Group Theory in Quantum Mechanics Based on AMOP Lectures 14-15 Lecture 25 (4.27.17) Atomic, Molecular, and Optical Physics

Introduction to Rotational Eigenstates and Spectra I

(Int.J.Mol.Sci, 14, 714(2013) p.755-774, QTCA Unit 7 Ch. 21-25) (PSDS - Ch. 5, 7)

Three (3) applications of R(3) rotation and U(2) unitary representations $D^{J}_{mn}(\alpha,\beta,\gamma)$ 1. Atomic and molecular $D^{J^*}_{mn}(\alpha,\beta,\gamma)$ -wavefunctions

 $``Mock-Mach'' lab-vs-body-defined states |J_{mn}\rangle = \mathsf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J*}_{mn}(\alpha,\beta,\gamma) \mathsf{R}(\alpha,\beta,\gamma) |_{(0,0,0)}\rangle$

2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha,\beta,\gamma)$ -transformation matrices General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn}^{J} = \sum_{m'} D^{J}_{m'n}(\alpha,\beta,\gamma)|_{m'n}^{J}$ Angular momentum cones and high J properties End Lect.24

Partial listing of the Harter-Soft/Heyoka LearnIt Web Apps as of April 24, 2017 (Apps are being upgraded as time permits)

Production Links - For the students & general public

BohrIt - Production; URL is "http://www.uark.edu/ua/modphys/markup/BohrItWeb.html" BounceIt - Production; URL is "http://www.uark.edu/ua/modphys/markup/BoxItWeb.html" BoxIt - Production; URL is "http://www.uark.edu/ua/modphys/markup/CoulItWeb.html" CoulIt - Production; URL is "http://www.uark.edu/ua/modphys/markup/CoulItWeb.html" Cycloidulum - Production; URL is "http://www.uark.edu/ua/modphys/markup/CycloidulumWeb.html" LearnIt - Production; URL is "http://www.uark.edu/ua/modphys" or "http://www.uark.edu/ua/modphys" or "http://www.uark.edu/ua/modphys" JerkIt - Production; URL is "http://www.uark.edu/ua/modphys" or "http://www.uark.edu/ua/modphys/markup/LearnItWeb.html" Pendulum - Production; URL is "http://www.uark.edu/ua/modphys/markup/JerkItWeb.html" QuantIt - Production; URL is "http://www.uark.edu/ua/modphys/markup/QuantItWeb.html" Relativity - Pirelli Entrant: URL is "http://www.uark.edu/ua/modphys/markup/QuantItWeb.html" Trebuchet Production; URL is "http://www.uark.edu/ua/modphys/markup/TrebuchetWeb.html"

Testing Links - For internal use and testing by Harter & Heyoka

BohrIt - Testing; URL is "http://www.uark.edu/ua/modphys/testing/markup/BohrItWeb.html" BounceIt - Testing; URL is "http://www.uark.edu/ua/modphys/testing/markup/BounceItWeb.html" BoxIt - Testing; URL is "http://www.uark.edu/ua/modphys/testing/markup/BoxItWeb.html" CoulIt - Testing; URL is "http://www.uark.edu/ua/modphys/testing/markup/CoulItWeb.html" Cycloidulum - Testing; URL is "http://www.uark.edu/ua/modphys/testing/markup/CoulItWeb.html" Harter-Soft Web Apps - Quick Reference - Testing; URL is "http://www.uark.edu/ua/modphys/testing/markup/CycloidulumWeb.html" JerkIt - Testing; URL is "http://www.uark.edu/ua/modphys/testing/markup/JerkItWeb.html" Pendulum - Testing; URL is "http://www.uark.edu/ua/modphys/testing/markup/PendulumWeb.html" Pendulum - Testing; URL is "http://www.uark.edu/ua/modphys/testing/markup/PendulumWeb.html"

Link to the complete listing of Harter-Soft LearnIt Web Apps and resources for Physics

Three (3) applications of R(3) rotation and U(2) unitary representations $D^{J}_{mn}(\alpha, \beta, \gamma)$ Atomic and molecular $D^{J^*}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions

 $(Mock-Mach" lab-vs-body-defined states |J_{mn}\rangle = \mathbf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J*}_{mn}(\alpha,\beta,\gamma) \mathbf{R}(\alpha,\beta,\gamma)|_{(0,0,0)}\rangle$

2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha,\beta,\gamma)|J_{m'n}\rangle$ Angular momentum cones and high J properties

$$1. Atomic and molecular D^{j*}_{mn}(\alpha,\beta,\gamma)-wavefunctions {j \ m} |\mathbf{R}(\alpha\beta\gamma)|_{n}^{j} = D_{m,n}^{j}(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!}\sqrt{(j+m)!(j-m)!} \sum_{k} (-1)^{k} \left(\cos\frac{\beta}{2}\right)^{2j+m-n-2k} \left(\sin\frac{\beta}{2}\right)^{n-m+2k} e^{-i(m\alpha+n\gamma)} e^{-i(m\alpha+n\gamma)}$$

$$(j+m-k)!(n-m+k)!k!(j-n-k)!$$

$$Vector (j=\ell=1) \ representation D^{1}(\alpha\beta\gamma) = \begin{pmatrix} e^{-i\alpha} & \cdots & \vdots \\ \vdots & 1 & \cdots & e^{i\alpha} \end{pmatrix} \left[\frac{1+\cos\beta}{2} & \frac{-\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \cos\beta & \frac{-\sin\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \\ \frac{1+\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \\ \frac{1+\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \\ \frac{1+\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{\sqrt{2}} \frac{1+\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{\sqrt{2}} \\ \frac{1+\cos\beta}{\sqrt{2}} & \frac{1$$

$$\begin{array}{ll} \text{I. Atomic and molecular } D^{j*}_{mn}(\alpha,\beta,\gamma) \text{-wavefunctions} \\ \left\langle {}_{m}^{j} \right| \mathbf{R}(\alpha\beta\gamma) \left| {}_{n}^{j} \right\rangle = D_{m,n}^{j}(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!}\sqrt{(j+m)!(j-m)!} \frac{\sum_{k} (-1)^{k} \left(\cos\frac{\beta}{2}\right)^{2j+m-n-2k} \left(\sin\frac{\beta}{2}\right)^{n-m+2k} e^{-i(m\alpha+n\gamma)}}{(j+m-k)!(n-m+k)!k!(j-n-k)!} \\ \text{Vector } (j=\ell=1) \text{ representation} \\ D^{1}(\alpha\beta\gamma) = \begin{pmatrix} e^{-i\alpha} & \cdots \\ \ddots & e^{i\alpha} \end{pmatrix} \left(\frac{1+\cos\beta}{\sqrt{2}} & \frac{-\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \cos\beta & -\frac{\sin\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \cos\beta & -\frac{\sin\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} & \frac{1+\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} & \frac{1+\cos\beta}{2} \\ \text{Here half-angle identities were used. } \cos^{2}\beta = \frac{1+\cos\beta}{2}, \sin^{2}\beta = \frac{1-\cos\beta}{2}, \sin^{2}\beta = \frac{\sin\beta}{2}, \\ \text{Center } (n=0) \text{ column with the factor } \sqrt{\frac{2\ell+1}{4\pi}} \\ \text{gives set of spherical harmonics } Y^{\ell}_{m}. \end{array}$$

$$Y_m^{\ell}(\phi\theta) = D_{m,n=0}^{\ell^*}(\phi\theta0)\sqrt{\frac{2\ell+1}{4\pi}}$$

Dipole (j==1) wavefunctions $D_{1,0}^{1*}(\phi\theta0) = -e^{i\phi} \frac{\sin\theta}{\sqrt{2}} = -\frac{\cos\phi\sin\theta + i\cos\phi\sin\theta}{\sqrt{2}} = -\frac{x + iy}{r\sqrt{2}}$ $D_{0,0}^{1*}(\phi\theta0) = \cos\theta = \cos\theta = z/r$ $D_{-1,0}^{1*}(\phi\theta0) = e^{-i\phi} \frac{\sin\theta}{\sqrt{2}} = \frac{\cos\phi\sin\theta - i\cos\phi\sin\theta}{\sqrt{2}} = \frac{x - iy}{r\sqrt{2}}$

$$1. Atomic and molecular $D^{j*}mn(\alpha, \beta, \gamma)$ -wavefunctions

$$\begin{cases} j \\ m \end{bmatrix} \mathbf{R}(\alpha\beta\gamma) \Big|_{n}^{j} \Big|_{n}^{j} = D_{m,n}^{j}(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!}\sqrt{(j+m)!(j-m)!} \frac{\sum_{k} (-1)^{k} \left(\cos\frac{\beta}{2}\right)^{2j+m-n-2k} \left(\sin\frac{\beta}{2}\right)^{n-m+2k}}{(j+m-k)!(n-m+k)!k!(j-n-k)!} e^{-i(m\alpha+n\gamma)}$$

$$(j+m-k)!(n-m+k)!k!(j-n-k)!$$

$$Vector (j=\ell=1) representation$$

$$D^{1}(\alpha\beta\gamma) = \begin{pmatrix} e^{-i\alpha} & \cdots \\ \cdot & 1 & \cdot \\ \cdot & \cdot & e^{i\alpha} \end{pmatrix} \left(\frac{1+\cos\beta}{\sqrt{2}} & \frac{-\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \cos\beta & \frac{-\sin\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{\sqrt{2}} & e^{-i\gamma} \\ e^{i\alpha} & \frac{1-\cos\beta}{\sqrt{2}} & e^{i\alpha} & \frac{1-\cos\beta}{\sqrt{2}} e^{i\gamma} \\ e^{i\alpha} & \frac{1-\cos\beta}{\sqrt{2}} & e^{i\alpha} & \frac{1-\cos\beta}{\sqrt{2}} e^{i\gamma} \\ \frac{\sin\beta}{\sqrt{2}} & e^{i\alpha} & \frac{1-\cos\beta}{\sqrt{2}} e^{i\gamma} \\ \frac{\sin\beta}{\sqrt{2}} & e^{i\alpha} & \frac{1-\cos\beta}{\sqrt{2}} e^{i\gamma} \\ \frac{\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{\sqrt{2}} e^{i\gamma} \\ \frac{\sin\beta}{\sqrt{2}}$$$$

gives set of spherical harmonics
$$Y^{\ell}_{m}$$
.
 $Y^{\ell}_{m}(\phi\theta) = D^{\ell*}_{m,n=0}(\phi\theta0)\sqrt{\frac{2\ell+1}{4\pi}}$
Dipole $(j=\ell=1)$ wave functions
 $D^{1*}_{1,0}(\phi\theta0) = -e^{i\phi}\frac{\sin\theta}{\sqrt{2}} = -\frac{\cos\phi\sin\theta+i\cos\phi\sin\theta}{\sqrt{2}} = -\frac{x+iy}{r\sqrt{2}}$
 $D^{1*}_{0,0}(\phi\theta0) = \cos\theta = \cos\theta = z/r$
 $D^{1*}_{-1,0}(\phi\theta0) = e^{-i\phi}\frac{\sin\theta}{\sqrt{2}} = \frac{\cos\phi\sin\theta-i\cos\phi\sin\theta}{\sqrt{2}} = \frac{x-iy}{r\sqrt{2}}$
3-D linear-circular polarization T-matrix:
 $\begin{pmatrix} \langle 1 \\ 1 \\ 2 \\ \langle 1 \\ -1 \\ 1 \end{pmatrix}^{2} \langle 1 \\ \langle 1 \\ -1 \\ 1 \end{pmatrix}^{2} \langle 1 \\ -1 \\ 1 \end{pmatrix}^{2} \langle 1 \\ -1 \\ 1 \end{pmatrix}^{2} = \begin{pmatrix} -1 \\ -\frac{i}{\sqrt{2}} \\ 0 \\ 0 \\ -\frac{1}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} \\ 0 \\ -\frac{i}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} \\ 0 \\ -\frac{i}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}} \\ 0 \\ -\frac{i}{\sqrt{2}} \\ -\frac{i}{\sqrt{2}$

$$\begin{aligned} 1. Atomic and molecular D^{j} m(\alpha, \beta, \gamma) - wavefunctions \\ \begin{cases} i_{m}^{j} | \mathbf{R}(\alpha\beta\gamma) |_{n}^{j} \rangle = D_{m,n}^{j}(\alpha\beta\gamma) = \sqrt{(j+n)!(j-n)!}\sqrt{(j+m)!(j-m)!} \sum_{k=1}^{k} (-1)^{k} \left(\cos\frac{\beta}{2}\right)^{2+mm-2k} \left(\sin\frac{\beta}{2}\right)^{mm+2k} e^{-i(m\alpha+n\gamma)} \\ (j+m-k)!(n-m+k)!k!(j-n-k)! \\ (j+m-k)!(n-m+k)!k!(j-n-k)! \end{aligned}$$

$$\begin{aligned} \text{Vector } (j=\ell=1) \text{ representation} \\ D^{i}(\alpha\beta\gamma) = \left[e^{-m} + \cdots + e^{-m} \right] \left[\frac{1+\cos\beta}{2\sqrt{2}} - \frac{-m\beta}{2\sqrt{2}} + \frac{1-\cos\beta}{2\sqrt{2}} + \frac{1-\cos$$

$$Vector (j=\ell=1) representation$$

$$D^{1}(\alpha\beta\gamma) = \begin{pmatrix} e^{-i\alpha} & \cdot & \cdot \\ \cdot & 1 & \cdot \\ \cdot & 1 & \cdot \\ \cdot & \cdot & e^{i\alpha} \end{pmatrix} \begin{pmatrix} \frac{1+\cos\beta}{2} & \frac{-\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{\sin\beta}{\sqrt{2}} & \cos\beta & -\frac{-\sin\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{\sin\beta}{\sqrt{2}} & \frac{1+\cos\beta}{2} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{\sin\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{\sqrt{2}} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{1+\cos\beta}{\sqrt{2}} & \frac{1-\cos\beta}{2} \\ \frac{1-\cos\beta}{\sqrt{2}} & \frac{1-\cos\beta}{\sqrt{2}} \\$$

Dipole $(j = \ell = 1)$ *wave functions*

 $D_{1,0}^{1*}(\phi\theta0) = -e^{i\phi}\frac{\sin\theta}{\sqrt{2}} = -\frac{\cos\phi\sin\theta + i\cos\phi\sin\theta}{\sqrt{2}} = -\frac{x + iy}{r\sqrt{2}}$ $D_{0,0}^{1*}(\phi\theta0) = \cos\theta = \cos\theta = z/r$ $D_{-1,0}^{1*}(\phi\theta0) = e^{-i\phi}\frac{\sin\theta}{\sqrt{2}} = \frac{\cos\phi\sin\theta - i\cos\phi\sin\theta}{\sqrt{2}} = \frac{x - iy}{r\sqrt{2}}$



$$\Psi_{x}^{1}(\phi,\theta) = D_{x,z}^{1}(\phi,\theta,0)$$
$$= \cos\phi\sin\theta$$
$$\Psi_{y}^{1}(\phi,\theta) = D_{y,z}^{1}(\phi,\theta,0)$$
$$= \sin\phi\sin\theta$$
$$\Psi_{z}^{1}(\phi,\theta) = D_{z,z}^{1}(\phi,\theta,0)$$

 $=\cos\theta$

$$\Psi_{y} = D^{1}y0$$

j = 1

Standing

p-*Waves*



j = 1 Standing p-Waves







$$\Psi_x^1(\phi,\theta) = D_{x,z}^1(\phi,\theta,0)$$
$$= \cos\phi\sin\theta$$
$$\Psi_y^1(\phi,\theta) = D_{y,z}^1(\phi,\theta,0)$$
$$= \sin\phi\sin\theta$$
$$\Psi_z^1(\phi,\theta) = D_{z,z}^1(\phi,\theta,0)$$
$$= \cos\theta$$

Standing p-Wave Distributions

Moving *p*-Wave Distributions $|\Psi_{-1}|^2 = |D^1_{-10}|^2$



 $|\Psi_z|^2 = |D^1_{z0}|^2$

 $|\Psi_{v}|^{2} = |D^{I}_{v0}|^{2}$

 $0 |^2 \qquad |\Psi_1|^2 = |D^1_{10}|^2$



 $Tensor (j=\ell=2) representation \\ D^{2}(\alpha\beta0) = \begin{pmatrix} e^{-i2\alpha} \left(\frac{1+\cos\beta}{2}\right)^{2} & e^{-i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta \\ e^{-i\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{-i\alpha} \left(\frac{1+\cos\beta}{2}\right) (2\cos\beta-1) \\ \sqrt{\frac{3}{8}} \sin^{2}\beta & \sqrt{\frac{3}{2}} \sin\beta \cos\beta \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i\alpha} \left(\frac{1-\cos\beta}{2}\right) (2\cos\beta+1) \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i\alpha} \left(\frac{1-\cos\beta}{2}\right) (2\cos\beta+1) \\ e^{i2\alpha} \left(\frac{1-\cos\beta}{2}\right)^{2} & e^{i2\alpha} \left(\frac{1-\cos\beta}{2}\right) (2\cos\beta+1) \\ e^{i2\alpha} \left(\frac{1-\cos\beta}{2}\right)^{2} & e^{i2\alpha} \left(\frac{1-\cos\beta}{2}\right) \sin\beta \\ e^{i2\alpha} \left(\frac{1-\cos\beta}{2}\right)^{2} & e^{i2\alpha} \left(\frac{1-\cos\beta}{2}\right) \sin\beta \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i\alpha} \left(\frac{1-\cos\beta}{2}\right) \sin\beta \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i\alpha} \left(\frac{1-\cos\beta}{2}\right) \sin\beta \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i\alpha} \left(\frac{1-\cos\beta}{2}\right) \sin\beta \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right)^{2} \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta \\ e^{i2$

$$Tensor (j=\ell=2) \ representation \\ D^{2}(\alpha\beta0) = \begin{pmatrix} e^{-i2\alpha} \left(\frac{1+\cos\beta}{2}\right)^{2} & e^{-i2\alpha} \left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{-i\alpha} \left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{-i\alpha} \left(\frac{1+\cos\beta}{2}\right)\cos\beta - 1 \\ e^{-i\alpha} \left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{-i\alpha} \left(\frac{1+\cos\beta}{2}\right)(2\cos\beta-1) \\ \sqrt{\frac{3}{8}}\sin^{2}\beta & \sqrt{\frac{3}{2}}\sin\beta\cos\beta & \frac{3\cos^{2}\beta-1}{2} \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{i\alpha} \left(\frac{1-\cos\beta}{2}\right)(2\cos\beta+1) & \frac{3\cos^{2}\beta-1}{\sqrt{\frac{3}{2}}} \\ e^{i\alpha} \sin\beta\cos\beta & \sqrt{\frac{3}{8}}\sin^{2}\beta \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right)^{2} & e^{i2\alpha} \left(\frac{1-\cos\beta}{2}\right)\sin\beta & \sqrt{\frac{3}{8}}e^{i2\alpha}\sin\beta\cos\beta \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right)\sin\beta \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right)\sin\beta \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right)\sin\beta & e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right)\sin\beta \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right)\cos\beta \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right)\cos\beta \\ e^{i2\alpha} \left(\frac{1+\cos\beta}{2}\right)\cos$$

Spherical 2^k -multipole functions X_q^k or X-functions are D*-functions times the kth power of radius (r^k) .

$$\begin{split} \sqrt{4\pi/5} \ Y_{m=2}^{\ell=2}(\phi\theta) &= D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}}e^{i2\phi}\sin^2\theta &= \sqrt{\frac{3}{8}}\frac{(x+iy)^2}{r^2} \\ \sqrt{4\pi/5} \ Y_{m=1}^{\ell=2}(\phi\theta) &= D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}}e^{i\phi}\sin\theta\cos\theta &= -\sqrt{\frac{3}{2}}\frac{(x+iy)z}{r^2} \\ \sqrt{4\pi/5} \ Y_{m=0}^{\ell=2}(\phi\theta) &= D_{0,0}^{2*}(\phi\theta0) = \frac{3\cos^2\theta - 1}{2} &= \frac{3z^2 - r^2}{2r^2} \\ \sqrt{4\pi/5} \ Y_{m=-1}^{\ell=2}(\phi\theta) &= D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}}e^{-i\phi}\sin\theta\cos\theta &= \sqrt{\frac{3}{2}}\frac{(x-iy)z}{r^2} \\ \sqrt{4\pi/5} \ Y_{m=-2}^{\ell=2}(\phi\theta) &= D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}}e^{-i2\phi}\sin^2\theta &= \sqrt{\frac{3}{8}}\frac{(x-iy)^2}{r^2} \end{split}$$

Notation Switch:azimuth angle: $\alpha \rightarrow \phi$ polar angle: $\beta \rightarrow \theta$

$$X_{q}^{k} = r^{k} D_{q,0}^{k^{*}} = \sqrt{\frac{4\pi}{2k+1}} r^{k} Y_{q}^{k}$$







Tensor $(j=\ell=2)$ *representation* Spherical 2^k -multipole functions X_q^k or X-functions are D*-functions times the k^{th} power of radius (r^k) .

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$$X_q^k = r^k D_{q,0}^{k^*} = \sqrt{\frac{4\pi}{2k+1}} r^k Y_q^k$$





j = 2 Standing d-Waves

Notation Switch:azimuth angle: $\alpha \rightarrow \phi$ polar angle: $\beta \rightarrow \theta$











Note Pascal Triangle of (+) and (-) charges Three (3) applications of R(3) rotation and U(2) unitary representations $D^{J}_{mn}(\alpha,\beta,\gamma)$ 1. Atomic and molecular $D^{J*}_{mn}(\alpha,\beta,\gamma)$ -wavefunctions

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2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha,\beta,\gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha,\beta,\gamma)|J_{m'n}\rangle$ Angular momentum cones and high J properties

1. Atomic and molecular $D^{J^*}_{mn}(\alpha, \beta, \gamma)$ -wavefunctions "Mock-Mach" lab-vs-body-defined states $|J_{mn}\rangle = \mathsf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha, \beta, \gamma) D^{J^*}_{mn}(\alpha, \beta, \gamma) \mathsf{R}(\alpha, \beta, \gamma)|_{(0,0,0)}\rangle$

From Lecture 14 p.47

"Give me a place to stand... and I will move the Earth" Archimedes 287-212 B.C.E

Ideas of duality/relativity go way back (... VanVleck, Casimir..., Mach, Newton, Archimedes...)

Lab-fixed (Extrinsic-Global) \mathbf{R} , \mathbf{S} , vs. Body-fixed (Intrinsic-Local) $\mathbf{\bar{R}}$, $\mathbf{\bar{S}}$, vs.



Figure from Ch. 5 of PSDS (Originally in Rev. Mod. Phys. 50, 1, p. 37-83 (1978) Fig. 2)

"Mock-Mach" lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J*}_{mn}(\alpha,\beta,\gamma) \mathbf{R}(\alpha,\beta,\gamma)|_{(0,0,0)}\rangle$ For *SU*(2) and *R*(3), sum over rotations is an integral over Euler angles (αβγ). For integral-*j*=0, 1, 2,.. the *R*(3) integral over polar angle β ranges from 0 to π.

for
$$R(3): \frac{\ell^{j}}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{8\pi^{2}} \int_{0}^{2\pi} d\alpha \int_{0}^{\pi} d\beta \sin \beta \int_{0}^{2\pi} d\gamma = 2j+1 = \ell^{j}$$

For integral-j=1/2, 3/2,.. the U(2) integral over polar angle β ranges from $-\pi$ to π .

for
$$SU(2)$$
: $\frac{\ell^j}{N}\int d\left(\alpha\beta\gamma\right) = \frac{2j+1}{16\pi^2}\int_0^{2\pi} d\alpha \int_{-\pi}^{\pi} d\beta \sin\beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$

Eigenstates of angular momentum are built from projected initial position states $|000\rangle$.

$$\frac{\mathbf{P}_{m,n}^{j}|000\rangle}{\sqrt{\ell^{j}}} = \frac{1}{N} \int d(\alpha\beta\gamma) D_{m,n}^{j*}(\alpha\beta\gamma) \mathbf{R}(\alpha\beta\gamma)|000\rangle \sqrt{\ell^{j}} = \frac{1}{N} \int d(\alpha\beta\gamma) D_{m,n}^{j*}(\alpha\beta\gamma) \sqrt{\ell^{j}} |\alpha\beta\gamma\rangle$$

$$Lab \ z \text{-axis fixed} \text{in } Lab$$

$$\mathbf{J}$$

$$\mathbf{Rotor}$$

$$\mathbf{State}$$

$$\mathbf{J}$$

$$\mathbf{M}$$

$$\mathbf{J}$$

$$\mathbf{M}$$

Three (3) applications of R(3) rotation and U(2) unitary representations $D^{J}_{mn}(\alpha,\beta,\gamma)$ 1. Atomic and molecular $D^{J^*}_{mn}(\alpha,\beta,\gamma)$ -wavefunctions

"Mock-Mach" lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J*}_{mn}(\alpha,\beta,\gamma) \mathbf{R}(\alpha,\beta,\gamma)|_{(0,0,0)}\rangle$ 2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha,\beta,\gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathsf{R}_{(\alpha,\beta,\gamma)}|_{mn} \ge \sum_{m'} D^J_{m'n}(\alpha,\beta,\gamma)|_{m'n} \land$ Angular momentum cones and high J properties

"Mock-Mach" lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J*}_{mn}(\alpha,\beta,\gamma) \mathbf{R}_{(\alpha,\beta,\gamma)}|_{(0,0,0)}\rangle$ For SU(2) and R(3), sum over rotations is an integral over Euler angles $(\alpha\beta\gamma)$. For integral-j=0, 1, 2,... the R(3) integral over polar angle β ranges from 0 to π .

for
$$R(3): \frac{\ell^{j}}{N} \int d(\alpha \beta \gamma) = \frac{2j+1}{8\pi^{2}} \int_{0}^{2\pi} d\alpha \int_{0}^{\pi} d\beta \sin \beta \int_{0}^{2\pi} d\gamma = 2j+1 = \ell^{j}$$

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2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha,\beta,\gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn} \geq \sum_{m'} D^{J}_{m'n}(\alpha,\beta,\gamma)|_{m'n} \rangle$

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for
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: $\frac{\ell^j}{N}\int d(\alpha\beta\gamma) = \frac{2j+1}{16\pi^2}\int_0^{2\pi} d\alpha \int_{-\pi}^{\pi} d\beta \sin\beta \int_0^{2\pi} d\gamma = 2j+1 = \ell^j$

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General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn} \ge \sum_{m'} D^{J}_{m'n}(\alpha,\beta,\gamma)|_{m'n}$

"Mock-Mach" lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J*}_{mn}(\alpha,\beta,\gamma) \mathbf{R}(\alpha,\beta,\gamma)|_{(0,0,0)}\rangle$ For SU(2) and R(3), sum over rotations is an integral over Euler angles $(\alpha\beta\gamma)$. For integral-j=0, 1, 2,... the R(3) integral over polar angle β ranges from 0 to π .

for
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For integral-j=1/2, 3/2,.. the U(2) integral over polar angle β ranges from $-\pi$ to π .

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2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha,\beta,\gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn} \geq \sum_{m'} D^{J}_{m'n}(\alpha,\beta,\gamma)|_{m'n} \rangle$

Angular position is defined by a *rotational duality relativity relation* or "Mock-Mach" principle $\mathbf{R}(\alpha\beta\gamma)|000\rangle = |\alpha\beta\gamma\rangle = \mathbf{\bar{R}}^{\dagger}(\alpha\beta\gamma)|000\rangle \qquad \text{for all} \\ (\alpha\beta\gamma) \text{ and } (\alpha'\beta'\gamma') \qquad \mathbf{R}(\alpha\beta\gamma) \mathbf{\bar{R}}(\alpha'\beta'\gamma') = \mathbf{\bar{R}}(\alpha'\beta'\gamma') \mathbf{R}(\alpha\beta\gamma) \\ (\alpha\beta\gamma) \mathbf{R}(\alpha\beta\gamma) \mathbf{\bar{R}}(\alpha'\beta'\gamma') = \mathbf{\bar{R}}(\alpha'\beta'\gamma') \mathbf{R}(\alpha\beta\gamma) \\ \text{Left hand (LAB-m) and right hand (BODY-n) quantum numbers apply in turn.} \\ \text{LAB } m \leftrightarrow m' \mathbf{R}(\alpha\beta\gamma) \Big|_{m,n}^{j} \rangle = \sum_{m'=-j}^{j} D_{m',n}^{j}(\alpha\beta\gamma) \Big|_{m',n}^{j} \rangle \qquad \text{BOD } n \leftrightarrow n' \quad \mathbf{\bar{R}}(\alpha\beta\gamma) \Big|_{m,n}^{j} \rangle = \sum_{n'=-j}^{j} D_{n',n}^{j*}(\alpha\beta\gamma) \Big|_{m,n'}^{j} \rangle \\ \text{Same applies to the generators } \mathbf{S}_{Z} \text{ or } \mathbf{J}_{Z} \text{ of } SU(2) \text{ or } \mathbf{R}(3). \\ \text{LAB } m \\ eigenvalues \qquad \mathbf{S}_{Z} \Big|_{m,n}^{j} \rangle = m \Big|_{m,n}^{j} \rangle \qquad \text{BOD } n \\ eigenvalues \qquad \mathbf{\bar{S}}_{Z} \Big|_{m,n}^{j} \rangle = m \Big|_{m,n}^{j} \rangle$



2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha,\beta,\gamma)$ -transformation matrices General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn}^{J} \ge \sum_{m'} D^{J}_{m'n}(\alpha,\beta,\gamma)|_{m'n}^{J}$

Angular position is defined by a *rotational duality relativity relation* or "Mock-Mach" principle $\mathbf{R}(\alpha\beta\gamma)|000\rangle = |\alpha\beta\gamma\rangle = \mathbf{\bar{R}}^{\dagger}(\alpha\beta\gamma)|000\rangle \qquad \text{for all} \\ (\alpha\beta\gamma) \text{and}(\alpha'\beta'\gamma') \qquad \mathbf{R}(\alpha\beta\gamma)\mathbf{\bar{R}}(\alpha'\beta'\gamma') = \mathbf{\bar{R}}(\alpha'\beta'\gamma')\mathbf{R}(\alpha\beta\gamma)$ Left hand (LAB-*m*) and right hand (BODY-*n*) quantum numbers apply in turn. LAB $m \leftrightarrow m' \mathbf{R}(\alpha\beta\gamma)|_{m,n}^{j}\rangle = \sum_{m'=-j}^{j} D_{m',n}^{j}(\alpha\beta\gamma)|_{m',n}^{j}\rangle$ $\begin{array}{c} \text{BOD } n \leftrightarrow n' \quad \mathbf{\bar{R}}(\alpha\beta\gamma)|_{m,n}^{j}\rangle = \sum_{n'=-j}^{j} D_{n',n}^{j*}(\alpha\beta\gamma)|_{m,n}^{j}\rangle \\ \text{Same applies to the generators } \mathbf{S}_{Z} \text{ or } \mathbf{J}_{Z} \text{ of } SU(2) \text{ or } R(3). \\ \end{array}$ $\begin{array}{c} \text{BOD } n \\ \text{eigenvalues} \quad \mathbf{\bar{S}}_{Z}|_{m,n}^{j}\rangle = m|_{m,n}^{j}\rangle \\ \end{array}$ Three (3) applications of R(3) rotation and U(2) unitary representations $D^{J}_{mn}(\alpha,\beta,\gamma)$ 1. Atomic and molecular $D^{J^*}_{mn}(\alpha,\beta,\gamma)$ -wavefunctions

"Mock-Mach" lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J*}_{mn}(\alpha,\beta,\gamma) \mathbf{R}(\alpha,\beta,\gamma)|_{(0,0,0)}\rangle$

2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn} \ge \sum_{m'} D^{J}_{m'n}(\alpha,\beta,\gamma)|_{m'n} < Angular momentum cones and high J properties$

2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha, \beta, \gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn}^{J} \ge \sum_{m'} D^{J}_{m'n}(\alpha,\beta,\gamma)|_{m'n}^{J}$ Polarization analysis: Suppose a spin-*j* state $\mathbf{R}(0\beta 0)|_{n=1}^{j=2}$ exits an analyzer rotated by β and then enters a vertical ($\beta = 0$) analyzer and forced to choose from unrotated states $|_{m'}^{j=2}$

$$\mathbf{R}(0\beta 0)\Big|_{n}^{j}\Big\rangle = \sum_{m'=-j}^{j}\Big|_{m'}^{j}\Big\rangle\Big\langle_{m'}^{j}\Big|\mathbf{R}(0\beta 0)\Big|_{n}^{j}\Big\rangle$$
$$= \sum_{m'=-j}^{j}\Big|_{m'}^{j}\Big\rangle D_{m'n}^{j}(0\beta 0)$$



2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha,\beta,\gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn}^{J} \ge \sum_{m'} D^{J}_{m'n}(\alpha,\beta,\gamma)|_{m'n}^{J}$ Polarization analysis: Suppose a spin-*j* state $\mathbf{R}(0\beta 0)|_{n=1}^{j=2}$ exits an analyzer rotated by β and then enters a vertical ($\beta = 0$) analyzer and forced to choose from unrotated states $|_{m'}^{j=2}$

$$\mathbf{R}(0\beta 0)\Big|_{n}^{j}\Big\rangle = \sum_{m'=-j}^{j}\Big|_{m'}^{j}\Big\rangle\Big\langle_{m'}^{j}\Big|\mathbf{R}(0\beta 0)\Big|_{n}^{j}\Big\rangle$$
$$= \sum_{m'=-j}^{j}\Big|_{m'}^{j}\Big\rangle D_{m'n}^{j}(0\beta 0)$$

Overlap of state $\mathbf{R}(\alpha\beta\gamma)|_{l}^{2}$ with unrotated $|_{m'}^{j=2}\rangle$ is the corresponding D-matrix element.

 $\left\langle {}^{j'}_{m'} \left| \mathbf{R} \left(\alpha \beta \gamma \right) \right|_{1}^{2} \right\rangle = \delta^{j'2} D_{m'1}^{2} \left(\alpha \beta \gamma \right) = \left\langle {}^{j'}_{m'} \right|_{1}^{2} \right\rangle_{R}$

 $D^{j}_{m'n}(0\beta 0)$ plotted vs. β for fixed j,m',n

QTforCA Unit 8. Ch. 23 Fig. 23.2.1



2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha,\beta,\gamma)$ -transformation matrices General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn}^{J} = \sum_{m'} D^{J}_{m'n}(\alpha,\beta,\gamma)|_{m'n}^{J}$

$$D^{2}(\alpha\beta) = \begin{pmatrix} e^{-i2\alpha} \left(\frac{1+\cos\beta}{2}\right)^{2} & e^{-i2\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta \\ e^{-i\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{-i\alpha} \left(\frac{1+\cos\beta}{2}\right) (2\cos\beta-1) \\ \sqrt{\frac{3}{8}} \sin^{2}\beta & \sqrt{\frac{3}{2}} \sin\beta\cos\beta \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i\alpha} \left(\frac{1-\cos\beta}{2}\right) (2\cos\beta+1) \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta & e^{i\alpha} \left(\frac{1-\cos\beta}{2}\right) (2\cos\beta+1) \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right)^{2} & e^{i2\alpha} \left(\frac{1-\cos\beta}{2}\right) (2\cos\beta+1) \\ \sqrt{\frac{3}{8}} e^{i2\alpha} \sin^{2}\beta \\ \sqrt{\frac{3}{8}} e^{i2\alpha} \sin^{2}\beta \\ \sqrt{\frac{3}{8}} e^{i2\alpha} \sin^{2}\beta \\ \sqrt{\frac{3}{8}} e^{i2\alpha} \sin^{2}\beta \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) (2\cos\beta-1) & -e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) \sin\beta \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) (2\cos\beta-1) & -e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) (2\cos\beta-1) \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) (2\cos\beta-1) & -e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) (2\cos\beta-1) \\ e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) (2\cos\beta-1) & -e^{i\alpha} \left(\frac{1+\cos\beta}{2}\right) (2\cos\beta-1) \\ e^{i\alpha}$$

Overlap of state $\mathbf{R}(\alpha\beta\gamma)|_{l}^{2}$ with unrotated $|_{m'}^{j=2}\rangle$ is the corresponding D-matrix element.

$$\left\langle {}^{j'}_{m'} \left| \mathbf{R} \left(\alpha \beta \gamma \right) \right|_{1}^{2} \right\rangle = \delta^{j'2} D_{m'1}^{2} \left(\alpha \beta \gamma \right) = \left\langle {}^{j'}_{m'} \right|_{1}^{2} \right\rangle_{R}$$

 $D^{j}_{m'n}(0\beta 0)$ plotted vs. β for fixed j,m',n

QTforCA Unit 8. Ch. 23 Fig. 23.2.5





Three (3) applications of R(3) rotation and U(2) unitary representations $D^{J}_{mn}(\alpha,\beta,\gamma)$ 1. Atomic and molecular $D^{J*}_{mn}(\alpha,\beta,\gamma)$ -wavefunctions

"Mock-Mach" lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J*}_{mn}(\alpha,\beta,\gamma) \mathbf{R}(\alpha,\beta,\gamma)|_{(0,0,0)}\rangle$ 2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha,\beta,\gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|J_{mn}\rangle = \sum_{m'} D^J_{m'n}(\alpha,\beta,\gamma)|J_{m'n}\rangle$ Angular momentum cones and high J properties

Angular momentum cones and high J properties















Three (3) applications of R(3) rotation and U(2) unitary representations $D^{J}_{mn}(\alpha,\beta,\gamma)$ 1. Atomic and molecular $D^{J*}_{mn}(\alpha,\beta,\gamma)$ -wavefunctions

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General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn} \ge \sum_{m'} D^{J}_{m'n}(\alpha,\beta,\gamma)|_{m'n}$ Angular momentum cones is high J properties

Angular momentum cones and high J properties

Using literal interpretation of $\binom{J}{m}$ to derive approximate number Δm of "most-busy" counters and determine most probable *m*-values.







QuantIt web simulation: Visualizing D representations


Using literal interpretation of $\begin{pmatrix} J \\ m \end{pmatrix}$ to derive approximate number Δm of "most-busy" counters and determine most probable *m*-values.





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Using literal interpretation of $\begin{pmatrix} J \\ m \end{pmatrix}$ to derive approximate number Δm of "most-busy" counters and determine most probable *m*-values.





Using literal interpretation of $\begin{pmatrix} J \\ m \end{pmatrix}$ to derive approximate number Δm of "most-busy" counters and determine most probable *m*-values.





Three (3) applications of R(3) rotation and U(2) unitary representations $D^{J}_{mn}(\alpha,\beta,\gamma)$ 1. Atomic and molecular $D^{J^*}_{mn}(\alpha,\beta,\gamma)$ -wavefunctions "Mock-Mach" lab-vs-body-defined states $|J_{mn}\rangle = \mathsf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J^*}_{mn}(\alpha,\beta,\gamma) \mathsf{R}(\alpha,\beta,\gamma)|_{(0,0,0)}\rangle$ 2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha,\beta,\gamma)$ -transformation matrices General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn} \geq \sum_{m'} D^{J}_{m'n}(\alpha,\beta,\gamma)|_{m'n} \rangle$ Angular momentum cones and high J properties 3. Atomic and molecular multipole Hamiltonian tensor operators \mathbf{T}_q^k and eigenvalues Multipole \mathbf{T}_q^k expansion of asymmetric-rotor Hamiltonians $\mathbf{H} = A \mathbf{J}_x^2 + B \mathbf{J}_y^2 + C \mathbf{J}_z^2$ Multipole \mathbf{T}_q^k expansion of symmetric-rotor Hamiltonians $\mathbf{H}=B\mathbf{J}_x^2+B\mathbf{J}_y^2+C\mathbf{J}_z^2$ Rotational Energy Surfaces (RE or RES) of symmetric rotor and eigensolutions Rotational Energy Surfaces (RE or RES) of asymmetric rotor and energy levels Sketch of modern molecular electronic, vibrational, and rotational spectroscopy *Example of CO*₂ *rovibration* $(v=0) \Leftrightarrow (v=1)$ *bands* Introduction to RE symmetry and RES analysis of rovibrational Hamiltonians Asymmetric Top eigensolutions for J=1-2

Angular momentum cones and high J properties of LAB vs BOD wavefunctions



QTforCA Unit 8. Ch. 23 Fig. 23.2.4

QTforCA Unit 8. Ch. 23 Fig. 23.2.7

Angular momentum cones and high J properties of LAB vs BOD wavefunctions



Angular momentum cones and high J properties of LAB vs BOD wavefunctions



Three (3) applications of R(3) rotation and U(2) unitary representations $D^{J}_{mn}(\alpha,\beta,\gamma)$ 1. Atomic and molecular $D^{J*}_{mn}(\alpha,\beta,\gamma)$ -wavefunctions

"Mock-Mach" lab-vs-body-defined states $|J_{mn}\rangle = \mathsf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J^*}_{mn}(\alpha,\beta,\gamma) \mathsf{R}(\alpha,\beta,\gamma)|_{(0,0,0)}\rangle$ 2. R(3) rotation and U(2) unitary $D^J_{mn}(\alpha,\beta,\gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn} \ge \sum_{m'} D^J_{m'n}(\alpha,\beta,\gamma)|_{m'n}$ Angular momentum cones and high J properties

 Atomic and molecular multipole Hamiltonian tensor operators T_q^k and eigenvalues Multipole T_q^k expansion of asymmetric-rotor Hamiltonians H=AJ_x²+BJ_y²+CJ_z²
 Multipole T_q^k expansion of symmetric-rotor Hamiltonians H=BJ_x²+BJ_y²+CJ_z²
 Rotational Energy Surfaces (RE or RES) of symmetric rotor and eigensolutions Rotational Energy Surfaces (RE or RES) of asymmetric rotor and energy levels
 Sketch of modern molecular electronic, vibrational, and rotational spectroscopy Example of CO₂ rovibration (v=0)⇔(v=1)bands
 Introduction to RE symmetry and RES analysis of rovibrational Hamiltonians Asymmetric Top eigensolutions for J=1-2

Spherical 2^k-multipole functions X_q^k or X-functions are D*-functions times the kth power of radius (r^k) . Consider k=2 "quadrupole" functions $\sum_{i=1}^{k} (r+iv)^2$ $X_a^k = r^k D_{a,0}^{k*} = \sqrt{\frac{4\pi}{2+1}} r^k Y_a^k$

$$\begin{split} \sqrt{4\pi/5} \ Y_{m=2}^{\ell=2}(\phi\theta) &= D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}}e^{i2\phi}\sin^2\theta \\ &= \sqrt{\frac{3}{8}}\frac{(x+iy)^2}{r^2} \\ \sqrt{4\pi/5} \ Y_{m=1}^{\ell=2}(\phi\theta) \\ &= D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}}e^{i\phi}\sin\theta\cos\theta \\ &= -\sqrt{\frac{3}{2}}\frac{(x+iy)z}{r^2} \\ \sqrt{4\pi/5} \ Y_{m=0}^{\ell=2}(\phi\theta) \\ &= D_{0,0}^{2*}(\phi\theta0) = \frac{3\cos^2\theta - 1}{2} \\ &= \frac{3z^2 - r^2}{2r^2} \\ \sqrt{4\pi/5} \ Y_{m=-1}^{\ell=2}(\phi\theta) \\ &= D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}}e^{-i\phi}\sin\theta\cos\theta \\ &= \sqrt{\frac{3}{2}}\frac{(x-iy)z}{r^2} \\ \sqrt{4\pi/5} \ Y_{m=-2}^{\ell=2}(\phi\theta) \\ &= D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}}e^{-i2\phi}\sin^2\theta \\ &= \sqrt{\frac{3}{8}}\frac{(x-iy)^2}{r^2} \end{split}$$

Spherical 2^k -multipole functions X_q^k or X-functions are D*-functions times the k^{th} power of radius (r^k) . Consider k=2 "quadrupole" functions

$$\begin{split} & \sqrt{4\pi/5} \ Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}}e^{i2\phi}\sin^2\theta = \sqrt{\frac{3}{8}}\frac{(x+iy)^2}{r^2} \\ & \sqrt{4\pi/5} \ Y_{m=1}^{\ell=2}(\phi\theta) = D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}}e^{i\phi}\sin\theta\cos\theta = -\sqrt{\frac{3}{2}}\frac{(x+iy)z}{r^2} \\ & \sqrt{4\pi/5} \ Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3\cos^2\theta - 1}{2} = \frac{3z^2 - r^2}{2r^2} \\ & \sqrt{4\pi/5} \ Y_{m=0}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}}e^{-i\phi}\sin\theta\cos\theta = \sqrt{\frac{3}{2}}\frac{(x-iy)z}{r^2} \\ & \sqrt{4\pi/5} \ Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}}e^{-i\phi}\sin\theta\cos\theta = \sqrt{\frac{3}{2}}\frac{(x-iy)z}{r^2} \\ & \sqrt{4\pi/5} \ Y_{m=-2}^{\ell=2}(\phi\theta) = D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}}e^{-i2\phi}\sin^2\theta = \sqrt{\frac{3}{8}}\frac{(x-iy)^2}{r^2} \end{split}$$

Spherical 2^k-multipole functions X_q^k or X-functions are D*-functions times the kth power of radius (r^k) . Consider k=2 "quadrupole" functions

$$\frac{\sqrt{4\pi/5}}{\sqrt{4\pi/5}} Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}} e^{i2\phi} \sin\theta \cos\theta = \sqrt{\frac{3}{8}} \frac{(x+iy)^2}{r^2} \qquad X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}} r^k Y_q^k \\
\sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) = D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin\theta \cos\theta = -\sqrt{\frac{3}{2}} \frac{(x+iy)z}{r^2} \qquad \sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3\cos^2\theta - 1}{2} = \frac{3z^2 - r^2}{2r^2} \qquad \sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = x_0^2(\phi\theta0) = r^2 \frac{3\cos^2\theta - 1}{2} = \frac{3z^2 - r^2}{2} = \frac{2z^2 - x^2 - y^2}{2} \\
\sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}} e^{-i\phi} \sin\theta \cos\theta = \sqrt{\frac{3}{2}} \frac{(x-iy)z}{r^2} \qquad The (x,y,z) \text{ polynomials become} \\
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$$\rightarrow \qquad \mathbf{T}_{0}^{2} = \frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \mathbf{J}^{2} \frac{3\cos^{2}\theta - 1}{2} = \mathbf{J}^{2} P_{2}(\cos\theta)$$

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$$\sqrt{4\pi/5} Y_{m=1}^{\ell=2}(\phi\theta) = D_{1,0}^{2*}(\phi\theta0) = -\sqrt{\frac{3}{2}}e^{i\phi}\sin\theta\cos\theta = -\sqrt{\frac{3}{2}}\frac{(x+iy)z}{r^{2}} \qquad \sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = r^{2}\frac{3\cos^{2}\theta-1}{2} = \frac{3z^{2}-r^{2}}{2} = \frac{3z^{2}-r^{2}}{2}$$

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$$X_{2}^{2}(\phi\theta0) = \sqrt{\frac{3}{8}}r^{2}e^{i2\phi}\sin^{2}\theta = \sqrt{\frac{3}{8}}(x+iy)^{2} = \sqrt{\frac{3}{8}}(x^{2}+2ixy-y^{2}) \qquad T_{0}^{2} = \frac{2J_{z}^{2}-J_{y}^{2}}{2} = J^{2}\frac{3\cos^{2}\theta-1}{2} = J^{2}P_{2}(\cos\theta)$$

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$$\sqrt{4\pi/5} Y_{m=0}^{t=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = -\frac{3\cos^2\theta - 1}{2} = \frac{3z^2 - r^2}{2r^2}$$

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$$The (x,y,z) polynomials become (J_x,J_y,J_z) rotor tensor operators$$

$$X_2^2(\phi\theta0) = \sqrt{\frac{3}{8}}e^{-i2\phi}\sin^2\theta = \sqrt{\frac{3}{8}}(x+iy)^2 = \sqrt{\frac{3}{8}}(x^2+2ixy-y^2)$$

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Building Hamiltonian $\mathbf{H} = A \mathbf{J}_x^2 + B \mathbf{J}_y^2 + C \mathbf{J}_z^2$ out of scalar and tensor operators Spherical 2^k-multipole functions X^{k}_{q} or X-functions are D*-functions times the kth power of radius (r^{k}) . *Consider k=2 "quadrupole" functions* $\sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}}e^{i2\phi}\sin^2\theta = \sqrt{\frac{3}{8}\frac{(x+iy)^2}{x^2}} \qquad X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}}r^k Y_q^k$ $\sqrt{4\pi/5} Y_{m=1}^{\ell=2} \left(\phi \theta \right) = D_{1,0}^{2*} \left(\phi \theta 0 \right) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin \theta \cos \theta = -\sqrt{\frac{3}{2}} \frac{\left(x + iy \right) z}{2}$ $\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3\cos^2\theta - 1}{2} = \frac{3z^2 - r^2}{2y^2} \longrightarrow \sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = r^2 \frac{3\cos^2\theta - 1}{2} = \frac{3z^2 - r^2}{2} = \frac{2z^2 - x^2 - y^2}{2}$ $\sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}}e^{-i\phi}\sin\theta\cos\theta = \sqrt{\frac{3}{2}}\frac{(x-iy)z}{2}$ $\sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) = D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}e^{-i2\phi}\sin^2\theta} = \sqrt{\frac{3}{8}\frac{(x-iy)^2}{2}}$ The (x, y, z) polynomials become (J_x, J_y, J_z) rotor tensor operators $X_{2}^{2}(\phi\theta0) = \sqrt{\frac{3}{8}r^{2}e^{i2\phi}\sin^{2}\theta} = \sqrt{\frac{3}{8}(x+iy)^{2}} = \sqrt{\frac{3}{8}(x^{2}+2ixy-y^{2})}$ $\mathbf{T}_{0}^{2} = \frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \mathbf{J}^{2} \frac{3\cos^{2}\theta - 1}{2} = \mathbf{J}^{2} P_{2}(\cos\theta)$ $+ \frac{X_{-2}^{2}(\phi\theta0)}{\sqrt{\frac{3}{8}}e^{-i2\phi}\sin^{2}\theta} = \sqrt{\frac{3}{8}(x-iy)^{2}} = \sqrt{\frac{3}{8}(x^{2}-2ixy-y^{2})}$ $= X_{2}^{2}(\phi\theta0) + X_{-2}^{2}(\phi\theta0) = \sqrt{\frac{3}{2}}r^{2}\frac{e^{i2\phi} + e^{-i2\phi}}{2}\sin^{2}\theta = \sqrt{\frac{3}{2}}(x^{2} - y^{2}) = \sqrt{\frac{3}{2}}r^{2}\cos 2\phi\sin^{2}\theta \qquad \longrightarrow \qquad \mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2} = \sqrt{6}\frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \sqrt{\frac{3}{2}}\mathbf{J}^{2}\sin^{2}\theta\cos 2\phi$

Building Hamiltonian $\mathbf{H} = A \mathbf{J}_x^2 + B \mathbf{J}_y^2 + C \mathbf{J}_z^2$ out of scalar and tensor operators Spherical 2^k -multipole functions X^k_q or X-functions are D*-functions times the kth power of radius (r^k) . *Consider k*=2 *"quadrupole" functions* $\sqrt{4\pi/5} Y_{m=2}^{\ell=2}(\phi\theta) = D_{2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}}e^{i2\phi}\sin^2\theta = \sqrt{\frac{3}{8}\frac{(x+iy)^2}{x^2}} \qquad X_q^k = r^k D_{q,0}^{k*} = \sqrt{\frac{4\pi}{2k+1}}r^k Y_q^k$ $\sqrt{4\pi/5} Y_{m=1}^{\ell=2} \left(\phi \theta \right) = D_{1,0}^{2*} \left(\phi \theta 0 \right) = -\sqrt{\frac{3}{2}} e^{i\phi} \sin \theta \cos \theta = -\sqrt{\frac{3}{2}} \frac{\left(x + iy \right) z}{2}$ $\sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = D_{0,0}^{2*}(\phi\theta0) = \frac{3\cos^2\theta - 1}{2} = \frac{3z^2 - r^2}{2r^2} \longrightarrow \sqrt{4\pi/5} Y_{m=0}^{\ell=2}(\phi\theta) = r^2 \frac{3\cos^2\theta - 1}{2} = \frac{3z^2 - r^2}{2} = \frac{2z^2 - x^2 - y^2}{2}$ $\sqrt{4\pi/5} Y_{m=-1}^{\ell=2}(\phi\theta) = D_{-1,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{2}}e^{-i\phi}\sin\theta\cos\theta = \sqrt{\frac{3}{2}}\frac{(x-iy)z}{2}$ $\sqrt{4\pi/5} Y_{m=-2}^{\ell=2}(\phi\theta) = D_{-2,0}^{2*}(\phi\theta0) = \sqrt{\frac{3}{8}}e^{-i2\phi}\sin^2\theta = \sqrt{\frac{3}{8}\frac{(x-iy)^2}{2}}$ The (x, y, z) polynomials become (J_x, J_y, J_z) rotor tensor operators $X_{2}^{2}(\phi\theta0) = \sqrt{\frac{3}{8}r^{2}e^{i2\phi}\sin^{2}\theta} = \sqrt{\frac{3}{8}(x+iy)^{2}} = \sqrt{\frac{3}{8}(x^{2}+2ixy-y^{2})}$ $\mathbf{T}_{0}^{2} = \frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \mathbf{J}^{2} \frac{3\cos^{2}\theta - 1}{2} = \mathbf{J}^{2} P_{2}(\cos\theta)$ $+ \frac{X_{-2}^{2}(\phi\theta0)}{\sqrt{\frac{3}{8}}e^{-i2\phi}\sin^{2}\theta} = \sqrt{\frac{3}{8}(x-iy)^{2}} = \sqrt{\frac{3}{8}(x^{2}-2ixy-y^{2})}$ $= X_{2}^{2}(\phi\theta0) + X_{-2}^{2}(\phi\theta0) = \sqrt{\frac{3}{2}}r^{2}\frac{e^{i2\phi} + e^{-i2\phi}}{2}\sin^{2}\theta = \sqrt{\frac{3}{2}}(x^{2} - y^{2}) = \sqrt{\frac{3}{2}}r^{2}\cos 2\phi\sin^{2}\theta \qquad \longrightarrow \qquad \mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2} = \sqrt{6}\frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \sqrt{\frac{3}{2}}\mathbf{J}^{2}\sin^{2}\theta\cos 2\phi$

$$= X_2^2(\phi\theta0) - X_{-2}^2(\phi\theta0) = \sqrt{\frac{3}{2}}r^2 \frac{e^{i2\phi} - e^{-i2\phi}}{2}\sin^2\theta = \sqrt{\frac{3}{8}}(i4xy) = i\sqrt{6}xy = i\sqrt{\frac{3}{2}}r^2\sin 2\phi\sin^2\theta \longrightarrow \mathbf{T}_2^2 - \mathbf{T}_{-2}^2 = i\sqrt{6}\mathbf{J}_x\mathbf{J}_y$$

etc.

And, don't forget scalar: $\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2$

Three (3) applications of R(3) rotation and U(2) unitary representations $D^{J}_{mn}(\alpha,\beta,\gamma)$ 1. Atomic and molecular $D^{J*}_{mn}(\alpha,\beta,\gamma)$ -wavefunctions

"Mock-Mach" lab-vs-body-defined states $|J_{mn}\rangle = \mathsf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J^*}_{mn}(\alpha,\beta,\gamma) \mathsf{R}(\alpha,\beta,\gamma)|_{(0,0,0)}\rangle$ 2. R(3) rotation and U(2) unitary $D^J_{mn}(\alpha,\beta,\gamma)$ -transformation matrices

General Stern-Gerlach and polarization transformations $\mathbf{R}_{(\alpha,\beta,\gamma)}|_{mn} \ge \sum_{m'} D^J_{m'n}(\alpha,\beta,\gamma)|_{m'n}$ Angular momentum cones and high J properties

 Atomic and molecular multipole Hamiltonian tensor operators T_q^k and eigenvalues Multipole T_q^k expansion of asymmetric-rotor Hamiltonians H=AJ_x²+BJ_y²+CJ_z²
 Multipole T_q^k expansion of symmetric-rotor Hamiltonians H=BJ_x²+BJ_y²+CJ_z²
 Rotational Energy Surfaces (RE or RES) of symmetric rotor and eigensolutions Rotational Energy Surfaces (RE or RES) of asymmetric rotor and energy levels
 Sketch of modern molecular electronic, vibrational, and rotational spectroscopy Example of CO₂ rovibration (v=0)⇔(v=1)bands
 Introduction to RE symmetry and RES analysis of rovibrational Hamiltonians Asymmetric Top eigensolutions for J=1-2 Making symmetric rotor Hamiltonian $\mathbf{H} = B \mathbf{J}_x^2 + B \mathbf{J}_y^2 + C \mathbf{J}_z^2$ out of scalar \mathbf{T}_0^2 and tensor \mathbf{T}_q^2 operators $\mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2 \begin{bmatrix} \mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \\ \mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_y^2}{2} \end{bmatrix} = \mathbf{J}^2 \frac{3\cos^2\theta - 1}{2} = \mathbf{J}^2 P_2(\cos\theta) \begin{bmatrix} \mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} \\ \frac{1}{2} - \frac{1}{2} - \frac{1}{2} \frac{1}{2} \mathbf{J}^2 \sin^2\theta \cos 2\phi \end{bmatrix}$





$$\begin{array}{l} \text{Making symmetric rotor Hamiltonian } \mathbf{H} = B \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} \text{ out of scalar } \mathbf{T}_{0}^{2} \text{ and tensor } \mathbf{T}_{q}^{2} \text{ operators} \\ \mathbf{T}_{0}^{0} = \mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \\ \hline \mathbf{T}_{0}^{2} = \frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \mathbf{J}^{2} \frac{3\cos^{2}\theta - 1}{2} = \mathbf{J}^{2}P_{2}(\cos\theta) \\ \hline \mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2} = \sqrt{6} \frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^{2} \sin^{2}\theta\cos2\phi \\ \mathbf{H} = A\mathbf{J}_{x}^{2} + B\mathbf{J}_{y}^{2} + C\mathbf{J}_{z}^{2} \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ + (\frac{-1}{6}A + \frac{-1}{6}B + \frac{2}{6}C)(-\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2} + 2\mathbf{J}_{z}^{2}) \\ + (\frac{1}{2}A + \frac{-1}{2}B + 0C)(\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2} + 2\mathbf{J}_{z}^{2}) \end{array}$$

$$\begin{array}{l} \label{eq:horizondal} \begin{aligned} & \text{Making symmetric rotor Hamiltonian } \mathbf{H} = B \mathbf{J}_x^2 + B \mathbf{J}_y^2 + C \mathbf{J}_z^2 \ \text{out of scalar } \mathbf{T}_0^2 \ \text{and tensor } \mathbf{T}_q^2 \ \text{operators} \\ & \mathbf{T}_0^0 = \mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2 = \mathbf{J}^2 \\ \hline \mathbf{T}_0^2 = \frac{2\mathbf{J}_z^2 - \mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \mathbf{J}^2 \frac{3\cos^2\theta - 1}{2} = \mathbf{J}^2 P_2(\cos\theta) \\ \hline \mathbf{T}_2^2 + \mathbf{T}_{-2}^2 = \sqrt{6} \frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^2 \sin^2\theta \cos 2\theta \\ & \mathbf{H} = A \mathbf{J}_x^2 + B \mathbf{J}_y^2 + C \mathbf{J}_z^2 \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2) \\ & = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_x^2 + \mathbf{J}_y^2 + \mathbf{J}_z^2) \\ & + (\frac{-1}{6}A + \frac{-1}{6}B + \frac{2}{6}C)(-\mathbf{J}_x^2 - \mathbf{J}_y^2 + 2\mathbf{J}_z^2) \\ & + (\frac{1}{\sqrt{6}}A + \frac{-1}{3}B + \frac{2}{3}C)(\sqrt{6}\frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2}) \\ & + (\frac{1}{\sqrt{6}}A + \frac{-1}{\sqrt{6}}B + 0C)(\sqrt{6}\frac{\mathbf{J}_x^2 - \mathbf{J}_y^2}{2}) \end{aligned}$$

$$\begin{aligned} \begin{array}{l} \text{Making symmetric rotor Hamiltonian } \mathbf{H} = \mathbf{B} \mathbf{J}_{x}^{2} + \mathbf{B} \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} \text{ out of scalar } \mathbf{T}_{0}^{2} \text{ and tensor } \mathbf{T}_{q}^{2} \text{ operators} \\ \mathbf{T}_{0}^{0} = \mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \\ \hline \mathbf{T}_{0}^{2} = \frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \mathbf{J}^{2} \frac{3\cos^{2}\theta - 1}{2} = \mathbf{J}^{2}P_{2}(\cos\theta) \\ \hline \mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2} = \sqrt{6} \frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^{2} \sin^{2}\theta\cos2\phi \\ \hline \mathbf{H} = \mathbf{A} \mathbf{J}_{x}^{2} + \mathbf{B} \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} \\ = \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C\right)\left(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}\right) \\ = \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C\right)\left(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}\right) \\ = \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C\right)\left(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}\right) \\ = \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C\right)\left(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}\right) \\ + \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C\right)\left(\frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2}\right) \\ + \left(\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C\right)\left(\frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2}\right) \\ + \left(\frac{1}{\sqrt{6}}A + \frac{-1}{3}B + \frac{2}{3}C\right)\left(\frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2}\right) \\ + \left(\frac{1}{\sqrt{6}}(A - B)(\mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2})\right) \\ \end{array}$$

$$\begin{aligned} \text{Making symmetric rotor Hamiltonian } \mathbf{H} &= B \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} \text{ out of scalar } \mathbf{T}_{0}^{2} \text{ and tensor } \mathbf{T}_{q}^{2} \text{ operators} \\ \mathbf{T}_{0}^{0} &= \mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \\ \mathbf{T}_{0}^{2} &= \frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \mathbf{J}^{2} \frac{3\cos^{2}\theta - 1}{2} = \mathbf{J}^{2}P_{2}(\cos\theta) \\ \mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2} &= \sqrt{6} \frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^{2}\sin^{2}\theta\cos2\phi \\ \mathbf{H} &= A\mathbf{J}_{x}^{2} + B\mathbf{J}_{y}^{2} + C\mathbf{J}_{z}^{2} \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}(A + B + C)(\mathbf{T}_{0}^{0}) \\ &+ (\frac{1}{3}A + \frac{1}{3}B + \frac{2}{3}C)(\frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}) \\ &+ (\frac{1}{3}(-A - B + 2C)(\mathbf{T}_{0}^{2}) \\ &+ (\frac{1}{\sqrt{6}}(A + \frac{-1}{\sqrt{6}}B + 0C)(\sqrt{6}\frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2}) \\ &+ (\frac{1}{\sqrt{6}}(A - B)(\mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2}) \end{aligned}$$

Resulting asymmetric top Hamiltonian expansion:

asymmetry

 $\mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \frac{1}{3} (A + B + C)(\mathbf{T}_{0}^{0}) + \frac{1}{3} (2C - A - B)(\mathbf{T}_{0}^{2}) + \frac{A - B}{\sqrt{6}} (\mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2})$

$$\begin{array}{l} \mbox{Making symmetric rotor Hamiltonian } \mathbf{H} = B \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} \ out of scalar \ \mathbf{T}_{0}^{2} \ and tensor \ \mathbf{T}_{q}^{2} \ operators \\ \mathbf{T}_{0}^{0} = \mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \\ \hline \mathbf{T}_{0}^{2} = \frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \mathbf{J}^{2} \frac{3\cos^{2}\theta - 1}{2} = \mathbf{J}^{2}P_{2}(\cos\theta) \\ \hline \mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2} = \sqrt{6} \frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^{2} \sin^{2}\theta\cos2\phi \\ \hline \mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ + (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = \frac{1}{3}(A + B + C)(\mathbf{T}_{0}^{0}) \\ + (\frac{1}{2}A + \frac{-1}{2}B + 0C)(\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2} + 2\mathbf{J}_{z}^{2}) \\ + (\frac{1}{\sqrt{6}}A + \frac{-1}{\sqrt{6}}B + 0C)(\sqrt{6}\frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2}) \\ + (\frac{1}{\sqrt{6}}(A - B)(\mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2}) \\ \end{array}$$

Resulting asymmetric top Hamiltonian expansion:

asymmetry

$$\mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \frac{1}{3} (A + B + C) (\mathbf{T}_{0}^{0}) + \frac{1}{3} (2C - A - B) (\mathbf{T}_{0}^{2}) + \frac{A - B}{\sqrt{6}} (\mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2})$$

Resulting semi-classical asymmetric top Hamiltonian expansion: asymmetry

$$\mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \frac{1}{3} (A + B + C)(\mathbf{J}^{2}) + \frac{1}{3} (2C - A - B)(\mathbf{J}^{2} \frac{3\cos^{2} \theta - 1}{2}) + \frac{A - B}{\sqrt{6}} (\sqrt{\frac{3}{2}} \mathbf{J}^{2} \sin^{2} \theta \cos 2\phi)$$

$$\begin{array}{l} \mbox{Making symmetric rotor Hamiltonian } \mathbf{H} = \mathbf{B} \mathbf{J}_{x}^{2} + \mathbf{B} \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} \ out of scalar } \mathbf{T}_{0}^{2} \ and tensor \\ \mathbf{T}_{0}^{2} = \mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \\ \hline \mathbf{T}_{0}^{2} = \frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \mathbf{J}^{2} \frac{3\cos^{2}\theta - 1}{2} = \mathbf{J}^{2}P_{2}(\cos\theta) \\ \hline \mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2} = \sqrt{6} \frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^{2} \sin^{2}\theta\cos2\phi \\ \hline \mathbf{H} = \mathbf{A} \mathbf{J}_{x}^{2} + \mathbf{B} \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} \\ = (\frac{1}{3}\mathbf{A} + \frac{1}{3}\mathbf{B} + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}\mathbf{A} + \frac{1}{3}\mathbf{B} + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}\mathbf{A} + \frac{1}{3}\mathbf{B} + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}\mathbf{A} + \frac{1}{3}\mathbf{B} + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}\mathbf{A} + \frac{1}{3}\mathbf{B} + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}\mathbf{A} + \frac{1}{3}\mathbf{B} + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ + (\frac{1}{3}\mathbf{A} + \frac{1}{3}\mathbf{B} + \frac{1}{3}C)(\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = \frac{1}{3}(\mathbf{A} + \mathbf{B} + C)(\mathbf{T}_{0}^{0}) \\ + (\frac{1}{2}\mathbf{A} + \frac{-1}{6}\mathbf{B} + \frac{2}{6}C)(-\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ + (\frac{1}{\sqrt{6}}\mathbf{A} + \frac{-1}{3}\mathbf{B} + \frac{2}{3}C)(\frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{y}^{2}}{2}) \\ + (\frac{1}{\sqrt{6}}(\mathbf{A} - \mathbf{B})(\mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2}) \\ \end{array}$$

Resulting asymmetric top Hamiltonian expansion:

asymmetry

$$\mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \frac{1}{3} (A + B + C) (\mathbf{T}_{0}^{0}) + \frac{1}{3} (2C - A - B) (\mathbf{T}_{0}^{2}) + \frac{A - B}{\sqrt{6}} (\mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2})$$

Resulting semi-classical asymmetric top Hamiltonian expansion: asymmetry

$$\mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \frac{1}{3} (A + B + C) (\mathbf{J}^{2}) + \frac{1}{3} (2C - A - B) (\mathbf{J}^{2} \frac{3\cos^{2} \theta - 1}{2}) + \frac{A - B}{\sqrt{6}} (\sqrt{\frac{3}{2}} \mathbf{J}^{2} \sin^{2} \theta \cos 2\phi)$$
$$\mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \left[\frac{A + B + C}{3} + \frac{2C - A - B}{6} (3\cos^{2} \theta - 1) + \frac{A - B}{2} \sin^{2} \theta \cos 2\phi \right]$$

$$\begin{array}{l} \text{Making symmetric rotor Hamiltonian } \mathbf{H} = B \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} \text{ out of scalar } \mathbf{T}_{0}^{2} \text{ and tensor } \mathbf{T}_{q}^{2} \text{ operators} \\ \mathbf{T}_{0}^{0} = \mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \\ \mathbf{T}_{0}^{2} = \frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \mathbf{J}^{2} \frac{3\cos^{2}\theta - 1}{2} = \mathbf{J}^{2}P_{2}(\cos\theta) \\ \mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2} = \sqrt{6} \frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^{2} \sin^{2}\theta\cos2q \\ \mathbf{H} = A\mathbf{J}_{x}^{2} + B\mathbf{J}_{y}^{2} + C\mathbf{J}_{z}^{2} \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ = \frac{1}{3}(A + B + C)(\mathbf{T}_{0}^{0}) \\ + (\frac{-1}{6}A + \frac{-1}{6}B + \frac{2}{6}C)(-\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2} + 2\mathbf{J}_{z}^{2}) \\ + (\frac{1}{3}A + \frac{-1}{3}B + \frac{2}{3}C)(\frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}) \\ + (\frac{1}{\sqrt{6}}A + \frac{-1}{\sqrt{6}}B + 0C)(\sqrt{6}\frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}) \\ + (\frac{1}{\sqrt{6}}(A - B)(\mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2}) \end{array}$$

asymmetry

Resulting asymmetric top Hamiltonian expansion:

 $\mathbf{H} = \mathbf{A}\mathbf{J}_{x}^{2} + \mathbf{B}\mathbf{J}_{y}^{2} + C\mathbf{J}_{z}^{2} = \frac{1}{3}(\mathbf{A} + \mathbf{B} + C)(\mathbf{T}_{0}^{0}) + \frac{1}{3}(2C - \mathbf{A} - \mathbf{B})(\mathbf{T}_{0}^{2}) + \frac{\mathbf{A} - \mathbf{B}}{\sqrt{6}}(\mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2})$

Resulting semi-classical asymmetric top Hamiltonian expansion: asymmetry term

$$\mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \frac{1}{3} (A + B + C) (\mathbf{J}^{2}) + \frac{1}{3} (2C - A - B) (\mathbf{J}^{2} \frac{3\cos^{2} \theta - 1}{2}) + \frac{A - B}{\sqrt{6}} (\sqrt{\frac{3}{2}} \mathbf{J}^{2} \sin^{2} \theta \cos 2\phi)$$
$$\mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \left[\frac{A + B + C}{3} + \frac{2C - A - B}{6} (3\cos^{2} \theta - 1) + \frac{A - B}{2} \sin^{2} \theta \cos 2\phi \right]$$

Resulting semi-classical symmetric top Hamiltonian expansion: (A = B)

$$\mathbf{H} = B \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \left[\frac{B + B + C}{3} + \frac{2C - B - B}{6} (3\cos^{2}\theta - 1) + \frac{B - B}{2} \sin^{2}\theta \cos 2\phi \right] = \mathbf{J}^{2} \left[\frac{B + C - B}{3} 3\cos^{2}\theta \right]$$

$$\begin{aligned} \text{Making symmetric rotor Hamiltonian } \mathbf{H} &= B \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} \text{ out of scalar } \mathbf{T}_{0}^{2} \text{ and tensor } \mathbf{T}_{q}^{2} \text{ operators} \\ \mathbf{T}_{0}^{0} &= \mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \\ \mathbf{T}_{0}^{2} &= \frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \mathbf{J}^{2} \frac{3\cos^{2}\theta - 1}{2} = \mathbf{J}^{2}P_{2}(\cos\theta) \\ \mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2} &= \sqrt{6} \frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}}{2} = \sqrt{\frac{3}{2}} \mathbf{J}^{2}\sin^{2}\theta\cos2\phi \\ \mathbf{H} &= A\mathbf{J}_{x}^{2} + B\mathbf{J}_{y}^{2} + C\mathbf{J}_{z}^{2} \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}A + \frac{1}{3}B + \frac{1}{3}C)(\mathbf{J}_{x}^{2} + \mathbf{J}_{y}^{2} + \mathbf{J}_{z}^{2}) \\ &= (\frac{1}{3}(A + B + C)(\mathbf{T}_{0}^{0}) \\ &+ (\frac{1}{3}A + \frac{1}{3}B + \frac{2}{3}C)(\frac{2\mathbf{J}_{z}^{2} - \mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}) \\ &+ (\frac{1}{3}(-A - B + 2C)(\mathbf{T}_{0}^{2}) \\ &+ (\frac{1}{\sqrt{6}}A + \frac{-1}{\sqrt{6}}B + 0C)(\sqrt{6}\frac{\mathbf{J}_{x}^{2} - \mathbf{J}_{y}^{2}) \\ &+ (\frac{1}{\sqrt{6}}(A - B)(\mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2}) \end{aligned}$$

asymmetry

Resulting asymmetric top Hamiltonian expansion:

$$\mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \frac{1}{3} (A + B + C) (\mathbf{T}_{0}^{0}) + \frac{1}{3} (2C - A - B) (\mathbf{T}_{0}^{2}) + \frac{A - B}{\sqrt{6}} (\mathbf{T}_{2}^{2} + \mathbf{T}_{-2}^{2})$$

Resulting semi-classical asymmetric top Hamiltonian expansion: asymmetry

$$\mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \frac{1}{3} (A + B + C) (\mathbf{J}^{2}) + \frac{1}{3} (2C - A - B) (\mathbf{J}^{2} \frac{3\cos^{2} \theta - 1}{2}) + \frac{A - B}{\sqrt{6}} (\sqrt{\frac{3}{2}} \mathbf{J}^{2} \sin^{2} \theta \cos 2\phi)$$
$$\mathbf{H} = A \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \left[\frac{A + B + C}{3} + \frac{2C - A - B}{6} (3\cos^{2} \theta - 1) + \frac{A - B}{2} \sin^{2} \theta \cos 2\phi \right]$$

Resulting semi-classical symmetric top Hamiltonian expansion: (A = B)

$$\mathbf{H} = B \mathbf{J}_{x}^{2} + B \mathbf{J}_{y}^{2} + C \mathbf{J}_{z}^{2} = \mathbf{J}^{2} \left[\frac{B + B + C}{3} + \frac{2C - B - B}{6} (3\cos^{2}\theta - 1) + \frac{B - B}{2} \sin^{2}\theta \cos 2\phi \right] = \mathbf{J}^{2} \left[B + (C - B)\cos^{2}\theta \right]$$
$$= B \mathbf{J}^{2} + (C - B)\mathbf{J}_{z}^{2} = B \mathbf{J}^{2} + (C - B)\mathbf{J}^{2}\cos^{2}\theta$$

Three (3) applications of R(3) rotation and U(2) unitary representations $D^{J}_{mn}(\alpha,\beta,\gamma)$ 1. Atomic and molecular $D^{J*}_{mn}(\alpha,\beta,\gamma)$ -wavefunctions

"Mock-Mach" lab-vs-body-defined states $|J_{mn}\rangle = \mathbf{P}_{mn} J|_{(0,0,0)}\rangle = \int d(\alpha,\beta,\gamma) D^{J*}_{mn}(\alpha,\beta,\gamma) \mathbf{R}(\alpha,\beta,\gamma)|_{(0,0,0)}\rangle$ 2. R(3) rotation and U(2) unitary $D^{J}_{mn}(\alpha,\beta,\gamma)$ -transformation matrices

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Sketch of modern molecular electronic, vibrational, and rotational spectroscopy Example of CO₂ rovibration (v=0)⇔(v=1)bands
Introduction to RE symmetry and RES analysis of rovibrational Hamiltonians Asymmetric Top eigensolutions for J=1-2 Rotational Energy Surfaces (RE or RES) of symmetric rotor and eigensolutions Plot Hamiltonian $\mathbf{H} = B\mathbf{J}^2 + (C - B)\mathbf{J}_z^2$ radially as $H(\Theta) = BJ(J+1) + (C - B)J(J+1)\cos^2\Theta$ j \ m,<mark>n</mark> / *Conventional notation:* n=KBOD



LAB m=Mn=K



Rotational Energy Surfaces (RE or RES) of symmetric rotor and eigensolutions Plot Hamiltonian $\mathbf{H}=B\mathbf{J}^2 + (C-B)\mathbf{J}_z^2$ radially as $H(\Theta)=BJ(J+1) + (C-B)J(J+1)\cos^2\Theta$ $\begin{vmatrix} j\\m,n \end{vmatrix}$ Conventional notation: n=K $H(\Theta_K^J)=BJ(J+1) + (C-B)J(J+1)\cos^2\Theta_K^J$ $H(\Theta_K^J)=BJ(J+1) + (C-B)J(J+1)\cos^2\Theta_K^J$ M=Mn=K



Rotational Energy Surfaces (RE or RES) of symmetric rotor and eigensolutions

 $H(\Theta) = BJ(J+1) + (C-B)J(J+1)\cos^2\Theta \qquad \text{where}: \mathbf{J}_z = |\mathbf{J}|\cos\Theta$ $H(\Theta_K^J) = BJ(J+1) + (C-B)J(J+1)\cos^2\Theta_K^J \qquad \text{where}: \mathbf{J}_z = |\mathbf{J}|\cos\Theta$ $= \sqrt{J(J+1)}\cos\Theta$ Plot Hamiltonian $\mathbf{H} = B\mathbf{J}^2 + (C - B)\mathbf{J}_z^2$ radially as $H(\Theta) = BJ(J+1) + (C - B)J(J+1)\cos^2\Theta$ $\begin{pmatrix} j \\ m, n \end{pmatrix}$ *Conventional notation:* n=K $=BJ(J+1)+(C-B)K^{2}$ LAB BOD m=Mn=K



(Here this gives exact quantum eigenvalues!)



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Asymmetric Top eigensolutions for J=1-2

Applications of R(3) rotation and U(2) representations

Molecular and nuclear eigenlevels

$$\mathbf{H}_{symmetric top} = B\mathbf{J}_{\overline{X}}^2 + B\mathbf{J}_{\overline{Y}}^2 + B\mathbf{J}_{\overline{Z}}^2 + (A - B)\mathbf{J}_{\overline{Z}}^2 = B\mathbf{J} \bullet \mathbf{J} + (A - B)\mathbf{J}_{\overline{Z}}^2$$



QTforCA Unit 8. Ch. 23 Fig. 23.2.4

QTforCA Unit 8. Ch. 23 Fig. 23.1.3

Applications of R(3) rotation and U(2) representations Molecular and nuclear eigenlevels



QTforCA Unit 8. Ch. 23 Fig. 23.2.4

QTforCA Unit 8. Ch. 23 Fig. 23.1.3

Applications of R(3) rotation and U(2) representations

Molecular and nuclear eigenlevels

$$\mathbf{H}_{symmetric top} = B\mathbf{J}_{\overline{X}}^2 + B\mathbf{J}_{\overline{Y}}^2 + B\mathbf{J}_{\overline{Z}}^2 + (A - B)\mathbf{J}_{\overline{Z}}^2 = B\mathbf{J} \bullet \mathbf{J} + (A - B)\mathbf{J}_{\overline{Z}}^2$$


Applications of R(3) rotation and U(2) representations Molecular and nuclear eigenlevels



QTforCA Unit 8. Ch. 23 Fig. 23.2.4

QTforCA Unit 8. Ch. 23 Fig. 23.1.3



QTforCA Unit 8. Ch. 23 Fig. 23.2.4

QTforCA Unit 8. Ch. 23 Fig. 23.1.3

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RES of symmetric rotor (Prolate and Oblate)



Asymmetric Top Eigensolutions Related to RE Surface and semi-classical J-phase paths



after QTforCA Unit 8. Ch. 25 Fig. 25.4.1

RES of symmetric rotor (Prolate and Oblate)



after QTforCA Unit 8. Ch. 25 Fig. 25.4.1



Separatrix circle pair dihedral angle

 θ_{sep} =atan $(\frac{A-B}{B-C})$



Int.J.Molecular Science 14.(2013) Fig.3 p. 733

Molecular Symmetry and Dynamics | 32.2 Rotational Energy Surfaces and Semiclassical Rotational Dynamics



J = 10 rotational energy surface and related level spectrum for an asymmetric rigid rotator (A = 0.2, $B = 1-C = 0.6 \text{ cm}^{-1}$)

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Introduction to RE symmetry and RES analysis of rovibrational Hamiltonians Asymmetric Top eigensolutions for J=1-2

*Example of CO*₂ *rotational* $(v=0) \Leftrightarrow (v=1)$ *bands*



*Example of CO*₂ *rotational* $(v=0) \Leftrightarrow (v=1)$ *bands*



Example of frequency hierarchy for 16µm spectra of CF4 (Freon-14) W.G.Harter Ch. 31 Atomic, Molecular, & Optical Physics Handbook Am. Int. of Physics Gordon Drake Editor (1996)



Example of frequency hierarchy for 16µm spectra of CF4 (Freon-14) W.G.Harter Fig. 32.7 Springer Handbook of Atomic, Molecular, & Optical Physics Gordon Drake Editor (2005)



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Asymmetric Top eigensolutions for J=1-2



Go to Lecture 26 p. 15 to 25 to...

(For more detailed and clearer discussion)

 $j,m,n \text{ formulas for momentum operator matrix elements:} \qquad (\text{Go to Lecture 26 p. 15 to 25 to...})$ $n_{\uparrow} = j + m \quad , \quad n_{\downarrow} = j - m$ $\begin{vmatrix} j \\ m \end{vmatrix} = \frac{(\mathbf{a}_{\uparrow}^{+})^{j+m}(\mathbf{a}_{\downarrow}^{+})^{j-m}}{\sqrt{(j+m)!}\sqrt{(j-m)!}} | 0,0 \rangle = \frac{|n_{\uparrow},n_{\downarrow}\rangle}{\sqrt{(n_{\uparrow})!}\sqrt{(n_{\downarrow})!}} \qquad \mathbf{a}_{\uparrow}^{+}\mathbf{a}_{\downarrow}|n_{\uparrow},n_{\downarrow}\rangle = \sqrt{n_{\uparrow}+1}\sqrt{n_{\downarrow}}|n_{\uparrow}+1|n_{\downarrow}-1\rangle} \Rightarrow \mathbf{J}_{\downarrow}|_{m}^{j}\rangle = \sqrt{j+m+1}\sqrt{j-m}|_{m+1}^{j}\rangle$ $\mathbf{a}_{\uparrow}^{+}\mathbf{a}_{\downarrow} = \mathbf{J}_{+} = \mathbf{J}_{X} + i\mathbf{J}_{Y}$ $\mathbf{a}_{\downarrow}^{+}\mathbf{a}_{\uparrow} = \mathbf{J}_{-} = \mathbf{J}_{X} - i\mathbf{J}_{Y} = \mathbf{J}_{+}^{\dagger}$ $\mathbf{J}_{X} = \frac{1}{2}[\mathbf{J}_{+} + \mathbf{J}_{-}]$ $\mathbf{J}_{Y} = -\frac{i}{2}[\mathbf{J}_{+} - \mathbf{J}_{-}]$

LAB matrix elements use the usual atomic formula:

$$\begin{pmatrix} J \\ m',n' \end{pmatrix} \left| \mathbf{J}_{\mathbf{X}} \right|_{m,n}^{J} \right\rangle = D_{m',m}^{J} \ (\mathbf{J}_{\mathbf{X}}) \delta_{n'n} = \frac{1}{2} \left[\delta_{m'm+1} \sqrt{(j-m)(j+m+1)} + \delta_{m'm-1} \sqrt{(j+m)(j-m+1)} \right] \delta_{n'n} \\ \begin{pmatrix} J \\ m',n' \end{pmatrix} \left| \mathbf{J}_{\mathbf{Y}} \right|_{m,n}^{J} \right\rangle = D_{m',m}^{J} \ (\mathbf{J}_{\mathbf{Y}}) \delta_{n'n} = \frac{-i}{2} \left[\delta_{m'm+1} \sqrt{(j-m)(j+m+1)} - \delta_{m'm-1} \sqrt{(j+m)(j-m+1)} \right] \delta_{n'n} \\ \begin{pmatrix} J \\ m',n' \end{pmatrix} \left| \mathbf{J}_{\mathbf{Z}} \right|_{m,n}^{J} \right\rangle = D_{m',m}^{J} \ (\mathbf{J}_{\mathbf{Z}}) \delta_{n'n} = \delta_{m'm} m \ \delta_{n'n}$$

BOD matrix elements are the same after switching *m*'s into *n*'s and changing sign of J_Y matrix (*-conjugation)

$$\begin{pmatrix} J\\m',n' \\ m',n' \\ m',n' \\ n' \\ m',n' \\ m'$$

Hamiltonian matrices for asymmetric rotor Hamiltonian

$$\mathbf{H} = \frac{1}{2} \left(\frac{\mathbf{J}_{\bar{X}}^{2}}{I_{\bar{X}}} + \frac{\mathbf{J}_{\bar{Y}}^{2}}{I_{\bar{Y}}} + \frac{\mathbf{J}_{\bar{Z}}^{2}}{I_{\bar{Z}}} \right) = A \mathbf{J}_{\bar{X}}^{2} + B \mathbf{J}_{\bar{Y}}^{2} + C \mathbf{J}_{\bar{Z}}^{2}$$

First are matrix formulas for BOD J² components.

$$\begin{aligned} \mathbf{J}_{\bar{X}}^{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle &= \frac{1}{2} \sqrt{(j-n)(j+n+1)} \mathbf{J}_{\bar{X}} \left| \begin{smallmatrix} J \\ m,n+1 \end{smallmatrix} \right\rangle &= \frac{1}{4} \sqrt{(j-n)(j+n+1)} \sqrt{(j-n-1)(j+n+2)} \left| \begin{smallmatrix} J \\ m,n+2 \end{smallmatrix} \right\rangle + \frac{1}{4} (j-n)(j+n+1) \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &+ \frac{1}{2} \sqrt{(j+n)(j-n+1)} \mathbf{J}_{\bar{X}} \left| \begin{smallmatrix} J \\ m,n-2 \end{smallmatrix} \right\rangle + \frac{1}{4} (j+n)(j-n+1) \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &+ \frac{1}{4} \sqrt{(j+n)(j-n+1)} \sqrt{(j+n-1)(j-n+2)} \left| \begin{smallmatrix} J \\ m,n-2 \end{smallmatrix} \right\rangle \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle &+ \frac{\sqrt{(j+n)(j+n-1)(j-n+1)}(j+n+2)} \left| \begin{smallmatrix} J \\ m,n-2 \end{smallmatrix} \right\rangle \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &= \frac{-1}{4} \sqrt{(j-n)(j+n+1)} \mathbf{J}_{\bar{Y}} \left| \begin{smallmatrix} J \\ m,n+2 \end{smallmatrix} \right\rangle \\ &= \frac{-1}{4} \sqrt{(j-n)(j+n+1)} \sqrt{(j-n-1)(j+n+2)} \left| \begin{smallmatrix} J \\ m,n+2 \end{smallmatrix} \right\rangle \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &= \frac{-1}{4} \sqrt{(j-n)(j-n-1)(j+n+1)} \mathbf{J}_{\bar{Y}} \left| \begin{smallmatrix} J \\ m,n+2 \end{smallmatrix} \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &- \frac{\sqrt{(j-n)(j-n-1)(j+n+1)}(j+n+2)}}{4} \left| \begin{smallmatrix} J \\ m,n+2 \end{smallmatrix} \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &- \frac{\sqrt{(j+n)(j+n-1)(j-n+2)}}{4} \left| \begin{smallmatrix} J \\ m,n-2 \end{smallmatrix} \right\rangle \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &- \frac{\sqrt{(j+n)(j+n-1)(j-n+2)}}{4} \left| \begin{smallmatrix} J \\ m,n-2 \end{smallmatrix} \right\rangle \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &- \frac{\sqrt{(j+n)(j+n-1)(j-n+2)}}{4} \left| \begin{smallmatrix} J \\ m,n-2 \end{smallmatrix} \right\rangle \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right\rangle \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2} \left| \begin{smallmatrix} J \\ m,n \end{smallmatrix} \right) \\ &+ \frac{j(j+1)-n^{2}}{2}$$

This gives the rigid asymmetric-top matrix formula for general *A*, *B*, *C* and *J*,*n*.:

$$(A\mathbf{J}_{\overline{X}}^{2} + B\mathbf{J}_{\overline{Y}}^{2} + C\mathbf{J}_{\overline{Z}}^{2})\Big|_{m,n}^{J} \rangle = = (A-B)\frac{\sqrt{(j-n)(j-n-1)(j+n+1)(j+n+2)}}{4}\Big|_{m,n+2}^{J} \rangle + [(A+B)\frac{j(j+1)-n^{2}}{2} + Cn^{2}]\Big|_{m,n}^{J} \rangle + (A-B)\frac{\sqrt{(j+n)(j+n-1)(j-n+1)(j-n+2)}}{4}\Big|_{m,n-2}^{J} \rangle$$

$$(J=I)-\text{Matrix for } A=I, B=2, C=3.$$

$$\begin{pmatrix} 1\\m,n' \\ m,n' \\$$

(*J*=2)-Matrix for *A*=1, *B*=2, *C*=3.

$$\left\langle A\mathbf{J}_{\overline{X}}^{2} + B\mathbf{J}_{\overline{Y}}^{2} + C\mathbf{J}_{\overline{Z}}^{2} \right\rangle^{J=2} = \begin{pmatrix} (A+B) + 4C & \cdot & \frac{\sqrt{6}}{2}(A-B) & \cdot & \cdot \\ \cdot & \frac{5}{2}(A+B) + C & \cdot & \frac{3}{2}(A-B) & \cdot \\ \frac{\sqrt{6}}{2}(A-B) & \cdot & 3(A+B) & \cdot & \frac{\sqrt{6}}{2}(A-B) \\ \cdot & \frac{3}{2}(A-B) & \cdot & \frac{5}{2}(A+B) + C & \cdot \\ \cdot & \cdot & \frac{\sqrt{6}}{2}(A-B) & \cdot & (A+B) + 4C \end{pmatrix} = \begin{pmatrix} 15 & -\frac{\sqrt{6}}{2} & & \\ \frac{15}{2} & -\frac{3}{2} & & \\ -\frac{\sqrt{6}}{2} & 6 & -\frac{\sqrt{6}}{2} \\ & -\frac{3}{2} & \frac{15}{2} & \\ & -\frac{\sqrt{6}}{2} & 15 \end{pmatrix}$$



(*J*=2)-Matrix for *A*=1, *B*=2, *C*=3.

$$\left\langle A\mathbf{J}_{\overline{X}}^{2} + B\mathbf{J}_{\overline{Y}}^{2} + C\mathbf{J}_{\overline{Z}}^{2} \right\rangle^{J=2} = \begin{pmatrix} (A+B) + 4C & \cdot & \frac{\sqrt{6}}{2}(A-B) & \cdot & \cdot & \cdot \\ & \cdot & \frac{5}{2}(A+B) + C & \cdot & \frac{3}{2}(A-B) & \cdot & \cdot \\ & \frac{\sqrt{6}}{2}(A-B) & \cdot & 3(A+B) & \cdot & \frac{\sqrt{6}}{2}(A-B) \\ & \cdot & \frac{3}{2}(A-B) & \cdot & \frac{5}{2}(A+B) + C & \cdot & \cdot \\ & \cdot & \cdot & \frac{\sqrt{6}}{2}(A-B) & \cdot & (A+B) + 4C \end{pmatrix} = \begin{pmatrix} 15 & -\frac{\sqrt{6}}{2} & \cdot \\ & \frac{15}{2} & -\frac{3}{2} & \cdot \\ & \frac{-\sqrt{6}}{2} & 6 & -\frac{\sqrt{6}}{2} \\ & & -\frac{3}{2} & \frac{15}{2} & \cdot \\ & & & -\frac{\sqrt{6}}{2} & 15 \end{pmatrix}$$

Matrix is nearly diagonalized in standing-wave D_2 -symmetry basis

$$\begin{vmatrix} A_1 2^+ \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ +2 \end{vmatrix} + \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -2 \end{vmatrix}, \qquad \begin{vmatrix} B_1 1^+ \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ +1 \end{vmatrix} + \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \begin{vmatrix} A_1 0 \\ P_1 2^+ \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix}, \qquad \end{vmatrix}$$

The following basis transformation "almost diagonalizes" $\langle \mathbf{H} \rangle^{J=2}$ by reducing it to block form. Let: $\Sigma = A + B$ and $\Delta = A - B$ to shorten expressions.

$$\begin{pmatrix} 1 & \cdot & \cdot & \cdot & 1 \\ 1 & \cdot & \cdot & -1 \\ \cdot & 1 & \cdot & 1 & \cdot \\ \cdot & 1 & \cdot & -1 & \cdot \\ \cdot & \sqrt{2} & \cdot & \sqrt{2} \end{pmatrix} \begin{pmatrix} 4C - \Sigma & \cdot & \sqrt{6\Delta} & \cdot & \cdot \\ \cdot & C + \frac{\Sigma}{2} & \cdot & \frac{3\Delta}{2} & \cdot \\ \cdot & C + \frac{\Sigma}{2} & \cdot & \frac{3\Delta}{2} & \cdot \\ \cdot & \frac{\sqrt{6}\Delta}{2} & \cdot & \Sigma & \cdot & \sqrt{2} \\ \cdot & \frac{3\Delta}{2} & \cdot & C + \frac{\Sigma}{2} & \cdot \\ \cdot & \cdot & \sqrt{2} & \frac{3\Delta}{2} & \cdot & C + \frac{\Sigma}{2} & \cdot \\ \cdot & \cdot & \sqrt{2} & \frac{3\Delta}{2} & \cdot & C + \frac{\Sigma}{2} & \cdot \\ \cdot & \cdot & \sqrt{2} & \frac{\sqrt{6}\Delta}{2} & \cdot & 4C - \Sigma \end{pmatrix} \begin{pmatrix} 1 & 1 & \cdot & \cdot & \cdot \\ \cdot & 1 & 1 & \cdot \\ \cdot & \cdot & \cdot & \sqrt{2} \\ \cdot & 1 & -1 & \cdot \\ 1 - 1 & \cdot & \cdot \end{pmatrix} \begin{pmatrix} 1 & 1 & \cdot & \cdot & \cdot \\ \cdot & 1 & 1 & \cdot \\ \cdot & \cdot & \cdot & \sqrt{2} \\ \cdot & 1 & -1 & \cdot \\ 1 - 1 & \cdot & \cdot \end{pmatrix} \end{pmatrix}$$

$$= \begin{pmatrix} 4C + \Sigma & \cdot & \cdot & \sqrt{3}\Delta \\ \cdot & 4C + \Sigma & \cdot & \cdot & \sqrt{3}\Delta \\ \cdot & 4C + \Sigma & \cdot & \cdot & \sqrt{3}\Delta \\ \cdot & 4C + \Sigma & \cdot & C + \frac{5\Sigma}{2} + \frac{3\Delta}{2} & \cdot \\ \cdot & C + \frac{5\Sigma}{2} + \frac{3\Delta}{2} & \cdot & C \\ \cdot & C + \frac{5\Sigma}{2} - \frac{3\Delta}{2} & \cdot \\ \sqrt{3}\Delta & \cdot & \cdot & C + \frac{5\Sigma}{2} - \frac{3\Delta}{2} & \cdot \\ \sqrt{3}(A - B) & \cdot & C + A + A B & \cdot \\ \sqrt{3}(A - B) & \cdot & C + A + B & \cdot \\ \sqrt{3}(A - B) & \cdot & C + A + B & \cdot \\ \sqrt{3}(A - B & \cdot & C + A + B & \cdot \\ \sqrt{3}(A - B & \cdot & C + A + B & \cdot \\ \sqrt{3}(A - B & \cdot & C + A + B & \cdot \\ \sqrt{3}(A - B & \cdot & C + A + B & \cdot \\ \sqrt{3}(A - B & \cdot & C + A + B & \cdot \\ \sqrt{3}(A - B & \cdot &$$

$\left(4C+A+B\right)$				$\sqrt{3}(A-B)$	$\begin{vmatrix} A_1 2^+ \\ -2 \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ +2 \end{vmatrix} + \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -2 \end{vmatrix}$
	4C + A + B				$\begin{vmatrix} B_2 2 \end{vmatrix} = \sqrt{2} \begin{vmatrix} 2 \\ +2 \end{vmatrix} = \sqrt{2} \begin{vmatrix} 2 \\ -2 \end{vmatrix}$
•	•	C + 4A + B	•		$ \begin{vmatrix} B_1 1^+ \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ +1 \end{vmatrix} + \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -1 \end{vmatrix} $
•			C + A + 4B		$\left \begin{array}{c} A_{2} 1^{-} \right\rangle = \left \begin{array}{c} 1 \\ 2 \\ 1 \end{array} \right\rangle - \left \begin{array}{c} 1 \\ 2 \\ 1 \end{array} \right\rangle - \left \begin{array}{c} 1 \\ 2 \\ 1 \end{array} \right\rangle$
$\sqrt{3}(A-B)$				3A+3B	$\begin{vmatrix} \mathbf{a}_{2} \\ \mathbf{a}_{1} \\ \mathbf{a}_{1} \\ \mathbf{a}_{1} \\ \mathbf{a}_{2} \end{vmatrix} = \begin{vmatrix} \mathbf{a}_{1} \\ \mathbf{a}_{2} \\ \mathbf{a}_{1} \end{vmatrix}$



$\left(4C + A + B\right)$				$\sqrt{3}(A-B)$	$\begin{vmatrix} \mathbf{A}_{1} 2^{+} \rangle = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ +2 \end{vmatrix} + \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ -2 \end{vmatrix}$
	4C + A + B				$\left \frac{B_2 2^-}{2} \right\rangle = \sqrt{\frac{1}{2}} \left \frac{2}{+2} \right\rangle - \sqrt{\frac{1}{2}} \left \frac{2}{-2} \right\rangle$
		C + 4A + B	•		$\left \frac{B_{1}}{2} \right ^{+} = \frac{1}{\sqrt{2}} \left \frac{2}{+1} \right\rangle + \frac{1}{\sqrt{2}} \left \frac{2}{-1} \right\rangle$
.			C + A + 4B		$\left A_{2} 1^{-} \right\rangle = \left \frac{1}{2} \right \left \frac{2}{2} \right\rangle - \left \frac{1}{2} \right \left \frac{2}{2} \right\rangle$
$\sqrt{3}(A-B)$				3A+3B)	$\begin{vmatrix} -2 \\ -2 \end{vmatrix} = \begin{vmatrix} 2 \\ 0 \end{vmatrix}$

Need only diagonalize the two *A*₁'s:

(It is n=0 versus $n=2^+$)

$$\begin{pmatrix} 4C + A + B & \sqrt{3}(A - B) \\ \sqrt{3}(A - B) & 3A + 3B \end{pmatrix} \begin{vmatrix} A_1 2^+ \\ + 2 \end{vmatrix} = \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ + 2 \\ + 2 \end{vmatrix} + \frac{1}{\sqrt{2}} \begin{vmatrix} 2 \\ - 2 \\ - 2 \end{vmatrix}$$

D ₂	1	\mathbf{R}_{x}	R _y	R _z
A ₁	1	1	1	1
A_2	1	-1	1	-1
<i>B</i> ₁	1	1	-1	-1
<i>B</i> ₂	1	-1	-1	1



$\left(4C + A + B\right)$				$\sqrt{3}(A-B)$
	4C + A + B			
	•	C + 4A + B	•	
	•	•	C + A + 4B	
$\sqrt{3}(A-B)$				3A+3B

Need only diagonalize the two
$$A_1$$
's:

(It is n=0 versus $n=2^+$)

$$\begin{pmatrix} 4C + A + B & \sqrt{3}(A - B) \\ \sqrt{3}(A - B) & 3A + 3B \end{pmatrix} \begin{vmatrix} A_1 2^+ \\ + \sqrt{2} \end{vmatrix} = \sqrt{2} \begin{vmatrix} 2 \\ + 2 \end{vmatrix} + \sqrt{2} \begin{vmatrix} 2 \\ + 2 \end{vmatrix} + \sqrt{2} \begin{vmatrix} 2 \\ + 2 \end{vmatrix}$$
$$= \begin{vmatrix} 2 \\ 0 \end{vmatrix}$$
$$= \begin{vmatrix} 2C + 2A + 2B \end{vmatrix} \cdot \mathbf{1} + \begin{pmatrix} 2C - A - B & \sqrt{3}(A - B) \\ \sqrt{3}(A - B) & -(2C - A - B) \end{pmatrix}$$

D ₂	1	\mathbf{R}_{x}	R _y	R _z
A ₁	1	1	1	1
A_2	1	-1	1	-1
<i>B</i> ₁	1	1	-1	-1
<i>B</i> ₂	1	-1	-1	1



 $\left| A_{1} 2^{+} \right\rangle = \frac{1}{\sqrt{2}} \left| {}^{2}_{+2} \right\rangle + \frac{1}{\sqrt{2}} \left| {}^{2}_{-2} \right\rangle$

 $\left|\frac{B_{2}}{2}2^{-}\right\rangle = \frac{1}{\sqrt{2}}\left|\frac{2}{+2}\right\rangle - \frac{1}{\sqrt{2}}\left|\frac{2}{-2}\right\rangle$

 $\left|\frac{B_{1}}{B_{1}}\right|^{+} = \frac{1}{\sqrt{2}} \left|\frac{2}{+1}\right\rangle + \frac{1}{\sqrt{2}} \left|\frac{2}{-1}\right\rangle$

 $\left| \frac{A_2}{2} 1^{-} \right\rangle = \frac{1}{\sqrt{2}} \left| \frac{2}{+1} \right\rangle - \frac{1}{\sqrt{2}} \left| \frac{2}{-1} \right\rangle$

 $\left| A_{1} 0 \right\rangle = \left| \begin{array}{c} 2 \\ 0 \end{array} \right\rangle$

Need only diagonalize the two *A*₁'s:



Need only diagonalize the two *A*₁'s:



Review of freshman Chemistry and Physics (contd)Momentum 101p = m v $J = L = I \omega$ BANG!(linear)(rotation) $E = \frac{1}{2}m v^2 = p^2/2m$ $E = \frac{1}{2}I \omega^2 = J^2/2I$ BUCK\$

Simple Rigid Rotor Hamiltonian... (Hamiltonian H=E is $\frac{BANGI}{energy}$ in terms of momentum) $\mathbf{H} = A\mathbf{J}_x^2 + B\mathbf{J}_y^2 + C\mathbf{J}_z^2 + \cdots$...and its multi-pole expansion...



(Derivation follows next lecture...)

Partial listing of the Harter-Soft/Heyoka LearnIt Web Apps as of April 24, 2017 (Apps are being upgraded as time permits)

Production Links - For the students & general public

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