

## Assignment 11 - PHYS 5103-11/13/19-Due Wed. Nov. 20 CMwBang! Ch 4.1 thru Ch.4.4. and Lectures 21-23

**Ex.1(a)** Do ABCD expansion of Hamiltonian  $\mathbf{H} = \Omega_0 \mathbf{1} + \vec{\Omega} \cdot \vec{\mathbf{S}}$  using p. 54 of Lect. 22 for  $\mathbf{H} = \frac{1}{5} \begin{pmatrix} 34 & -12 \\ -12 & 41 \end{pmatrix} = \sqrt{\mathbf{K}}$

(A square-root in last part of Assignment 10.) Evaluate crank vector  $\vec{\Omega} = (\Omega_A, \Omega_B, \Omega_C)$  and overall frequency  $\Omega_0 = \underline{\hspace{2cm}}$ . Evaluate beat or splitting frequency  $\frac{1}{2}|\Omega| = \underline{\hspace{2cm}}$  and plot eigen-frequency levels. (See p.50-54 of Lect.23)

**(b)** Sketch a 3D ABC-space showing the crank vector  $\vec{\Omega} = (\Omega_A, \Omega_B, \Omega_C)$  and the angle it makes with the **A**-axis.

**(c)** Show how a rotation  $|\Theta| = |\Omega|t = \pi$  of a spin-vector **S** starting on the **A**-axis would end up.

**(d)** Do ABCD expansion of 2D Hooke spring matrix **K**. Compare resulting crank vector  $\vec{\Omega}$  and eigenvectors of **K** with those of **H**.

**(e)** Given initial conditions ( $X(0)=1, Y(0)=0, \mathbf{V}_0=0$ ), derive and plot the resulting (*Tschebycheff*) path in the XY-plane .

**Ex.2(a)** Do ABCD expansion of Hamiltonian  $\mathbf{H} = \begin{pmatrix} 5 & -3 \\ -3 & 5 \end{pmatrix} = \sqrt{\mathbf{K}}$  and plot eigen-frequency levels as in **Ex.1**.

**(b)** Sketch a 3D ABC-space as in **Ex.1**.

**(c)** Show rotations as in **Ex.1**.

**(d)** Do ABCD expansion of 2D Hooke spring matrix **K** as in **Ex.1**.

**(e)** Given initial conditions ( $X(0)=1, Y(0)=0, \mathbf{V}_0=0$ ), derive and plot a resulting (*Tschebycheff*) path in the XY-plane .

**Ex.3** Derivation in Lect. 23 (p.47-65) of eigenvectors equates spin-vector  $\mathbf{S}(\alpha, \beta, \cdot)$  to crank-vector  $\pm \Omega[\varphi, \vartheta, \cdot]$ .

Try using the Projector operator method introduced in Lect. 21 p. 40-44. Are results the same? Compare ease of use.

**Ex.4** The clearest example of 2-state or spin  $\frac{1}{2}$  resonance behavior are A, B or C type of evolution in which the spin vector moves from axis to axis as demonstrated by animations accessed on pages 71 thru 88.

**(a)** Uncoupled oscillation of the AD type (p.71). Let Hamiltonian have  $A=1.5$  and  $D=0.5$  with  $B=0=C$  with initial oscillator variables  $x_1(0)=1=x_2(0)$  and  $p_1(0)=0=p_2(0)$ . Describe initial spin vector (p.80 Lect.22) and its evolution.

**(b)** Balanced coupled oscillation of the B type (p.76). Explain why phase lag is always  $\pi/2$  when initial position and velocity of just one oscillator is zero. (Helpful hints on p. 94-97 or p.87 of Lect. 21.)

**(c)** Coriolis coupled oscillation of the C type (p.87). How does this resemble motion of a Foucault pendulum?

**Ex.5** For any of the apps discussed in **Ex.4** you may access the control panel and reset the A, B, C, and D parameters that determine the crank vector  $\vec{\Omega}$  and overall frequency  $\Omega_0$ . See if you can set these and the spin vector **S** so **S** goes from the A-axis to the B-axis to the C-axis and back thru the A-axis. Make  $\Omega_0$  at least 40 times larger than the other A, B, and C components of  $\vec{\Omega}$ . Show a screen clip picture of the resulting evolution.