefunction notation $\psi(x) = \langle x | \psi \rangle$ shows quite a **difference**...

...particularly in the orthonormality integral.

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Hamilton-Cayley equation and projectors

Idempotent projectors (how eigenvalues \Rightarrow eigenvectors)

Operator orthonormality and Completeness (Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

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Orthonormality vs. Completeness vis-a`-vis Operator vs. State

➔ *Lagrange functional interpolation formula* **←**

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Mixed mode beat dynamics and fixed $\pi/2$ phase

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Initial state projection, mixed mode beat dynamics with variable phase

A Proof of Projector Completeness (Truer-than-true by Lagrange interpolation)

Compare matrix *completeness relation* and *functional spectral decompositions*

$$\mathbf{1} = \mathbf{P}_1 + \mathbf{P}_2 + \dots + \mathbf{P}_n = \sum_{\varepsilon_k} \mathbf{P}_k = \sum_{\varepsilon_k} \frac{\prod_{m \neq k} (\mathbf{M} - \varepsilon_m \mathbf{1})}{\prod_{m \neq k} (\varepsilon_k - \varepsilon_m)} \quad f(\mathbf{M}) = f(\varepsilon_1)\mathbf{P}_1 + f(\varepsilon_2)\mathbf{P}_2 + \dots + f(\varepsilon_n)\mathbf{P}_n = \sum_{\varepsilon_k} f(\varepsilon_k)\mathbf{P}_k = \sum_{\varepsilon_k} f(\varepsilon_k) \frac{\prod_{m \neq k} (\mathbf{M} - \varepsilon_m \mathbf{1})}{\prod_{m \neq k} (\varepsilon_k - \varepsilon_m)}$$

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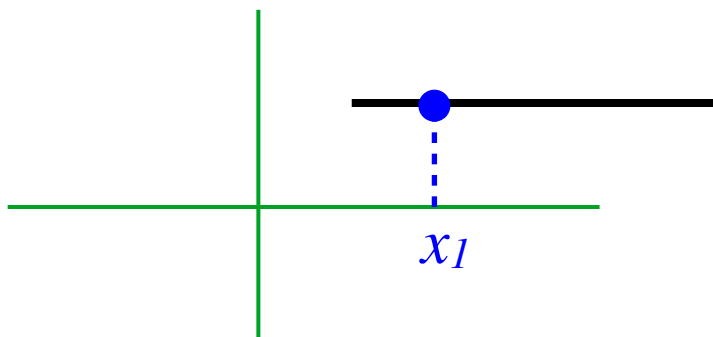
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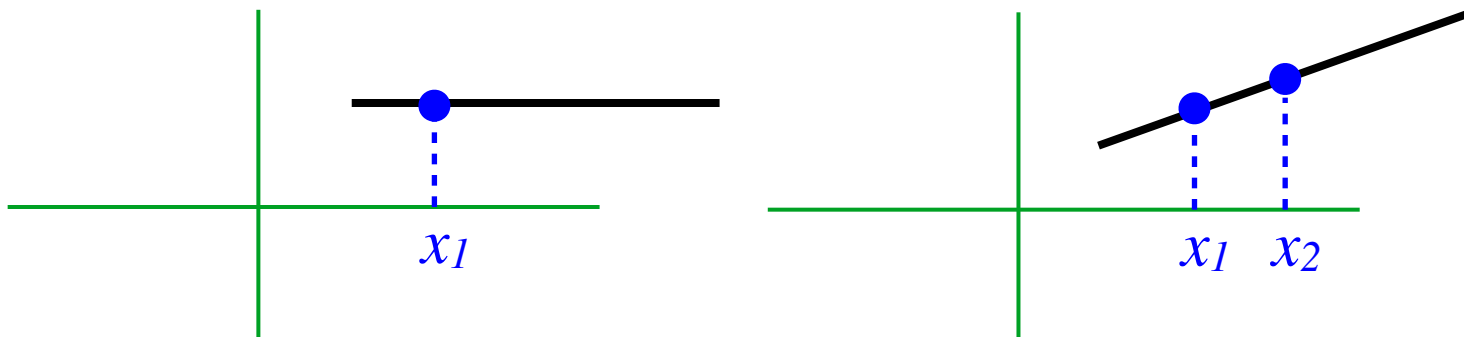
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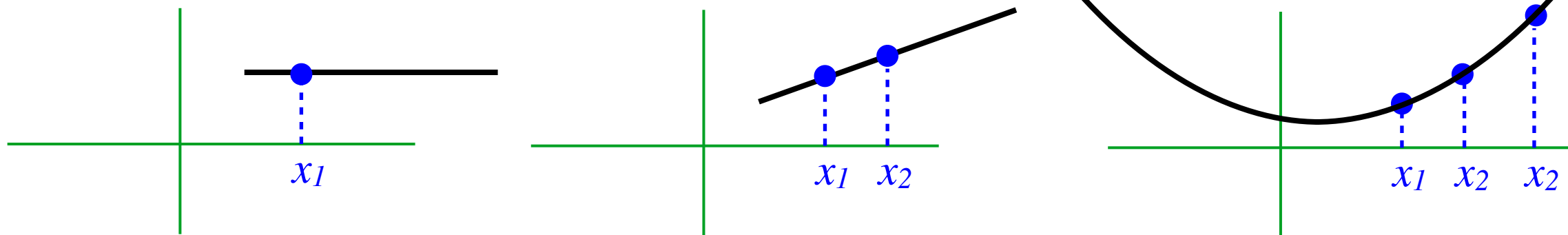
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However, only *select* values ε_k work for eigen-forms $\mathbf{M}\mathbf{P}_k = \varepsilon_k \mathbf{P}_k$ or orthonormality $\mathbf{P}_j \mathbf{P}_k = \delta_{jk} \mathbf{P}_k$.

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Diagonalizing Transformations (D-Ttran) from projectors

Given our eigenvectors and their Projectors.

$$\mathbf{P}_1 = \frac{(\mathbf{M} - 5 \cdot \mathbf{1})}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} = k_1 \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \end{pmatrix}}{k_1} = |\epsilon_1\rangle\langle\epsilon_1|$$
$$\mathbf{P}_2 = \frac{(\mathbf{M} - 1 \cdot \mathbf{1})}{(5 - 1)} = \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = k_2 \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{3}{2} & \frac{1}{2} \end{pmatrix}}{k_2} = |\epsilon_2\rangle\langle\epsilon_2|$$

Diagonalizing Transformations (D-Ttran) from projectors

Given our eigenvectors and their Projectors. $\mathbf{P}_1 = \frac{(\mathbf{M} - 5 \cdot \mathbf{1})}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} = k_1 \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \end{pmatrix}}{k_1} = |\varepsilon_1\rangle\langle\varepsilon_1|$

$$\mathbf{P}_2 = \frac{(\mathbf{M} - 1 \cdot \mathbf{1})}{(5 - 1)} = \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = k_2 \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{3}{2} & \frac{1}{2} \end{pmatrix}}{k_2} = |\varepsilon_2\rangle\langle\varepsilon_2|$$

Load distinct bras $\langle\varepsilon_1|$ and $\langle\varepsilon_2|$ into d-tran **rows**, kets $|\varepsilon_1\rangle$ and $|\varepsilon_2\rangle$ into inverse d-tran **columns**.

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$(\epsilon_1, \epsilon_2) \leftarrow (1, 2)$ *d-Tran matrix* $(1, 2) \leftarrow (\epsilon_1, \epsilon_2)$ **INVERSE** *d-Tran matrix*

$$\begin{pmatrix} \langle\epsilon_1|x\rangle & \langle\epsilon_1|y\rangle \\ \langle\epsilon_2|x\rangle & \langle\epsilon_2|y\rangle \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{3}{2} & \frac{1}{2} \end{pmatrix}, \quad \begin{pmatrix} \langle x|\epsilon_1\rangle & \langle x|\epsilon_2\rangle \\ \langle y|\epsilon_1\rangle & \langle y|\epsilon_2\rangle \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{3}{2} & \frac{1}{2} \end{pmatrix}$$

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$(1, 2) \leftarrow (\epsilon_1, \epsilon_2)$ **INVERSE** *d-Tran matrix*

$$\begin{pmatrix} \langle\epsilon_1|x\rangle & \langle\epsilon_1|y\rangle \\ \langle\epsilon_2|x\rangle & \langle\epsilon_2|y\rangle \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{3}{2} & \frac{1}{2} \end{pmatrix}, \quad \begin{pmatrix} \langle x|\epsilon_1\rangle & \langle x|\epsilon_2\rangle \\ \langle y|\epsilon_1\rangle & \langle y|\epsilon_2\rangle \end{pmatrix} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{3}{2} & \frac{1}{2} \end{pmatrix}$$

Use *Dirac labeling for all components* so transformation is OK

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$$\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{3}{2} & \frac{1}{2} \end{pmatrix} \cdot \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \cdot \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{3}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 5 \end{pmatrix}$$

Diagonalizing Transformations (D-Tran) from projectors

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Check inverse-d-tran is really inverse of *your* d-tran.

$$\begin{pmatrix} \langle\epsilon_1|1\rangle & \langle\epsilon_1|2\rangle \\ \langle\epsilon_2|1\rangle & \langle\epsilon_2|2\rangle \end{pmatrix} \cdot \begin{pmatrix} \langle 1|\epsilon_1\rangle & \langle 1|\epsilon_2\rangle \\ \langle 2|\epsilon_1\rangle & \langle 2|\epsilon_2\rangle \end{pmatrix} = \begin{pmatrix} \langle\epsilon_1|1|\epsilon_1\rangle & \langle\epsilon_1|1|\epsilon_2\rangle \\ \langle\epsilon_2|1|\epsilon_1\rangle & \langle\epsilon_2|1|\epsilon_2\rangle \end{pmatrix}$$

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Check inverse-d-tran is really inverse of *your* d-tran. In standard quantum matrices inverses are “easy”

$$\begin{pmatrix} \langle\epsilon_1|x\rangle & \langle\epsilon_1|y\rangle \\ \langle\epsilon_2|x\rangle & \langle\epsilon_2|y\rangle \end{pmatrix} \cdot \begin{pmatrix} \langle x|\epsilon_1\rangle & \langle x|\epsilon_2\rangle \\ \langle y|\epsilon_1\rangle & \langle y|\epsilon_2\rangle \end{pmatrix} = \begin{pmatrix} \langle\epsilon_1|\mathbf{1}|\epsilon_1\rangle & \langle\epsilon_1|\mathbf{1}|\epsilon_2\rangle \\ \langle\epsilon_2|\mathbf{1}|\epsilon_1\rangle & \langle\epsilon_2|\mathbf{1}|\epsilon_2\rangle \end{pmatrix} \begin{pmatrix} \langle\epsilon_1|x\rangle & \langle\epsilon_1|y\rangle \\ \langle\epsilon_2|x\rangle & \langle\epsilon_2|y\rangle \end{pmatrix} = \begin{pmatrix} \langle x|\epsilon_1\rangle & \langle x|\epsilon_2\rangle \\ \langle y|\epsilon_1\rangle & \langle y|\epsilon_2\rangle \end{pmatrix}^\dagger = \begin{pmatrix} \langle x|\epsilon_1\rangle^* & \langle y|\epsilon_1\rangle^* \\ \langle x|\epsilon_2\rangle^* & \langle y|\epsilon_2\rangle^* \end{pmatrix} = \begin{pmatrix} \langle x|\epsilon_1\rangle & \langle x|\epsilon_2\rangle \\ \langle y|\epsilon_1\rangle & \langle y|\epsilon_2\rangle \end{pmatrix}^{-1}$$

$$\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{3}{2} & \frac{1}{2} \end{pmatrix} \cdot \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{3}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

2D harmonic oscillator equations

Lagrangian and matrix forms and Reciprocity symmetry

2D harmonic oscillator equation eigensolutions

Geometric method

Matrix-algebraic eigensolutions with example $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

Secular equation

Hamilton-Cayley equation and projectors

Idempotent projectors (how eigenvalues \Rightarrow eigenvectors)

Operator orthonormality and Completeness (Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

Spectral Decompositions

Functional spectral decomposition

Orthonormality vs. Completeness vis-a`-vis Operator vs. State

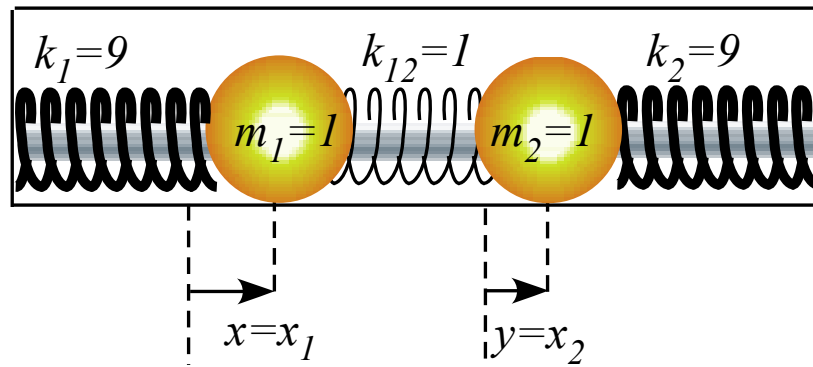
Lagrange functional interpolation formula

Diagonalizing Transformations (D-Ttran) from projectors

→ *2D-HO eigensolution example with bilateral (B-Type) symmetry* **←**
Mixed mode beat dynamics and fixed $\pi/2$ phase

2D-HO eigensolution example with asymmetric (A-Type) symmetry
Initial state projection, mixed mode beat dynamics with variable phase

Analyzing 2D-HO beats and mixed mode eigen-solutions



$$\mathbf{K} = \begin{pmatrix} K_{11} & K_{12} \\ K_{12} & K_{22} \end{pmatrix} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} = \begin{pmatrix} 10 & -1 \\ -1 & 10 \end{pmatrix}$$

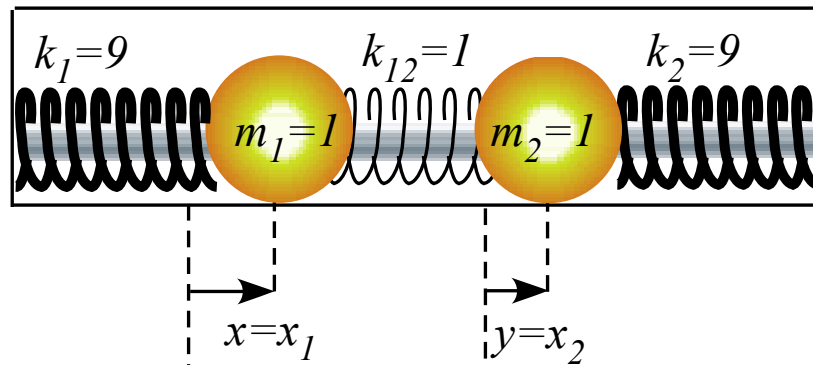
$Det(\mathbf{K}) = 10 \cdot 10 - 1 = 99$
 $Trace(\mathbf{K}) = 10 + 10 = 20$

The \mathbf{K} secular equation $K^2 - Trace(\mathbf{K})K + Det(\mathbf{K}) = K^2 - 20K + 99 = 0 = (K - 9)(K - 11) = (K - K_1)(K - K_2)$

Eigenvalues K_k and squared eigenfrequencies $\omega_0(\epsilon_k)^2$

$$K_1 = \omega_0^2(\epsilon_1) = 9, \quad K_2 = \omega_0^2(\epsilon_2) = 11,$$

Analyzing 2D-HO beats and mixed mode eigen-solutions



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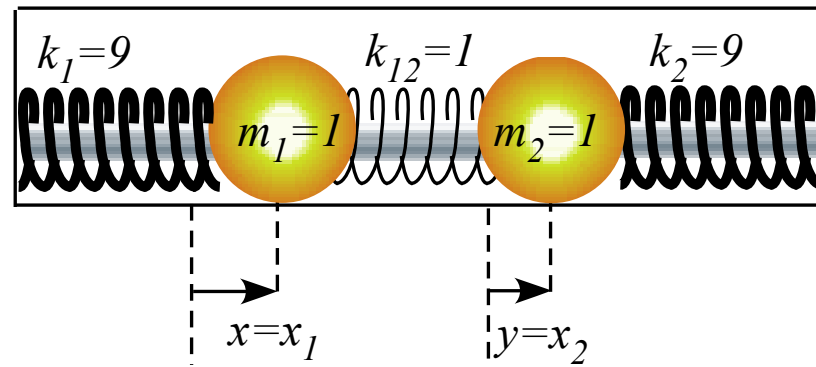
$$K_1 = \omega_0^2(\epsilon_1) = 9, \quad K_2 = \omega_0^2(\epsilon_2) = 11,$$

Eigen-projectors \mathbf{P}_k

$$\mathbf{P}_1 = \frac{\begin{pmatrix} K_{11} - K_2 & K_{12} \\ K_{12} & K_{22} - K_2 \end{pmatrix}}{K_1 - K_2} = \frac{\begin{pmatrix} 10 - 11 & -1 \\ -1 & 10 - 11 \end{pmatrix}}{9 - 11} = \frac{\begin{pmatrix} 1 & +1 \\ +1 & 1 \end{pmatrix}}{2}$$

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Analyzing 2D-HO beats and mixed mode eigen-solutions



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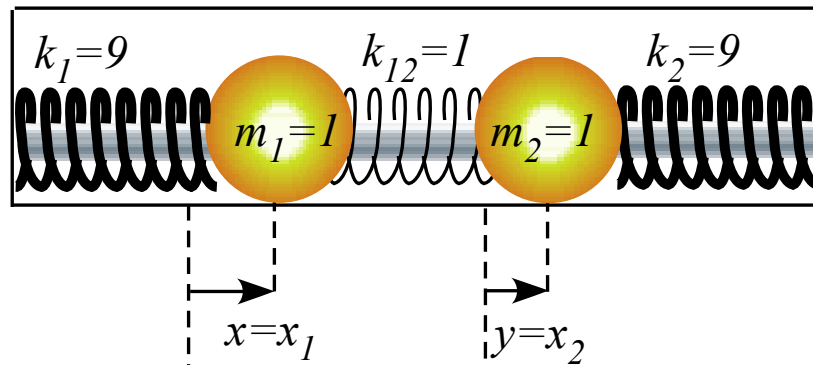
$$= \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix} = |\epsilon_1\rangle\langle\epsilon_1|$$

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$$= \begin{pmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & -1/\sqrt{2} \end{pmatrix} = |\epsilon_2\rangle\langle\epsilon_2|$$

Eigenbra vectors: $\langle\epsilon_1| = \begin{pmatrix} 1/\sqrt{2} & +1/\sqrt{2} \end{pmatrix}$, $\langle\epsilon_2| = \begin{pmatrix} 1/\sqrt{2} & -1/\sqrt{2} \end{pmatrix}$

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$$\mathbf{P}_1 = \frac{\begin{pmatrix} K_{11} - K_2 & K_{12} \\ K_{12} & K_{22} - K_2 \end{pmatrix}}{K_1 - K_2} = \frac{\begin{pmatrix} 10 - 11 & -1 \\ -1 & 10 - 11 \end{pmatrix}}{9 - 11} = \frac{\begin{pmatrix} 1 & +1 \\ +1 & 1 \end{pmatrix}}{2}$$

$$= \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix} = |\epsilon_1\rangle\langle\epsilon_1|$$

$$\mathbf{P}_2 = \frac{\begin{pmatrix} K_{11} - K_1 & K_{12} \\ K_{12} & K_{22} - K_1 \end{pmatrix}}{K_2 - K_1} = \frac{\begin{pmatrix} 10 - 9 & -1 \\ -1 & 10 - 9 \end{pmatrix}}{11 - 9} = \frac{\begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}}{2}$$

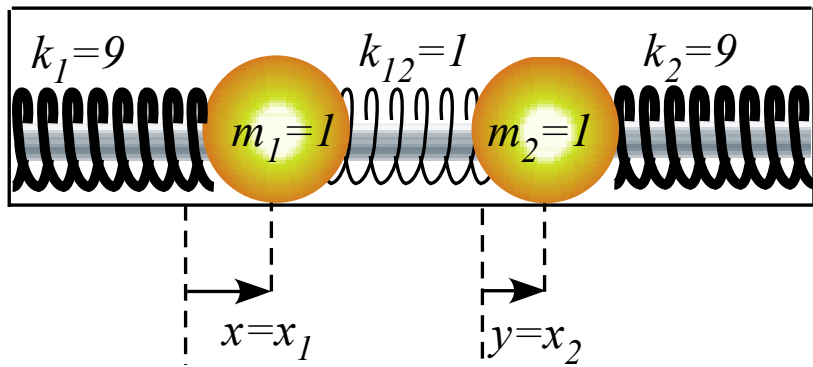
$$= \begin{pmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & -1/\sqrt{2} \end{pmatrix} = |\epsilon_2\rangle\langle\epsilon_2|$$

Eigenbra vectors: $\langle\epsilon_1| = \left(1/\sqrt{2} \quad +1/\sqrt{2} \right)$, $\langle\epsilon_2| = \left(1/\sqrt{2} \quad -1/\sqrt{2} \right)$

Mixed mode dynamics

$$|x(t)\rangle = |\epsilon_1\rangle \langle\epsilon_1|x(0)\rangle e^{-i\omega_1 t} + |\epsilon_2\rangle \langle\epsilon_2|x(0)\rangle e^{-i\omega_2 t}$$

$$\begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} \langle\epsilon_1|x(0)\rangle e^{-i\omega_1 t} + \begin{pmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} \langle\epsilon_2|x(0)\rangle e^{-i\omega_2 t}$$



Analyzing 2D-HO beats and mixed mode eigen-solutions

$$\mathbf{K} = \begin{pmatrix} K_{11} & K_{12} \\ K_{12} & K_{22} \end{pmatrix} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} = \begin{pmatrix} 10 & -1 \\ -1 & 10 \end{pmatrix}$$

$$\text{Det}(\mathbf{K}) = 10 \cdot 10 - 1 = 99$$

$$\text{Trace}(\mathbf{K}) = 10 + 10 = 20$$

The \mathbf{K} secular equation $K^2 - \text{Trace}(\mathbf{K})K + \text{Det}(\mathbf{K}) = K^2 - 20K + 99 = 0 = (K - 9)(K - 11) = (K - K_1)(K - K_2)$

Eigenvalues K_k and squared eigenfrequencies $\omega_0(\epsilon_k)^2$

$$K_1 = \omega_0^2(\epsilon_1) = 9, \quad K_2 = \omega_0^2(\epsilon_2) = 11,$$

Eigen-projectors \mathbf{P}_k

$$\mathbf{P}_1 = \frac{\begin{pmatrix} K_{11} - K_2 & K_{12} \\ K_{12} & K_{22} - K_2 \end{pmatrix}}{K_1 - K_2} = \frac{\begin{pmatrix} 10 - 11 & -1 \\ -1 & 10 - 11 \end{pmatrix}}{9 - 11} = \frac{\begin{pmatrix} 1 & +1 \\ +1 & 1 \end{pmatrix}}{2}$$

$$= \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix} = |\epsilon_1\rangle\langle\epsilon_1|$$

$$\mathbf{P}_2 = \frac{\begin{pmatrix} K_{11} - K_1 & K_{12} \\ K_{12} & K_{22} - K_1 \end{pmatrix}}{K_2 - K_1} = \frac{\begin{pmatrix} 10 - 9 & -1 \\ -1 & 10 - 9 \end{pmatrix}}{11 - 9} = \frac{\begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}}{2}$$

$$= \begin{pmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & -1/\sqrt{2} \end{pmatrix} = |\epsilon_2\rangle\langle\epsilon_2|$$

Eigenbra vectors: $\langle\epsilon_1| = \left(1/\sqrt{2} \quad +1/\sqrt{2} \right)$, $\langle\epsilon_2| = \left(1/\sqrt{2} \quad -1/\sqrt{2} \right)$

Mixed mode dynamics

$$|x(t)\rangle = |\epsilon_1\rangle \langle\epsilon_1|x(0)\rangle e^{-i\omega_1 t} + |\epsilon_2\rangle \langle\epsilon_2|x(0)\rangle e^{-i\omega_2 t}$$

$$\begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} \langle\epsilon_1|x(0)\rangle e^{-i\omega_1 t} + \begin{pmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} \langle\epsilon_2|x(0)\rangle e^{-i\omega_2 t}$$

100% modulation (SWR=0) $\frac{e^{ia} + e^{ib}}{2} = e^{\frac{i(a+b)}{2}} \frac{e^{\frac{i(a-b)}{2}} + e^{-\frac{i(a-b)}{2}}}{2}$

$$\begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = \begin{pmatrix} \frac{e^{-i\omega_1 t} + e^{-i\omega_2 t}}{2} \\ \frac{e^{-i\omega_1 t} - e^{-i\omega_2 t}}{2} \end{pmatrix} = \frac{e^{-\frac{i(\omega_1 + \omega_2)t}}{2}} \begin{pmatrix} e^{-\frac{i(\omega_1 - \omega_2)t}{2}} + e^{\frac{i(\omega_1 - \omega_2)t}{2}} \\ e^{-\frac{i(\omega_1 - \omega_2)t}{2}} - e^{\frac{i(\omega_1 - \omega_2)t}{2}} \end{pmatrix}$$

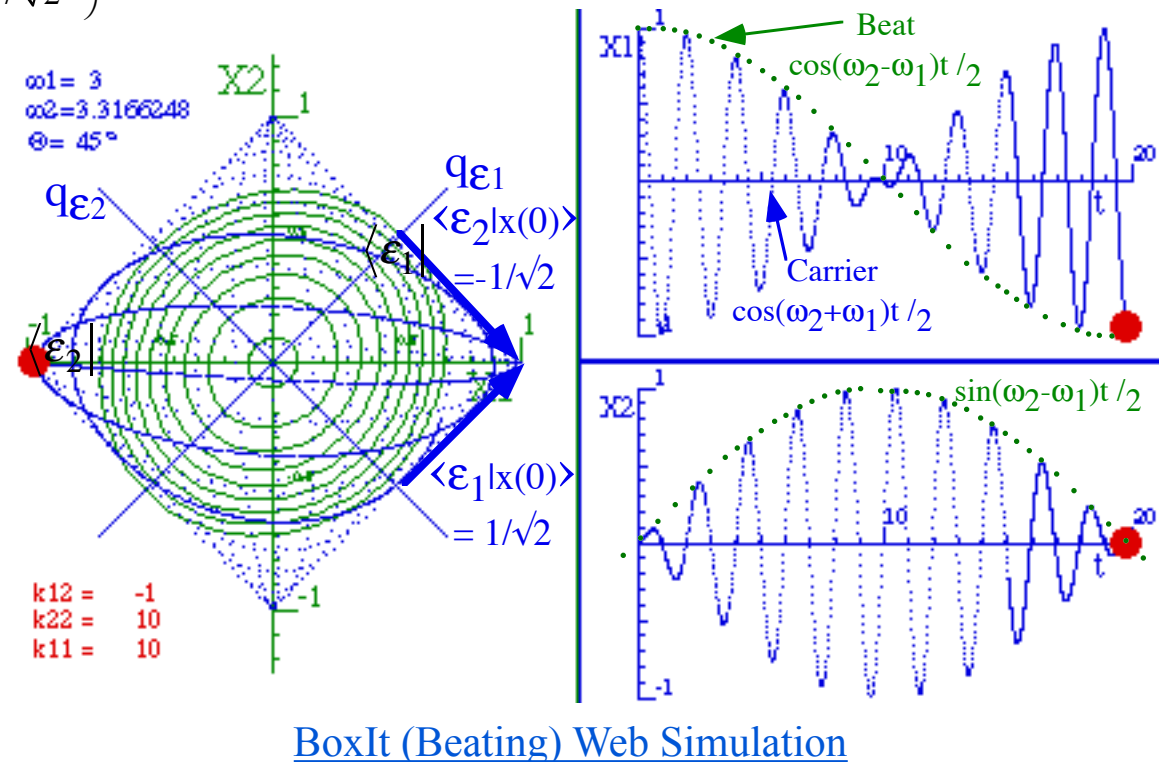
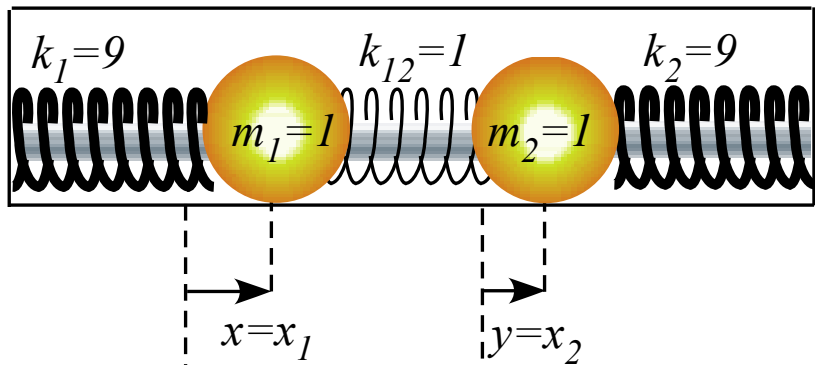


Fig. 3.3.9 Beats in weakly coupled symmetric oscillators with equal mode magnitudes.



Analyzing 2D-HO beats and mixed mode eigen-solutions

$$\mathbf{K} = \begin{pmatrix} K_{11} & K_{12} \\ K_{12} & K_{22} \end{pmatrix} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} = \begin{pmatrix} 10 & -1 \\ -1 & 10 \end{pmatrix}$$

$$\text{Det}(\mathbf{K}) = 10 \cdot 10 - 1 = 99$$

$$\text{Trace}(\mathbf{K}) = 10 + 10 = 20$$

The \mathbf{K} secular equation $K^2 - \text{Trace}(\mathbf{K})K + \text{Det}(\mathbf{K}) = K^2 - 20K + 99 = 0 = (K - 9)(K - 11) = (K - K_1)(K - K_2)$

Eigenvalues K_k and squared eigenfrequencies $\omega_0(\epsilon_k)^2$

$$K_1 = \omega_0^2(\epsilon_1) = 9, \quad K_2 = \omega_0^2(\epsilon_2) = 11,$$

Eigen-projectors \mathbf{P}_k

$$\mathbf{P}_1 = \frac{\begin{pmatrix} K_{11} - K_2 & K_{12} \\ K_{12} & K_{22} - K_2 \end{pmatrix}}{K_1 - K_2} = \frac{\begin{pmatrix} 10 - 11 & -1 \\ -1 & 10 - 11 \end{pmatrix}}{9 - 11} = \frac{\begin{pmatrix} 1 & +1 \\ +1 & 1 \end{pmatrix}}{2}$$

$$= \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix} = |\epsilon_1\rangle\langle\epsilon_1|$$

$$\mathbf{P}_2 = \frac{\begin{pmatrix} K_{11} - K_1 & K_{12} \\ K_{12} & K_{22} - K_1 \end{pmatrix}}{K_2 - K_1} = \frac{\begin{pmatrix} 10 - 9 & -1 \\ -1 & 10 - 9 \end{pmatrix}}{11 - 9} = \frac{\begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}}{2}$$

$$= \begin{pmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{pmatrix} \begin{pmatrix} 1/\sqrt{2} & -1/\sqrt{2} \end{pmatrix} = |\epsilon_2\rangle\langle\epsilon_2|$$

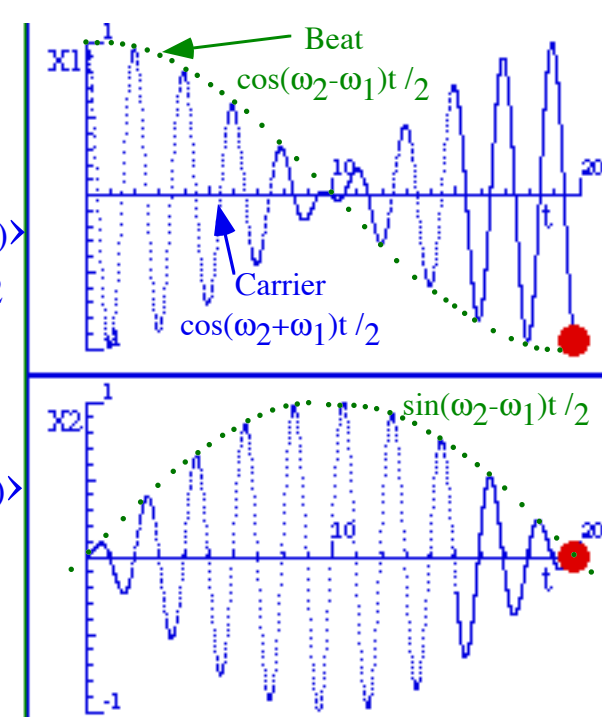
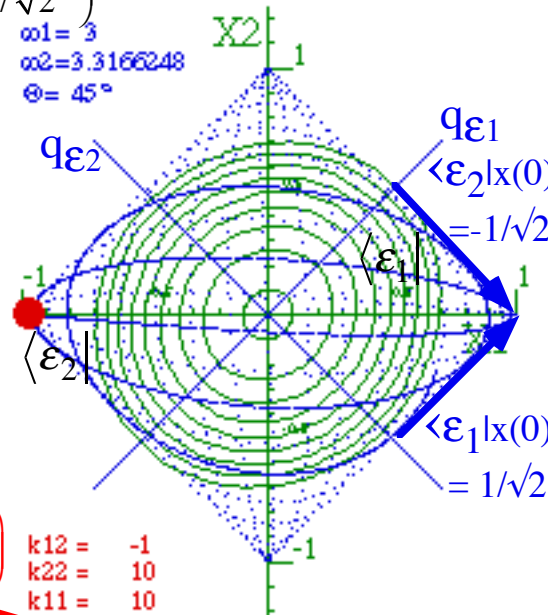
Eigenbra vectors: $\langle\epsilon_1| = \left(1/\sqrt{2} \quad +1/\sqrt{2} \right)$, $\langle\epsilon_2| = \left(1/\sqrt{2} \quad -1/\sqrt{2} \right)$

Mixed mode dynamics

$$|x(t)\rangle = |\epsilon_1\rangle \langle\epsilon_1|x(0)\rangle e^{-i\omega_1 t} + |\epsilon_2\rangle \langle\epsilon_2|x(0)\rangle e^{-i\omega_2 t}$$

$$\begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} \langle\epsilon_1|x(0)\rangle e^{-i\omega_1 t} + \begin{pmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} \langle\epsilon_2|x(0)\rangle e^{-i\omega_2 t}$$

100% modulation (SWR=0) $\frac{e^{ia} + e^{ib}}{2} = e^{i\frac{a+b}{2}} \frac{e^{i\frac{a-b}{2}} + e^{-i\frac{a-b}{2}}}{2} = e^{i\frac{a+b}{2}} \cos\left(\frac{a-b}{2}\right)$



BoxIt (Beating) Web Simulation

Note: Beat frequency is half-difference of eigenvalues

Note the i phase

Fig. 3.3.9 Beats in weakly coupled symmetric oscillators with equal mode magnitudes.

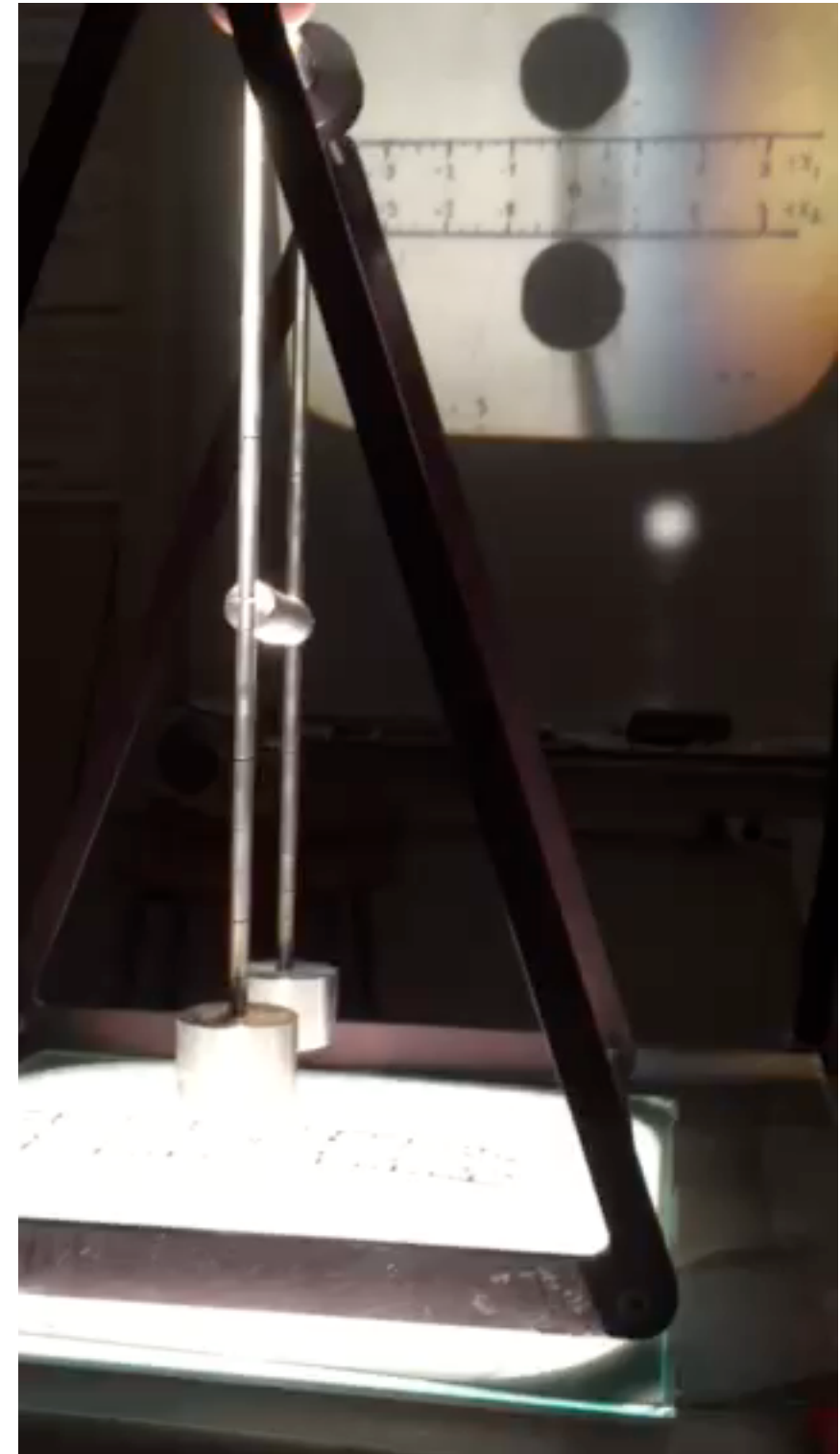
Videos of Coupled Pendula aided by Overhead Projector



[View on YouTube](#) 

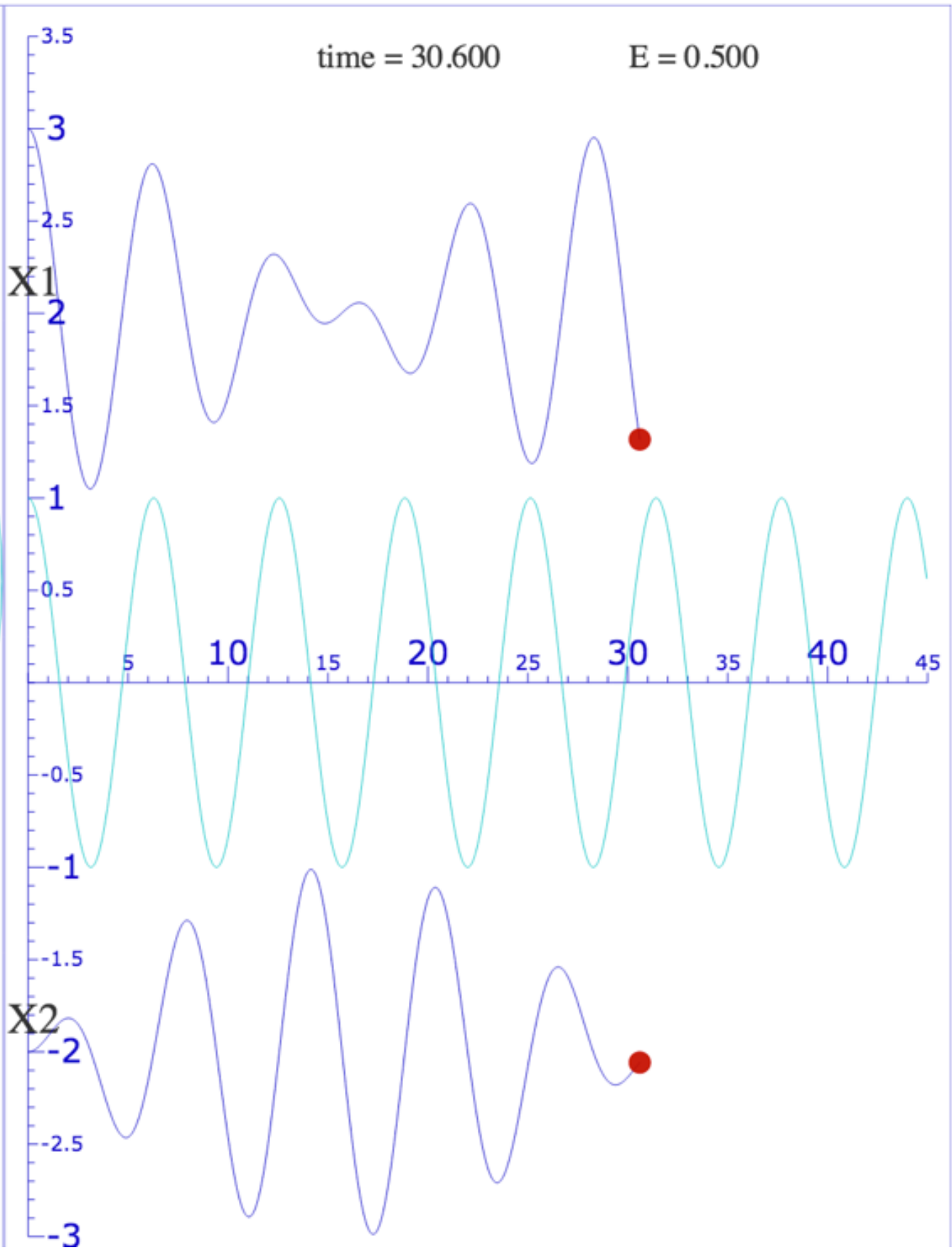
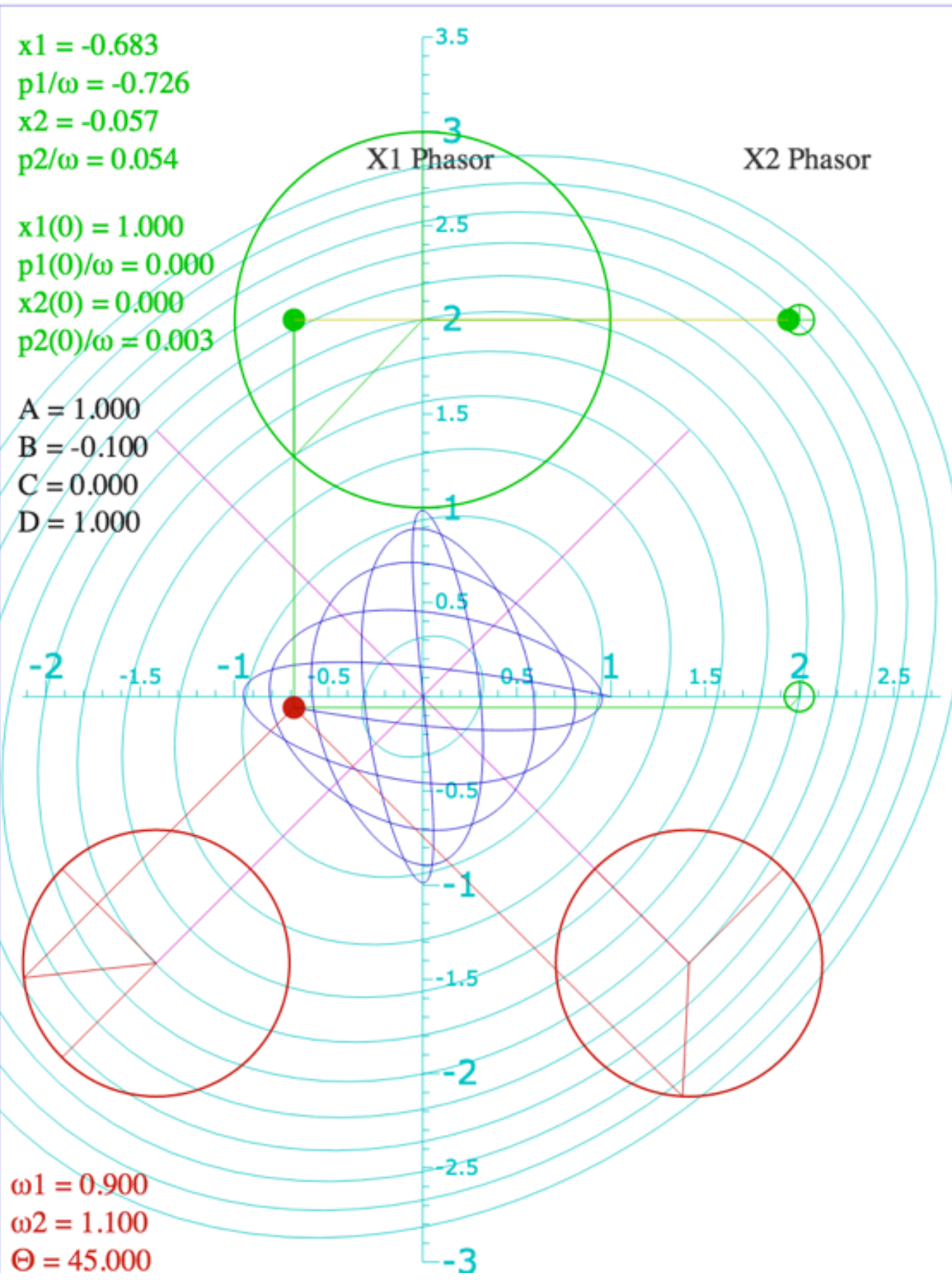
*Launch embedded videos
using your browser/App
or*

⇐ view on YouTube ⇒



[View on YouTube](#) 

Stronger coupling on the left, illustrated indirectly by a darker looking spring on screen



BoxIt (Beating) Web Simulation ($A=1, B=-0.1, C=0, D=1$)

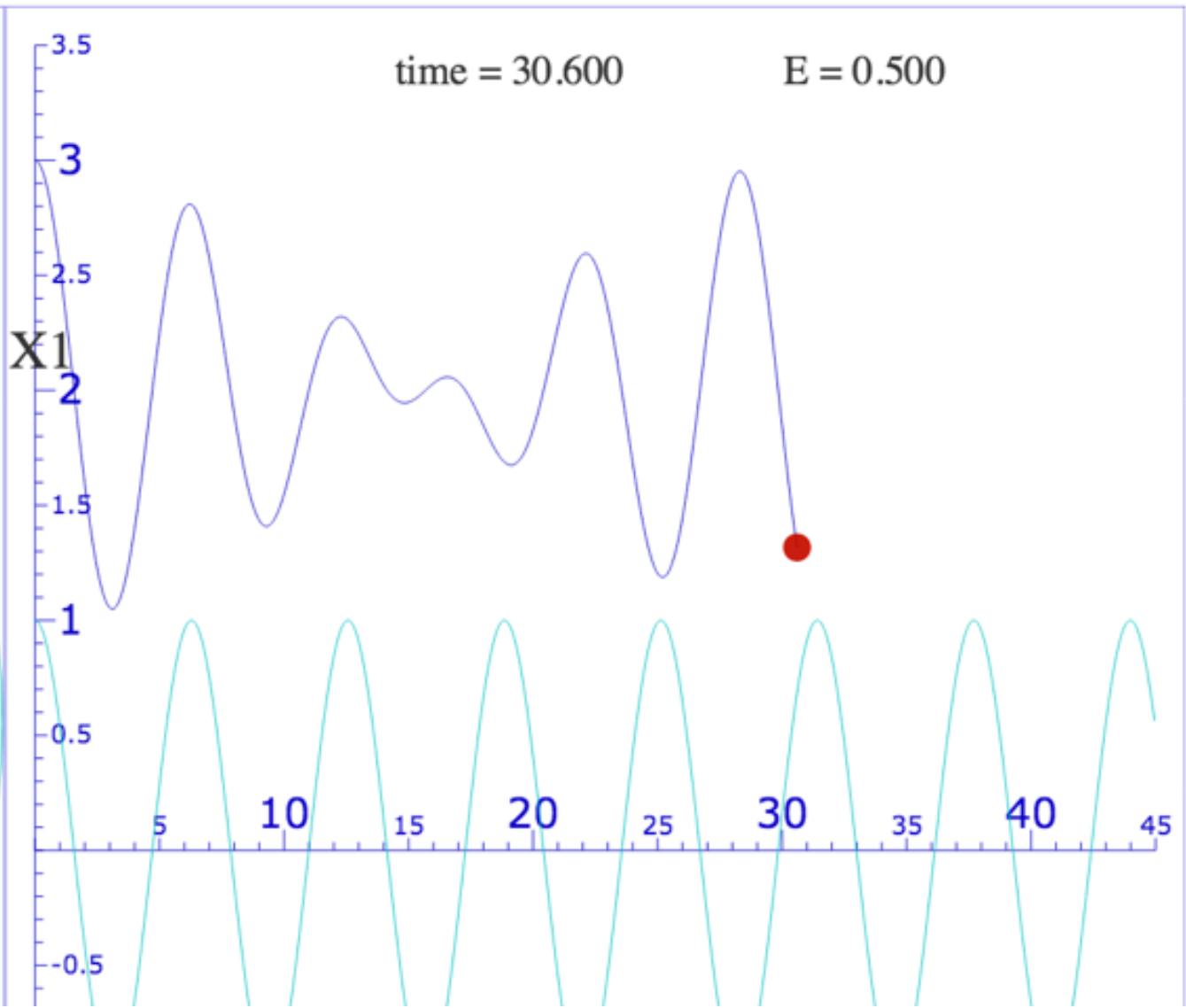
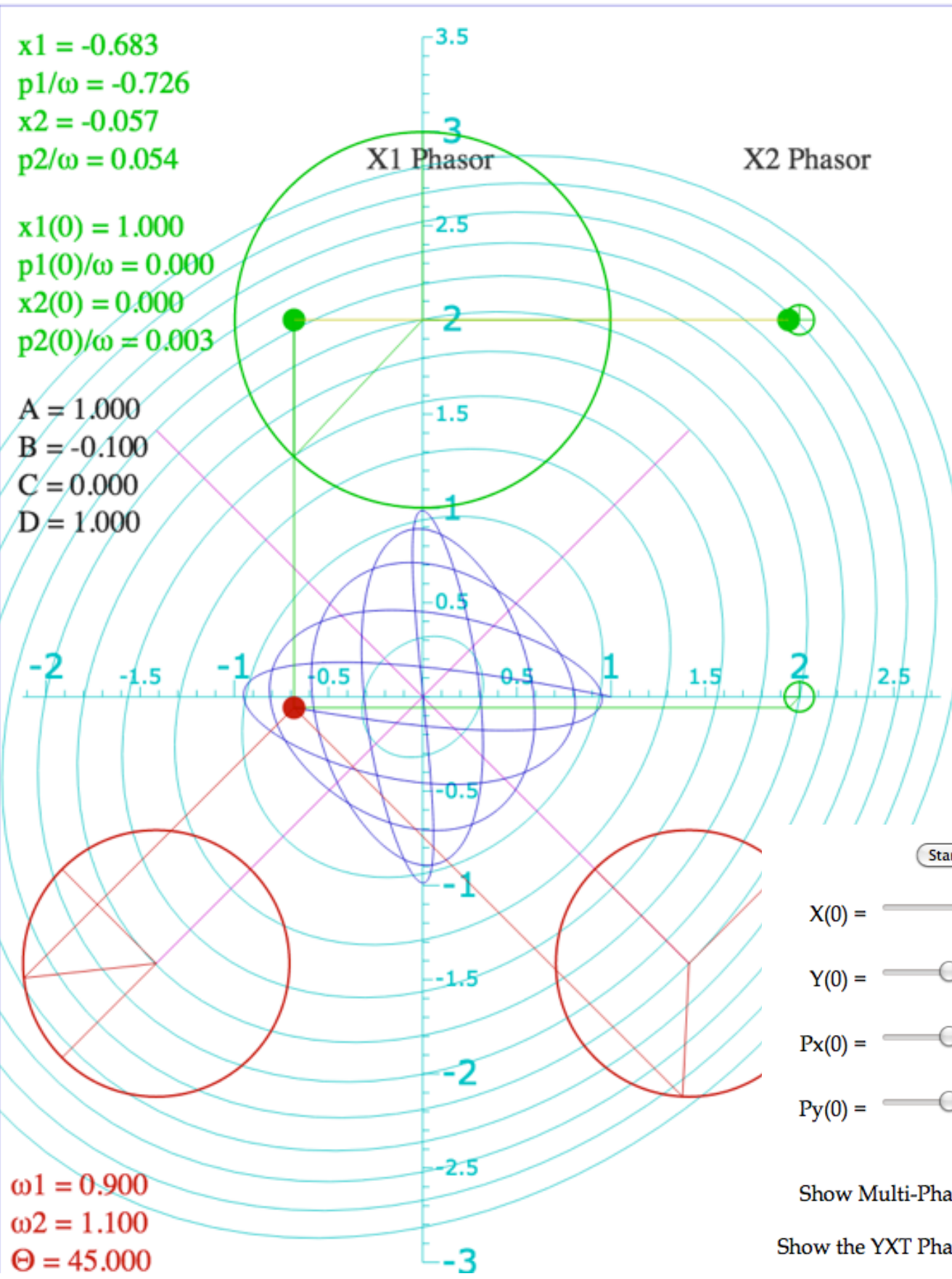
Controls Resume Reset T=0 Erase Paths

Speed x10[^]

$x1 = -0.683$
 $p1/\omega = -0.726$
 $x2 = -0.057$
 $p2/\omega = 0.054$
 $x1(0) = 1.000$
 $p1(0)/\omega = 0.000$
 $x2(0) = 0.000$
 $p2(0)/\omega = 0.003$

$A = 1.000$
 $B = -0.100$
 $C = 0.000$
 $D = 1.000$

$\omega1 = 0.900$
 $\omega2 = 1.100$
 $\Theta = 45.000$



Start Resume Reset T=0 Erase Paths

Speed x10[^]

$X(0) =$ $A =$ Number of Derivatives =
 $Y(0) =$ $B =$
 $Px(0) =$ $C =$
 $Py(0) =$ $D =$

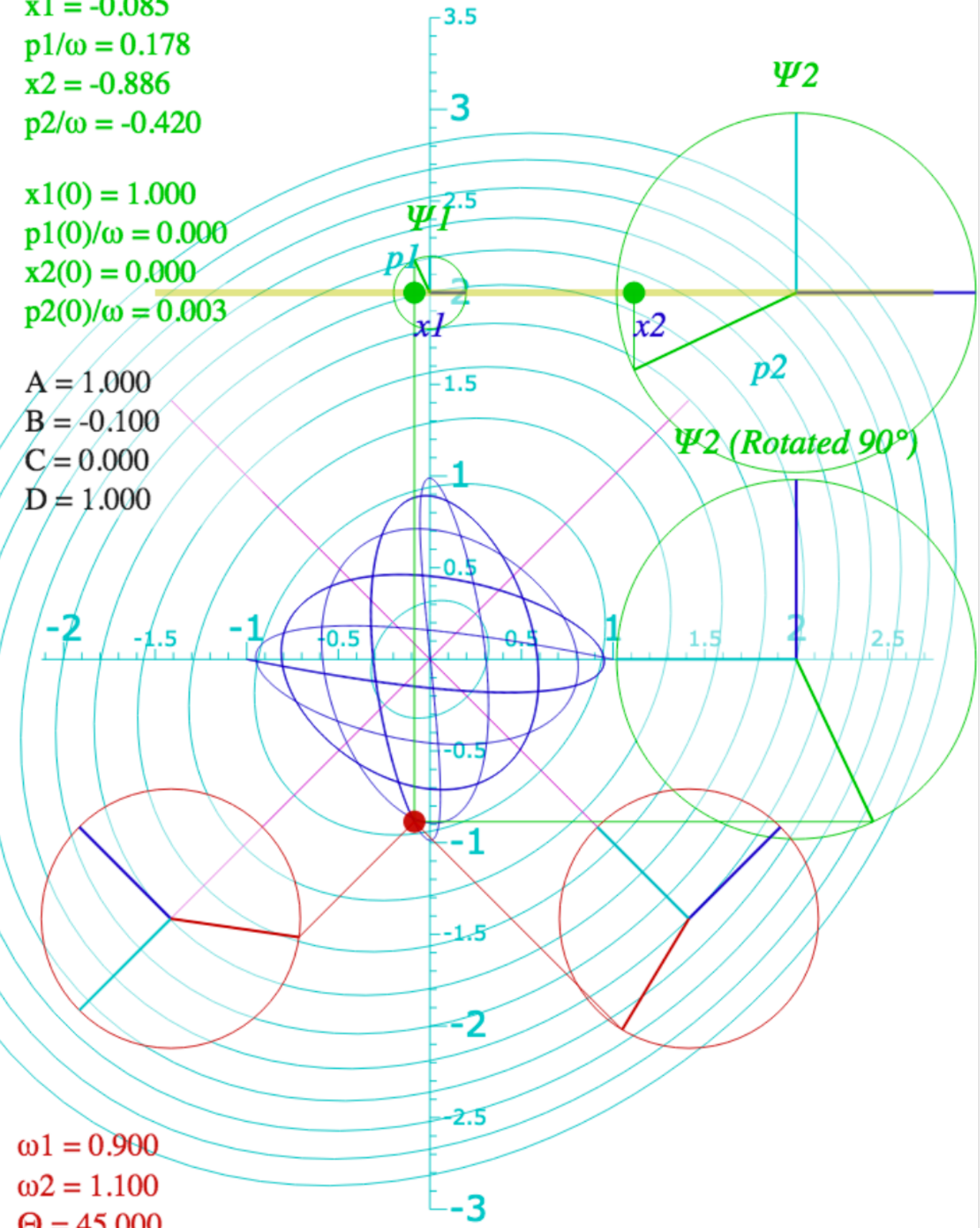
- Show Multi-Phasor View
- Show the YXT Phasor View
- Draw Main Phasors
- Draw Vector Heads
- wantVectorHeads, wantTimeRateTangents
- Draw PE Levels
- Left Phasor Rides on Right Phasor
- Draw Box Lines
- Left Phasor Rides on Right Phasor
- Draw Modal Phasors
- Draw Time Rate Tangents
- Normalize Phasors
- Print $\omega1:\omega2$ fractions

$x1 = -0.085$
 $p1/\omega = 0.178$
 $x2 = -0.886$
 $p2/\omega = -0.420$

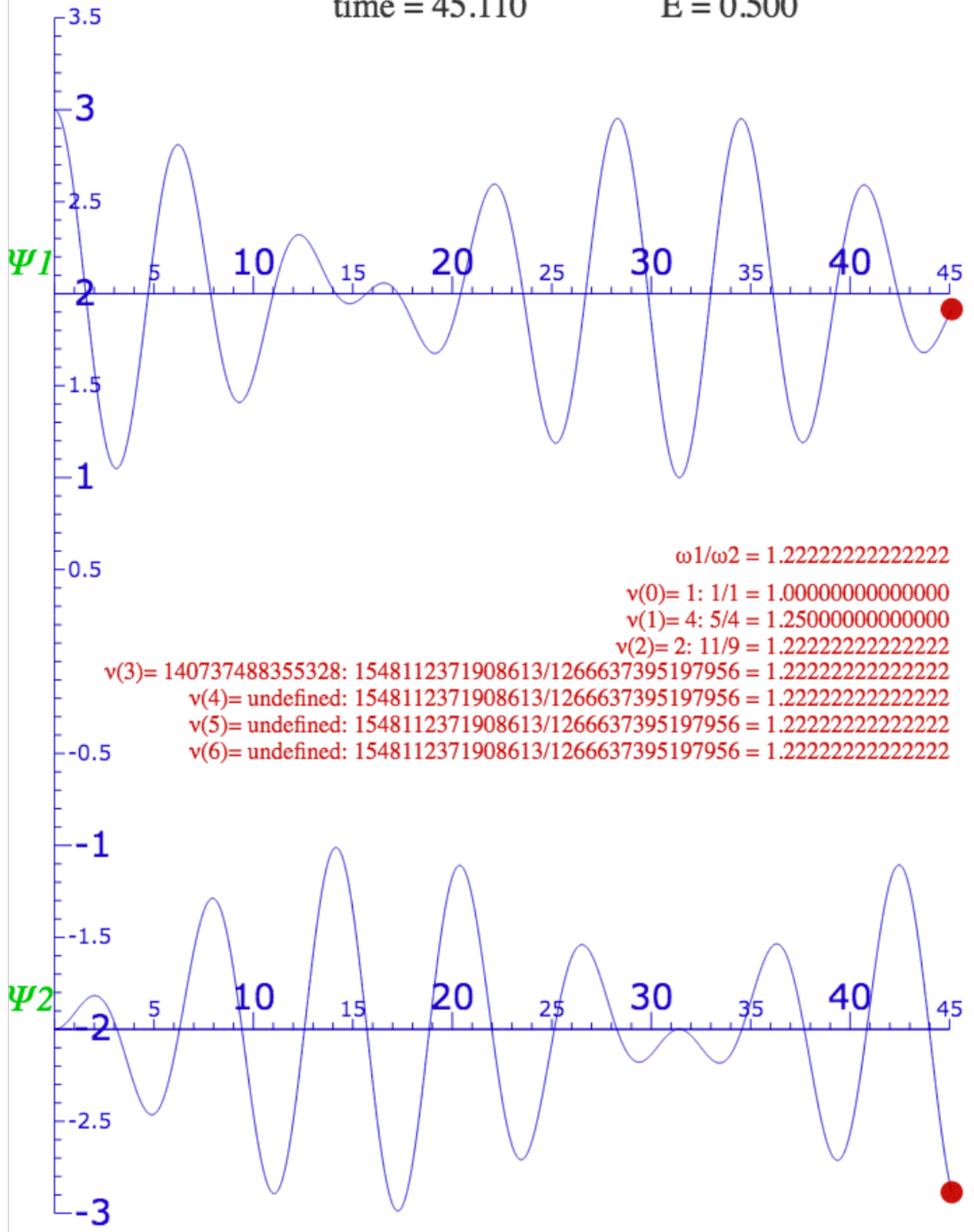
$x1(0) = 1.000$
 $p1(0)/\omega = 0.000$
 $x2(0) = 0.000$
 $p2(0)/\omega = 0.003$

$A = 1.000$
 $B = -0.100$
 $C = 0.000$
 $D = 1.000$

$\omega1 = 0.900$
 $\omega2 = 1.100$
 $\Theta = 45.000$



time = 45.110 E = 0.500



$\omega1/\omega2 = 1.22222222222222$
 $v(0) = 1: 1/1 = 1.00000000000000$
 $v(1) = 4: 5/4 = 1.25000000000000$
 $v(2) = 2: 11/9 = 1.22222222222222$
 $v(3) = 140737488355328: 1548112371908613/1266637395197956 = 1.22222222222222$
 $v(4) = \text{undefined}: 1548112371908613/1266637395197956 = 1.22222222222222$
 $v(5) = \text{undefined}: 1548112371908613/1266637395197956 = 1.22222222222222$
 $v(6) = \text{undefined}: 1548112371908613/1266637395197956 = 1.22222222222222$

BoxIt (Beating) Web Simulation ($A=1, B=-0.1, C=0, D=1$) with frequency ratios

Approximating decimal frequencies $\omega=\alpha$ using successive levels of *continued fractions*.

$$\alpha = n_0 + \frac{1}{n_1 + \frac{1}{n_2 + \frac{1}{n_3 + \frac{1}{n_4 + \ddots}}}}$$

Pi ($\pi=3.14159265\dots$) converges rather quickly by cf.

$$A_0 = \alpha = 3.14159265\dots$$

$$n_0 = INT(A_0) = 3$$

$$\pi \cong = 3.000\dots$$

$$A_1 = \frac{1}{A_0 - n_0} = 7.06\dots$$

$$n_1 = INT(A_1) = 7$$

$$\pi \cong 3 + \frac{1}{7} = \frac{22}{7} = 3.1428$$

$$A_2 = \frac{1}{A_1 - n_1} = 15.99\dots$$

$$n_2 = INT(A_2) = 15$$

$$\pi \cong 3 + \frac{1}{7 + \frac{1}{15}} = \frac{333}{106} = 3.141509$$

$$A_3 = \frac{1}{A_2 - n_2} = 1.003\dots$$

$$n_3 = INT(A_3) = 1$$

$$\pi \cong 3 + \frac{1}{7 + \frac{1}{15 + 1}} = \frac{355}{113} = 3.14159292$$

Not so much for the *Golden Mean* $G=(1+\sqrt{5})/2=1.618\dots$

$$A_0 = G = 1.618033989\dots$$

$$n_0 = INT(A_0) = 1$$

$$G \cong = 1.000\dots$$

$$A_1 = \frac{1}{A_0 - n_0} = 1.6180\dots$$

$$n_1 = INT(A_1) = 1$$

$$G \cong 1 + \frac{1}{1} = \frac{2}{1} = 2.000$$

$$A_2 = \frac{1}{A_1 - n_1} = 1.6180\dots$$

$$n_2 = INT(A_2) = 1$$

$$G \cong 1 + \frac{1}{1 + \frac{1}{1}} = \frac{3}{2} = 1.500$$

$$A_3 = \frac{1}{A_2 - n_2} = 1.6180\dots$$

$$n_3 = INT(A_3) = 1$$

$$G \cong 1 + \frac{1}{1 + \frac{1}{1 + 1}} = \frac{5}{3} = 1.666\dots$$

2D harmonic oscillator equations

Lagrangian and matrix forms and Reciprocity symmetry

2D harmonic oscillator equation eigensolutions

Geometric method

Matrix-algebraic eigensolutions with example $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

Secular equation

Hamilton-Cayley equation and projectors

Idempotent projectors (how eigenvalues \Rightarrow eigenvectors)

Operator orthonormality and Completeness (Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

Spectral Decompositions

Functional spectral decomposition

Orthonormality vs. Completeness vis-a`-vis Operator vs. State

Lagrange functional interpolation formula

Diagonalizing Transformations (D-Ttran) from projectors

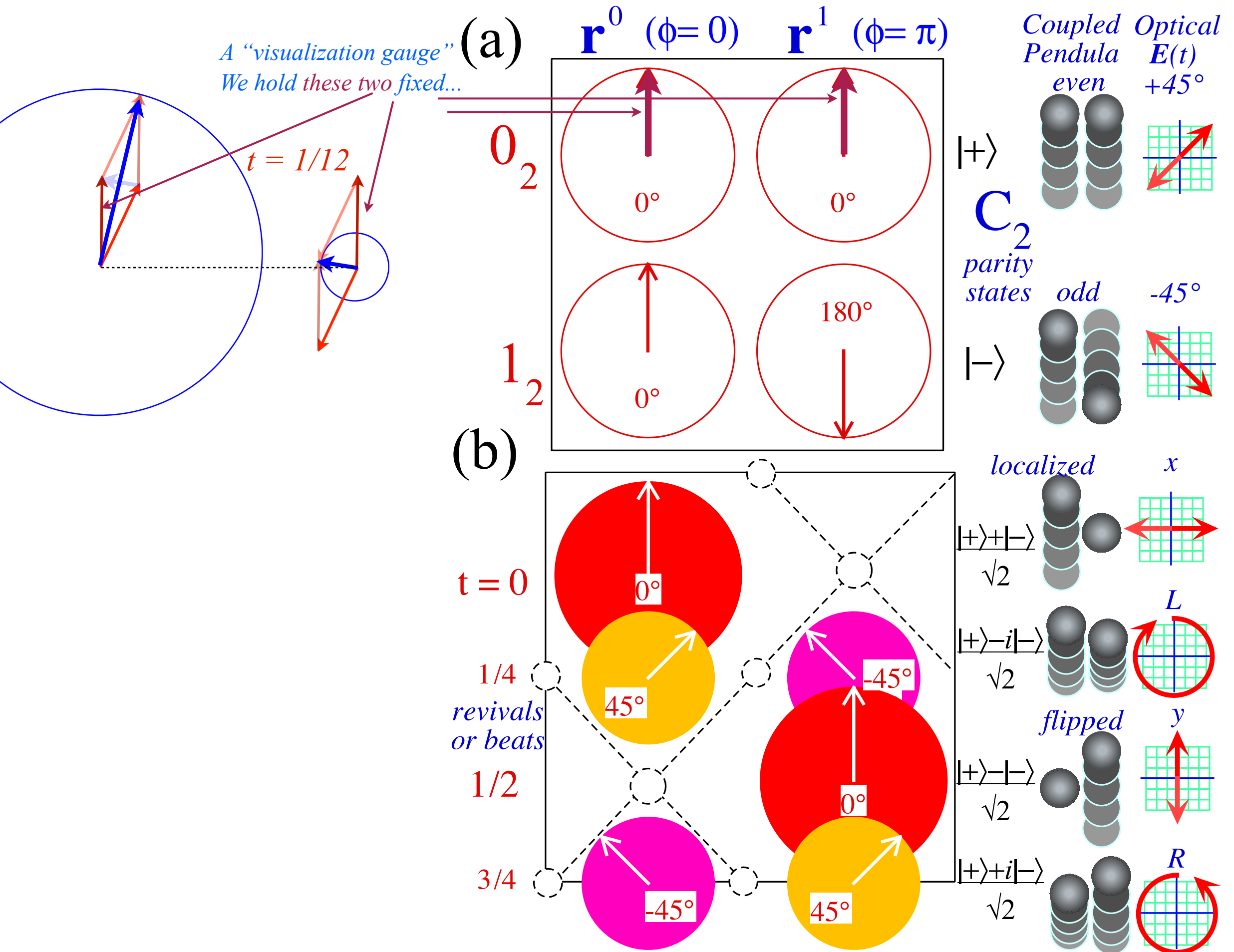
2D-HO eigensolution example with bilateral (B-Type) symmetry

➔ Mixed mode beat dynamics and fixed $\pi/2$ phase ←

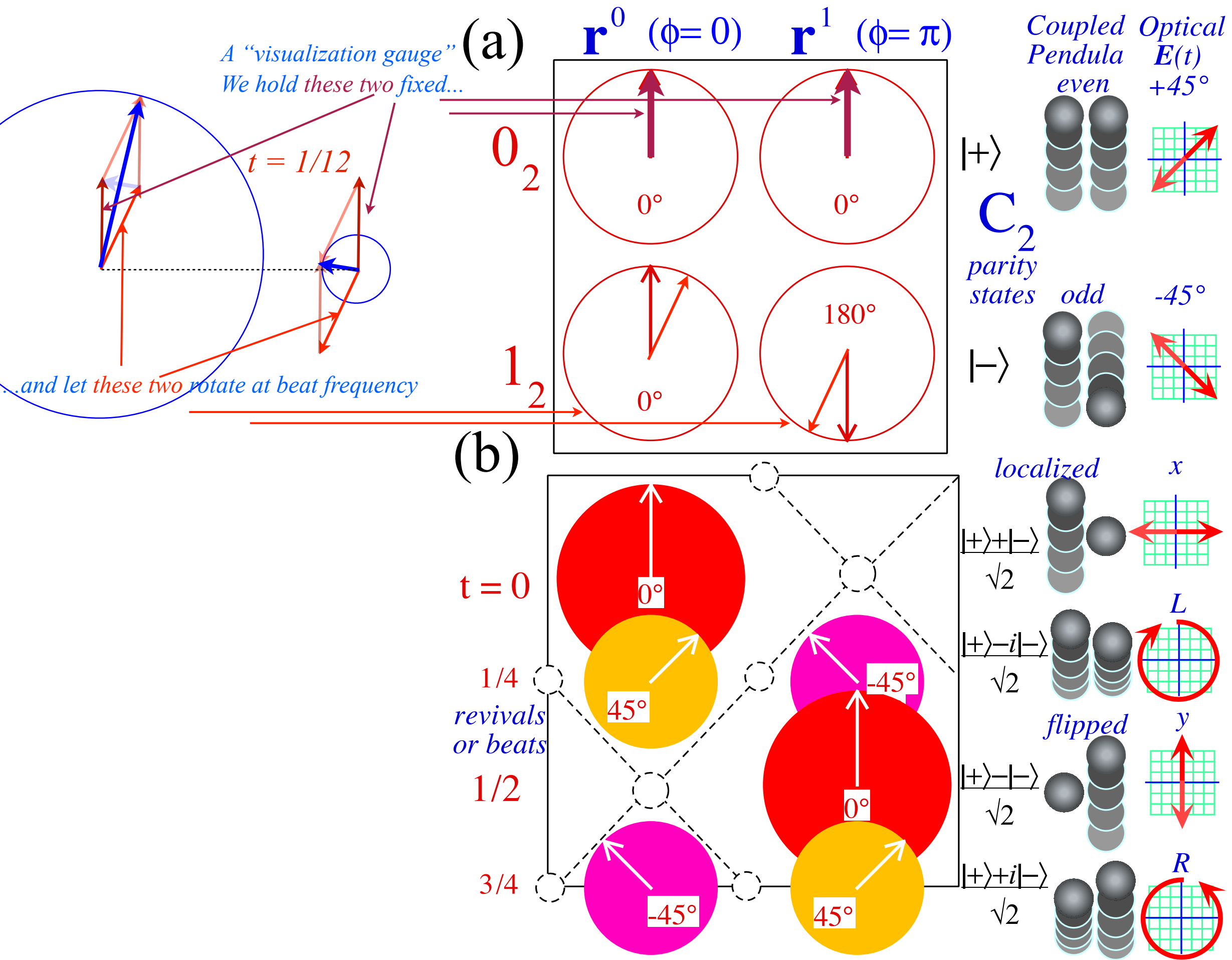
2D-HO eigensolution example with asymmetric (A-Type) symmetry

Initial state projection, mixed mode beat dynamics with variable phase

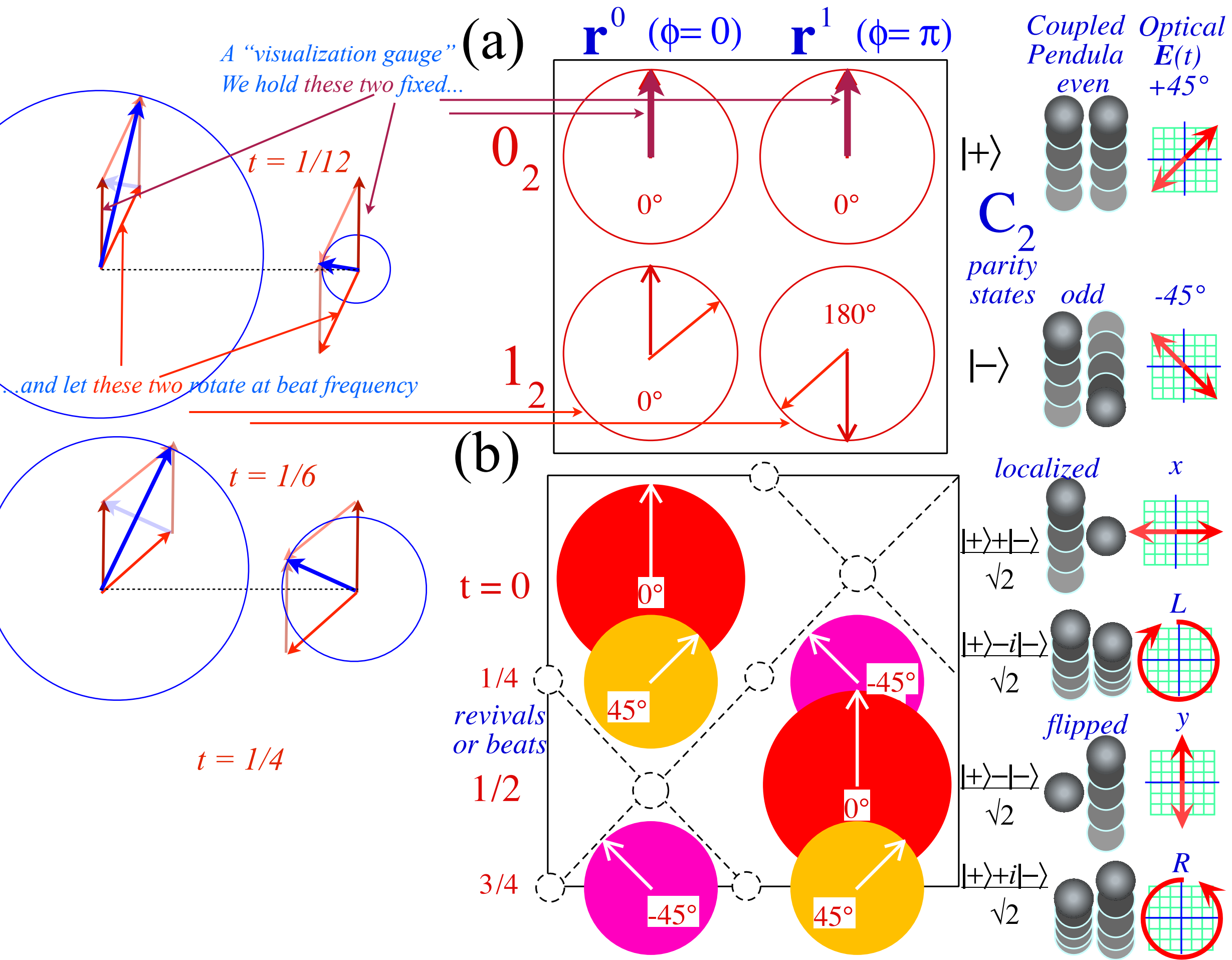
2D-HO beats and mixed mode geometry



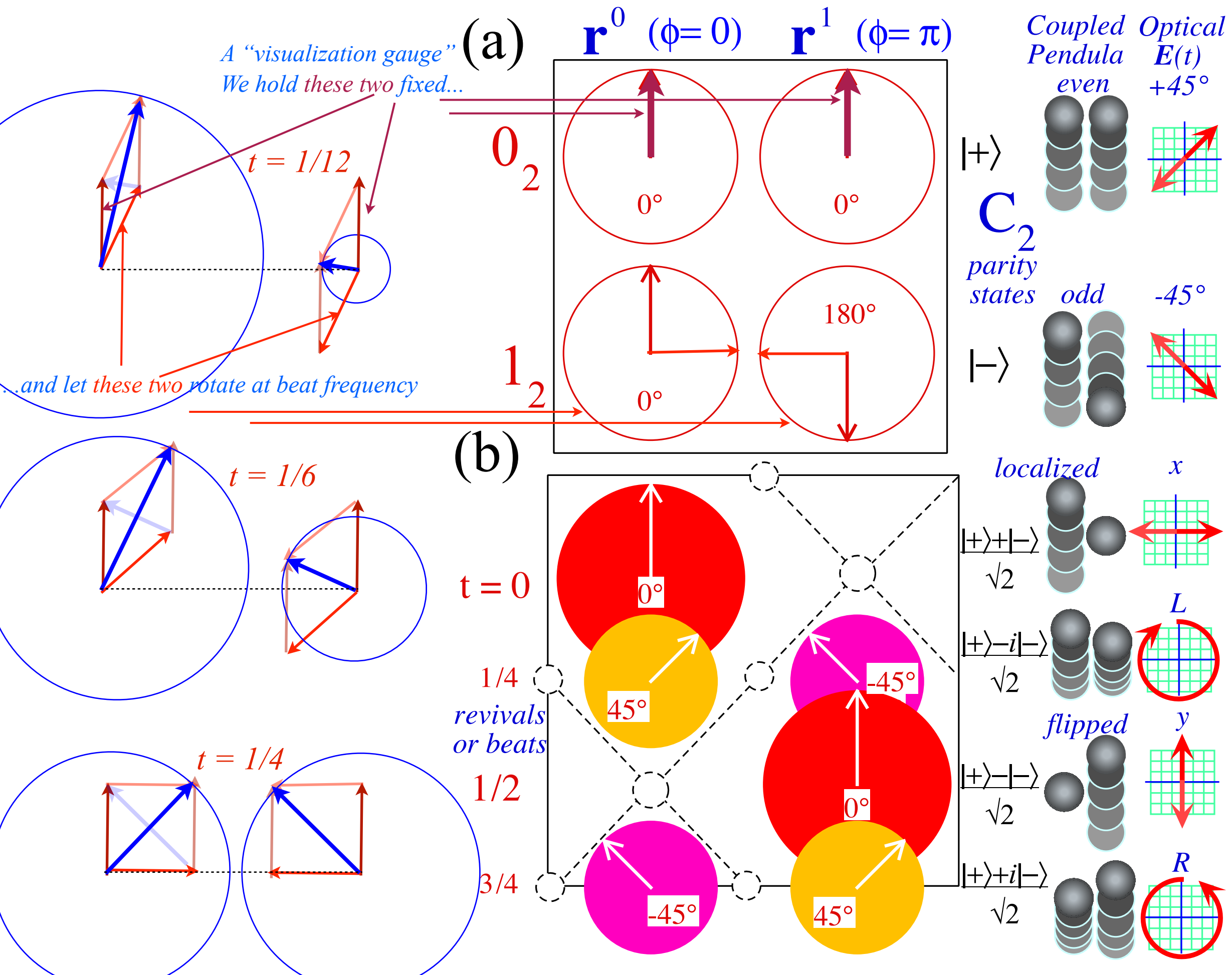
2D-HO beats and mixed mode geometry



2D-HO beats and mixed mode geometry



2D-HO beats and mixed mode geometry



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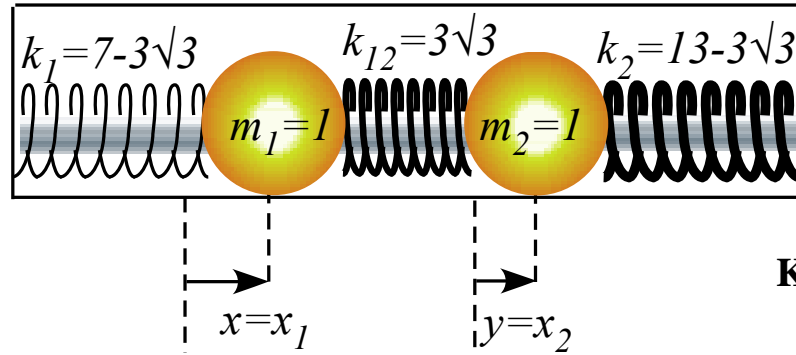
Diagonalizing Transformations (D-Ttran) from projectors

2D-HO eigensolution example with bilateral (B-Type) symmetry

Mixed mode beat dynamics and fixed $\pi/2$ phase

➔ *2D-HO eigensolution example with asymmetric (A-Type) symmetry* **←**
Initial state projection, mixed mode beat dynamics with variable phase

Spectral decomposition of 2D-HO mode dynamics for lower symmetry

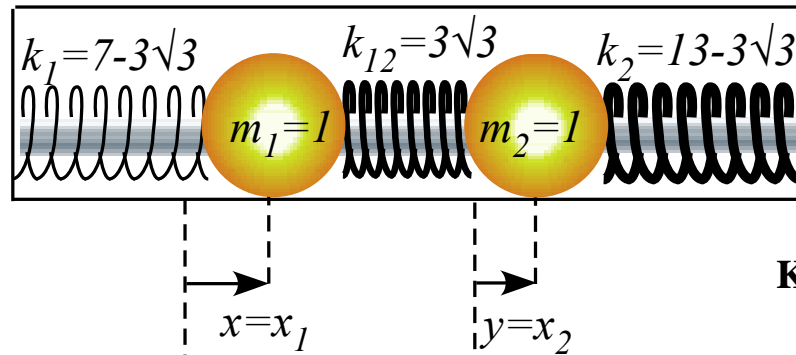


$$\mathbf{K} = \begin{pmatrix} K_{11} & K_{12} \\ K_{12} & K_{22} \end{pmatrix} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} = \begin{pmatrix} 7 & -3\sqrt{3} \\ -3\sqrt{3} & 13 \end{pmatrix}$$

$$\text{Det}(\mathbf{K}) = 7 \cdot 13 - 27 = 91 - 27 = 64$$

$$\text{Trace}(\mathbf{K}) = 7 + 13 = 20$$

Spectral decomposition of 2D-HO mode dynamics for lower symmetry



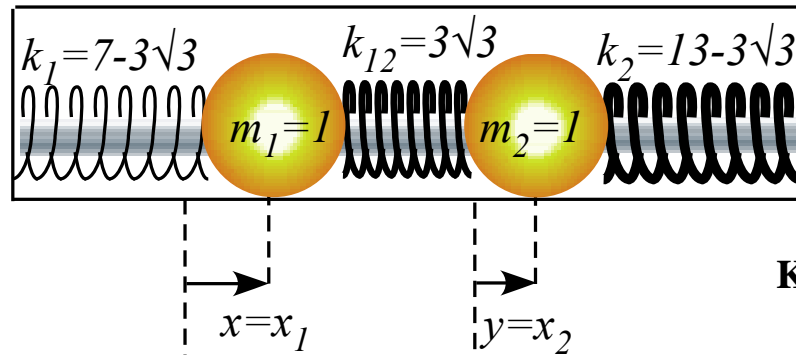
$$\mathbf{K} = \begin{pmatrix} K_{11} & K_{12} \\ K_{12} & K_{22} \end{pmatrix} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} = \begin{pmatrix} 7 & -3\sqrt{3} \\ -3\sqrt{3} & 13 \end{pmatrix}$$

The \mathbf{K} secular equation $K^2 - \text{Trace}(\mathbf{K})K + \text{Det}(\mathbf{K}) = K^2 - 20K + 64 = 0$

$$\text{Det}(\mathbf{K}) = 7 \cdot 13 - 27 = 91 - 27 = 64$$

$$\text{Trace}(\mathbf{K}) = 7 + 13 = 20$$

Spectral decomposition of 2D-HO mode dynamics for lower symmetry

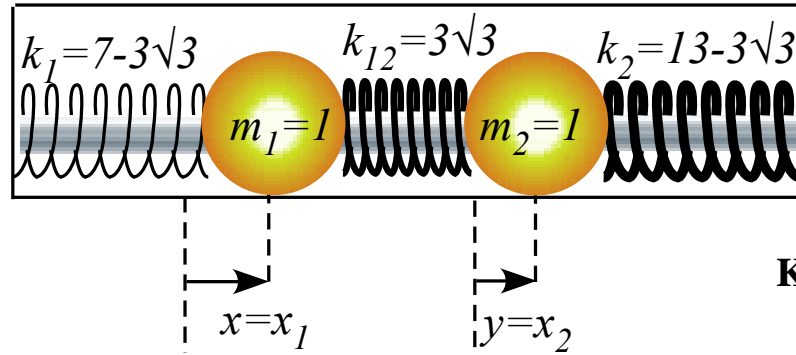


$$\mathbf{K} = \begin{pmatrix} K_{11} & K_{12} \\ K_{12} & K_{22} \end{pmatrix} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} = \begin{pmatrix} 7 & -3\sqrt{3} \\ -3\sqrt{3} & 13 \end{pmatrix}$$

The \mathbf{K} secular equation $K^2 - \text{Trace}(\mathbf{K})K + \text{Det}(\mathbf{K}) = K^2 - 20K + 64 = 0 = (K - 4)(K - 16)$

$\text{Det}(\mathbf{K}) = 7 \cdot 13 - 27 = 91 - 27 = 64$
 $\text{Trace}(\mathbf{K}) = 7 + 13 = 20$

Spectral decomposition of 2D-HO mode dynamics for lower symmetry

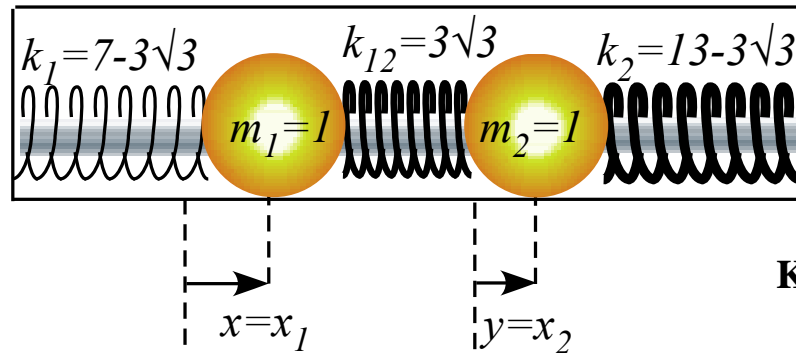


$$\mathbf{K} = \begin{pmatrix} K_{11} & K_{12} \\ K_{12} & K_{22} \end{pmatrix} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} = \begin{pmatrix} 7 & -3\sqrt{3} \\ -3\sqrt{3} & 13 \end{pmatrix}$$

The \mathbf{K} secular equation $K^2 - \text{Trace}(\mathbf{K})K + \text{Det}(\mathbf{K}) = K^2 - 20K + 64 = 0 = (K - 4)(K - 16)$ $\text{Det}(\mathbf{K}) = 7 \cdot 13 - 27 = 91 - 27 = 64$
 $\text{Trace}(\mathbf{K}) = 7 + 13 = 20$

Eigenvalues K_k and squared eigenfrequencies $\omega_0(\epsilon_k)^2$ $K_1 = \omega_0^2(\epsilon_1) = 4, \quad K_2 = \omega_0^2(\epsilon_2) = 16,$

Spectral decomposition of 2D-HO mode dynamics for lower symmetry



$$\mathbf{K} = \begin{pmatrix} K_{11} & K_{12} \\ K_{12} & K_{22} \end{pmatrix} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} = \begin{pmatrix} 7 & -3\sqrt{3} \\ -3\sqrt{3} & 13 \end{pmatrix}$$

The \mathbf{K} secular equation $K^2 - \text{Trace}(\mathbf{K})K + \text{Det}(\mathbf{K}) = K^2 - 20K + 64 = 0 = (K - 4)(K - 16)$

$$\text{Det}(\mathbf{K}) = 7 \cdot 13 - 27 = 91 - 27 = 64$$

$$\text{Trace}(\mathbf{K}) = 7 + 13 = 20$$

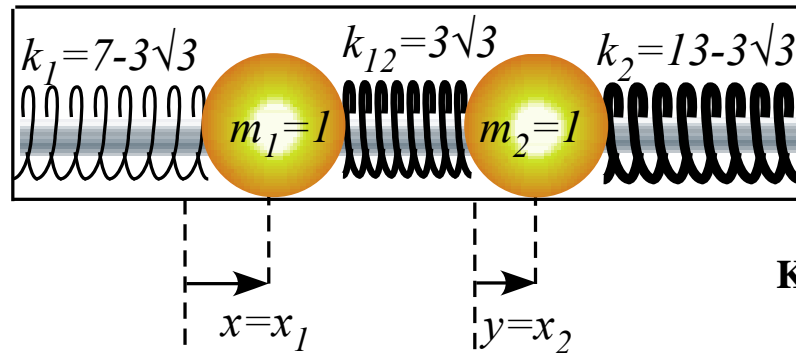
Eigenvalues K_k and squared eigenfrequencies $\omega_0(\epsilon_k)^2$

$$K_1 = \omega_0^2(\epsilon_1) = 4, \quad K_2 = \omega_0^2(\epsilon_2) = 16,$$

Eigen-projectors \mathbf{P}_k

$$\begin{aligned} \mathbf{P}_1 &= \frac{\begin{pmatrix} K_{11} - K_2 & K_{12} \\ K_{12} & K_{22} - K_2 \end{pmatrix}}{K_1 - K_2} = \frac{\begin{pmatrix} 7 - 16 & -3\sqrt{3} \\ -3\sqrt{3} & 13 - 16 \end{pmatrix}}{4 - 16} = \frac{\begin{pmatrix} 9 & +3\sqrt{3} \\ +3\sqrt{3} & 3 \end{pmatrix}}{12} \\ &= \frac{\begin{pmatrix} 3 & \sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}}{4} = \begin{pmatrix} \sqrt{3}/2 \\ 1/2 \end{pmatrix} \begin{pmatrix} \sqrt{3}/2 & 1/2 \end{pmatrix} = |\epsilon_1\rangle\langle\epsilon_1| \end{aligned}$$

Spectral decomposition of 2D-HO mode dynamics for lower symmetry



$$\mathbf{K} = \begin{pmatrix} K_{11} & K_{12} \\ K_{12} & K_{22} \end{pmatrix} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} = \begin{pmatrix} 7 & -3\sqrt{3} \\ -3\sqrt{3} & 13 \end{pmatrix}$$

The \mathbf{K} secular equation $K^2 - \text{Trace}(\mathbf{K})K + \text{Det}(\mathbf{K}) = K^2 - 20K + 64 = 0 = (K - 4)(K - 16)$

$\text{Det}(\mathbf{K}) = 7 \cdot 13 - 27 = 91 - 27 = 64$
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Eigenvalues K_k and squared eigenfrequencies $\omega_0(\epsilon_k)^2$

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Eigen-projectors \mathbf{P}_k

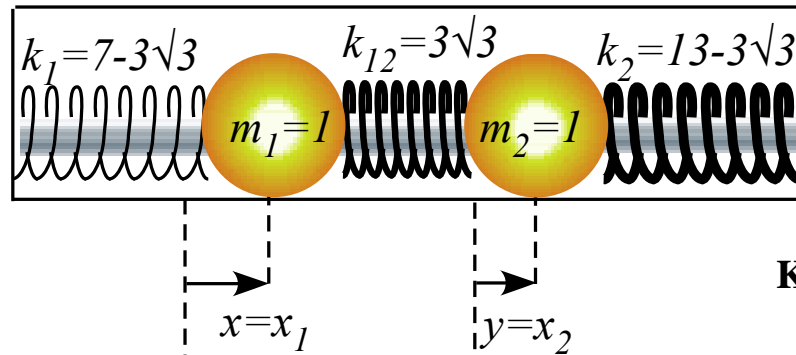
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$$= \frac{\begin{pmatrix} 3 & \sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}}{4} = \begin{pmatrix} \sqrt{3}/2 \\ 1/2 \end{pmatrix} \begin{pmatrix} \sqrt{3}/2 & 1/2 \end{pmatrix} = |\epsilon_1\rangle\langle\epsilon_1|$$

$$\mathbf{P}_2 = \frac{\begin{pmatrix} K_{11} - K_1 & K_{12} \\ K_{12} & K_{22} - K_1 \end{pmatrix}}{K_2 - K_1} = \frac{\begin{pmatrix} 7 - 4 & -3\sqrt{3} \\ -3\sqrt{3} & 13 - 4 \end{pmatrix}}{16 - 4} = \frac{\begin{pmatrix} 3 & -3\sqrt{3} \\ -3\sqrt{3} & 9 \end{pmatrix}}{12}$$

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Spectral decomposition of 2D-HO mode dynamics for lower symmetry



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2D harmonic oscillator equations

Lagrangian and matrix forms and Reciprocity symmetry

2D harmonic oscillator equation eigensolutions

Geometric method

Matrix-algebraic eigensolutions with example $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$

Secular equation

Hamilton-Cayley equation and projectors

Idempotent projectors (how eigenvalues \Rightarrow eigenvectors)

Operator orthonormality and Completeness (Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$)

Spectral Decompositions

Functional spectral decomposition

Orthonormality vs. Completeness vis-a`-vis Operator vs. State

Lagrange functional interpolation formula

Diagonalizing Transformations (D-Ttran) from projectors

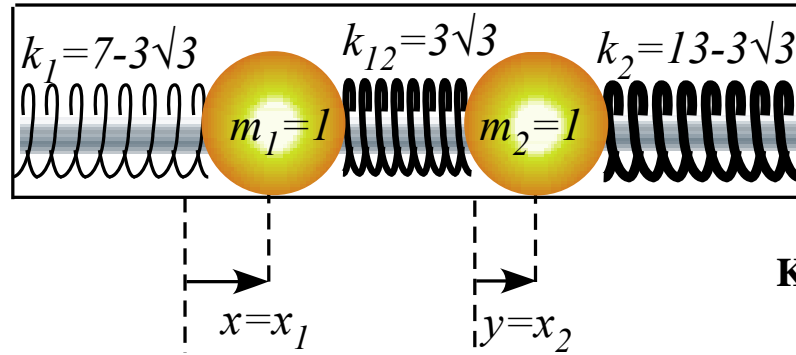
2D-HO eigensolution example with bilateral (B-Type) symmetry

Mixed mode beat dynamics and fixed $\pi/2$ phase

2D-HO eigensolution example with asymmetric (A-Type) symmetry

➔ Initial state projection, mixed mode beat dynamics with variable phase ←

Spectral decomposition of 2D-HO mode dynamics for lower symmetry



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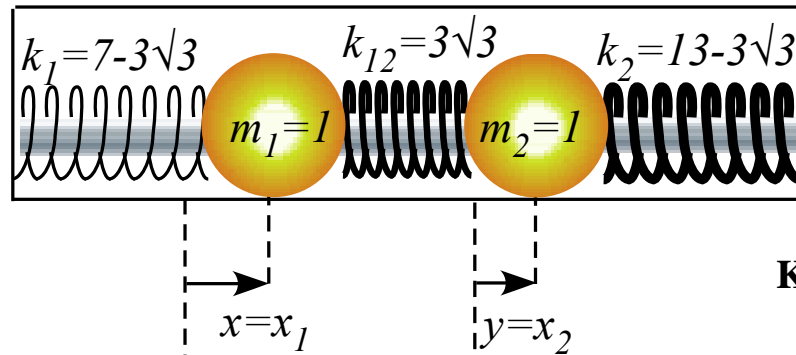
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Eigenbra vectors: $\langle\epsilon_1| = \begin{pmatrix} \sqrt{3}/2 & 1/2 \end{pmatrix}$, $\langle\epsilon_2| = \begin{pmatrix} -1/2 & \sqrt{3}/2 \end{pmatrix}$

Spectral decomposition of initial state $\mathbf{x}(0) = (1, 0)$:

$$\mathbf{1} \cdot \mathbf{x}(0) = (\mathbf{P}_1 + \mathbf{P}_2) \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{3}}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \begin{pmatrix} \frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} \frac{-1}{2} \\ \frac{\sqrt{3}}{2} \end{pmatrix} \otimes \begin{pmatrix} \frac{-1}{2} & \frac{\sqrt{3}}{2} \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

Spectral decomposition of 2D-HO mode dynamics for lower symmetry



$$\mathbf{K} = \begin{pmatrix} K_{11} & K_{12} \\ K_{12} & K_{22} \end{pmatrix} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} = \begin{pmatrix} 7 & -3\sqrt{3} \\ -3\sqrt{3} & 13 \end{pmatrix}$$

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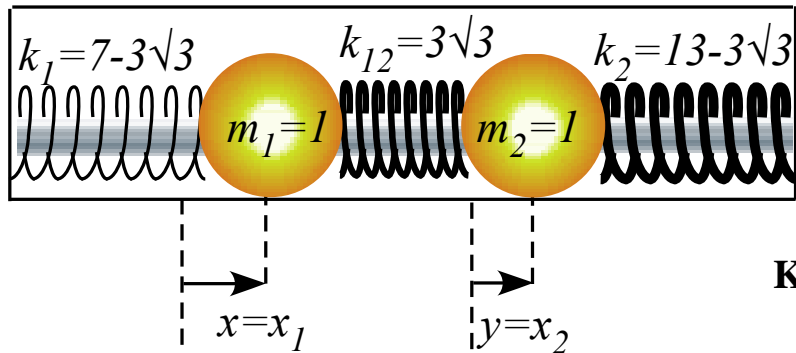
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$$= \begin{pmatrix} \sqrt{3}/2 \\ 1/2 \end{pmatrix} \begin{pmatrix} \sqrt{3}/2 \\ 1/2 \end{pmatrix} + \begin{pmatrix} -1/2 \\ \sqrt{3}/2 \end{pmatrix} \begin{pmatrix} -1/2 \\ \sqrt{3}/2 \end{pmatrix} \quad (\text{Note projection onto eigen-axes})$$

Spectral decomposition of 2D-HO mode dynamics for lower symmetry



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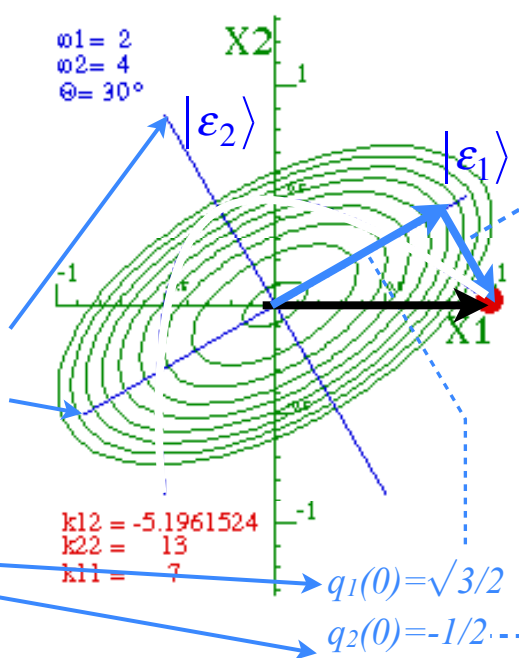
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$$= \begin{pmatrix} \sqrt{3}/2 \\ 1/2 \end{pmatrix} \begin{pmatrix} \sqrt{3}/2 \\ 1/2 \end{pmatrix} + \begin{pmatrix} -1/2 \\ \sqrt{3}/2 \end{pmatrix} \begin{pmatrix} -1/2 \\ \sqrt{3}/2 \end{pmatrix}$$

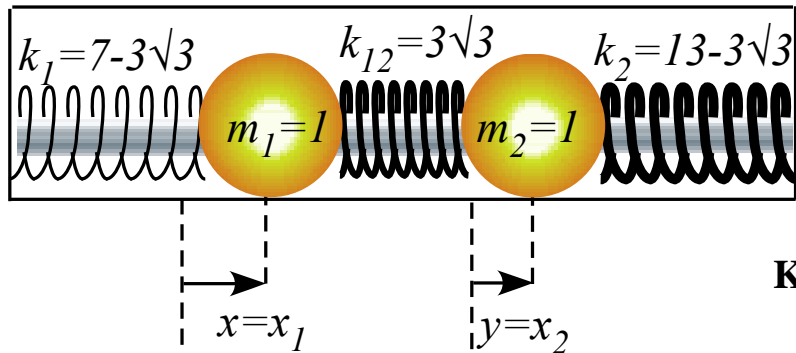
$$\begin{pmatrix} q_1(t) = \frac{\sqrt{3}}{2} \cos 2t, & q_2(t) = -\frac{1}{2} \cos 4t \end{pmatrix}$$

$$\mathbf{x}(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$



(Note projection of $\mathbf{x}(0)$ onto eigen-axes)

Spectral decomposition of 2D-HO mode dynamics for lower symmetry



$$\mathbf{K} = \begin{pmatrix} K_{11} & K_{12} \\ K_{12} & K_{22} \end{pmatrix} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix} = \begin{pmatrix} 7 & -3\sqrt{3} \\ -3\sqrt{3} & 13 \end{pmatrix}$$

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$$\begin{pmatrix} q_1(t) = \frac{\sqrt{3}}{2} \cos 2t, & q_2(t) = -\frac{1}{2} \cos 4t \end{pmatrix}$$

Using $\cos 4t = 2 \cos^2 2t - 1$ derives a parabolic trajectory!

$$q_2(t) = -\frac{1}{2} (2 \cos^2 2t - 1) = -\frac{4}{3} [q_1(t)]^2 + \frac{1}{2}$$

$$\mathbf{x}(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

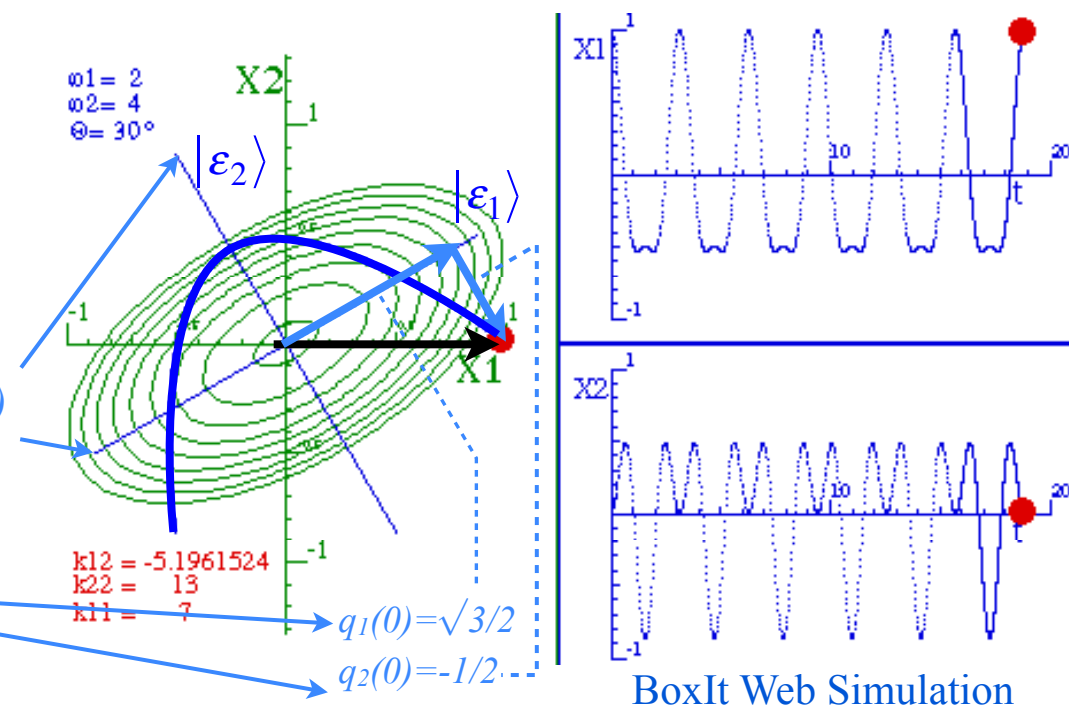
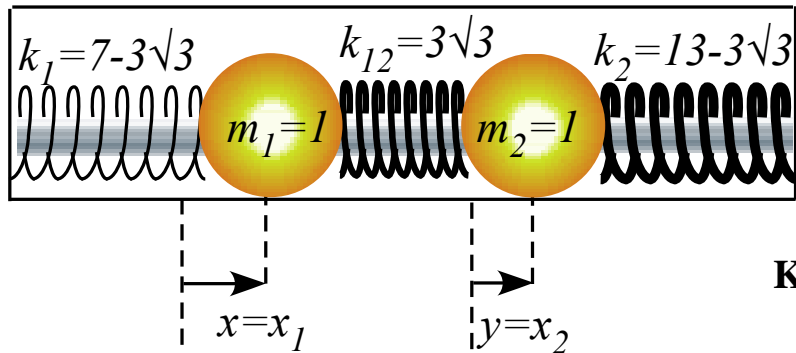


Fig. 3.3.6 Normal coordinate axes, coupled oscillator trajectories and equipotential ($V=\text{const.}$) ovals for an integral 1:2 eigenfrequency ratio ($\omega_0(\epsilon_1)=2.0$, $\omega_0(\epsilon_2)=4.0$) and zero initial velocity.

BoxIt Web Simulation

Spectral decomposition of 2D-HO mode dynamics for lower symmetry



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Eigenbra vectors: $\langle\epsilon_1| = \begin{pmatrix} \sqrt{3}/2 & 1/2 \end{pmatrix}, \quad \langle\epsilon_2| = \begin{pmatrix} -1/2 & \sqrt{3}/2 \end{pmatrix}$

Spectral decomposition of initial state $\mathbf{x}(0) = (1, 0)$:

$$\mathbf{1} \cdot \mathbf{x}(0) = (\mathbf{P}_1 + \mathbf{P}_2) \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \sqrt{3}/2 \\ 1/2 \end{pmatrix} \otimes \begin{pmatrix} \sqrt{3}/2 & 1/2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} -1/2 \\ \sqrt{3}/2 \end{pmatrix} \otimes \begin{pmatrix} -1/2 & \sqrt{3}/2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

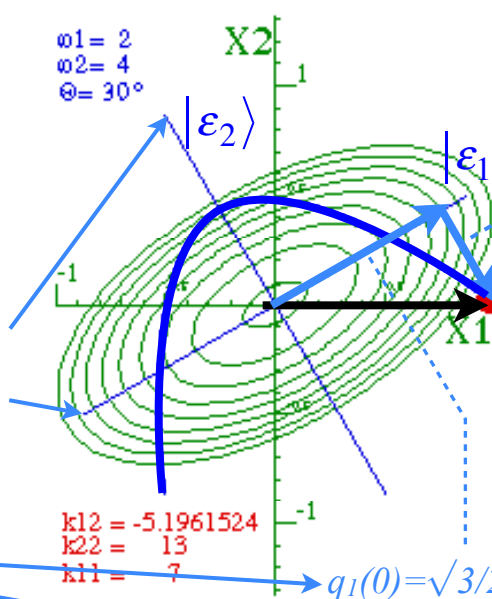
$$= \begin{pmatrix} \sqrt{3}/2 \\ 1/2 \end{pmatrix} \begin{pmatrix} \sqrt{3}/2 \\ 1/2 \end{pmatrix} + \begin{pmatrix} -1/2 \\ \sqrt{3}/2 \end{pmatrix} \begin{pmatrix} -1/2 \\ \sqrt{3}/2 \end{pmatrix}$$

$$\begin{pmatrix} q_1(t) = \frac{\sqrt{3}}{2} \cos 2t, & q_2(t) = -\frac{1}{2} \cos 4t \end{pmatrix}$$

Using $\cos 4t = 2 \cos^2 2t - 1$ derives a parabolic trajectory!

$$q_2(t) = -\frac{1}{2} 2 \cos^2 2t + \frac{1}{2} = -\frac{4}{3} [q_1(t)]^2 + \frac{1}{2}$$

$$\mathbf{x}(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$



[BoxIt Web Simulation](#)

[Pafnuty Chebyshev](#)



Pafnuty Lvovich Chebyshev was a Russian mathematician. His name can be alternatively transliterated as Chebychev, Chebysheff, Chebyshev, Tchebychev or Tchebycheff, or Tschebyschew or Tschebyschew. Wikipedia

Born: May 16, 1821, Borovsk
Died: December 8, 1894, Saint Petersburg

Example of a Tschebycheff Polynomial order 2