Lecture 16 thru 17 Thur. 3.10. to Tue. 3.15.2016

Introduction to coupled oscillation and eigenmodes (Ch. 3-4 of Unit 2)

Review of 1D FDHO (Forced-Damped-Harmonic Oscillator) response Amplitude and phase variation due to resonance

2D harmonic oscillator (2D-HO) equations of motion Lagrangian and matrix forms

2D harmonic oscillator equation eigensolutions (normal modes) 2D classical HO compared to U(2) quantum 2-state system Introducing ABCD Hamilton Pauli spinor symmetry expansion

Eigensolutions by geometry for 2D-HO with bilateral (B-Type) symmetry Symmetric (low frequency) mode versus antisymmetric (high frequency) mode Mixed mode beat dynamics (with constant $\pi/2$ phase-lag) Geometry of phase and polarization

Eigensolutions by matrix-algebra with example $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$ Secular equation Hamilton-Cayley equation and projectors Idempotent projectors (how eigenvalues \Rightarrow eigenvectors) Operator orthonormality and Completeness (Idempotent means: $\mathbf{P} \cdot \mathbf{P} = \mathbf{P}$) Spectral Decompositions Functional spectral decomposition



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link to time plot

Response functions for very low q oscillator



link to response



Lorentz Response ($\Gamma=0.2$)

link to time plot









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link to time plot



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2D HO kinetic energy $T(v_1, v_2)$

$$T = \frac{1}{2}m_1\dot{x}_1^2 + \frac{1}{2}m_2\dot{x}_2^2$$



2D HO kinetic energy $T(v_1, v_2)$ $T = \frac{1}{2}m_1\dot{x}_1^2 + \frac{1}{2}m_2\dot{x}_2^2$ $2D \text{ HO potential energy } V(x_1, x_2)$ $V = \frac{1}{2}k_1x_1^2 + \frac{1}{2}k_2x_2^2 + \frac{1}{2}k_{12}(x_1 - x_2)^2$ $= \frac{1}{2}(k_1 + k_{12})x_1^2 - k_{12}x_1x_2 + \frac{1}{2}(k_2 + k_{12})x_2^2$

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Lagrange-Newton equations for 2D HO

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_1} \right) = m_1 \ddot{x}_1 = F_1 = -\frac{\partial V}{\partial x_1} = -\left(k_1 + k_{12}\right) x_1 + k_{12} x_2$$
$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_2} \right) = m_2 \ddot{x}_2 = F_2 = -\frac{\partial V}{\partial x_2} = k_{12} x_1 - \left(k_2 + k_{12}\right) x_2$$



2D HO kinetic energy $T(v_1, v_2)$ 2D HO potential energy $V(x_1, x_2)$ $T = \frac{1}{2}m_1\dot{x}_1^2 + \frac{1}{2}m_2\dot{x}_2^2$ $V = \frac{1}{2}k_1x_1^2 + \frac{1}{2}k_2x_2^2 + \frac{1}{2}k_{12}\left(x_1 - x_2\right)^2$ $=\frac{1}{2}(k_1+k_{12})x_1^2-k_{12}x_1x_2+\frac{1}{2}(k_2+k_{12})x_2^2$ Lagrange-Newton equations for 2D HO

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2D HO Matrix operator equations

$$\begin{pmatrix} m_{1} & 0 \\ 0 & m_{2} \end{pmatrix} \begin{pmatrix} \ddot{x}_{1} \\ \ddot{x}_{2} \end{pmatrix} = - \begin{pmatrix} k_{1} + k_{12} & -k_{12} \\ -k_{12} & k_{2} + k_{12} \end{pmatrix} \begin{pmatrix} x_{1} \\ x_{2} \end{pmatrix}$$



2D HO kinetic energy $T(v_1, v_2)$ 2D HO potential energy $V(x_1, x_2)$ $T = \frac{1}{2}m_1\dot{x}_1^2 + \frac{1}{2}m_2\dot{x}_2^2$ $V = \frac{1}{2}k_1x_1^2 + \frac{1}{2}k_2x_2^2 + \frac{1}{2}k_{12}\left(x_1 - x_2\right)^2$ $=\frac{1}{2}(k_1+k_{12})x_1^2-k_{12}x_1x_2+\frac{1}{2}(k_2+k_{12})x_2^2$ Lagrange-Newton equations for 2D HO $\frac{d}{dt}\left(\frac{\partial T}{\partial \dot{x}_1}\right) = m_1 \ddot{x}_1 = F_1 = -\frac{\partial V}{\partial x_1} = -\left(k_1 + k_{12}\right)x_1 + k_{12}x_2$

 $\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_2} \right) = m_2 \ddot{x}_2 = F_2 = -\frac{\partial V}{\partial x_2} = k_{12} x_1 - \left(k_2 + k_{12} \right) x_2$

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Matrix operator notation:

$$\mathbf{M} \cdot |\ddot{\mathbf{x}}\rangle = -\mathbf{K} \cdot |\mathbf{x}\rangle$$

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2D HO kinetic energy
$$T(v_1, v_2)$$

 $T = \frac{1}{2}m_1\dot{x}_1^2 + \frac{1}{2}m_2\dot{x}_2^2$
 $= \frac{1}{2}\langle \dot{\mathbf{x}} | \mathbf{M} | \dot{\mathbf{x}} \rangle$
2D HO potential energy $V(x_1, x_2)$
 $V = \frac{1}{2}(k_1 + k_{12})x_1^2 - k_{12}x_1x_2 + \frac{1}{2}(k_2 + k_{12})x_2^2$
 $= \frac{1}{2}\langle \mathbf{x} | \mathbf{K} | \mathbf{x} \rangle$ where: $\mathbf{K} = \begin{pmatrix} k_1 + k_{12} & -k_{12} \\ -k_{12} & k_2 + k_{12} \end{pmatrix}$

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_1} \right) = m_1 \ddot{x}_1 = F_1 = -\frac{\partial V}{\partial x_1} = -\left(k_1 + k_{12}\right) x_1 + k_{12} x_2$$
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2. Need to find *eigenvectors* $|\mathbf{e}_1\rangle$, $|\mathbf{e}_2\rangle$,... of acceleration matrix such that: $\mathbf{A}|\mathbf{e}_n\rangle = \varepsilon_n|\mathbf{e}_n\rangle = \omega_n^2|\mathbf{e}_n\rangle$

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 so: $|\mathbf{e}_1(t)\rangle = e^{-i\omega_1 t} |\mathbf{e}_1(0)\rangle$

where ε_1 is 1st eigenvalue and ω_1 is 1st eigenfrequency

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 so: $|\mathbf{e}_2(t)\rangle = e^{-i\omega_2 t} |\mathbf{e}_2(0)\rangle$
where ε_2 is 2^{nd} eigenvalue and ω_2 is 2^{nd} eigenfrequency

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To introduce eigensolutions we take a simple case of unit masses $(m_1 = l = m_2)$

So equation of motion is simply: $|\ddot{\mathbf{x}}\rangle = -\mathbf{K}|\mathbf{x}\rangle$

1. May rewrite equation $\mathbf{M} \cdot |\ddot{\mathbf{x}}\rangle = -\mathbf{K} \cdot |\mathbf{x}\rangle$ in *acceleration* matrix form: $|\ddot{\mathbf{x}}\rangle = -\mathbf{A}|\mathbf{x}\rangle$ where: $\mathbf{A} = \mathbf{M}^{-1} \cdot \mathbf{K}$

$$\begin{pmatrix} \ddot{x}_{1} \\ \ddot{x}_{2} \end{pmatrix} = - \begin{pmatrix} m_{1} & 0 \\ 0 & m_{2} \end{pmatrix}^{-1} \begin{pmatrix} k_{1} + k_{12} & -k_{12} \\ -k_{12} & k_{2} + k_{12} \end{pmatrix} \begin{pmatrix} x_{1} \\ x_{2} \end{pmatrix} = - \begin{pmatrix} \frac{k_{1} + k_{12}}{m_{1}} & \frac{-k_{12}}{m_{1}} \\ \frac{-k_{12}}{m_{2}} & \frac{k_{2} + k_{12}}{m_{2}} \end{pmatrix} \begin{pmatrix} x_{1} \\ x_{2} \end{pmatrix}$$

2. Need to find *eigenvectors* $|\mathbf{e}_1\rangle$, $|\mathbf{e}_2\rangle$,... of acceleration matrix such that: $\mathbf{A}|\mathbf{e}_n\rangle = \varepsilon_n|\mathbf{e}_n\rangle = \omega_n^2|\mathbf{e}_n\rangle$

Then equations decouple to:
$$\frac{d^2}{dt^2} |\mathbf{e}_1\rangle = |\ddot{\mathbf{e}}_1\rangle = -\mathbf{A} |\mathbf{e}_1\rangle = -\mathbf{E}_1 |\mathbf{e}_1\rangle = -\mathbf{\omega}_1^2 |\mathbf{e}_1\rangle \text{ so: } |\mathbf{e}_1(t)\rangle = e^{-i\omega_1 t} |\mathbf{e}_1(0)\rangle$$

where ε_1 is 1st eigenvalue and ω_1 is 1st eigenfrequency

and:
$$\frac{d^2}{dt^2} |\mathbf{e}_2\rangle \equiv |\ddot{\mathbf{e}}_2\rangle = -\mathbf{A} |\mathbf{e}_2\rangle = -\varepsilon_2 |\mathbf{e}_2\rangle = -\omega_2^2 |\mathbf{e}_2\rangle \text{ so: } |\mathbf{e}_2(t)\rangle = e^{-i\omega_2 t} |\mathbf{e}_2(0)\rangle$$

where ε_2 is 2^{nd} eigenvalue and ω_2 is 2^{nd} eigenfrequency

To introduce eigensolutions we take a simple case of unit masses $(m_1=1=m_2)$

So equation of motion is simply: $|\ddot{\mathbf{x}}\rangle = -\mathbf{K}|\mathbf{x}\rangle$

Eigenvectors $|\mathbf{x}\rangle = |\mathbf{e}_n\rangle$ are in special directions where $|\ddot{\mathbf{x}}\rangle = -\mathbf{K}|\mathbf{x}\rangle$ is in same direction as $|\mathbf{x}\rangle$

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$$\frac{d^2}{dt^2} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = - \begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \quad \text{versus} \quad \hbar i \frac{d}{dt} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} H_{11} & H_{12} \\ H_{12}^* & H_{22} \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}$$

$$\frac{d^2}{dt^2} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = - \begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \quad \text{versus} \quad \hbar i \frac{d}{dt} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} H_{11} & H_{12} \\ H_{12}^* & H_{22} \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} \\ \frac{d^2}{dt^2} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = - \begin{pmatrix} G & H-iJ \\ H+iJ & K \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \text{versus} \quad \hbar i \frac{d}{dt} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix}$$

Modern theorists use natural units so $\hbar = 1.05 \cdot 10^{-34}$ *equals* $\hbar = 1$

$$\frac{d^2}{dt^2} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = - \begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \quad \text{versus} \quad \hbar i \frac{d}{dt} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} H_{11} & H_{12} \\ H_{12}^* & H_{22} \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} \\ \frac{d^2}{dt^2} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = - \begin{pmatrix} G & H-iJ \\ H+iJ & K \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \text{versus} \quad \hbar i \frac{d}{dt} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix}$$

Modern theorists use natural units so $\hbar = 1.05 \cdot 10^{-34}$ *equals* $\hbar = 1$

Let us square the quantum operator $i\frac{d}{dt} = \begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix}$

$$\frac{d^2}{dt^2} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = - \begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \quad \text{versus} \quad \hbar i \frac{d}{dt} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} H_{11} & H_{12} \\ H_{12}^* & H_{22} \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} \\ \frac{d^2}{dt^2} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = - \begin{pmatrix} G & H-iJ \\ H+iJ & K \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \text{versus} \quad \hbar i \frac{d}{dt} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix}$$

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Let us square the quantum operator
$$i\frac{d}{dt} = \begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix}$$

 $i\frac{d}{dt}i\frac{d}{dt} = \begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix} \begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix} = \begin{pmatrix} A^2+B^2+C^2 & (B-iC)(A+D) \\ (B+iC)(A+D) & D^2+B^2+C^2 \end{pmatrix}$

$$\frac{d^2}{dt^2} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = -\begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \quad \text{versus} \quad \hbar i \frac{d}{dt} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} H_{11} & H_{12} \\ H_{12}^* & H_{22} \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} \\ \frac{d^2}{dt^2} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = -\begin{pmatrix} G & H-iJ \\ H+iJ & K \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \quad \text{versus} \quad \hbar i \frac{d}{dt} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix}$$

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 $-\frac{d^2}{dt^2} = \mathbf{H}^2 = \begin{pmatrix} A^2+B^2+C^2 & (B-iC)(A+D) \\ (B+iC)(A+D) & D^2+B^2+C^2 \end{pmatrix}$

$$\frac{d^2}{dt^2} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = -\begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \quad \text{versus} \quad \hbar i \frac{d}{dt} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} H_{11} & H_{12} \\ H_{12}^* & H_{22} \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} \\ \frac{d^2}{dt^2} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = -\begin{pmatrix} G & H-iJ \\ H+iJ & K \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \quad \text{versus} \quad \hbar i \frac{d}{dt} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix}$$

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$$i\frac{d}{dt} = \begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix}$$

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 $-\frac{d^2}{dt^2} = \mathbf{H}^2 = \begin{pmatrix} A^2 + B^2 + C^2 & (B-iC)(A+D) \\ (B+iC)(A+D) & D^2 + B^2 + C^2 \end{pmatrix}$

2D classical HO same as the U(2) quantum 2-state system ...if we set K-spring matrix to squared quantum operator H²

$$\mathbf{K} = \begin{pmatrix} k_{11} & k_{12} - i \cdot j_{12} \\ k_{12} - i \cdot j_{12} & k_{22} \end{pmatrix} = \begin{pmatrix} G & H - i \cdot J \\ H + i \cdot J & K \end{pmatrix} = \mathbf{H}^2 = \begin{pmatrix} A^2 + B^2 + C^2 & (B - iC)(A + D) \\ (B + iC)(A + D) & D^2 + B^2 + C^2 \end{pmatrix}$$

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Introducing ABCD Hamilton Pauli spinor symmetry expansion

Decompose the Hamiltonian operator **H** into four *ABCD symmetry operators* (Labeled to provide dynamic mnemonics as well as colorful analogies)

$$\begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix} = A \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + B \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + C \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + D \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = A\mathbf{e}_{11} + B\mathbf{\sigma}_B + C\mathbf{\sigma}_C + D\mathbf{e}_{22}$$
$$= \frac{A-D}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} + B \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + C \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \frac{A+D}{2} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Introducing ABCD Hamilton Pauli spinor symmetry expansion

Decompose the Hamiltonian operator **H** into four *ABCD symmetry operators* (Labeled to provide dynamic mnemonics as well as colorful analogies)

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$$= \frac{A-D}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} + B \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + C \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} + \frac{A+D}{2} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$
$$\mathbf{H} = \frac{A-D}{2} \mathbf{\sigma}_A + B \mathbf{\sigma}_B + C \mathbf{\sigma}_C + \frac{A+D}{2} \mathbf{\sigma}_0 \qquad \dots current-carrier...$$

Symmetry archetypes: *A (Asymmetric-diagonal) B (Bilateral-balanced) C (Chiral-circular-complex-Coriolis-cyclotron-curly...)* Color scheme based on traffic signals

STOP (standing waves)

CAUTION (stretched waves)

GO (moving waves)
Introducing ABCD Hamilton Pauli spinor symmetry expansion

Decompose the Hamiltonian operator **H** into four *ABCD symmetry operators* (Labeled to provide dynamic mnemonics as well as colorful analogies)

Symmetry archetypes: *A (Asymmetric-diagonal) B (Bilateral-balanced) C (Chiral-circular-complex-Coriolis-cyclotron-curly...)* Color scheme based on traffic signals

STOP (standing waves)

```
CAUTION (stretched waves)
```

GO (moving waves)



Fig. 3.4.1 Potentials for (a) C_2^A -asymmetric-diagonal, (ab) C_2^{AB} -mixed, (b) C_2^B -bilateral U(2)system.

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Fig. 3.3.4 Plot of potential function $V(x_1,x_2)$ *showing elliptical* $V(x_1,x_2)$ *=const. level curves.*



(details of gradient expression)



(details of gradient expression)

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Fig. 3.3.5 Topography lines of potential function $V(x_1,x_2)$ and orthogonal ε_+ and ε_- normal mode slopes

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B-Type coupling

$$\begin{pmatrix} A & B-iC \\ B+iC & D \end{pmatrix} = \begin{pmatrix} A & B \\ B & A \end{pmatrix}$$

Spring set down for STRONGER coupling (higher |B|)

Spring set *up* for weaker coupling (lower |B|)





http://www.uark.edu/ua/modphys/markup/BoxItWeb.html?

AU2=1.0&BU2=-0.01&CU2=0.0&DU2=1.0&xInitial=1.0&yInitial=0.0&pxInitial=0.0&pyInitial=0.0&wantBoxLines=0&wantPELevels=1&timeMax=330.0



http://www.uark.edu/ua/modphys/markup/BoxItWeb.html?

AU2=1.0&BU2=-0.10&CU2=0.0&DU2=1.0&xInitial=1.0&yInitial=0.0&pxInitial=0.0&pyInitial=0.0&wantBoxLines=0&wantPELevels=1&timeMax=330.0





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2D-HO beats and mixed mode geometry



2D-HO beats and mixed mode geometry



2D-HO beats and mixed mode geometry



2D-HO beats and mixed mode geometry



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 Eigensolutions by matrix-algebra with example M= (4 1) Secular equation Hamilton-Cayley equation and projectors Idempotent projectors (how eigenvalues ⇒ eigenvectors) Operator orthonormality and Completeness (Idempotent means: P·P=P) Spectral Decompositions Functional spectral decomposition

 $\mathbf{M}|\boldsymbol{\varepsilon}\rangle = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \boldsymbol{\varepsilon} \begin{pmatrix} x \\ y \end{pmatrix} \text{ or: } \begin{pmatrix} 4-\boldsymbol{\varepsilon} & 1 \\ 3 & 2-\boldsymbol{\varepsilon} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

An *eigenvector* $|\varepsilon_k\rangle$ of **M** is in a direction that is left unchanged by **M**.

$$\mathbf{M}|\boldsymbol{\varepsilon}_{k}\rangle = \boldsymbol{\varepsilon}_{k}|\boldsymbol{\varepsilon}_{k}\rangle, \text{ or: } (\mathbf{M}-\boldsymbol{\varepsilon}_{k}\mathbf{1})|\boldsymbol{\varepsilon}_{k}\rangle = \mathbf{0}$$

 ε_k is *eigenvalue* associated with eigenvector $|\varepsilon_k\rangle$ direction. A change of basis to $\{|\varepsilon_1\rangle, |\varepsilon_2\rangle, \dots, |\varepsilon_n\rangle\}$ called *diagonalization* gives

 $\begin{pmatrix} \langle \boldsymbol{\varepsilon}_{1} | \mathbf{M} | \boldsymbol{\varepsilon}_{1} \rangle & \langle \boldsymbol{\varepsilon}_{1} | \mathbf{M} | \boldsymbol{\varepsilon}_{2} \rangle & \cdots & \langle \boldsymbol{\varepsilon}_{1} | \mathbf{M} | \boldsymbol{\varepsilon}_{n} \rangle \\ \langle \boldsymbol{\varepsilon}_{2} | \mathbf{M} | \boldsymbol{\varepsilon}_{1} \rangle & \langle \boldsymbol{\varepsilon}_{2} | \mathbf{M} | \boldsymbol{\varepsilon}_{2} \rangle & \cdots & \langle \boldsymbol{\varepsilon}_{2} | \mathbf{M} | \boldsymbol{\varepsilon}_{n} \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \boldsymbol{\varepsilon}_{n} | \mathbf{M} | \boldsymbol{\varepsilon}_{1} \rangle & \langle \boldsymbol{\varepsilon}_{n} | \mathbf{M} | \boldsymbol{\varepsilon}_{2} \rangle & \cdots & \langle \boldsymbol{\varepsilon}_{n} | \mathbf{M} | \boldsymbol{\varepsilon}_{n} \rangle \end{pmatrix} = \begin{pmatrix} \boldsymbol{\varepsilon}_{1} & 0 & \cdots & 0 \\ 0 & \boldsymbol{\varepsilon}_{2} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \boldsymbol{\varepsilon}_{n} \end{pmatrix}$

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 ε_k is *eigenvalue* associated with eigenvector $|\varepsilon_k\rangle$ direction. A change of basis to $\{|\varepsilon_1\rangle, |\varepsilon_2\rangle, \dots, |\varepsilon_n\rangle\}$ called *diagonalization* gives

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Eigensolutions by matrix-algebra with example $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$ Secular equation Hamilton-Cayley equation and projectors Idempotent projectors (how eigenvalues \Rightarrow eigenvectors) Operator orthonormality and Completeness (Idempotent means: P·P=P) Spectral Decompositions Functional spectral decomposition

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$$\mathbf{M} | \boldsymbol{\varepsilon}_{k} \rangle = \boldsymbol{\varepsilon}_{k} | \boldsymbol{\varepsilon}_{k} \rangle, \text{ or: } (\mathbf{M} - \boldsymbol{\varepsilon}_{k} \mathbf{1}) | \boldsymbol{\varepsilon}_{k} \rangle = \mathbf{0}$$

 ε_k is *eigenvalue* associated with eigenvector $|\varepsilon_k\rangle$ direction. A change of basis to $\{|\varepsilon_1\rangle, |\varepsilon_2\rangle, \dots, |\varepsilon_n\rangle\}$ called *diagonalization* gives

 $\begin{pmatrix} \langle \boldsymbol{\varepsilon}_1 | \mathbf{M} | \boldsymbol{\varepsilon}_1 \rangle & \langle \boldsymbol{\varepsilon}_1 | \mathbf{M} | \boldsymbol{\varepsilon}_2 \rangle & \cdots & \langle \boldsymbol{\varepsilon}_1 | \mathbf{M} | \boldsymbol{\varepsilon}_n \rangle \\ \langle \boldsymbol{\varepsilon}_2 | \mathbf{M} | \boldsymbol{\varepsilon}_1 \rangle & \langle \boldsymbol{\varepsilon}_2 | \mathbf{M} | \boldsymbol{\varepsilon}_2 \rangle & \cdots & \langle \boldsymbol{\varepsilon}_2 | \mathbf{M} | \boldsymbol{\varepsilon}_n \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \boldsymbol{\varepsilon}_n | \mathbf{M} | \boldsymbol{\varepsilon}_1 \rangle & \langle \boldsymbol{\varepsilon}_n | \mathbf{M} | \boldsymbol{\varepsilon}_2 \rangle & \cdots & \langle \boldsymbol{\varepsilon}_n | \mathbf{M} | \boldsymbol{\varepsilon}_n \rangle \end{pmatrix} = \begin{pmatrix} \boldsymbol{\varepsilon}_1 & 0 & \cdots & 0 \\ 0 & \boldsymbol{\varepsilon}_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \boldsymbol{\varepsilon}_n \end{pmatrix}$

First step in finding eigenvalues: Solve secular equation

$$\det |\mathbf{M} - \boldsymbol{\varepsilon} \mathbf{1}| = 0 = (-1)^n \left(\boldsymbol{\varepsilon}^n + a_1 \boldsymbol{\varepsilon}^{n-1} + a_2 \boldsymbol{\varepsilon}^{n-2} + \dots + a_{n-1} \boldsymbol{\varepsilon} + a_n \right)$$

where:

$$a_1 = -Trace\mathbf{M}, \dots, a_k = (-1)^k \sum \text{diagonal k-by-k minors of } \mathbf{M}, \dots, a_n = (-1)^n \det |\mathbf{M}|$$

$$\mathbf{M}|\boldsymbol{\varepsilon}\rangle = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \boldsymbol{\varepsilon} \begin{pmatrix} x \\ y \end{pmatrix} \text{ or: } \begin{pmatrix} 4-\boldsymbol{\varepsilon} & 1 \\ 3 & 2-\boldsymbol{\varepsilon} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Trying to solve by Kramer's inversion:

$$x = \frac{\det \begin{pmatrix} 0 & 1 \\ 0 & 2 - \varepsilon \end{pmatrix}}{\det \begin{pmatrix} 4 - \varepsilon & 1 \\ 3 & 2 - \varepsilon \end{pmatrix}} \quad \text{and} \quad y = \frac{\det \begin{pmatrix} 4 - \varepsilon & 0 \\ 3 & 0 \end{pmatrix}}{\det \begin{pmatrix} 4 - \varepsilon & 1 \\ 3 & 2 - \varepsilon \end{pmatrix}}$$

$$0 = \det \left| \mathbf{M} - \varepsilon \cdot \mathbf{1} \right| = \det \left| \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} - \varepsilon \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right| = \det \left| \begin{pmatrix} 4 - \varepsilon & 1 \\ 3 & 2 - \varepsilon \end{pmatrix} \right|$$
$$0 = (4 - \varepsilon)(2 - \varepsilon) - 1 \cdot 3 = 8 - 6\varepsilon + \varepsilon^2 - 1 \cdot 3 = \varepsilon^2 - 6\varepsilon + 5$$

$$0 = \varepsilon^2 - Trace(\mathbf{M})\varepsilon + \det(\mathbf{M})$$

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 ε_k is *eigenvalue* associated with eigenvector $|\varepsilon_k\rangle$ direction. A change of basis to $\{|\varepsilon_1\rangle, |\varepsilon_2\rangle, \dots, |\varepsilon_n\rangle\}$ called *diagonalization* gives

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First step in finding eigenvalues: Solve secular equation

$$\det |\mathbf{M} - \boldsymbol{\varepsilon} \mathbf{1}| = 0 = (-1)^n \left(\boldsymbol{\varepsilon}^n + a_1 \boldsymbol{\varepsilon}^{n-1} + a_2 \boldsymbol{\varepsilon}^{n-2} + \dots + a_{n-1} \boldsymbol{\varepsilon} + a_n \right)$$

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$$a_1 = -Trace \mathbf{M}, \dots, a_k = (-1)^k \sum \text{diagonal k-by-k minors of } \mathbf{M}, \dots, a_n = (-1)^n \det |\mathbf{M}|$$

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$$\mathbf{M}|\varepsilon\rangle = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \varepsilon \begin{pmatrix} x \\ y \end{pmatrix} \text{ or: } \begin{pmatrix} 4-\varepsilon & 1 \\ 3 & 2-\varepsilon \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Trying to solve by Kramer's inversion:

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$$0 = \det \left| \mathbf{M} - \varepsilon \cdot \mathbf{I} \right| = \det \left| \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} - \varepsilon \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right| = \det \left| \begin{pmatrix} 4 - \varepsilon & 1 \\ 3 & 2 - \varepsilon \end{pmatrix} \right|$$
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2D harmonic oscillator (2D-HO) equations of motion Lagrangian and matrix forms



2D harmonic oscillator equation eigensolutions (normal modes) Eigensolutions by geometry for 2D-HO with bilateral (B-Type) symmetry Symmetric (low frequency) mode versus antisymmetric (high frequency) mode Mixed mode beat dynamics (with constant $\pi/2$ phase-lag) Geometry of phase and polarization

Eigensolutions by matrix-algebra with example $M = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$ Secular equation Hamilton-Cayley equation A projectors Idempotent projectors (how eigenvalues \Rightarrow eigenvectors) Operator orthonormality and Completeness (Idempotent means: P·P=P) Spectral Decompositions Functional spectral decomposition

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Secular equation has *n*-factors, one for each eigenvalue.

det
$$|\mathbf{M} - \varepsilon \mathbf{1}| = 0 = (-1)^n (\varepsilon - \varepsilon_1) (\varepsilon - \varepsilon_2) \cdots (\varepsilon - \varepsilon_n)$$

Each ε replaced by **M** and each ε_k by $\varepsilon_k \mathbf{1}$ gives *Hamilton-Cayley* matrix equation.

$$\mathbf{0} = (\mathbf{M} - \varepsilon_1 \mathbf{1}) (\mathbf{M} - \varepsilon_2 \mathbf{1}) \cdots (\mathbf{M} - \varepsilon_n \mathbf{1})$$

Obviously true if M has diagonal form. (But, that's circular logic. Faith needed!)

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$$0 = \mathbf{M}^{2} - 6\mathbf{M} + 5\mathbf{1} = (\mathbf{M} - 1 \cdot \mathbf{1})(\mathbf{M} - 5 \cdot \mathbf{1})$$
$$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}^{2} - 6 \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} + 5 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

2D harmonic oscillator (2D-HO) equations of motion Lagrangian and matrix forms



2D harmonic oscillator equation eigensolutions (normal modes) Eigensolutions by geometry for 2D-HO with bilateral (B-Type) symmetry Symmetric (low frequency) mode versus antisymmetric (high frequency) mode Mixed mode beat dynamics (with constant $\pi/2$ phase-lag) Geometry of phase and polarization

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First step in finding eigenvalues: Solve secular equation

$$\det |\mathbf{M} - \boldsymbol{\varepsilon} \mathbf{1}| = 0 = (-1)^n \left(\boldsymbol{\varepsilon}^n + a_1 \boldsymbol{\varepsilon}^{n-1} + a_2 \boldsymbol{\varepsilon}^{n-2} + \dots + a_{n-1} \boldsymbol{\varepsilon} + a_n \right)$$

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 $\mathbf{0} = (\mathbf{M} - \boldsymbol{\varepsilon}_1 \mathbf{1}) (\mathbf{M} - \boldsymbol{\varepsilon}_2 \mathbf{1}) \cdots (\mathbf{M} - \boldsymbol{\varepsilon}_n \mathbf{1})$

Obviously true if M has diagonal form. (But, that's circular logic. Faith needed!)

Replace j^{th} HC-factor by (1) to make *projection operators*

$$\mathbf{p}_{1} = (\mathbf{1})(\mathbf{M} - \varepsilon_{2}\mathbf{1})\cdots(\mathbf{M} - \varepsilon_{n}\mathbf{1})$$
$$\mathbf{p}_{2} = (\mathbf{M} - \varepsilon_{1}\mathbf{1})(\mathbf{1})\cdots(\mathbf{M} - \varepsilon_{n}\mathbf{1})$$
$$\vdots$$
$$\mathbf{p}_{n} = (\mathbf{M} - \varepsilon_{1}\mathbf{1})(\mathbf{M} - \varepsilon_{2}\mathbf{1})\cdots(\mathbf{1})$$

$$\mathbf{M}|\boldsymbol{\varepsilon}\rangle = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \boldsymbol{\varepsilon}\begin{pmatrix} x \\ y \end{pmatrix} \text{ or: } \begin{pmatrix} 4-\boldsymbol{\varepsilon} & 1 \\ 3 & 2-\boldsymbol{\varepsilon} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Trying to solve by Kramer's inversion:

$$x = \frac{\det \begin{vmatrix} 0 & 1 \\ 0 & 2-\varepsilon \end{vmatrix}}{\det \begin{vmatrix} 4-\varepsilon & 1 \\ 3 & 2-\varepsilon \end{vmatrix}} \quad \text{and} \quad y = \frac{\det \begin{vmatrix} 4-\varepsilon & 0 \\ 3 & 0 \end{vmatrix}}{\det \begin{vmatrix} 4-\varepsilon & 1 \\ 3 & 2-\varepsilon \end{vmatrix}}$$

$$0 = \det |\mathbf{M} - \varepsilon \cdot \mathbf{1}| = \det \begin{vmatrix} 4 & 1 \\ 3 & 2 \end{vmatrix} - \varepsilon \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = \det \begin{vmatrix} 4 - \varepsilon & 1 \\ 3 & 2 - \varepsilon \end{vmatrix}$$
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 so let: $\varepsilon_1 = 1$ and: $\varepsilon_2 = 5$

$$0 = \mathbf{M}^{2} - 6\mathbf{M} + 5\mathbf{1} = (\mathbf{M} - 1\cdot\mathbf{1})(\mathbf{M} - 5\cdot\mathbf{1})$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}^{2} - 6\begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} + 5\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\mathbf{p}_{1} = (\mathbf{1})(\mathbf{M} - 5\cdot\mathbf{1}) = \begin{pmatrix} 4-5 & 1 \\ 3 & 2-5 \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix}$$

$$\mathbf{p}_{2} = (\mathbf{M} - 1\cdot\mathbf{1})(\mathbf{1}) = \begin{pmatrix} 4-1 & 1 \\ 3 & 2-1 \end{pmatrix} = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$$

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 ε_k is *eigenvalue* associated with eigenvector $|\varepsilon_k\rangle$ direction. A change of basis to $\{|\varepsilon_1\rangle, |\varepsilon_2\rangle, \dots, |\varepsilon_n\rangle\}$ called *diagonalization* gives

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First step in finding eigenvalues: Solve secular equation

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Each ε replaced by **M** and each ε_k by $\varepsilon_k \mathbf{1}$ gives *Hamilton-Cayley* matrix equation. $\mathbf{0} = (\mathbf{M} - \varepsilon_1 \mathbf{1})(\mathbf{M} - \varepsilon_2 \mathbf{1}) \cdots (\mathbf{M} - \varepsilon_n \mathbf{1})$

Obviously true if **M** has diagonal form. (But, that's circular logic. Faith needed!)

Replace *j*th HC-factor by (1) to make *projection operators* $\mathbf{p}_k = \prod (\mathbf{M} - \varepsilon_j \mathbf{1})$ $\mathbf{p}_1 = (\mathbf{1} \)(\mathbf{M} - \varepsilon_2 \mathbf{1}) \cdots (\mathbf{M} - \varepsilon_n \mathbf{1})$ $\mathbf{p}_{2} = (\mathbf{M} - \varepsilon_{1}\mathbf{1})(\mathbf{1})\cdots(\mathbf{M} - \varepsilon_{n}\mathbf{1}) \quad (\text{Assume <u>distinct</u> e-values here:$ *Non-degeneracy clause* $)}$ $\varepsilon_{j} \neq \varepsilon_{k} \neq \dots$ $\mathbf{p}_n = (\mathbf{M} - \varepsilon_1 \mathbf{1})(\mathbf{M} - \varepsilon_2 \mathbf{1}) \cdots (\mathbf{1})$

Each \mathbf{p}_k contains *eigen-bra-kets* since: $(\mathbf{M} - \varepsilon_k \mathbf{1})\mathbf{p}_k = 0$ or: $\mathbf{M}\mathbf{p}_k = \varepsilon_k \mathbf{p}_k = \mathbf{p}_k \mathbf{M}$.

$$\mathbf{M}|\varepsilon\rangle = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \varepsilon \begin{pmatrix} x \\ y \end{pmatrix} \text{ or: } \begin{pmatrix} 4-\varepsilon & 1 \\ 3 & 2-\varepsilon \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Trying to solve by Kramer's inversion:

$$x = \frac{\det \begin{vmatrix} 0 & 1 \\ 0 & 2 - \varepsilon \end{vmatrix}}{\det \begin{vmatrix} 4 - \varepsilon & 1 \\ 3 & 2 - \varepsilon \end{vmatrix}} \quad \text{and} \quad y = \frac{\det \begin{vmatrix} 4 - \varepsilon & 0 \\ 3 & 0 \end{vmatrix}}{\det \begin{vmatrix} 4 - \varepsilon & 1 \\ 3 & 2 - \varepsilon \end{vmatrix}}$$

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$$\mathbf{Mp}_{1} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \cdot \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} = 1 \cdot \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} = 1 \cdot \mathbf{p}_{1}$$

$$\mathbf{Mp}_{2} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \cdot \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = 5 \cdot \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = 5 \cdot \mathbf{p}_{2}$$

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Each ε replaced by **M** and each ε_k by $\varepsilon_k \mathbf{1}$ gives *Hamilton-Cayley* matrix equation. $\mathbf{0} = (\mathbf{M} - \varepsilon_1 \mathbf{1})(\mathbf{M} - \varepsilon_2 \mathbf{1}) \cdots (\mathbf{M} - \varepsilon_n \mathbf{1})$

Obviously true if **M** has diagonal form. (But, that's circular logic. Faith needed!)

Replace *j*th HC-factor by (1) to make *projection operators* $\mathbf{p}_k = \prod (\mathbf{M} - \varepsilon_j \mathbf{1})$ $\mathbf{p}_1 = (\mathbf{1} \)(\mathbf{M} - \varepsilon_2 \mathbf{1}) \cdots (\mathbf{M} - \varepsilon_n \mathbf{1})$ *Notice* \mathbf{p}_k *commutes with* $\mathbf{M}_{,...}$ Each \mathbf{p}_k contains *eigen-bra-kets* since: $(\mathbf{M} - \varepsilon_k \mathbf{1})\mathbf{p}_k = 0$ or: $\mathbf{M}\mathbf{p}_k = \varepsilon_k \mathbf{p}_k = \mathbf{p}_k \mathbf{M}$.

since \mathbf{M}^{I} , \mathbf{M}^{2} ,..commute with \mathbf{M}

$$\mathbf{M}|\varepsilon\rangle = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \varepsilon \begin{pmatrix} x \\ y \end{pmatrix} \text{ or: } \begin{pmatrix} 4-\varepsilon & 1 \\ 3 & 2-\varepsilon \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Trying to solve by Kramer's inversion:

$$x = \frac{\det \begin{vmatrix} 0 & 1 \\ 0 & 2 - \varepsilon \end{vmatrix}}{\det \begin{vmatrix} 4 - \varepsilon & 1 \\ 3 & 2 - \varepsilon \end{vmatrix}} \quad \text{and} \quad y = \frac{\det \begin{vmatrix} 4 - \varepsilon & 0 \\ 3 & 0 \end{vmatrix}}{\det \begin{vmatrix} 4 - \varepsilon & 1 \\ 3 & 2 - \varepsilon \end{vmatrix}}$$

$$D = \det \left| \mathbf{M} - \varepsilon \cdot \mathbf{I} \right| = \det \left| \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} - \varepsilon \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right| = \det \left| \begin{pmatrix} 4 - \varepsilon & 1 \\ 3 & 2 - \varepsilon \end{pmatrix} \right|$$
$$0 = (4 - \varepsilon)(2 - \varepsilon) - 1 \cdot 3 = 8 - 6\varepsilon + \varepsilon^2 - 1 \cdot 3 = \varepsilon^2 - 6\varepsilon + 5$$
$$0 = \varepsilon^2 - Trace(\mathbf{M})\varepsilon + \det(\mathbf{M}) = \varepsilon^2 - 6\varepsilon + 5$$

$$0 = (\varepsilon - 1)(\varepsilon - 5)$$
 so let: $\varepsilon_1 = 1$ and: $\varepsilon_2 = 5$

$$0 = \mathbf{M}^{2} - 6\mathbf{M} + 5\mathbf{1} = (\mathbf{M} - 1 \cdot \mathbf{1})(\mathbf{M} - 5 \cdot \mathbf{1})$$

$$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}^{2} - 6\begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} + 5\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\mathbf{p}_{1} = (\mathbf{1})(\mathbf{M} - 5 \cdot \mathbf{1}) = \begin{pmatrix} 4 - 5 & 1 \\ 3 & 2 - 5 \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix}$$

$$\mathbf{p}_{2} = (\mathbf{M} - 1 \cdot \mathbf{1})(\mathbf{1}) = \begin{pmatrix} 4 - 1 & 1 \\ 3 & 2 - 1 \end{pmatrix} = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$$

$$\mathbf{Mp}_{1} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \cdot \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} = 1 \cdot \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} = 1 \cdot \mathbf{p}_{1}$$

$$\mathbf{Mp}_{2} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \cdot \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = 5 \cdot \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = 5 \cdot \mathbf{p}_{2}$$

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 → Idempotent projectors (Convertionality and Completeness (Idempotent means: P·P=P) Operator orthonormality and Completeness (Idempotent means: P·P=P) Spectral Decompositions Functional spectral decomposition

$$\begin{aligned} \text{Matrix-algebraic method for finding eigenvector and eigenvalues}} & \text{With example matrix} & \mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \\ \mathbf{p}_{j} \mathbf{p}_{k} = \mathbf{p}_{j} \prod_{m \neq k} (\mathbf{M} - \varepsilon_{m} \mathbf{1}) = \prod_{m \neq k} (\mathbf{p}_{j} \mathbf{M} - \varepsilon_{m} \mathbf{p}_{j} \mathbf{1}) & \mathbf{M} \mathbf{p}_{k} = \varepsilon_{k} \mathbf{p}_{k} = \mathbf{p}_{k} \mathbf{M} \\ \text{Multiplication properties of } \mathbf{p}_{j} : \\ \mathbf{p}_{j} \mathbf{p}_{k} = \prod_{m \neq k} (\varepsilon_{j} \mathbf{p}_{j} - \varepsilon_{m} \mathbf{p}_{j}) = \mathbf{p}_{j} \prod_{m \neq k} (\varepsilon_{j} - \varepsilon_{m}) = \begin{cases} \mathbf{0} & \text{if } : j \neq k \\ \mathbf{p}_{k} \prod_{m \neq k} (\varepsilon_{k} - \varepsilon_{m}) & \text{if } : j = k \end{cases} & \mathbf{W} \\ \mathbf{p}_{k} \prod_{m \neq k} (\varepsilon_{k} - \varepsilon_{m}) & \text{if } : j = k \end{aligned}$$

$$\begin{array}{ll} \text{Matrix-algebraic method for finding eigenvector and eigenvalues}} & \text{With example matrix} & \mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \\ \mathbf{p}_{j}\mathbf{p}_{k} = \mathbf{p}_{j}\prod_{m\neq k} (\mathbf{M} - \varepsilon_{m}\mathbf{1}) = \prod_{m\neq k} (\mathbf{p}_{j}\mathbf{M} - \varepsilon_{m}\mathbf{p}_{j}\mathbf{1}) & \mathbf{M}\mathbf{p}_{k} = \varepsilon_{k}\mathbf{p}_{k} = \mathbf{p}_{k}\mathbf{M} \\ \text{Multiplication properties of } \mathbf{p}_{j}: \\ \mathbf{p}_{j}\mathbf{p}_{k} = \prod_{m\neq k} (\varepsilon_{j}\mathbf{p}_{j} - \varepsilon_{m}\mathbf{p}_{j}) = \mathbf{p}_{j}\prod_{m\neq k} (\varepsilon_{j} - \varepsilon_{m}) = \begin{cases} \mathbf{0} & \text{if } : j \neq k \\ \mathbf{p}_{k}\prod_{m\neq k} (\varepsilon_{k} - \varepsilon_{m}) & \text{if } : j = k \end{cases} \\ \mathbf{p}_{k}\prod_{m\neq k} (\varepsilon_{k} - \varepsilon_{m}) & \text{if } : j = k \end{cases} \\ \text{Last step:} \\ \text{make Idempotent Projectors:} & \mathbf{P}_{k} = \frac{\mathbf{p}_{k}}{\prod_{m\neq k} (\varepsilon_{k} - \varepsilon_{m})} = \frac{\prod_{m\neq k} (\mathbf{M} - \varepsilon_{m}\mathbf{1})}{\prod_{m\neq k} (\varepsilon_{k} - \varepsilon_{m})} & \mathbf{P}_{1} = \frac{(\mathbf{M} - \mathbf{5} \cdot \mathbf{1})}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} \\ \mathbf{P}_{2} = \frac{(\mathbf{M} - \mathbf{1} \cdot \mathbf{1})}{(5 - 1)} = \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} \end{array}$$

$$\begin{array}{ll} Matrix-algebraic method for finding eigenvector and eigenvalues \\ \mathbf{p}_{j}\mathbf{p}_{k} = \mathbf{p}_{j}\prod_{m\neq k} (\mathbf{M}-\varepsilon_{m}\mathbf{1}) = \prod_{m\neq k} (\mathbf{p}_{j}\mathbf{M}-\varepsilon_{m}\mathbf{p}_{j}\mathbf{1}) \\ Multiplication properties of \mathbf{p}_{j}: \\ \mathbf{p}_{j}\mathbf{p}_{k} = \prod_{m\neq k} (\varepsilon_{j}\mathbf{p}_{j}-\varepsilon_{m}\mathbf{p}_{j}) = \mathbf{p}_{j}\prod_{m\neq k} (\varepsilon_{j}-\varepsilon_{m}) = \begin{cases} \mathbf{0} & if: j\neq k \\ \mathbf{p}_{k}\prod_{m\neq k} (\varepsilon_{k}-\varepsilon_{m}) & if: j=k \end{cases} \\ \mathbf{p}_{k}\prod_{m\neq k} (\varepsilon_{k}-\varepsilon_{m}) & if: j=k \end{cases} \\ \mathbf{p}_{k} \prod_{m\neq k} (\varepsilon_{k}-\varepsilon_{m}) = \mathbf{p}_{j}\prod_{m\neq k} (\varepsilon_{k}-\varepsilon_{m}) \\ (Idempotent means: \mathbf{P}\cdot\mathbf{P}=\mathbf{P}) \\ \mathbf{P}_{j}\mathbf{P}_{k} = \begin{cases} \mathbf{0} & if: j\neq k \\ \prod_{m\neq k} (\varepsilon_{k}-\varepsilon_{m}) = \prod_{m\neq k} (\varepsilon_{k}-\varepsilon_{m}) \\ \mathbf{P}_{k} = \varepsilon_{k}\mathbf{p}_{k} = \mathbf{p}_{k}\mathbf{M} \\ \mathbf{P}_{k} & if: j=k \end{cases} \\ \mathbf{P}_{k} = \varepsilon_{k}\mathbf{P}_{k} = \mathbf{P}_{k}\mathbf{M} \\ \mathbf{P}_{k} = \varepsilon_{k}\mathbf{P}_{k}\mathbf{P}_{k} = \mathbf{P}_{k}\mathbf{M} \\ \mathbf{P}_{k} = \varepsilon_{k}\mathbf{P}_{k}\mathbf{P}_{k} = \mathbf{P}_{k}\mathbf{M} \\ \mathbf{P}_{k} = \mathbf{P}_{k}\mathbf{P}_{k} = \mathbf{P}_{k}\mathbf{M} \\ \mathbf{P}_{k} = \mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k}\mathbf{P}_{k$$

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$$\begin{array}{ll} Matrix-algebraic method for finding eigenvector and eigenvalues \\ \mathbf{p}_{j}\mathbf{p}_{k} = \mathbf{p}_{j}\prod_{m\neq k}(\mathbf{M}-\varepsilon_{m}\mathbf{1}) = \prod_{m\neq k}(\mathbf{p}_{j}\mathbf{M}-\varepsilon_{m}\mathbf{p}_{j}\mathbf{1}) \\ M\mathbf{p}_{k} = \varepsilon_{k}\mathbf{p}_{k} = \mathbf{p}_{k}\mathbf{M} \\ Multiplication properties of \mathbf{p}_{j}: \\ \mathbf{p}_{j}\mathbf{p}_{k} = \prod_{m\neq k}(\varepsilon_{j}\mathbf{p}_{j}-\varepsilon_{m}\mathbf{p}_{j}) = \mathbf{p}_{j}\prod_{m\neq k}(\varepsilon_{j}-\varepsilon_{m}) = \begin{cases} \mathbf{0} & if: j\neq k \\ \mathbf{p}_{k}\prod_{m\neq k}(\varepsilon_{k}-\varepsilon_{m}) & if: j=k \end{cases} \\ \mathbf{p}_{k}$$

$$\begin{aligned} \text{Matrix-algebraic method for finding eigenvector and eigenvalues}}_{\mathbf{p},\mathbf{p}_{k}} & \text{With example matrix} & \mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} \\ \mathbf{p},\mathbf{p}_{k} = \mathbf{p},\prod_{m,k} (\mathbf{M} - \varepsilon_{m}) = \prod_{m,k} (\mathbf{p},\mathbf{M} - \varepsilon_{m}\mathbf{p},1) & \mathbf{M}\mathbf{p}_{k} = \varepsilon_{k}\mathbf{p}_{k} = \mathbf{p}_{k}\mathbf{M} \\ \text{Multiplication properties of } \mathbf{p}_{1}: \\ \mathbf{p},\mathbf{p}_{k} = \prod_{m,k} (\varepsilon_{1}\mathbf{p}_{1} - \varepsilon_{m}\mathbf{p}_{1}) = \mathbf{p},\prod_{m,k} (\varepsilon_{1} - \varepsilon_{m}) = f(\varepsilon_{1} - \varepsilon_{m}) & \text{if } j \neq k \\ \mathbf{p},\prod_{m,k} (\varepsilon_{1} - \varepsilon_{m}) = \mathbf{p},\prod_{m,k} (\varepsilon_{1} - \varepsilon_{m}) = \mathbf{p},\prod_{m,k} (\varepsilon_{1} - \varepsilon_{m}) & \text{if } j \neq k \\ \text{make Idempotent Projectors: } \mathbf{P}_{k} = \frac{\mathbf{p}_{1}}{\prod_{m,k} (\varepsilon_{k} - \varepsilon_{m})} = \frac{\mathbf{p}_{1}}{\prod_{m,k} (\varepsilon_{m} - \varepsilon_{m})} = \frac{\mathbf{p}_{1}}{\prod_$$

Review of 1D FDHO (Forced-Damped-Harmonic Oscillator) response Amplitude and phase variation due to resonance

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 $\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$ $\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix}$ $\mathbf{p}_{1} \mathbf{p}_{k} = \prod_{m \neq k} (\varepsilon_{j} \mathbf{p}_{j} - \varepsilon_{m} \mathbf{p}_{j}) = \mathbf{p}_{j} \prod_{m \neq k} (\varepsilon_{j} - \varepsilon_{m}) = \begin{cases} \mathbf{0} & if : j \neq k \\ \mathbf{p}_{k} \prod_{m \neq k} (\varepsilon_{k} - \varepsilon_{m}) & if : j = k \end{cases}$ $\mathbf{p}_{1} \mathbf{p}_{2} = (\mathbf{M} - \mathbf{1} \cdot \mathbf{1}) = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$ $\mathbf{p}_{2} = (\mathbf{M} - \mathbf{1} \cdot \mathbf{1}) = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$ $\mathbf{p}_{1} \mathbf{p}_{2} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ $\mathbf{p}_{1} \mathbf{p}_{2} = (\mathbf{M} - \mathbf{1} \cdot \mathbf{1}) = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$ $\mathbf{p}_{1} \mathbf{p}_{2} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ $\mathbf{p}_{1} \mathbf{p}_{2} = (\mathbf{M} - \mathbf{1} \cdot \mathbf{1}) = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$ $\mathbf{p}_{1} \mathbf{p}_{2} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ $\mathbf{p}_{1} \mathbf{p}_{2} = (\mathbf{M} - \mathbf{1} \cdot \mathbf{1}) = \begin{pmatrix} -1 & 1 \\ 3 & 1 \end{pmatrix}$ $\mathbf{p}_{1} \mathbf{p}_{2} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ $\mathbf{p}_{1} \mathbf{p}_{2} = (\mathbf{M} - \mathbf{1} \cdot \mathbf{1}) = \begin{pmatrix} -1 & 1 \\ 3 & 1 \end{pmatrix}$ $\mathbf{p}_{2} = (\mathbf{M} - \mathbf{1} \cdot \mathbf{1}) = \begin{pmatrix} -1 & 1 \\ 3 & 1 \end{pmatrix}$ $\mathbf{p}_{3} \mathbf{p}_{4} = \mathbf{p} \mathbf{p}_{4}$ $\mathbf{p}_{4} \mathbf{p}_{4} = \mathbf{p}_{4}$ $\mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4} = \mathbf{p}_{4}$ $\mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4} = \mathbf{p}_{4}$ $\mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4}$ $\mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4}$ $\mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4}$ $\mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4}$ $\mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4}$ $\mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4} \mathbf{p}_{4}$ Matrix and operator Spectral Decompositons Multiplication properties of \mathbf{p}_i : $\begin{array}{l} \text{Last step.} \\ \text{make Idempotent Projectors: } \mathbf{P}_{k} = \frac{\mathbf{P}_{k}}{\prod\limits_{m \neq k} (\varepsilon_{k} - \varepsilon_{m})} = \frac{\prod\limits_{m \neq k} (\mathbf{M} - \varepsilon_{m} \mathbf{1})}{\prod\limits_{m \neq k} (\varepsilon_{k} - \varepsilon_{m})} \end{array} \begin{array}{l} \mathbf{P}_{1} = \frac{(\mathbf{M} - 5 \cdot \mathbf{1})}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} = k_{1} \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \frac{\left(\frac{1}{2} & -\frac{1}{2}\right)}{k_{1}} = |\varepsilon_{1}\rangle\langle\varepsilon_{1}| \end{array}$ $\mathbf{P}_{j}\mathbf{P}_{k} = \begin{cases} \mathbf{0} & if: j \neq k \\ \mathbf{P}_{k} & if: j = k \end{cases} \quad \begin{array}{c} \mathbf{M}\mathbf{p}_{k} = \varepsilon_{k}\mathbf{p}_{k} = \mathbf{p}_{k}\mathbf{M} \\ implies: \\ \mathbf{M}\mathbf{P}_{k} = \varepsilon_{k}\mathbf{P}_{k} = \mathbf{P}_{k}\mathbf{M} \end{cases} \quad \mathbf{P}_{2} = \frac{(\mathbf{M} - 1\cdot\mathbf{1})}{(5-1)} = \frac{1}{4}\begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = k_{2}\begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{3}{2} & \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}}{k_{2}} = |\varepsilon_{2}\rangle\langle\varepsilon_{2}|$ The **P**_{*i*} are *Mutually Ortho-Normal* $\begin{array}{c} \cdot \left(\begin{array}{c} \langle \boldsymbol{\varepsilon}_1 | \boldsymbol{\varepsilon}_1 \rangle & \langle \boldsymbol{\varepsilon}_1 | \boldsymbol{\varepsilon}_2 \rangle \\ \langle \boldsymbol{\varepsilon}_2 | \boldsymbol{\varepsilon}_1 \rangle & \langle \boldsymbol{\varepsilon}_2 | \boldsymbol{\varepsilon}_2 \rangle \end{array} \right) \end{array}$ as are bra-ket $\langle \varepsilon_i | \text{and} | \varepsilon_i \rangle$ inside \mathbf{P}_i 's $= \left(\begin{array}{c} 1 & 0 \\ 0 & 1 \end{array} \right)$...and the \mathbf{P}_i satisfy a Completeness Relation: $\mathbf{P}_1 + \mathbf{P}_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ $1 = P_1 + P_2 + ... + P_n$ $\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = 1\mathbf{P}_1 + 5\mathbf{P}_2 = 1|1\rangle\langle 1| + 5|2\rangle\langle 2| = 1 \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} + 5 \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix}$ $= |\varepsilon_1\rangle \langle \varepsilon_1| + |\varepsilon_2\rangle \langle \varepsilon_2| + \dots + |\varepsilon_n\rangle \langle \varepsilon_n| \quad \vdots$ $=|\boldsymbol{\varepsilon}_1\rangle\langle\boldsymbol{\varepsilon}_1|+|\boldsymbol{\varepsilon}_2\rangle\langle\boldsymbol{\varepsilon}_2|$ Eigen-operators $\mathbf{MP}_k = \varepsilon_k \mathbf{P}_k$ then give *Spectral Decomposition* of operator **M** $\mathbf{M} = \mathbf{MP}_1 + \mathbf{MP}_2 + \dots + \mathbf{MP}_n = \varepsilon_1 \mathbf{P}_1 + \varepsilon_2 \mathbf{P}_2 + \dots + \varepsilon_n \mathbf{P}_n$...and *Functional Spectral Decomposition* of any function $f(\mathbf{M})$ of \mathbf{M} $f(\mathbf{M}) = f(\varepsilon_1)\mathbf{P}_1 + f(\varepsilon_2)\mathbf{P}_2 + \dots + f(\varepsilon_n)\mathbf{P}_n$

Matrix and operator Spectral Decompositons $\mathbf{M} = \left(\begin{array}{cc} 4 & 1 \\ 3 & 2 \end{array}\right)$ $\mathbf{p}_1 = (\mathbf{M} - 5 \cdot \mathbf{1}) = \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} \qquad \mathbf{p}_1 \mathbf{p}_2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ $\mathbf{p}_{j}\mathbf{p}_{k} = \mathbf{p}_{j}\prod(\mathbf{M} - \boldsymbol{\varepsilon}_{m}\mathbf{1}) = \prod(\mathbf{p}_{j}\mathbf{M} - \boldsymbol{\varepsilon}_{m}\mathbf{p}_{j}\mathbf{1}) \qquad \mathbf{M}\mathbf{p}_{k} = \boldsymbol{\varepsilon}_{k}\mathbf{p}_{k} = \mathbf{p}_{k}\mathbf{M}$ Multiplication properties of \mathbf{p}_i : $\mathbf{p}_2 = (\mathbf{M} - 1 \cdot \mathbf{1}) = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$ $\mathbf{p}_{j}\mathbf{p}_{k} = \prod_{m \neq k} \left(\varepsilon_{j}\mathbf{p}_{j} - \varepsilon_{m}\mathbf{p}_{j} \right) = \mathbf{p}_{j}\prod_{m \neq k} \left(\varepsilon_{j} - \varepsilon_{m} \right) = \begin{cases} \mathbf{0} & \text{if } : j \neq k \\ \mathbf{p}_{k}\prod_{m \neq k} \left(\varepsilon_{k} - \varepsilon_{m} \right) & \text{if } : j = k \end{cases}$ make *Idempotent Projectors*: $\mathbf{P}_{k} = \frac{\mathbf{P}_{k}}{\prod_{m \neq k} (\varepsilon_{k} - \varepsilon_{m})} = \frac{\prod_{m \neq k} (\mathbf{M} - \varepsilon_{m} \mathbf{1})}{\prod_{m \neq k} (\varepsilon_{k} - \varepsilon_{m})} = \frac{\prod_{m \neq k} (\mathbf{M} - \varepsilon_{m} \mathbf{1})}{\prod_{m \neq k} (\varepsilon_{k} - \varepsilon_{m})} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} = k_{1} \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \frac{\begin{pmatrix} \frac{1}{2} & -\frac{1}{2} \end{pmatrix}}{k_{1}} = |\varepsilon_{1}\rangle\langle\varepsilon_{1}|$ Factoring bra-kets into "Ket-Bras: $\mathbf{P}_{j}\mathbf{P}_{k} = \begin{cases} \mathbf{0} & if: j \neq k \\ \mathbf{P}_{k} & if: j = k \end{cases} \qquad \begin{array}{c} m \neq k \\ \mathbf{M}\mathbf{p}_{k} = \varepsilon_{k}\mathbf{p}_{k} = \mathbf{p}_{k}\mathbf{M} \\ implies: \\ \mathbf{M}\mathbf{P}_{k} = \varepsilon_{k}\mathbf{P}_{k} - \mathbf{D}\mathbf{M} \end{cases} \qquad \mathbf{P}_{2} = \frac{(\mathbf{M} - 1 \cdot \mathbf{1})}{(5 - 1)} = \frac{1}{4} \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} = k_{2} \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} \otimes \frac{\left(\frac{3}{2} - \frac{1}{2}\right)}{k_{2}} = |\varepsilon_{2}\rangle\langle\varepsilon_{2}|$ $\mathbf{MP}_{k} = \boldsymbol{\varepsilon}_{k} \mathbf{P}_{k} = \mathbf{P}_{k} \mathbf{M}$ The **P**_{*i*} are *Mutually Ortho-Normal* as are bra-ket $\langle \varepsilon_i | \text{and} | \varepsilon_i \rangle$ inside \mathbf{P}_i 's $= \left(\begin{array}{c} 1 & 0 \\ 0 & 1 \end{array} \right)$...and the \mathbf{P}_i satisfy a Completeness Relation: $\mathbf{P}_1 + \mathbf{P}_2 = \left(\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array}\right)$ $1 = P_1 + P_2 + ... + P_n$ $\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = 1\mathbf{P}_1 + 5\mathbf{P}_2 = 1|1\rangle\langle 1| + 5|2\rangle\langle 2| = 1 \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} + 5 \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix}$ $= |\varepsilon_1\rangle \langle \varepsilon_1| + |\varepsilon_2\rangle \langle \varepsilon_2| + \dots + |\varepsilon_n\rangle \langle \varepsilon_n|$ $=|\varepsilon_1\rangle\langle\varepsilon_1|+|\varepsilon_2\rangle\langle\varepsilon_2|$ Example: $\mathbf{M}^{50} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = \mathbf{1}^{50} \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} + \mathbf{5}^{50} \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 1+3\cdot5^{50} & 5^{50}-1 \\ 3\cdot5^{50}-3 & 5^{50}+3 \end{pmatrix}$ Eigen-operators $\mathbf{MP}_k = \varepsilon_k \mathbf{P}_k$ then give *Spectral Decomposition* of operator **M** $\mathbf{M} = \mathbf{MP}_1 + \mathbf{MP}_2 + \dots + \mathbf{MP}_n = \varepsilon_1 \mathbf{P}_1 + \varepsilon_2 \mathbf{P}_2 + \dots + \varepsilon_n \mathbf{P}_n$...and *Functional Spectral Decomposition* of any function $f(\mathbf{M})$ of \mathbf{M} $f(\mathbf{M}) = f(\varepsilon_1)\mathbf{P}_1 + f(\varepsilon_2)\mathbf{P}_2 + \dots + f(\varepsilon_n)\mathbf{P}_n$

Matrix and operator Spectral Decompositons $\mathbf{M} = \left(\begin{array}{cc} 4 & 1 \\ 3 & 2 \end{array}\right)$ $\mathbf{p}_1 = (\mathbf{M} - 5 \cdot \mathbf{1}) = \begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} \qquad \mathbf{p}_1 \mathbf{p}_2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ $\mathbf{p}_{j}\mathbf{p}_{k} = \mathbf{p}_{j}\prod(\mathbf{M} - \boldsymbol{\varepsilon}_{m}\mathbf{1}) = \prod(\mathbf{p}_{j}\mathbf{M} - \boldsymbol{\varepsilon}_{m}\mathbf{p}_{j}\mathbf{1}) \qquad \mathbf{M}\mathbf{p}_{k} = \boldsymbol{\varepsilon}_{k}\mathbf{p}_{k} = \mathbf{p}_{k}\mathbf{M}$ Multiplication properties of \mathbf{p}_i : $\mathbf{p}_2 = (\mathbf{M} - 1 \cdot \mathbf{1}) = \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix}$ $\mathbf{p}_{j}\mathbf{p}_{k} = \prod_{m \neq k} \left(\varepsilon_{j}\mathbf{p}_{j} - \varepsilon_{m}\mathbf{p}_{j} \right) = \mathbf{p}_{j}\prod_{m \neq k} \left(\varepsilon_{j} - \varepsilon_{m} \right) = \begin{cases} \mathbf{0} & \text{if } : j \neq k \\ \mathbf{p}_{k}\prod_{m \neq k} \left(\varepsilon_{k} - \varepsilon_{m} \right) & \text{if } : j = k \end{cases}$ Factoring bra-kets into "Ket-Bras: $\begin{array}{l} \text{Last step.} \\ \text{make Idempotent Projectors: } \mathbf{P}_{k} = \frac{\mathbf{P}_{k}}{\prod\limits_{m \neq k} (\varepsilon_{k} - \varepsilon_{m})} = \frac{\prod\limits_{m \neq k} (\mathbf{M} - \varepsilon_{m} \mathbf{1})}{\prod\limits_{m \neq k} (\varepsilon_{k} - \varepsilon_{m})} \end{array} \end{array} \begin{array}{l} \mathbf{P}_{1} = \frac{(\mathbf{M} - 5 \cdot \mathbf{1})}{(1 - 5)} = \frac{1}{4} \begin{pmatrix} 1 & -1 \\ -3 & 3 \end{pmatrix} = k_{1} \begin{pmatrix} \frac{1}{2} \\ -\frac{3}{2} \end{pmatrix} \otimes \frac{\left(\frac{1}{2} & -\frac{1}{2}\right)}{k_{1}} = |\varepsilon_{1}\rangle\langle\varepsilon_{1}| \end{aligned}$ $\mathbf{P}_{j}\mathbf{P}_{k} = \begin{cases} \mathbf{0} & if: j \neq k \\ \mathbf{P}_{k} & if: j = k \end{cases} \qquad \begin{array}{c} \mathbf{M}\mathbf{p}_{k} = \boldsymbol{\varepsilon}_{k}\mathbf{p}_{k} = \mathbf{p}_{k}\mathbf{M} \\ implies: \\ \mathbf{M}\mathbf{P}_{-c} = \mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c}\mathbf{P}_{-c$ $\mathbf{MP}_{k} = \boldsymbol{\varepsilon}_{k} \mathbf{P}_{k} = \mathbf{P}_{k} \mathbf{M}$ The **P**_{*i*} are *Mutually Ortho-Normal* $\begin{array}{c} \vdots \\ \left(\begin{array}{c} \langle \boldsymbol{\varepsilon}_1 | \boldsymbol{\varepsilon}_1 \rangle & \langle \boldsymbol{\varepsilon}_1 | \boldsymbol{\varepsilon}_2 \rangle \\ \langle \boldsymbol{\varepsilon}_2 | \boldsymbol{\varepsilon}_1 \rangle & \langle \boldsymbol{\varepsilon}_2 | \boldsymbol{\varepsilon}_2 \rangle \end{array} \right) \end{array}$ as are bra-ket $\langle \varepsilon_i | \text{and} | \varepsilon_i \rangle$ inside \mathbf{P}_i 's $= \left(\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array}\right)$...and the \mathbf{P}_i satisfy a Completeness Relation: $\mathbf{P}_1 + \mathbf{P}_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ $1 = P_1 + P_2 + ... + P_n$ $\mathbf{M} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = 1\mathbf{P}_1 + 5\mathbf{P}_2 = 1|1\rangle\langle 1| + 5|2\rangle\langle 2| = 1 \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} + 5 \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix}$ $= |\varepsilon_{I}\rangle\langle\varepsilon_{I}| + |\varepsilon_{2}\rangle\langle\varepsilon_{2}| + ... + |\varepsilon_{n}\rangle\langle\varepsilon_{n}|$ $=|\varepsilon_1\rangle\langle\varepsilon_1|+|\varepsilon_2\rangle\langle\varepsilon_2|$ Examples: $\mathbf{M}^{50} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = \mathbf{1}^{50} \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} + \mathbf{5}^{50} \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 1+3\cdot5^{50} & 5^{50}-1 \\ 3\cdot5^{50}-3 & 5^{50}+3 \end{pmatrix}$ Eigen-operators $\mathbf{MP}_k = \varepsilon_k \mathbf{P}_k$ then give *Spectral Decomposition* of operator **M** $\mathbf{M} = \mathbf{MP}_1 + \mathbf{MP}_2 + \dots + \mathbf{MP}_n = \varepsilon_1 \mathbf{P}_1 + \varepsilon_2 \mathbf{P}_2 + \dots + \varepsilon_n \mathbf{P}_n$...and *Functional Spectral Decomposition* of any function $f(\mathbf{M})$ of \mathbf{M} $\sqrt{\mathbf{M}} = \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = \pm \sqrt{1} \begin{pmatrix} \frac{1}{4} & -\frac{1}{4} \\ -\frac{3}{4} & \frac{3}{4} \end{pmatrix} \pm \sqrt{5} \begin{pmatrix} \frac{3}{4} & \frac{1}{4} \\ \frac{3}{4} & \frac{1}{4} \end{pmatrix} = \begin{pmatrix} \frac{1}{4} + \frac{3\sqrt{5}}{4} & -\frac{1}{4} + \frac{3\sqrt{5}}{4} \\ -\frac{3}{4} + \frac{3\sqrt{5}}{4} & \frac{3}{4} + \frac{3\sqrt{5}}{4} \end{pmatrix}$ $f(\mathbf{M}) = f(\varepsilon_1)\mathbf{P}_1 + f(\varepsilon_2)\mathbf{P}_2 + \dots + f(\varepsilon_n)\mathbf{P}_n$

