Lecture 19 Thur. 3.08.2012

Complex Variables, Series, and Field Coordinates I. (Ch. 10 of Unit 1)

1. The Story of e (A Tale of Great \$Interest\$) How good are those power series?

2. What good are complex exponentials? Easy trig Easy 2D vector analysis Easy oscillator phase analysis Easy 2D vector derivatives Easy 2D vector derivatives Easy 2D source-free field theory Easy 2D vector field-potential theory

The half-n'-half results: (Riemann-Cauchy Derivative Relations)

- 1. Complex numbers provide "automatic trigonometry"
- 2. Complex numbers add like vectors.
- 3. Complex exponentials Ae^{-iwt} track position <u>and</u> velocity using Phasor Clock.
- 4. Complex products provide 2D rotation operations.
- 5. Complex products provide 2D "dot"(•) and "cross"(x) products.
- 6. Complex derivative contains "divergence" ($\nabla \cdot F$) and "curl" ($\nabla x F$) of 2D vector field
- 7. Invent source-free 2D vector fields $[\nabla \cdot \mathbf{F}=0 \text{ and } \nabla \mathbf{x}\mathbf{F}=0]$
- 8. Complex potential ϕ contains "scalar"($\mathbf{F}=\nabla \Phi$) and "vector"($\mathbf{F}=\nabla x\mathbf{A}$) potentials

End of Part I. Lecture 19 Thur. 3.08.2012

Easy 2D circulation and flux integrals Easy 2D curvilinear coordinate discovery Easy 2D monopole, dipole, and 2ⁿ-pole analysis

- 9. Complex integrals f (z)dz count 2D "circulation" (]F•dr) and "flux" (]Fxdr)
- 10. Complex integrals define 2D monopole fields and potentials
- 11. Complex potentials define 2D Orthogonal Curvilinear Coordinates (OCC) of field
- 12. Complex derivatives give 2D dipole fields

Simple *interest* at some rate r based on a 1 year period.

You gave a principal p(0) to the bank and some time *t* later they would pay you $p(t)=(1+r \cdot t)p(0)$.

\$1.00 at rate r=1 (like Israel and Brazil that once had 100% interest.) gives \$2.00 at t=1 year.

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Semester compounded interest gives $p(\frac{t}{2}) = (1 + r \cdot \frac{t}{2})p(0)$ at the half-period $\frac{t}{2}$ and then use $p(\frac{t}{2})$ during the last half to figure final payment. Now \$1.00 at rate r=1 earns \$2.25.

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Trimester compounded interest gives $p(\frac{t}{3}) = (1+r \cdot \frac{t}{3})p(0)$ at the $1/3^{rd}$ -period $\frac{t}{3}$ or 1^{st} trimester and then use that to figure the 2nd trimester and so on. Now \$1.00 at rate r=1 earns \$2.37.

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$$p^{\frac{1}{1}}(t) = (1 + r \cdot \frac{t}{1})^{1} p(0) = \left(\frac{2}{1}\right)^{1} \cdot 1 = \frac{2}{1} = 2.00$$

$$+25\phi$$

$$p^{\frac{1}{2}}(t) = (1 + r \cdot \frac{t}{2})^{2} p(0) = \left(\frac{3}{2}\right)^{2} \cdot 1 = \frac{9}{4} = 2.25$$

$$+12\phi$$

$$p^{\frac{1}{3}}(t) = (1 + r \cdot \frac{t}{3})^{3} p(0) = \left(\frac{4}{3}\right)^{3} \cdot 1 = \frac{64}{27} = 2.37$$

$$+7\phi$$

$$p^{\frac{1}{4}}(t) = (1 + r \cdot \frac{t}{4})^{4} p(0) = \left(\frac{5}{4}\right)^{4} \cdot 1 = \frac{625}{256} = 2.44$$

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$$p^{\frac{1}{1}}(t) = (1 + r \cdot \frac{t}{1})^{1} p(0) = \left(\frac{2}{1}\right)^{1} \cdot 1 = \frac{2}{1} = 2.00$$

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$$p^{\frac{1}{4}}(t) = (1 + r \cdot \frac{t}{4})^{4} p(0) = \left(\frac{5}{4}\right)^{4} \cdot 1 = \frac{625}{256} = 2.44$$

Monthly:
$$p^{\frac{1}{12}}(t) = (1 + r \cdot \frac{t}{12})^{12} p(0) = \left(\frac{13}{12}\right)^{12} \cdot 1 = 2.613$$

Weekly: $p^{\frac{1}{52}}(t) = (1 + r \cdot \frac{t}{52})^{52} p(0) = \left(\frac{53}{52}\right)^{52} \cdot 1 = 2.693$
Daily: $p^{\frac{1}{365}}(t) = (1 + r \cdot \frac{t}{365})^{365} p(0) = \left(\frac{366}{365}\right)^{365} \cdot 1 = 2.7145$
Hrly: $p^{\frac{1}{8760}}(t) = (1 + r \cdot \frac{t}{8760})^{8760} p(0) = \left(\frac{8761}{8760}\right)^{8760} \cdot 1 = 2.7181$

$$p^{1/m}(1) = (1 + \frac{1}{m})^m \xrightarrow[m \to \infty]{=} e^{2.718281828459..} = e^{p^{1/m}(1)} = 2.7169239322 \qquad for m = 1,000 \qquad for m = 10,000 \qquad for m = 10,000 \qquad for m = 100,000 \qquad for m = 100,000 \qquad for m = 1,000,000 \qquad for m = 10,000,000 \qquad for m = 1,000,000 \qquad for m = 1,000,00$$

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$$p^{1/m}(1) = 2.7181459268$$

$$p^{1/m}(1) = 2.7182682372$$

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$$p^{1/m}(1) = 2.7182804693$$

$$p^{1/m}(1) = 2.7182816925$$

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Can improve efficiency using binomial theorem:

$$(x+y)^{n} = x^{n} + n \cdot x^{n-1}y + \frac{n(n-1)}{2!}x^{n-2}y^{2} + \frac{n(n-1)(n-2)}{3!}x^{n-3}y^{3} + \dots + n \cdot xy^{n-1} + y^{n}$$
$$(1 + \frac{r \cdot t}{n})^{n} = 1 + n \cdot \left(\frac{r \cdot t}{n}\right) + \frac{n(n-1)}{2!}\left(\frac{r \cdot t}{n}\right)^{2} + \frac{n(n-1)(n-2)}{3!}\left(\frac{r \cdot t}{n}\right)^{3} + \dots \qquad \text{Define: Factorials(!):}$$
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Can improve efficiency using binomial theorem:

$$\begin{aligned} (x+y)^{n} &= x^{n} + n \cdot x^{n-1}y + \frac{n(n-1)}{2!}x^{n-2}y^{2} + \frac{n(n-1)(n-2)}{3!}x^{n-3}y^{3} + \dots + n \cdot xy^{n-1} + y^{n} \\ (1+\frac{r \cdot t}{n})^{n} &= 1 + n \cdot \left(\frac{r \cdot t}{n}\right) + \frac{n(n-1)}{2!}\left(\frac{r \cdot t}{n}\right)^{2} + \frac{n(n-1)(n-2)}{3!}\left(\frac{r \cdot t}{n}\right)^{3} + \dots \end{aligned}$$
Define: Factorials(!):

$$0! = 1 = 1!, \quad 2! = 1\cdot 2, \quad 3! = 1\cdot 2\cdot 3, \dots \end{aligned}$$

$$\begin{aligned} e^{r \cdot t} &= 1 + r \cdot t + \frac{1}{2!}\left(r \cdot t\right)^{2} + \frac{1}{3!}\left(r \cdot t\right)^{3} + \dots = \sum_{p=0}^{o} \frac{\left(r \cdot t\right)^{p}}{p!} \end{aligned}$$

$$As \ n \to \infty \ let : n(n-1) \to n^{2}, n(n-1)(n-2) \to n^{3}, etc. \end{aligned}$$

$$p^{1/m}(1) = (1 + \frac{1}{m})^m \xrightarrow[m \to \infty]{=} e^{p^{1/m}(1)} = 2.7169239322 \qquad for m = 1,000 \\ p^{1/m}(1) = 2.7181459268 \qquad for m = 10,000 \\ p^{1/m}(1) = 2.7182682372 \qquad for m = 100,000 \\ p^{1/m}(1) = 2.7182804693 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182816925 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182816925 \qquad for m = 10,000,000 \\ p^{1/m}(1) = 2.7182818149 \qquad for m = 10,000,000 \\ p^{1/m}(1) = 2.7182818149 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.718$$

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Precision order:
$$(o=1)$$
-e-series = 2.00000 =1+1 $n(n-1)(n-2) \rightarrow n^3$, etc.
 $(o=2)$ -e-series = 2.50000 =1+1+1/2
 $(o=3)$ -e-series = 2.66667 =1+1+1/2+1/6
 $(o=4)$ -e-series = 2.70833 =1+1+1/2+1/6+1/24
 $(o=5)$ -e-series = 2.71667 =1+1+1/2+1/6+1/24+1/120
 $(o=6)$ -e-series = 2.71805 =1+1+1/2+1/6+1/24+1/120+1/720
 $(o=7)$ -e-series = 2.71825
 $(o=8)$ -e-series = 2.71828 About 12 summed quotients
for 6-figure precision (A lot better!)

Start with a general power series with constant coefficients $c_0, c_1, etc.$ Set t=0 to get $c_0 = x(0)$. $x(t) = c_0 + c_1t + c_2t^2 + c_3t^3 + c_4t^4 + c_5t^5 + \dots + c_nt^n + c_nt^n$

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Set
$$t=0$$
 to get $c_0 = x(0)$.

$$x(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + c_5 t^5 + \dots + c_n t^n + \dots$$

Rate of change of position x(t) is velocity v(t).

Set
$$t=0$$
 to get $c_1 = v(0)$.

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 3c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 3c_3t^2 + \frac{d}{dt}x(t) = 0 + c_1 +$$

Start with a general power series with constant coefficients c_0 , c_1 , etc.

Set
$$t=0$$
 to get $c_0 = x(0)$.

$$x(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + c_5 t^5 + \dots + c_n t^n + \dots$$

Set t=0 to get $c_1 = v(0)$.

Rate of change of position x(t) is velocity v(t).

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 3c_3t^2 + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + \frac{d}{dt}x(t) = 0 + \frac{d}{dt}x($$

Change of velocity v(t) is *acceleration* a(t).

Set
$$t=0$$
 to get $c_2 = \frac{1}{2}a(0)$.

$$a(t) = \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + \frac{d}{dt}v(t) = 0 + 2c_5t^2 + \frac{d}{dt}v(t) = 0 +$$

Start with a general power series with constant coefficients c_0 , c_1 , etc.

Set
$$t=0$$
 to get $c_0 = x(0)$.

Set t=0 to get $c_1 = v(0)$.

$$x(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + c_5 t^5 + \dots + c_n t^n + \dots$$

Rate of change of position x(t) is velocity v(t).

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + \frac{d}{dt}x(t) =$$

Change of velocity v(t) is *acceleration* a(t).

$$a(t) = \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + \frac{d}{dt}v(t) = 0 + 2c_5t^2 + \frac{d}{dt}v(t) = 0 +$$

Change of acceleration a(t) is *jerk j(t)*. (*Jerk* is NASA term.) Set t=0 to get $c_3 = \frac{1}{3!} j(0)$.

$$j(t) = \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_5t^2 + \dots + n(n-$$

Change of jerk j(t) is *inauguration* i(t). (Be silly like NASA!) Set t=0 to get $c_4 = \frac{1}{4!}i(0)$.

Set t=0 to get $c_2 = \frac{1}{2}a(0)$.

Start with a general power series with constant coefficients c_0 , c_1 , etc.

Set
$$t=0$$
 to get $c_0 = x(0)$.

Set t=0 to get $c_1 = v(0)$.

$$x(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + c_5 t^5 + \dots + c_n t^n + \dots$$

Rate of change of position x(t) is velocity v(t).

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + \frac{d}{dt}x(t) = 0 + \frac{d}{d$$

Change of velocity v(t) is acceleration a(t).

$$a(t) = \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + \frac{d}{dt}v(t) = 0 + 2c_5t^2 + \frac{d}{dt}v(t) = 0 +$$

Change of acceleration a(t) is *jerk j(t)*. (*Jerk* is NASA term.) Set t=0 to get $c_3 = \frac{1}{3!} j(0)$.

$$j(t) = \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_1t^2 + \dots + n(n-1)(n-2)c_1t^2$$

Change of jerk j(t) is *inauguration* i(t). (Be silly like NASA!) Set t=0 to get $c_4 = \frac{1}{4!}i(0)$.

Gives Maclaurin (or Taylor) power series

$$x(t) = x(0) + v(0)t + \frac{1}{2!}a(0)t^{2} + \frac{1}{3!}j(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \dots$$

Set t=0 to get $c_2 = \frac{1}{2}a(0)$.

Start with a general power series with constant coefficients c_0 , c_1 , etc.

Set
$$t=0$$
 to get $c_0 = x(0)$.

Set t=0 to get $c_1 = v(0)$.

Set t=0 to get $c_2 = \frac{1}{2}a(0)$.

$$x(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + c_5 t^5 + \dots + c_n t^n + \dots$$

Rate of change of position x(t) is velocity v(t).

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + \frac{d}{dt}x(t) =$$

Change of velocity v(t) is acceleration a(t).

$$a(t) = \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + \frac{d}{dt}v(t) = 0 + 2c_5t^2 + \frac{d}{dt}v(t) = 0 +$$

Change of acceleration a(t) is *jerk j(t)*. (*Jerk* is NASA term.) Set t=0 to get $c_3 = \frac{1}{3!} j(0)$.

$$j(t) = \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_5t^2 + \dots + n(n-1)(n-2)c_1t^2 + \dots + n(n-1)(n-2)c$$

Change of jerk j(t) is *inauguration* i(t). (Be silly like NASA!) Set t=0 to get $c_4 = \frac{1}{4!}i(0)$.

Gives Maclaurin (or Taylor) power series

$$x(t) = x(0) + v(0)t + \frac{1}{2!}a(0)t^{2} + \frac{1}{3!}j(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}i(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}i(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{5} + \frac{1}{3!$$

Good old UP I formula!

Start with a general power series with constant coefficients c_0 , c_1 , etc.

Set
$$t=0$$
 to get $c_0 = x(0)$.

Set t=0 to get $c_1 = v(0)$.

Set t=0 to get $c_2 = \frac{1}{2}a(0)$.

$$x(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + c_5 t^5 + \dots + c_n t^n + \dots$$

Rate of change of position x(t) is velocity v(t).

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + \frac{d}{dt}x(t) =$$

Change of velocity v(t) is acceleration a(t).

$$a(t) = \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + \frac{d}{dt}v(t) = 0 + 2c_5t^2 + \frac{d}{dt}v(t) = 0 +$$

Change of acceleration a(t) is *jerk j(t)*. (*Jerk* is NASA term.) Set t=0 to get $c_3 = \frac{1}{3!} j(0)$.

$$j(t) = \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \dots$$

Change of jerk j(t) is *inauguration* i(t). (Be silly like NASA!) Set t=0 to get $c_4 = \frac{1}{4!}i(0)$.

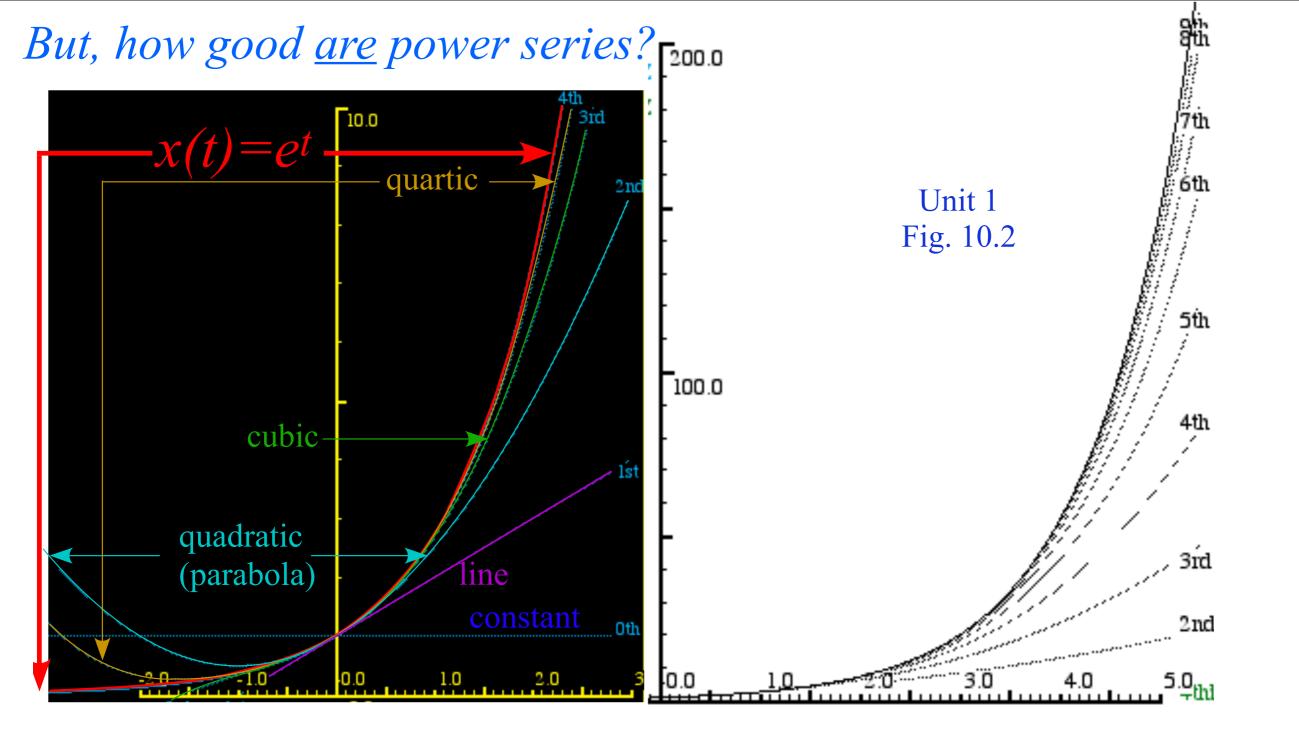
Gives Maclaurin (or Taylor) power series

$$x(t) = x(0) + v(0)t + \frac{1}{2!}a(0)t^{2} + \frac{1}{3!}j(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{4} + \frac{1}{5!}i(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{5!}i(0)t^{5} + \dots + \frac{1}{3!}i(0)t^{5} + \dots + \frac{1}{$$

Setting all initial values to $l = x(0) = v(0) = a(0) = j(0) = i(0) = \dots$

Good old UP I formula!

gives exponential:
$$e^{t} = 1 + t + \frac{1}{2!}t^{2} + \frac{1}{3!}t^{3} + \frac{1}{4!}t^{4} + \frac{1}{5!}t^{5} + \dots + \frac{1}{n!}t^{n} + \frac{1}{2!}t^{n} + \frac{1}{$$

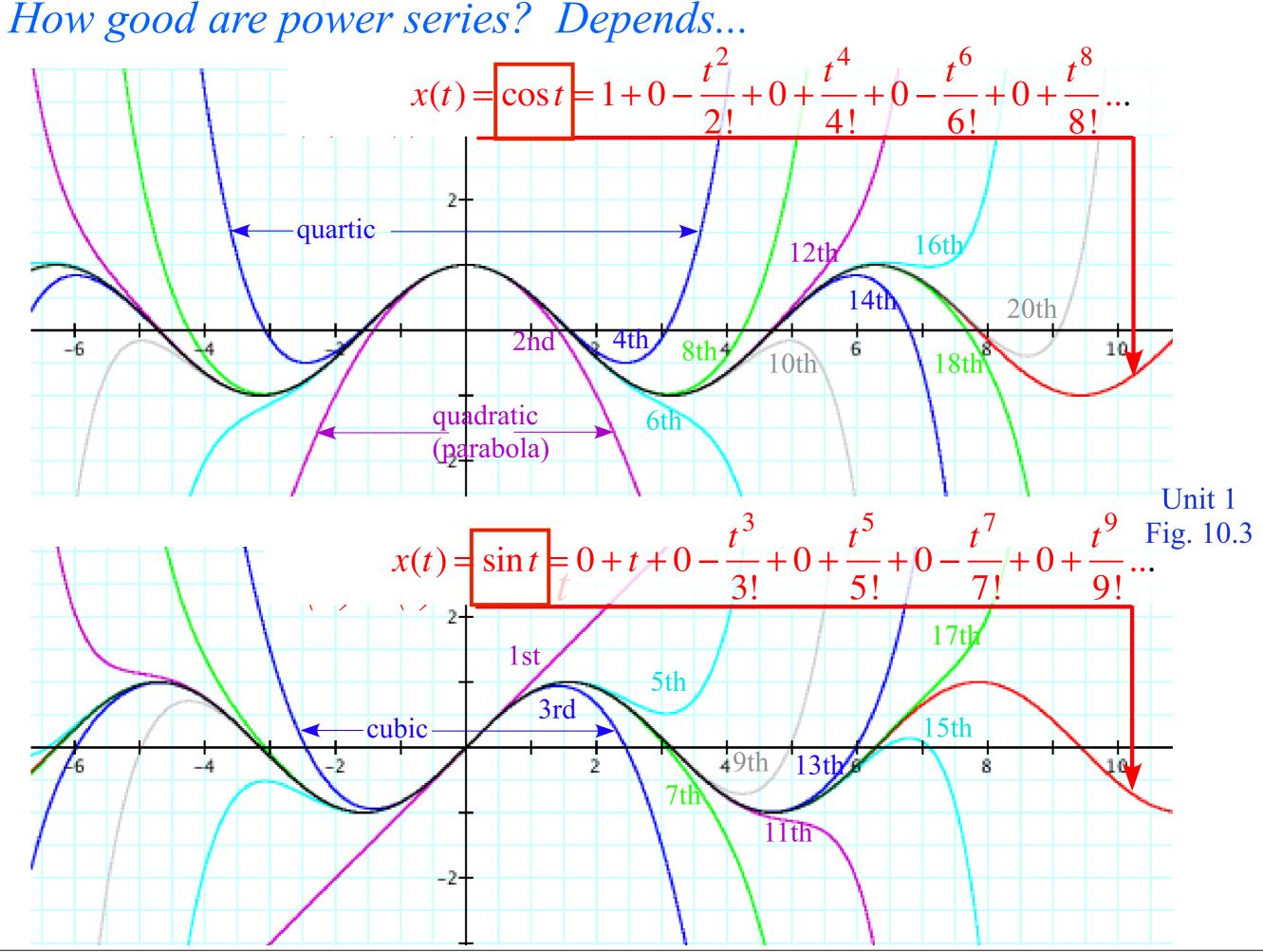


Gives Maclaurin (or Taylor) power series

$$x(t) = x(0) + v(0)t + \frac{1}{2!}a(0)t^{2} + \frac{1}{3!}j(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}x^{(n)}t^{n} + \frac{1}{3$$

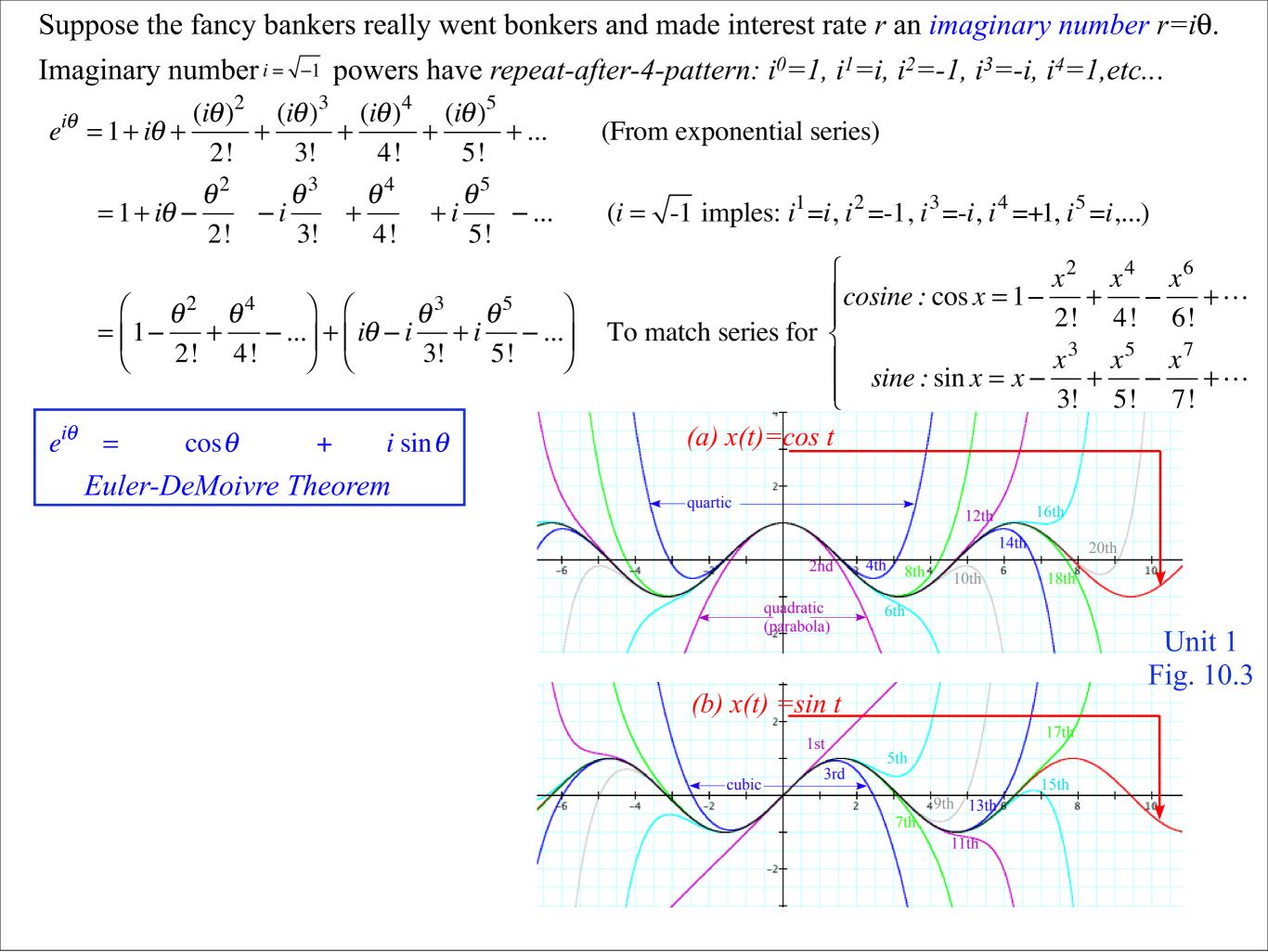
Setting all initial values to $1 = x(0) = v(0) = a(0) = j(0) = i(0) = \dots$

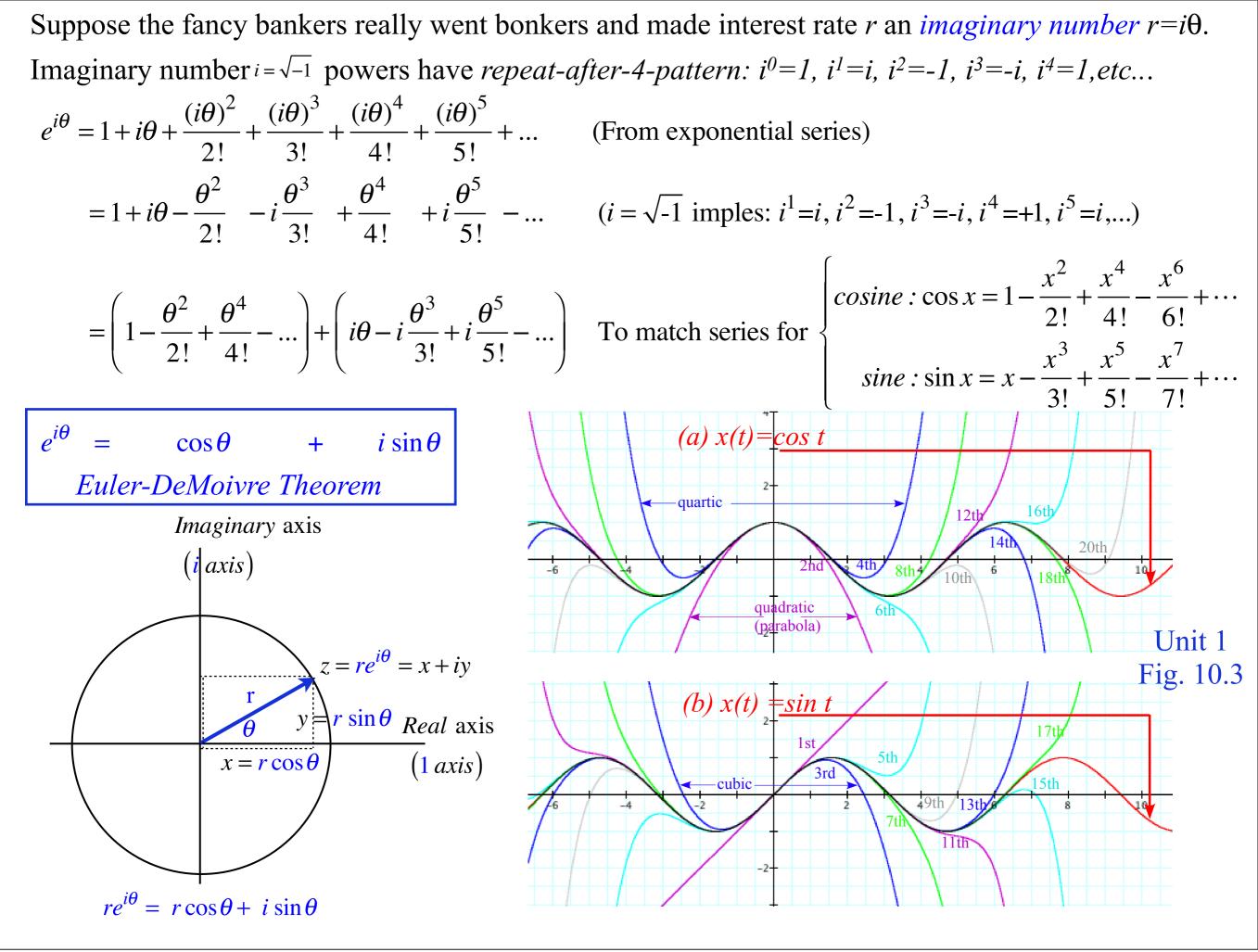
gives exponential:
$$e^{t} = 1 + t + \frac{1}{2!}t^{2} + \frac{1}{3!}t^{3} + \frac{1}{4!}t^{4} + \frac{1}{5!}t^{5} + \dots + \frac{1}{n!}t^{n} + \frac{1}{2!}t^{n} + \frac{1}{$$



Friday, March 9, 2012

Suppose the fancy bankers really went bonkers and made interest rate *r* an *imaginary number r=i* θ . Imaginary number $i = \sqrt{-1}$ powers have *repeat-after-4-pattern*: $i^{0}=1$, $i^{1}=i$, $i^{2}=-1$, $i^{3}=-i$, $i^{4}=1$, etc... $e^{i\theta} = 1 + i\theta + \frac{(i\theta)^{2}}{2!} + \frac{(i\theta)^{3}}{3!} + \frac{(i\theta)^{4}}{4!} + \frac{(i\theta)^{5}}{5!} + \dots$ (From exponential series) $= 1 + i\theta - \frac{\theta^{2}}{2!} - i\frac{\theta^{3}}{3!} + \frac{\theta^{4}}{4!} + i\frac{\theta^{5}}{5!} - \dots$ ($i = \sqrt{-1}$ imples: $i^{1}=i$, $i^{2}=-1$, $i^{3}=-i$, $i^{4}=+1$, $i^{5}=i$,...) $= \left(1 - \frac{\theta^{2}}{2!} + \frac{\theta^{4}}{4!} - \dots\right) + \left(i\theta - i\frac{\theta^{3}}{3!} + i\frac{\theta^{5}}{5!} - \dots\right)$





2. What Good Are Complex Exponentials?

What Good Are Complex Exponentials?

1. Complex numbers provide "automatic trigonometry"

Can't remember is $\cos(a+b)$ or $\sin(a+b)$? Just factor $e^{i(a+b)} = e^{ia}e^{ib}$...

$$e^{i(a+b)} = e^{ia} e^{ib}$$

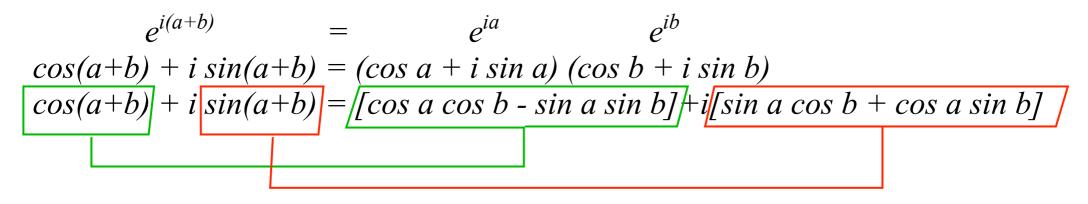
$$cos(a+b) + i sin(a+b) = (cos a + i sin a) (cos b + i sin b)$$

$$cos(a+b) + i sin(a+b) = [cos a cos b - sin a sin b] + i [sin a cos b + cos a sin b]$$

What Good Are Complex Exponentials?

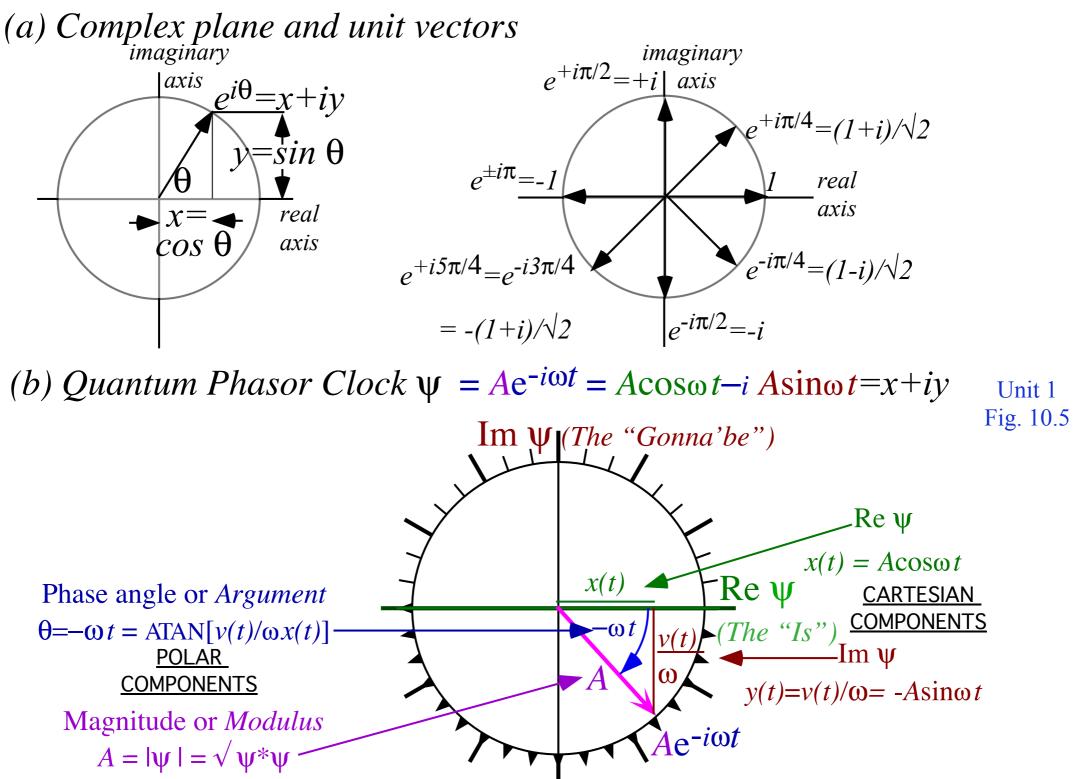
1. Complex numbers provide "automatic trigonometry"

Can't remember is $\cos(a+b)$ or $\sin(a+b)$? Just factor $e^{i(a+b)} = e^{ia}e^{ib}$...

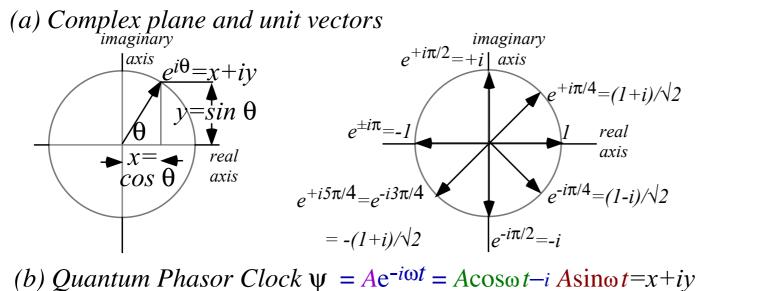


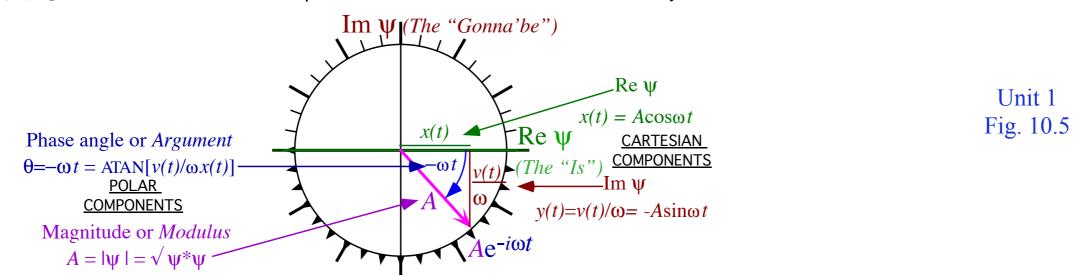
2. Complex numbers add like vectors. $z_{Sum} = z + z' = (x + iy) + (x' + iy') = (x + x') + i(y + y')$ $z_{diff} = z - z' = (x + iy) - (x' + iy') = (x - x') + i(y - y')$ (a) y = Im z' y' = Im z' x' = Re z'(b) z' z'z'

3.Complex exponentials Ae^{-iwt} track position <u>and</u> velocity using Phasor Clock.



3.Complex exponentials Ae^{-iwt} track position <u>and</u> velocity using Phasor Clock.





Some Rect-vs-Polar relations worth remembering

Cartesian

$$\begin{cases}
\psi_x = \operatorname{Re}\psi(t) = x(t) = A\cos\omega t = \frac{\psi + \psi^*}{2} \\
\psi_y = \operatorname{Im}\psi(t) = \frac{v(t)}{\omega} = -A\sin\omega t = \frac{\psi - \psi^*}{2i} \\
\psi = re^{+i\theta} = re^{-i\omega t} = r(\cos\omega t - i\sin\omega t) \\
\psi^* = re^{-i\theta} = re^{+i\omega t} = r(\cos\omega t + i\sin\omega t)
\end{cases}$$

$$Polar \begin{cases} r = A = |\psi| = \sqrt{\psi_x^2 + \psi_y^2} = \sqrt{\psi * \psi} \\ \theta = -\omega t = \arctan(\psi_y / \psi_x) \end{cases}$$
$$\cos \theta = \frac{1}{2} (e^{+i\theta} + e^{-i\theta})$$
$$\sin \theta = \frac{1}{2i} (e^{+i\theta} - e^{-i\theta})$$

4. Complex products provide 2D rotation operations.

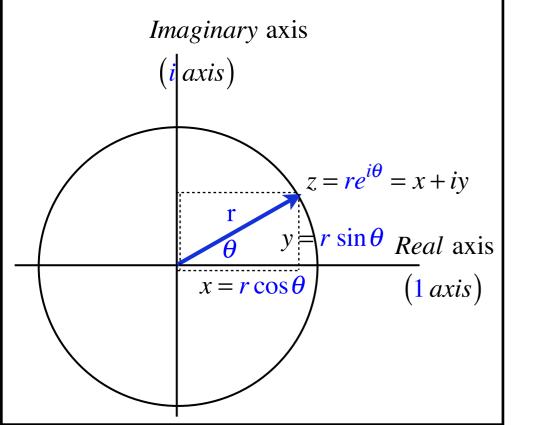
$$e^{i\phi} \cdot z = (\cos\phi + i\sin\phi) \cdot (x + iy) = x\cos\phi - y\sin\phi + i \quad (x\sin\phi + y\cos\phi)$$
$$\mathbf{R}_{+\phi} \cdot \mathbf{r} = (x\cos\phi - y\sin\phi) \hat{\mathbf{e}}_x + (x\sin\phi + y\cos\phi) \hat{\mathbf{e}}_y$$
$$\begin{pmatrix} \cos\phi & -\sin\phi\\ \sin\phi & \cos\phi \end{pmatrix} \cdot \begin{pmatrix} x\\ y \end{pmatrix} = \begin{pmatrix} x\cos\phi - y\sin\phi\\ x\sin\phi + y\cos\phi \end{pmatrix}$$

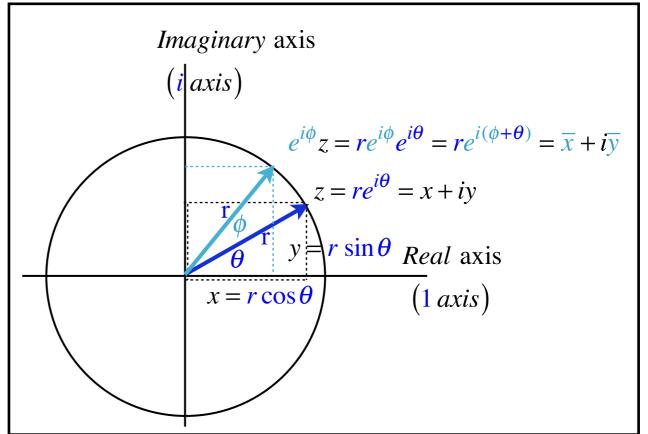
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 $e^{i\phi}$ acts on this: $z = re^{i\theta}$

to give this: $e^{i\phi} e^{i\phi} z = r e^{i\phi} e^{i\theta}$





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5. Complex products provide 2D "dot"(•) and "cross"(x) products.

Two complex numbers $A = A_x + iA_y$ and $B = B_x + iB_y$ and their "star" (*)-product A * B.

$$A * B = (A_x + iA_y)^* (B_x + iB_y) = (A_x - iA_y)(B_x + iB_y)$$

= $(A_x B_x + A_y B_y) + i(A_x B_y - A_y B_x) = \mathbf{A} \cdot \mathbf{B} + i | \mathbf{A} \times \mathbf{B} |_{Z \perp (x,y)}$
Real part is scalar or "dot"(•) product $\mathbf{A} \cdot \mathbf{B}$.
Imaginary part is vector or "cross"(×) product, but just the Z-component normal to xy-plane.

Rewrite *A***B* in polar form.

$$A * B = (|A|e^{i\theta_A})^* (|B|e^{i\theta_B}) = |A|e^{-i\theta_A}|B|e^{i\theta_B} = |A||B|e^{i(\theta_B - \theta_A)}$$
$$= |A||B|\cos(\theta_B - \theta_A) + i|A||B|\sin(\theta_B - \theta_A) = \mathbf{A} \cdot \mathbf{B} + i|\mathbf{A} \times \mathbf{B}|_{Z\perp(x,y)}$$

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Rewrite *A***B* in polar form.

Real part

$$A * B = (|A| e^{i\theta_A})^* (|B| e^{i\theta_B}) = |A| e^{-i\theta_A} |B| e^{i\theta_B} = |A| |B| e^{i(\theta_B - \theta_A)}$$
$$= |A| |B| \cos(\theta_B - \theta_A) + i|A| |B| \sin(\theta_B - \theta_A) = \mathbf{A} \cdot \mathbf{B} + i|\mathbf{A} \times \mathbf{B}|_{Z\perp(x,y)}$$
$$\mathbf{A} \cdot \mathbf{B} = |A| |B| \cos(\theta_B - \theta_A)$$
$$|\mathbf{A} \times \mathbf{B}| = |A| |B| \sin(\theta_B - \theta_A)$$
$$= |A| \cos\theta_A |B| \cos\theta_B + |A| \sin\theta_A |B| \sin\theta_B$$
$$= |A| \cos\theta_A |B| \sin\theta_B - |A| \sin\theta_A |B| \cos\theta_B$$
$$= A_x B_x + A_y B_y$$
$$= A_x B_y - A_y B_x$$

=

=

6. Complex derivative contains "divergence" ($\nabla \cdot \mathbf{F}$) and "curl" ($\nabla \mathbf{xF}$) of 2D vector field Relation of (z,z^*) to $(x=\operatorname{Rez},y=\operatorname{Imz})$ defines a z-derivative $\frac{df}{dz}$ and "star" z^* -derivative. $\frac{df}{dz^*}$ z = x + iy $x = \frac{1}{2}(z + z^*)$ $z^* = x - iy$ $y = \frac{1}{2i}(z - z^*)$ $\stackrel{Applying}{chain-rule}$ $\frac{df}{dz} = \frac{\partial x}{\partial z} \frac{\partial f}{\partial x} + \frac{\partial y}{\partial z} \frac{\partial f}{\partial y} = \frac{1}{2} \frac{\partial f}{\partial x} - \frac{i}{2} \frac{\partial f}{\partial y}$ $\frac{df}{dz^*} = \frac{\partial x}{\partial z} \frac{\partial f}{\partial x} + \frac{\partial y}{\partial z} \frac{\partial f}{\partial y} = \frac{1}{2} \frac{\partial f}{\partial x} + \frac{i}{2} \frac{\partial f}{\partial y}$

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$$z = x + iy \qquad x = \frac{1}{2} (z + z^*) \qquad \frac{df}{dz} = \frac{\partial x \partial f}{\partial z \partial x} + \frac{\partial y \partial f}{\partial z \partial y} = \frac{1}{2} \frac{\partial f}{\partial x} - \frac{i}{2} \frac{\partial f}{\partial y}$$
$$z^* = x - iy \qquad y = \frac{1}{2i} (z - z^*) \qquad \frac{df}{dz^*} = \frac{\partial x}{\partial z^* \partial x} + \frac{\partial y}{\partial z} \frac{\partial f}{\partial y} = \frac{1}{2} \frac{\partial f}{\partial x} + \frac{i}{2} \frac{\partial f}{\partial y}$$

Derivative chain-rule shows real part of $\frac{df}{dz}$ has 2D divergence $\nabla \cdot \mathbf{f}$ and imaginary part has curl $\nabla \times \mathbf{f}$.

$$\frac{df}{dz} = \frac{d}{dz} \left(f_x + i f_y \right) = \frac{1}{2} \left(\frac{\partial f}{\partial x} - i \frac{\partial f}{\partial y} \right) \left(f_x + i f_y \right) = \frac{1}{2} \left(\frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} \right) + \frac{i}{2} \left(\frac{\partial f_y}{\partial x} - \frac{\partial f_x}{\partial y} \right) = \frac{1}{2} \nabla \bullet \mathbf{f} + \frac{i}{2} |\nabla \times \mathbf{f}|_{Z \perp (x, y)}$$

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7. Invent source-free 2D vector fields $[\nabla \cdot \mathbf{F}=0 \text{ and } \nabla \mathbf{x}\mathbf{F}=0]$

We can invent *source-free 2D vector fields* that are both *zero-divergence* and *zero-curl*. Take any function f(z), conjugate it (change all *i*'s to -i) to give $f^*(z^*)$ for which $\frac{df^*}{dz} = 0$.

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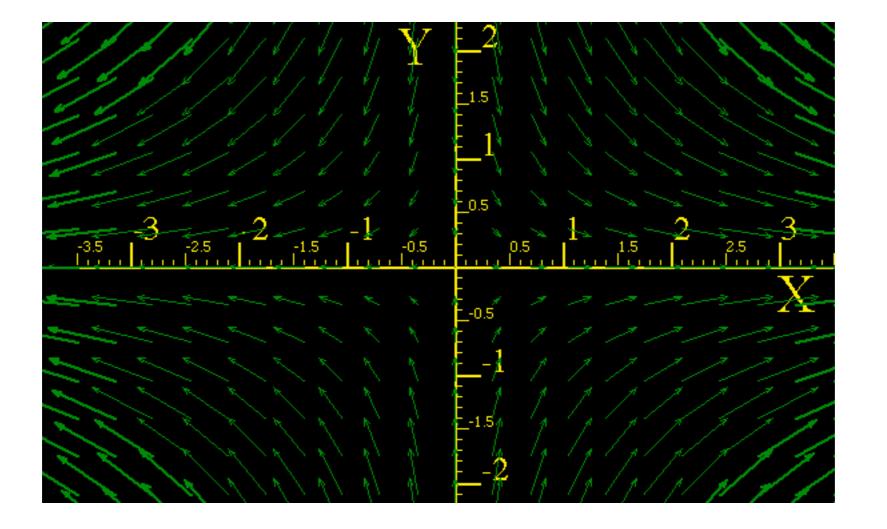
For example: if $f(z)=a\cdot z$ then $f^*(z^*)=a\cdot z^*=a(x-iy)$ is not function of z so it has zero z-derivative. $\mathbf{F}=(F_x,F_y)=(f^*_x,f^*_y)=(a\cdot x,-a\cdot y)$ has zero divergence: $\nabla \cdot \mathbf{F}=0$ and has zero curl: $|\nabla \times \mathbf{F}|=0$.

$$\nabla \bullet \mathbf{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} = \frac{\partial (ax)}{\partial x} + \frac{\partial F(-ay)}{\partial y} = 0 \qquad \qquad |\nabla \times \mathbf{F}|_{Z\perp(x,y)} = \frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} = \frac{\partial (-ay)}{\partial x} - \frac{\partial F(ax)}{\partial y} = 0$$

7. (contd.) Invent source-free 2D vector fields $[\nabla \cdot \mathbf{F}=0 \text{ and } \nabla x \mathbf{F}=0]$

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For example, if $f(z) = a \cdot z$ then $f^*(z^*) = a \cdot z^* = a(x - iy)$ is not function of z so it has zero z-derivative. $\mathbf{F} = (F_x, F_y) = (f^*_x, f^*_y) = (a \cdot x, -a \cdot y)$ has zero divergence: $\nabla \cdot \mathbf{F} = 0$ and has zero curl: $|\nabla \times \mathbf{F}| = 0$.



precursor to Unit 1 Fig. 10.7

 $\mathbf{F}=(f_{x}^{*},f_{y}^{*})=(a\cdot x,-a\cdot y)$ is a *divergence-free laminar (DFL)* field.

8. Complex potential ϕ contains "scalar" ($\mathbf{F}=\nabla \Phi$) and "vector" ($\mathbf{F}=\nabla x\mathbf{A}$) potentials

Any *DFL* field **F** is a gradient of a *scalar potential field* Φ or a curl of a *vector potential field* **A**. **F**= $\nabla \Phi$ **F**= $\nabla \times \mathbf{A}$

A *complex potential* $\phi(z) = \Phi(x,y) + iA(x,y)$ exists whose *z*-derivative is $f(z) = d\phi/dz$.

Its complex conjugate $\phi^*(z^*) = \Phi(x,y) - iA(x,y)$ has z^* -derivative $f^*(z^*) = d\phi^*/dz^*$ giving *DFL* field **F**.

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To find $\phi = \Phi + iA$ integrate $f(z) = a \cdot z$ to get ϕ and isolate real ($\mathsf{Re}\phi = \Phi$) and imaginary ($\mathsf{Im}\phi = A$) parts.

$$\phi = \frac{\Phi}{=\frac{1}{2}a(x^2 - y^2)} + i \quad A = \int f \cdot dz = \int az \cdot dz = \frac{1}{2}az^2 = \frac{1}{2}a(x + iy)^2$$

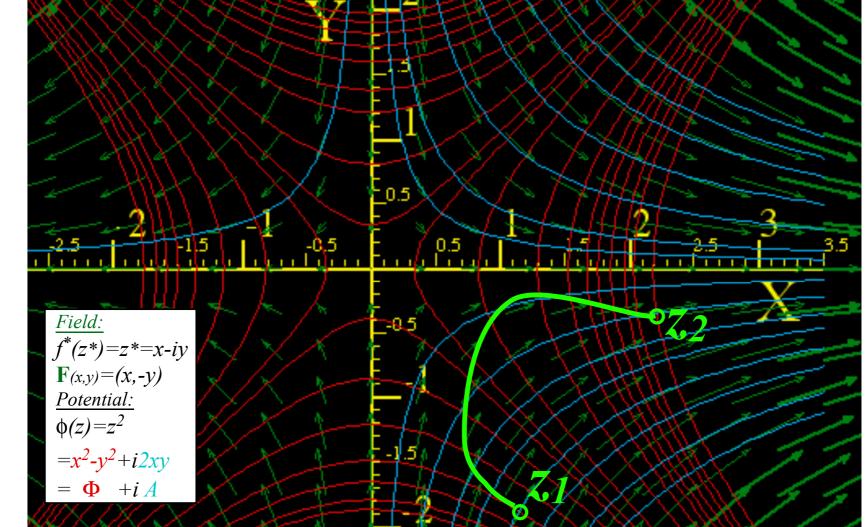
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$$\phi = \frac{\Phi}{|a|^2 - y^2} + i \quad A = \int f \cdot dz = \int az \cdot dz = \frac{1}{2} az^2 = \frac{1}{2} a(x + iy)^2$$



Unit 1 Fig. 10.7

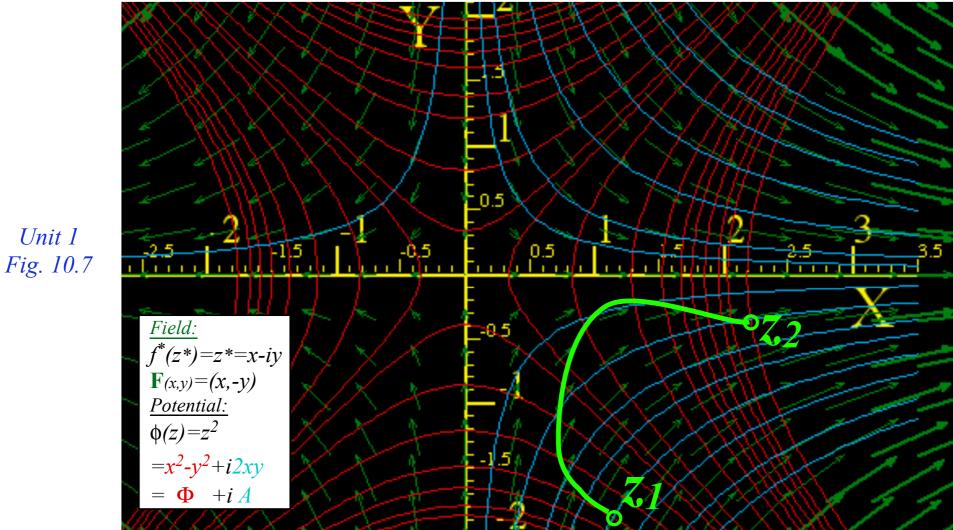
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To find $\phi = \Phi + iA$ integrate $f(z) = a \cdot z$ to get ϕ and isolate real (Re $\phi = \Phi$) and imaginary (Im $\phi = A$) parts.

+*i* $A = \int f \cdot dz = \int az \cdot dz = \frac{1}{2} az^2 = \frac{1}{2} a(x + iy)^2$ $= \underbrace{\Phi}_{=\frac{1}{2}a(x^2 - y^2)} + i \underbrace{A}_{=\frac{1}{2}a(x^2 - y^2)} + i \underbrace{A}_{=\frac{1}{2}a(x^2 - y^2)}$ $\phi =$



BONUS! *Get a free* coordinate system!

The (Φ, A) grid is a GCC coordinate system*: $q^{l} = \Phi = (x^{2} - y^{2})/2 = const.$ $q^2 = \mathbf{A} = (xy) = const.$

*Actually it's OCC.

Unit 1

8. (contd.) Complex potential ϕ contains "scalar"($F=\nabla \Phi$) and "vector"($F=\nabla xA$) potentials ...and either one (or half-n'-half!) works just as well.

Derivative $\frac{d\phi^*}{dz^*}$ has 2D gradient $\nabla \Phi = \begin{pmatrix} \frac{\partial \Phi}{\partial x} \\ \frac{\partial \Phi}{\partial y} \\ \frac{\partial \Phi}{\partial y} \end{pmatrix}$ of scalar Φ and curl $\nabla \times \mathbf{A} = \begin{pmatrix} \frac{\partial A}{\partial y} \\ -\frac{\partial A}{\partial y} \end{pmatrix}$ of vector \mathbf{A} (and they 're <u>equal</u>!) $\frac{d}{dz^*} \phi^* = \frac{d}{dz^*} (\Phi - i\mathbf{A}) = \frac{1}{2} (\frac{\partial}{\partial x} + i\frac{\partial}{\partial y}) (\Phi - i\mathbf{A}) = \frac{1}{2} (\frac{\partial \Phi}{\partial x} + i\frac{\partial \Phi}{\partial y}) + \frac{1}{2} (\frac{\partial A}{\partial y} - i\frac{\partial A}{\partial x}) = \frac{1}{2} \nabla \Phi + \frac{1}{2} \nabla \times \mathbf{A}$

8. (contd.) Complex potential ϕ contains "scalar"($F=\nabla \Phi$) and "vector"($F=\nabla xA$) potentials ...and either one (or half-n'-half!) works just as well.

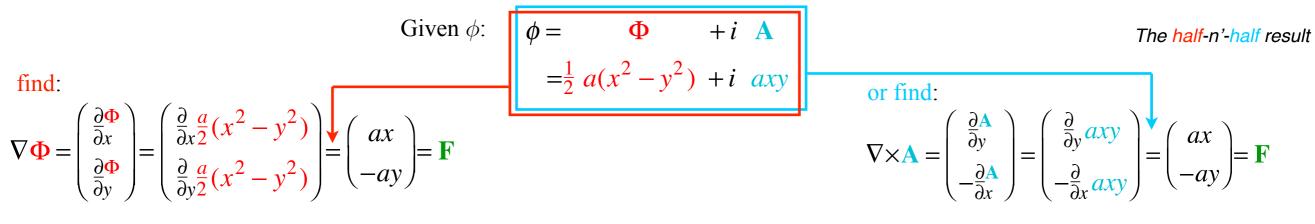
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Note, *mathematician definition* of force field $\mathbf{F} = +\nabla \Phi$ replaces usual physicist's definition $\mathbf{F} = -\nabla \Phi$

8. (contd.) Complex potential ϕ contains "scalar"($F=\nabla \Phi$) and "vector"($F=\nabla xA$) potentials ...and either one (or half-n'-half!) works just as well.

Derivative
$$\frac{d\phi^*}{dz^*}$$
 has 2D gradient $\nabla \Phi = \begin{pmatrix} \frac{\partial \Phi}{\partial x} \\ \frac{\partial \Phi}{\partial y} \end{pmatrix}$ of scalar Φ and curl $\nabla \times \mathbf{A} = \begin{pmatrix} \frac{\partial \mathbf{A}}{\partial y} \\ -\frac{\partial \mathbf{A}}{\partial y} \end{pmatrix}$ of vector \mathbf{A} (and they 're equal!)
$$\frac{d}{dz^*} \phi^* = \frac{d}{dz^*} (\Phi - i\mathbf{A}) = \frac{1}{2} (\frac{\partial}{\partial x} + i\frac{\partial}{\partial y}) (\Phi - i\mathbf{A}) = \frac{1}{2} (\frac{\partial \Phi}{\partial x} + i\frac{\partial \Phi}{\partial y}) + \frac{1}{2} (\frac{\partial \mathbf{A}}{\partial y} - i\frac{\partial \mathbf{A}}{\partial x}) = \frac{1}{2} \nabla \Phi + \frac{1}{2} \nabla \times \mathbf{A}$$

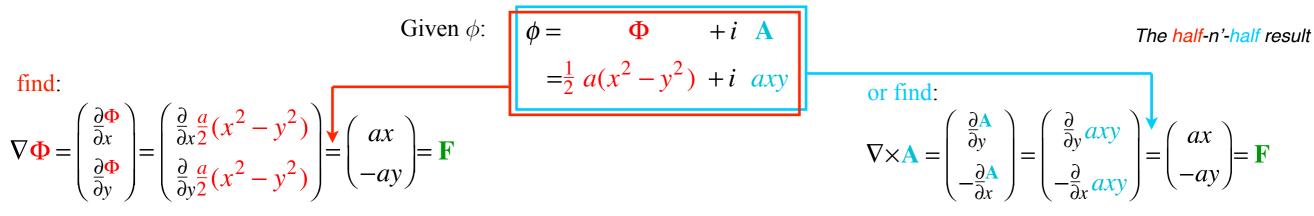
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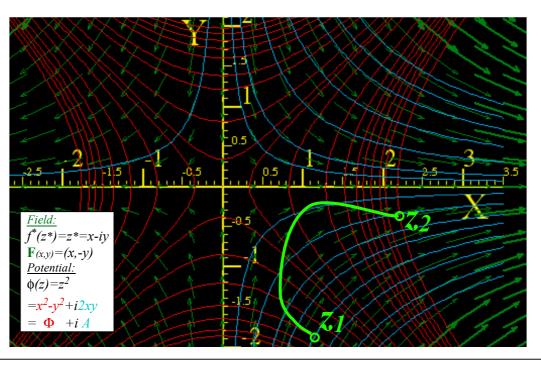
8. (contd.) Complex potential ϕ contains "scalar"($F=\nabla \Phi$) and "vector"($F=\nabla xA$) potentials ...and either one (or half-n'-half!) works just as well.

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Note, *mathematician definition* of force field $\mathbf{F} = +\nabla \Phi$ replaces usual physicist's definition $\mathbf{F} = -\nabla \Phi$



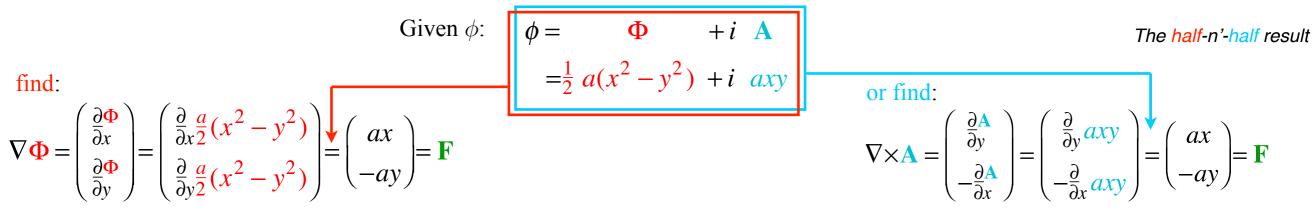
Scalar *static potential lines* Φ =*const.* and vector *flux potential lines* A=*const.* define *DFL field-net.*



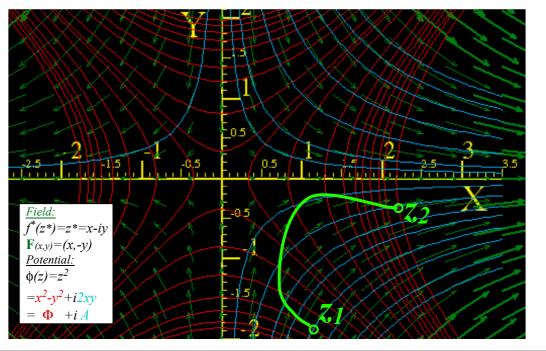
8. (contd.) Complex potential ϕ contains "scalar"($F=\nabla \Phi$) and "vector"($F=\nabla xA$) potentials ...and either one (or half-n'-half!) works just as well.

Derivative
$$\frac{d\phi^*}{dz^*}$$
 has 2D gradient $\nabla \Phi = \begin{pmatrix} \frac{\partial \Phi}{\partial x} \\ \frac{\partial \Phi}{\partial y} \end{pmatrix}$ of scalar Φ and curl $\nabla \times \mathbf{A} = \begin{pmatrix} \frac{\partial \mathbf{A}}{\partial y} \\ -\frac{\partial \mathbf{A}}{\partial y} \end{pmatrix}$ of vector \mathbf{A} (and they 're equal!)
The half-n'-half result
 $\frac{d}{dz^*} \phi^* = \frac{d}{dz^*} (\Phi - i\mathbf{A}) = \frac{1}{2} (\frac{\partial}{\partial x} + i\frac{\partial}{\partial y}) (\Phi - i\mathbf{A}) = \frac{1}{2} (\frac{\partial\Phi}{\partial x} + i\frac{\partial\Phi}{\partial y}) + \frac{1}{2} (\frac{\partial\Phi}{\partial y} - i\frac{\partial\mathbf{A}}{\partial x}) = \frac{1}{2} \nabla \Phi + \frac{1}{2} \nabla \times \mathbf{A}$

Note, *mathematician definition* of force field $\mathbf{F} = +\nabla \Phi$ replaces usual physicist's definition $\mathbf{F} = -\nabla \Phi$



Scalar *static potential lines* Φ =*const.* and vector *flux potential lines* A=*const.* define *DFL field-net.*



The half-n'-half results are called Riemann-Cauchy Derivative Relations

$$\frac{\partial \Phi}{\partial x} = \frac{\partial A}{\partial y} \quad \text{is:} \quad \frac{\partial \text{Re}f(z)}{\partial x} = \quad \frac{\partial \text{Im}f(z)}{\partial y}$$
$$\frac{\partial \Phi}{\partial y} = -\frac{\partial A}{\partial x} \quad \text{is:} \quad \frac{\partial \text{Re}f(z)}{\partial y} = -\frac{\partial \text{Im}f(z)}{\partial x}$$

9. Complex integrals f (z)dz count 2D "circulation" (**F**•dr) and "flux" (**F**xdr)

Integral of f(z) between point z_1 and point z_2 is potential difference $\Delta \phi = \phi(z_2) - \phi(z_1)$ $\Delta \phi = \phi(z_2) - \phi(z_1) = \int_{z_1}^{z_2} f(z) dz = \Phi(x_2, y_2) - \Phi(x_1, y_1) + i[A(x_2, y_2) - A(x_1, y_1)]$ $\Delta \phi = \Delta \Phi + i \Delta A$

In *DFL* field **F**, $\Delta \phi$ is independent of the integration path z(t) connecting z_1 and z_2 .