Assignment 2 Read Unit 1 Chapters 1 thru 6. Ex. 1.5.5 and 1.6.5 are due Thursday Sept. 1, 2016

## *Reflections on reflections ( A lesson in group representation theory)*

*Exercise 1.5.5* This exercise is intended to introduce matrix reflection and rotation operators and the groups they form. It involves the circular (V<sub>1</sub>, V<sub>2</sub>) plots (*"l'Etrangian space"*) introduced in Fig. 5.2b by eqs. (5.7)-(5.13) and the mirror diagrams in Fig. 5.3. All elastic ( $m_1 - m_2$ ) collisions map an initial **V**<sup>IN</sup>=(V<sub>1</sub>, V<sub>2</sub>) vector into a **V**<sup>FIN</sup> of the same length so all collisions map to unit vectors. All elastic  $m_1:m_2=3:1$  collisions are described by a  $D_6\sim C_{6\nu}$  group of products of three reflection matrices **F**, **C**, and **M** described around *eq.* (5.3) of *Unit 1*. Note also *inversion operation* **F**·**C**=**I** that commutes with all 12 operators in this  $D_6\sim C_{6\nu}$  group given in Lect. 3 p. 61 and described by operations as matrices and as reflections in (V<sub>1</sub>, V<sub>2</sub>) space.

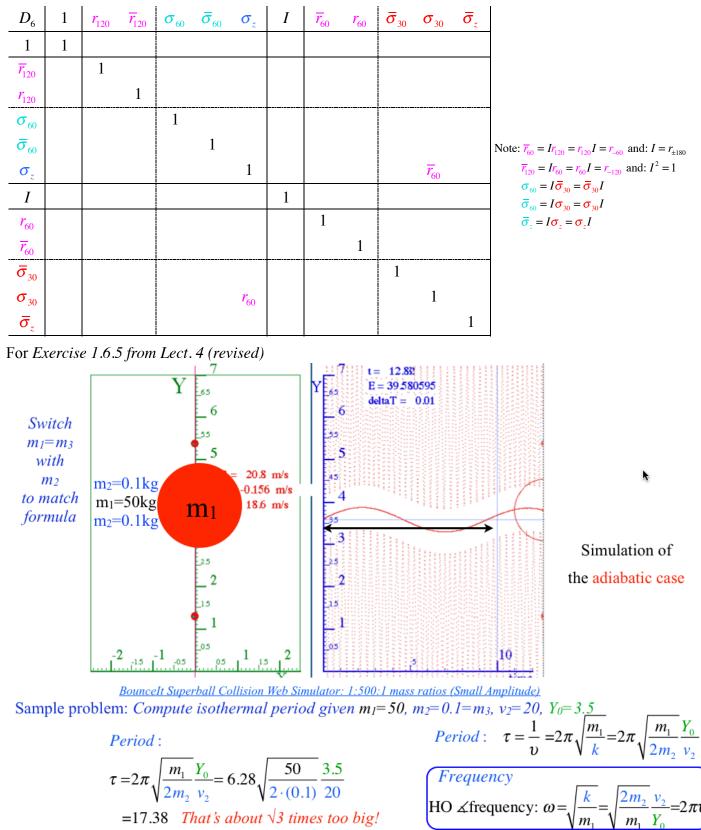
(a) As far as the 2-D hex-plane is concerned the inversion I is a *rotation*. By how much? \_\_\_\_\_\_° Explain. (b) Note how each reflection like  $\sigma_{30}$  is labeled by giving angle 30° of a mirror-plane-slope and each rotation like  $\mathbf{r}_{60}$  by the angle 60° it turns vectors. Show effect of  $\sigma_{30}$  and  $\mathbf{r}_{60}$  on unit initial vectors (V<sub>1</sub>, V<sub>2</sub>)=(1, 0)= $\mathbf{e}_{\mathbf{x}}$  and (0, 1)= $\mathbf{e}_{\mathbf{y}}$ . (This derives their matrix representations. See examples in Lect. 3 p. 56 thru p. 59.) (c) Finish the  $D_6 \sim C_{6v}$  group product table on page 61 of Lect. 3. First do sub-group  $D_3 \sim C_{3v}$  whose table is upper-left 6-by-6 block of the  $D_6 \sim C_{6v}$  table. Note that most  $C_{3v}$  elements do not commute with each other. ( $\mathbf{ab} \neq \mathbf{ba}$ ) Then note each of the remaining 6-by-6 blocks follow a predictable pattern based on defining reflections  $\sigma$  as product  $\sigma = \mathbf{l} \cdot \mathbf{r} = \mathbf{r} \cdot \mathbf{l}$  of inversion I and  $C_{3v}$  rotation  $\mathbf{r}$ . (This shows that  $C_{6v}$  reduces to outer product  $C_{6v} = C_{3v} \times C_i$  of subgroup  $C_{3v}$  with inversion group  $C_i = \{\mathbf{1}, \mathbf{l}\}$  since  $C_i$  commutes with  $C_{3v}$ .)

## KE becomes PE

*Exercise 1.6.5* In Fig. 6.3 (See also Lect. 4 p.45 to 48.<sup>†</sup>) a mass  $m_1=50kg$  ball is trapped between two smaller mass  $m_2=0.1kg$  balls of relatively high speed ( $v_2(0)=20m/s$  at t=0) that provide  $m_1$  with an effective force law F(x) based on isothermal approximation (6.11). We assume  $m_1$  moves only moderately far or fast from equilibrium at x=0. (We idealize "balls" as point masses here and in many other CM problems.)

(a) A further approximation is the one-Dimensional Harmonic Oscillator (1D-HO) force and PE in (6.12). If each mass  $m_2$  starts in an interval  $Y_0=3.5m$ , derive isothermal approximate 1D-HO frequency and period for mass  $m_1$ .

(b) What if the adiabatic approximation is used instead? Does the frequency decrease, increase, or just become anharmonic? Compare isothermal and adiabatic quantitative results for  $m_1=50kg$  ball being hit by two  $m_2=0.1kg$  balls each having speed of  $v_2(0)=20m/s$  as each starts bouncing in its space of about  $Y_0=3.5m$  on either side of the equilibrium point x=0 for the 1kg ball. Which seems to give best approximation to Lect. 4 p.45-48<sup>†</sup> results? † Lect. 4 p.45-48 was upgraded after class with additional details.



Unfinished group product table for Exercise 1.5.5 from Lect. 3