# Complex Variables, Series, and Field Coordinates I.

(*Ch.* 10 of Unit 1) 1. The Story of e (A Tale of Great \$Interest\$) *How good are those power series?* Taylor-Maclaurin series, imaginary interest, and complex exponentials Lecture 14 Tue 10 09 2. What good are complex exponentials? starts here 1. Complex numbers provide "automatic trigonometry" Easy trig 2. Complex numbers add like vectors. Easy 2D vector analysis *Easy oscillator phase analysis* 4. Complex products provide 2D rotation operations. Easy rotation and "dot" or "cross" products *3. Easy 2D vector calculus* Easy 2D vector derivatives Easy 2D source-free field theory 7. Invent source-free 2D vector fields  $[\nabla \cdot \mathbf{F}=0 \text{ and } \nabla \mathbf{x}\mathbf{F}=0]$ *Easy 2D vector field-potential theory* 4. *Riemann-Cauchy relations* (*What's analytic? What's not?*) The half-n'-half results: (Riemann-Cauchy Derivative Relations) Easy 2D curvilinear coordinate discovery *Easy 2D circulation and flux integrals Easy 2D monopole, dipole, and 2^n-pole analysis* 12. Complex derivatives give 2D dipole fields *Easy 2<sup>n</sup>-multipole field and potential expansion* 13. More derivatives give 2D 2<sup>N</sup>-pole fields...

- Easy stereo-projection visualization
- 5. Non-analytic 2D source field analysis

16. ...and non-analytic source analysis.

15. ...and Laurent Series...

- 3. Complex exponentials Ae<sup>-int</sup> track position and velocity using Phasor Clock.
- 5. Complex products provide 2D "dot"(•) and "cross"(x) products.
- 6. Complex derivative contains "divergence" ( $\nabla \cdot F$ ) and "curl" ( $\nabla x F$ ) of 2D vector field
- 8. Complex potential  $\phi$  contains "scalar" ( $\mathbf{F}=\nabla \Phi$ ) and "vector" ( $\mathbf{F}=\nabla x\mathbf{A}$ ) potentials
- 9. Complex potentials define 2D Orthogonal Curvilinear Coordinates (OCC) of field
- 10. Complex integrals f (z)dz count 2D "circulation" ( **F**•dr) and "flux" (**F**xdr)
- 11. Complex integrals define 2D monopole fields and potentials
- Lecture 15 Thur. 10.11
- starts here

Tuesday, October 9, 2012

Simple *interest* at some rate r based on a 1 year period.

You gave a principal p(0) to the bank and some time *t* later they would pay you  $p(t)=(1+r\cdot t)p(0)$ .

\$1.00 at rate r=1 (like Israel and Brazil that once had 100% interest.) gives \$2.00 at t=1 year.

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Semester compounded interest gives  $p(\frac{t}{2}) = (1 + r \cdot \frac{t}{2})p(0)$  at the half-period  $\frac{t}{2}$  and then use  $p(\frac{t}{2})$  during the last half to figure final payment. Now \$1.00 at rate r=1 earns \$2.25.

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$$p^{\frac{1}{3}}(t) = (1 + r \cdot \frac{t}{3})p(2\frac{t}{3}) = (1 + r \cdot \frac{t}{3})\cdot(1 + r \cdot \frac{t}{3})p(\frac{t}{3}) = (1 + r \cdot \frac{t}{3})\cdot(1 + r \cdot \frac{t}{3})\cdot(1 + r \cdot \frac{t}{3})p(0) = \frac{4}{3}\cdot \frac{4}{3}\cdot \frac{4}{3}\cdot 1 = \frac{64}{27} = 2.37$$

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So if you compound interest more and more frequently, do you approach INFININTEREST?

p

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$$p^{\frac{1}{1}}(t) = (1 + r \cdot \frac{t}{1})^{1} p(0) = \left(\frac{2}{1}\right)^{1} \cdot 1 = \frac{2}{1} = 2.00$$

$$+25\phi$$

$$p^{\frac{1}{2}}(t) = (1 + r \cdot \frac{t}{2})^{2} p(0) = \left(\frac{3}{2}\right)^{2} \cdot 1 = \frac{9}{4} = 2.25$$

$$+12\phi$$

$$p^{\frac{1}{3}}(t) = (1 + r \cdot \frac{t}{3})^{3} p(0) = \left(\frac{4}{3}\right)^{3} \cdot 1 = \frac{64}{27} = 2.37$$

$$+7\phi$$

$$p^{\frac{1}{4}}(t) = (1 + r \cdot \frac{t}{4})^{4} p(0) = \left(\frac{5}{4}\right)^{4} \cdot 1 = \frac{625}{256} = 2.44$$

Simple *interest* at some rate r based on a 1 year period.

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$$+25\phi$$

$$p^{\frac{1}{2}}(t) = (1 + r \cdot \frac{t}{2})^{2} p(0) = \left(\frac{3}{2}\right)^{2} \cdot 1 = \frac{9}{4} = 2.25$$

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$$p^{\frac{1}{4}}(t) = (1 + r \cdot \frac{t}{4})^{4} p(0) = \left(\frac{5}{4}\right)^{4} \cdot 1 = \frac{625}{256} = 2.44$$

Monthly: 
$$p^{\frac{1}{12}}(t) = (1 + r \cdot \frac{t}{12})^{12} p(0) = \left(\frac{13}{12}\right)^{12} \cdot 1 = 2.613$$
  
Weekly:  $p^{\frac{1}{52}}(t) = (1 + r \cdot \frac{t}{52})^{52} p(0) = \left(\frac{53}{52}\right)^{52} \cdot 1 = 2.693$   
Daily:  $p^{\frac{1}{365}}(t) = (1 + r \cdot \frac{t}{365})^{365} p(0) = \left(\frac{366}{365}\right)^{365} \cdot 1 = 2.7145$   
Hrly:  $p^{\frac{1}{8760}}(t) = (1 + r \cdot \frac{t}{8760})^{8760} p(0) = \left(\frac{8761}{8760}\right)^{8760} \cdot 1 = 2.7181$ 

$$p^{1/m}(1) = (1 + \frac{1}{m})^m \xrightarrow[m \to \infty]{=} e^{2.718281828459..} = e^{p^{1/m}(1)} = 2.7169239322 \qquad for m = 1,000 \qquad for m = 10,000 \qquad for m = 10,000 \qquad for m = 100,000 \qquad for m = 100,000 \qquad for m = 1,000,000 \qquad for m = 10,000,000 \qquad for m = 1,000,000 \qquad for m = 1,000,00$$

$$p^{1/m}(1) = (1 + \frac{1}{m})^m \xrightarrow[m \to \infty]{=} e^{2.718281828459..} p^{1/m}(1) = 2.7181459268 \qquad for m = 1,000 \qquad for m = 10,000 \qquad for m = 100,000 \qquad for m = 1,000,000 \qquad for m = 10,000,000 \qquad for m = 1,000,000,000 \qquad for m = 1,000,000 \qquad for m = 1,000,000 \qquad for m = 1,000,$$

Can improve computational efficiency using binomial theorem:

$$(x+y)^{n} = x^{n} + n \cdot x^{n-1}y + \frac{n(n-1)}{2!}x^{n-2}y^{2} + \frac{n(n-1)(n-2)}{3!}x^{n-3}y^{3} + \dots + n \cdot xy^{n-1} + y^{n}$$
$$(1+\frac{r \cdot t}{n})^{n} = 1 + n \cdot \left(\frac{r \cdot t}{n}\right) + \frac{n(n-1)}{2!}\left(\frac{r \cdot t}{n}\right)^{2} + \frac{n(n-1)(n-2)}{3!}\left(\frac{r \cdot t}{n}\right)^{3} + \dots \qquad \text{Define: Factorials(!):}$$
$$(1+\frac{r \cdot t}{n})^{n} = 1 + n \cdot \left(\frac{r \cdot t}{n}\right) + \frac{n(n-1)}{2!}\left(\frac{r \cdot t}{n}\right)^{2} + \frac{n(n-1)(n-2)}{3!}\left(\frac{r \cdot t}{n}\right)^{3} + \dots \qquad \text{Define: Factorials(!):}$$

$$p^{1/m}(1) = (1 + \frac{1}{m})^m \xrightarrow[m \to \infty]{=} e^{p^{1/m}(1)} = 2.7169239322 \qquad for m = 1,000 \\ p^{1/m}(1) = 2.7181459268 \qquad for m = 10,000 \\ p^{1/m}(1) = 2.7182682372 \qquad for m = 100,000 \\ p^{1/m}(1) = 2.7182804693 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182816925 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182816925 \qquad for m = 10,000,000 \\ p^{1/m}(1) = 2.7182818149 \qquad for m = 10,000,000 \\ p^{1/m}(1) = 2.7182818149 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.718$$

Can improve efficiency using binomial theorem:

$$\begin{aligned} (x+y)^{n} &= x^{n} + n \cdot x^{n-1}y + \frac{n(n-1)}{2!}x^{n-2}y^{2} + \frac{n(n-1)(n-2)}{3!}x^{n-3}y^{3} + \dots + n \cdot xy^{n-1} + y^{n} \\ (1+\frac{r \cdot t}{n})^{n} &= 1 + n \cdot \left(\frac{r \cdot t}{n}\right) + \frac{n(n-1)}{2!}\left(\frac{r \cdot t}{n}\right)^{2} + \frac{n(n-1)(n-2)}{3!}\left(\frac{r \cdot t}{n}\right)^{3} + \dots \\ e^{r \cdot t} &= 1 + r \cdot t + \frac{1}{2!}\left(r \cdot t\right)^{2} + \frac{1}{3!}\left(r \cdot t\right)^{3} + \dots \\ &= \sum_{p=0}^{o} \frac{\left(r \cdot t\right)^{p}}{p!} \end{aligned} \qquad \begin{aligned} As \ n \to \infty \ let : \\ n(n-1) \to n^{2}, \\ n(n-1)(n-2) \to n^{3}, etc. \end{aligned}$$

$$p^{1/m}(1) = (1 + \frac{1}{m})^m \xrightarrow[m \to \infty]{=} e^{2.718281828459..} p^{1/m}(1) = 2.7182682372 \qquad for m = 1,000 \\ p^{1/m}(1) = 2.7182682372 \qquad for m = 10,000 \\ p^{1/m}(1) = 2.7182682372 \qquad for m = 100,000 \\ p^{1/m}(1) = 2.7182804693 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182816925 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182816925 \qquad for m = 10,000,000 \\ p^{1/m}(1) = 2.7182818149 \qquad for m = 10,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818271 \qquad for m = 1,000,000,000 \\ p^{1/m}(1) = 2.7182818281 \qquad for m = 1,000$$

Can improve efficiency using binomial theorem:

$$\begin{aligned} (x+y)^{n} &= x^{n} + n \cdot x^{n-1}y + \frac{n(n-1)}{2!}x^{n-2}y^{2} + \frac{n(n-1)(n-2)}{3!}x^{n-3}y^{3} + \dots + n \cdot xy^{n-1} + y^{n} \\ (1+\frac{r \cdot t}{n})^{n} &= 1 + n \cdot \left(\frac{r \cdot t}{n}\right) + \frac{n(n-1)}{2!}\left(\frac{r \cdot t}{n}\right)^{2} + \frac{n(n-1)(n-2)}{3!}\left(\frac{r \cdot t}{n}\right)^{3} + \dots \\ & 0 = 1 = 1!, \quad 2! = 1\cdot 2, \quad 3! = 1\cdot 2\cdot 3, \dots \\ e^{r \cdot t} &= 1 + r \cdot t + \frac{1}{2!}\left(r \cdot t\right)^{2} + \frac{1}{3!}\left(r \cdot t\right)^{3} + \dots \\ &= \sum_{p=0}^{o} \frac{\left(r \cdot t\right)^{p}}{p!} \\ & n(n-1) \to n^{2}, \end{aligned}$$

Precision order: 
$$(o=1)$$
-e-series = 2.00000 =1+1  $n(n-1)(n-2) \rightarrow n^3$ , etc.  
 $(o=2)$ -e-series = 2.50000 =1+1+1/2  
 $(o=3)$ -e-series = 2.66667 =1+1+1/2+1/6  
 $(o=4)$ -e-series = 2.70833 =1+1+1/2+1/6+1/24  
 $(o=5)$ -e-series = 2.71667 =1+1+1/2+1/6+1/24+1/120  
 $(o=6)$ -e-series = 2.71805 =1+1+1/2+1/6+1/24+1/120+1/720  
 $(o=7)$ -e-series = 2.71825  
 $(o=8)$ -e-series = 2.71828 About 12 summed quotients  
for 6-figure precision (A lot better!)

Start with a general power series with constant coefficients  $c_0, c_1, etc.$  Set t=0 to get  $c_0 = x(0)$ .  $x(t) = c_0 + c_1t + c_2t^2 + c_3t^3 + c_4t^4 + c_5t^5 + \dots + c_nt^n + c_nt^n$ 

Start with a general power series with constant coefficients  $c_0$ ,  $c_1$ , etc.

Set 
$$t=0$$
 to get  $c_0 = x(0)$ .

$$x(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + c_5 t^5 + \dots + c_n t^n + \dots$$

Rate of change of position x(t) is velocity v(t).

Set 
$$t=0$$
 to get  $c_1 = v(0)$ .

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 3c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 3c_3t^2 + \frac{d}{dt}x(t) = 0 + c_1 +$$

Start with a general power series with constant coefficients  $c_0$ ,  $c_1$ , etc.

Set 
$$t=0$$
 to get  $c_0 = x(0)$ .

Set t=0 to get  $c_1 = v(0)$ .

$$x(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + c_5 t^5 + \dots + c_n t^n + \dots$$

Rate of change of position x(t) is velocity v(t).

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 3c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 3c_3t^2 + 4c_4t^3 + 3c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 3c_3t^2 + 3c_5t^2 +$$

Change of velocity v(t) is *acceleration* a(t).

Set t=0 to get  $c_2 = \frac{1}{2}a(0)$ .

$$a(t) = \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + \frac{d}{dt}v(t) = 0 + 2c_5t^2 + \frac{d}{dt}v(t) = 0 +$$

Start with a general power series with constant coefficients  $c_0$ ,  $c_1$ , etc. Set t=0 to get  $c_0 = x(0)$ .

$$x(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + c_5 t^5 + \dots + c_n t^n + \dots$$

Set t=0 to get  $c_1 = v(0)$ .

Rate of change of position x(t) is velocity v(t).

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + \frac{d}{dt}x(t$$

Change of velocity v(t) is acceleration a(t).

$$a(t) = \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + \frac{d}{dt}v(t) = 0 + 2c_5t^2 + \frac{d}{dt}v(t) = 0 +$$

Change of acceleration a(t) is *jerk j(t)*. (*Jerk* is NASA term.) Set t=0 to get  $c_3 = \frac{1}{3!} j(0)$ .  $j(t) = \frac{d}{dt} a(t) = 0 + 2 \cdot 3c_3 + 2 \cdot 3 \cdot 4c_4 t + 3 \cdot 4 \cdot 5c_5 t^2 + \dots + n(n-1)(n-2)c_n t^{n-3} + \dots$ 

Change of jerk j(t) is *inauguration* i(t). (Be silly like NASA!) Set t=0 to get  $c_4 = \frac{1}{4!}i(0)$ .

Set t=0 to get  $c_2 = \frac{1}{2}a(0)$ .

Start with a general power series with constant coefficients  $c_0$ ,  $c_1$ , etc. S

Set 
$$t=0$$
 to get  $c_0 = x(0)$ .

Set t=0 to get  $c_1 = v(0)$ .

Set t=0 to get  $c_2 = \frac{1}{2}a(0)$ .

$$x(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + c_5 t^5 + \dots + c_n t^n + \dots$$

Rate of change of position x(t) is velocity v(t).

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + \frac{d}{dt}x(t) =$$

Change of velocity v(t) is acceleration a(t).

$$a(t) = \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + \frac{d}{dt}v(t) = 0 + 2c_5t^2 + \frac{d}{dt}v(t) = 0 +$$

Change of acceleration a(t) is *jerk j(t)*. (*Jerk* is NASA term.) Set t=0 to get  $c_3 = \frac{1}{3!} j(0)$ .

$$j(t) = \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_1t^2 + \dots + n(n-1)(n-2)c_1t^2$$

Change of jerk j(t) is *inauguration* i(t). (Be silly like NASA!) Set t=0 to get  $c_4 = \frac{1}{4!}i(0)$ .

$$i(t) = \frac{d}{dt}j(t) = 0 + 2\cdot 3\cdot 4c_4 + 2\cdot 3\cdot 4\cdot 5c_5t + \dots + n(n-1)(n-2)(n-3)c_nt^{n-4} + \dots$$

Gives Maclaurin (or Taylor) power series

$$x(t) = x(0) + v(0)t + \frac{1}{2!}a(0)t^{2} + \frac{1}{3!}j(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \dots$$

Start with a general power series with constant coefficients  $c_0$ ,  $c_1$ , etc.

Set 
$$t=0$$
 to get  $c_0 = x(0)$ .

Set t=0 to get  $c_1 = v(0)$ .

Set t=0 to get  $c_2 = \frac{1}{2}a(0)$ .

$$x(t) = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + c_5 t^5 + \dots + c_n t^n + \dots$$

Rate of change of position x(t) is velocity v(t).

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + \frac{d}{dt}x(t) = 0 + \frac{d}{d$$

Change of velocity v(t) is acceleration a(t).

$$a(t) = \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + \frac{d}{dt}v(t) = 0 + 2c_5t^2 + \frac{d}{dt}v(t) = 0 +$$

Change of acceleration a(t) is *jerk j(t)*. (*Jerk* is NASA term.) Set t=0 to get  $c_3 = \frac{1}{3!} j(0)$ .

$$j(t) = \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_1t^2 + \dots + n(n-1)(n-2)c_1t^2$$

Change of jerk j(t) is *inauguration* i(t). (Be silly like NASA!) Set t=0 to get  $c_4 = \frac{1}{4!}i(0)$ .

$$i(t) = \frac{d}{dt}j(t) = 0 + 2\cdot 3\cdot 4c_4 + 2\cdot 3\cdot 4\cdot 5c_5t + \dots + n(n-1)(n-2)(n-3)c_nt^{n-4} + \dots$$

Gives Maclaurin (or Taylor) power series

$$x(t) = x(0) + v(0)t + \frac{1}{2!}a(0)t^{2} + \frac{1}{3!}j(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}i(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}i(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{5} + \frac{1}{3!$$

Good old UP I formula!

Start with a general power series with constant coefficients  $c_0$ ,  $c_1$ , etc.

Set 
$$t=0$$
 to get  $c_0 = x(0)$ .

Set t=0 to get  $c_1 = v(0)$ .

Set t=0 to get  $c_2 = \frac{1}{2}a(0)$ .

Rate of change of position x(t) is velocity v(t).

$$v(t) = \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t + 3c_3t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + 4c_4t^3 + 5c_5t^4 + \dots + nc_nt^{n-1} + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + 2c_2t^2 + \frac{d}{dt}x(t) = 0 + c_1 + \frac{d}{dt}x(t) =$$

Change of velocity v(t) is acceleration a(t).

$$a(t) = \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + 3\cdot 4c_4t^2 + 4\cdot 5c_5t^3 + \dots + n(n-1)c_nt^{n-2} + \frac{d}{dt}v(t) = 0 + 2c_2 + 2\cdot 3c_3t + \frac{d}{dt}v(t) = 0 + 2c_5t^2 + \frac{d}{dt}v(t) = 0 +$$

Change of acceleration a(t) is *jerk j(t)*. (*Jerk* is NASA term.) Set t=0 to get  $c_3 = \frac{1}{3!} j(0)$ .

$$j(t) = \frac{a}{dt}a(t) = 0 + 2\cdot 3c_3 + 2\cdot 3\cdot 4c_4t + 3\cdot 4\cdot 5c_5t^2 + \dots + n(n-1)(n-2)c_nt^{n-3} + \dots$$

Change of jerk j(t) is *inauguration* i(t). (Be silly like NASA!) Set t=0 to get  $c_4 = \frac{1}{4!}i(0)$ .

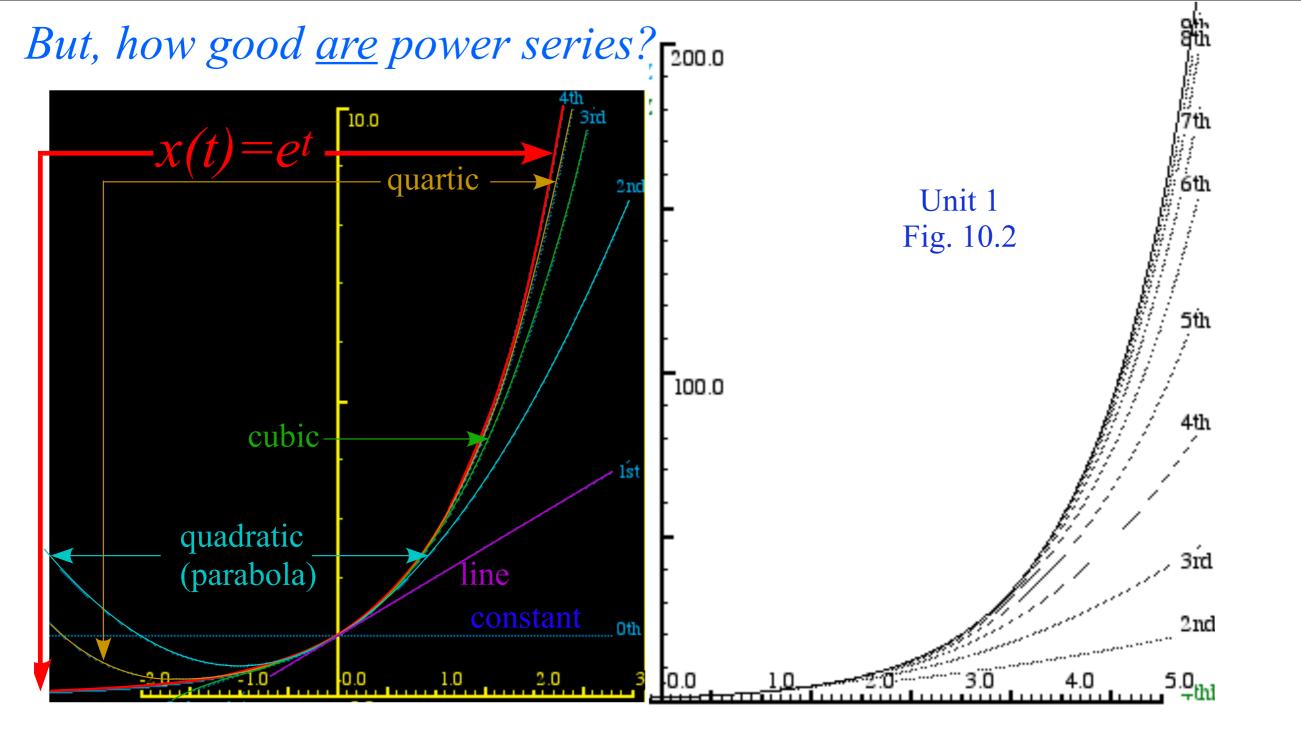
Gives Maclaurin (or Taylor) power series

$$x(t) = x(0) + v(0)t + \frac{1}{2!}a(0)t^{2} + \frac{1}{3!}j(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}i(0)t^{4} + \frac{1}{5!}i(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{5!}i(0)t^{5} + \dots + \frac{1}{3!}i(0)t^{5} + \dots + \frac{1}{$$

Setting all initial values to  $l = x(0) = v(0) = a(0) = j(0) = i(0) = \dots$ 

Good old UP I formula!

gives exponential: 
$$e^{t} = 1 + t + \frac{1}{2!}t^{2} + \frac{1}{3!}t^{3} + \frac{1}{4!}t^{4} + \frac{1}{5!}t^{5} + \dots + \frac{1}{n!}t^{n} + \frac{1}{2!}t^{n} + \frac{1}{$$

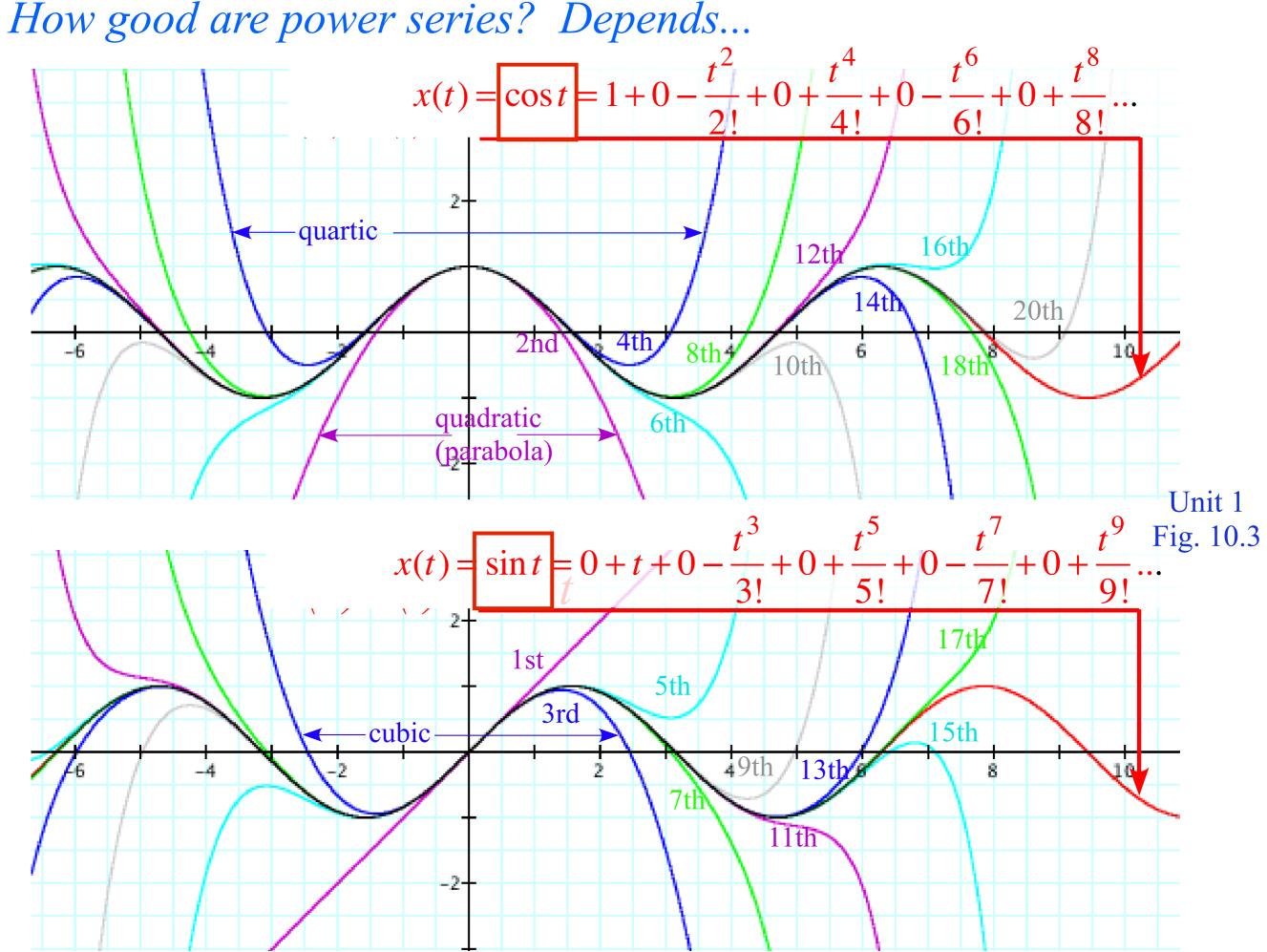


### Gives Maclaurin (or Taylor) power series

$$x(t) = x(0) + v(0)t + \frac{1}{2!}a(0)t^{2} + \frac{1}{3!}j(0)t^{3} + \frac{1}{4!}i(0)t^{4} + \frac{1}{5!}r(0)t^{5} + \dots + \frac{1}{n!}x^{(n)}t^{n} + \frac{1}{3!}x^{(n)}t^{n} + \frac{1}{3$$

Setting all initial values to  $1 = x(0) = v(0) = a(0) = j(0) = i(0) = \dots$ 

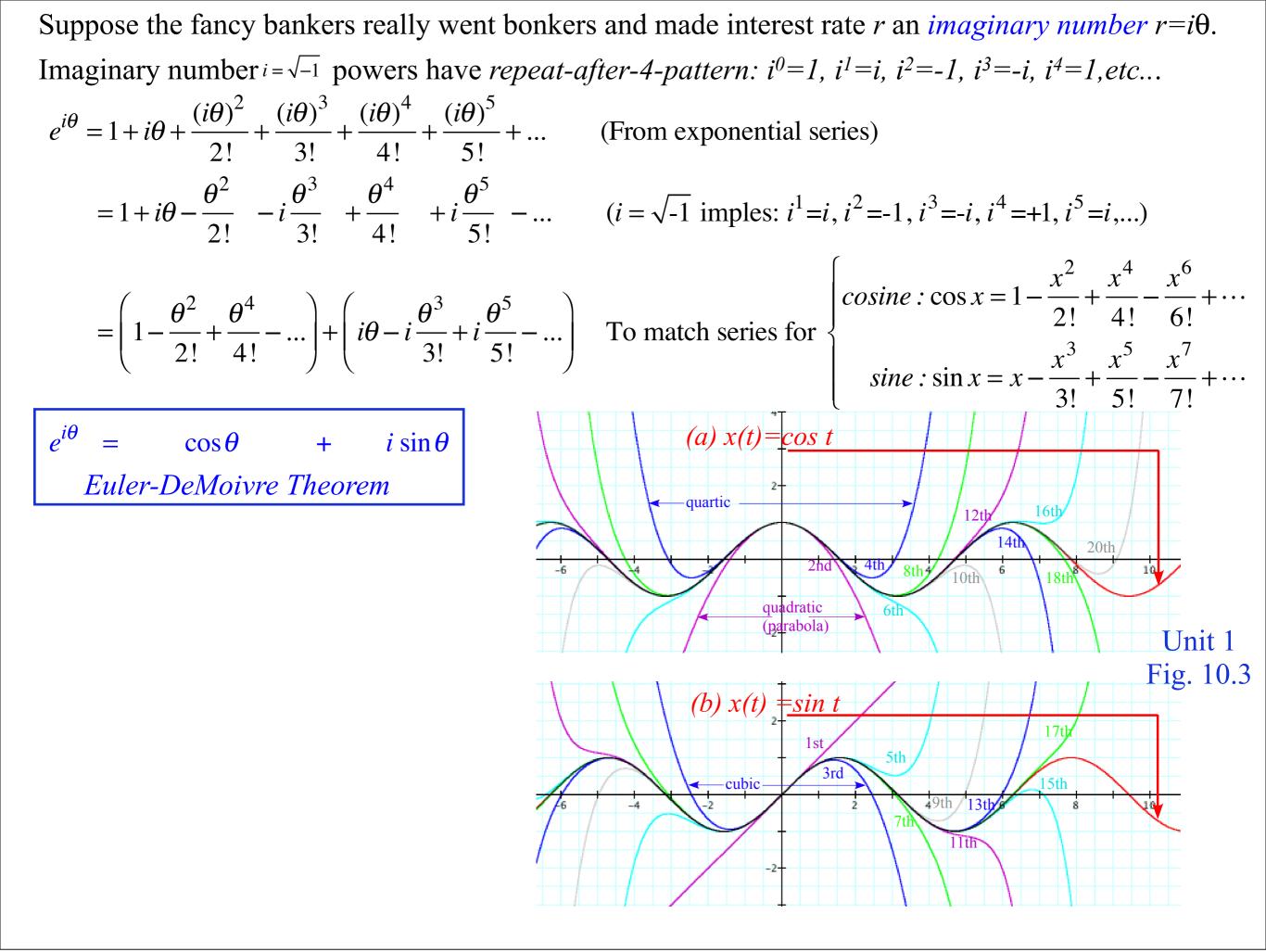
gives exponential: 
$$e^{t} = 1 + t + \frac{1}{2!}t^{2} + \frac{1}{3!}t^{3} + \frac{1}{4!}t^{4} + \frac{1}{5!}t^{5} + \dots + \frac{1}{n!}t^{n} + \frac{1}{2!}t^{n} + \frac{1}{$$

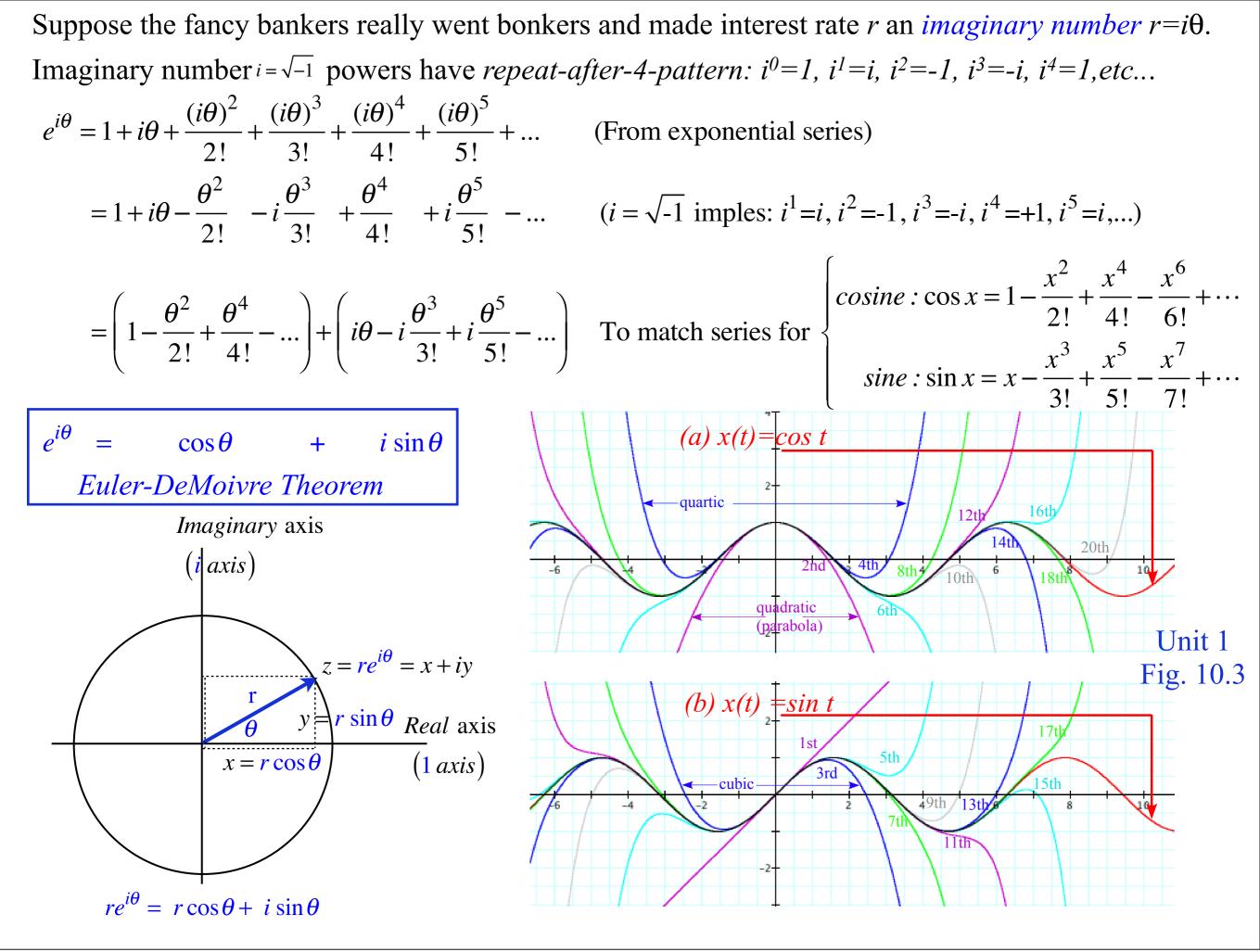


How good are those power series? Taylor-Maclaurin series,

imaginary interest, and complex exponentials

Suppose the fancy bankers really went bonkers and made interest rate *r* an *imaginary number r=i* $\theta$ . Imaginary number  $i = \sqrt{-1}$  powers have *repeat-after-4-pattern*:  $i^0 = 1$ ,  $i^1 = i$ ,  $i^2 = -1$ ,  $i^3 = -i$ ,  $i^4 = 1$ , etc...  $e^{i\theta} = 1 + i\theta + \frac{(i\theta)^2}{2!} + \frac{(i\theta)^3}{3!} + \frac{(i\theta)^4}{4!} + \frac{(i\theta)^5}{5!} + \dots$  (From exponential series)  $= 1 + i\theta - \frac{\theta^2}{2!} - i\frac{\theta^3}{3!} + \frac{\theta^4}{4!} + i\frac{\theta^5}{5!} - \dots$  ( $i = \sqrt{-1}$  imples:  $i^1 = i$ ,  $i^2 = -1$ ,  $i^3 = -i$ ,  $i^4 = +1$ ,  $i^5 = i$ ,...)  $= \left(1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} - \dots\right) + \left(i\theta - i\frac{\theta^3}{3!} + i\frac{\theta^5}{5!} - \dots\right)$ 





### 2. What Good Are Complex Exponentials?

Easy trig Easy 2D vector analysis Easy oscillator phase analysis Easy rotation and "dot" or "cross" products

## What Good Are Complex Exponentials?

### 1. Complex numbers provide "automatic trigonometry"

Can't remember is  $\cos(a+b)$  or  $\sin(a+b)$ ? Just factor  $e^{i(a+b)} = e^{ia}e^{ib}$ ...

$$e^{i(a+b)} = e^{ia} e^{ib}$$

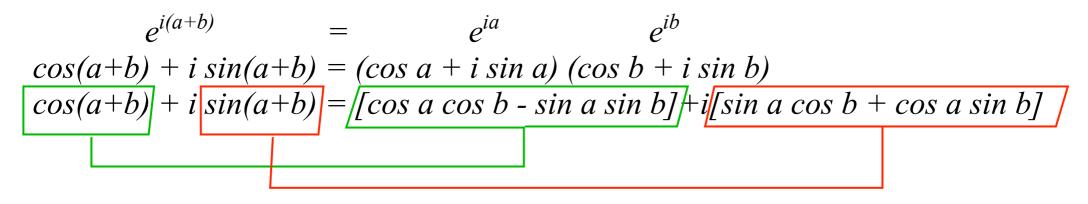
$$cos(a+b) + i sin(a+b) = (cos a + i sin a) (cos b + i sin b)$$

$$cos(a+b) + i sin(a+b) = [cos a cos b - sin a sin b] + i [sin a cos b + cos a sin b]$$

### What Good Are Complex Exponentials?

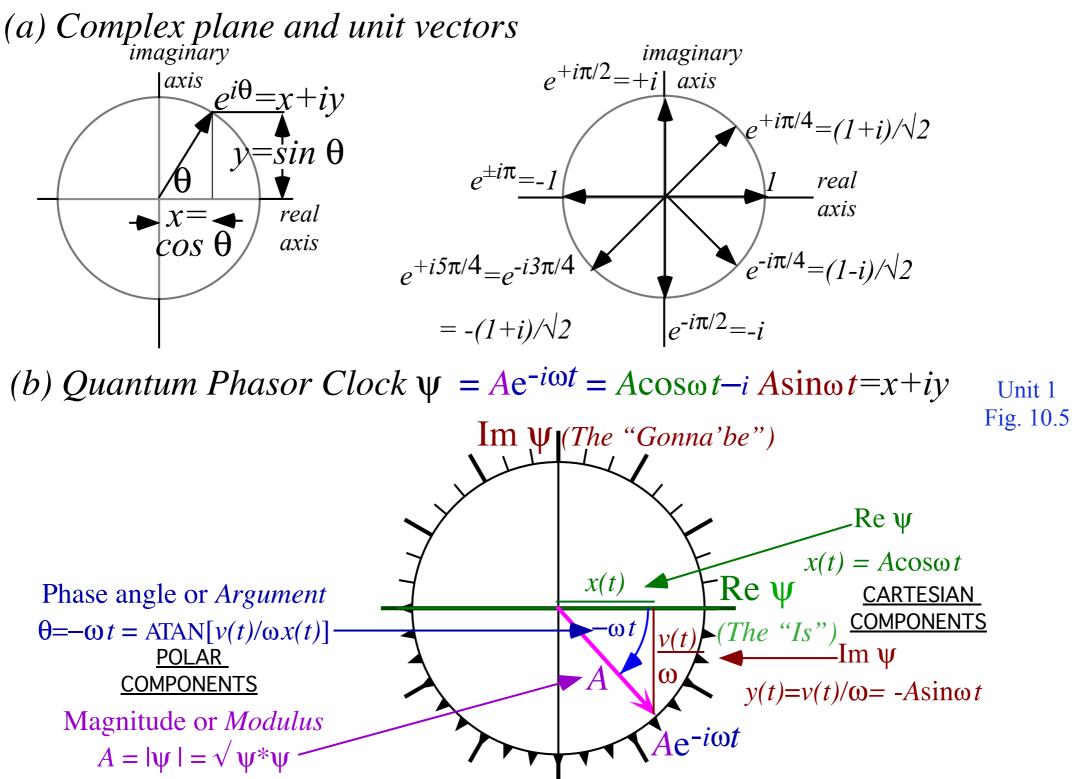
1. Complex numbers provide "automatic trigonometry"

Can't remember is  $\cos(a+b)$  or  $\sin(a+b)$ ? Just factor  $e^{i(a+b)} = e^{ia}e^{ib}$ ...

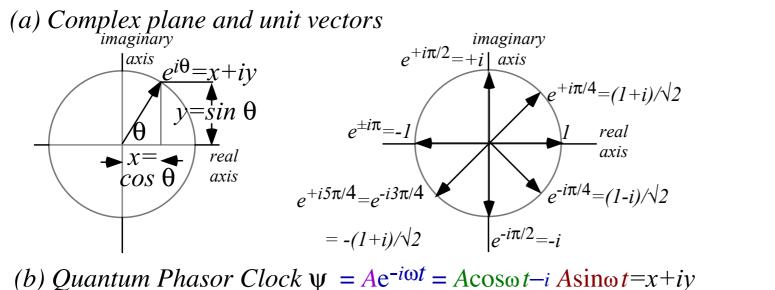


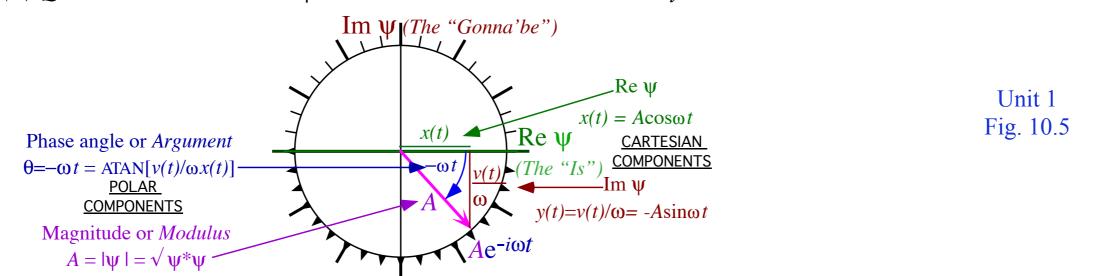
2. Complex numbers add like vectors.  $z_{Sum} = z + z' = (x + iy) + (x' + iy') = (x + x') + i(y + y')$   $z_{diff} = z - z' = (x + iy) - (x' + iy') = (x - x') + i(y - y')$ (a) y = Im z' y' = Im z' z'z'

3.Complex exponentials Ae<sup>-iwt</sup> track position <u>and</u> velocity using Phasor Clock.



3.Complex exponentials Ae<sup>-iwt</sup> track position <u>and</u> velocity using Phasor Clock.





Some Rect-vs-Polar relations worth remembering

Cartesian  

$$\begin{cases}
\psi_x = \operatorname{Re}\psi(t) = x(t) = A\cos\omega t = \frac{\psi + \psi^*}{2} \\
\psi_y = \operatorname{Im}\psi(t) = \frac{v(t)}{\omega} = -A\sin\omega t = \frac{\psi - \psi^*}{2i} \\
\psi = re^{+i\theta} = re^{-i\omega t} = r(\cos\omega t - i\sin\omega t) \\
\psi^* = re^{-i\theta} = re^{+i\omega t} = r(\cos\omega t + i\sin\omega t)
\end{cases}$$

$$Polar \begin{cases} r = A = |\psi| = \sqrt{\psi_x^2 + \psi_y^2} = \sqrt{\psi * \psi} \\ \theta = -\omega t = \arctan(\psi_y / \psi_x) \\ \cos \theta = \frac{1}{2} (e^{+i\theta} + e^{-i\theta}) \\ \sin \theta = \frac{1}{2i} (e^{+i\theta} - e^{-i\theta}) \\ \sin \theta = \frac{1}{2i} (e^{+i\theta} - e^{-i\theta}) \\ \sin \psi = \frac{\psi - \psi^*}{2i} \end{cases}$$

### 2. What Good Are Complex Exponentials?

Easy trig Easy 2D vector analysis Easy oscillator phase analysis Easy rotation and "dot" or "cross" products

4. Complex products provide 2D rotation operations.

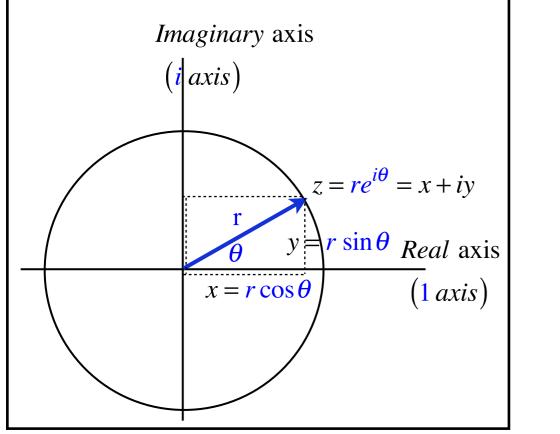
$$e^{i\phi} \cdot z = (\cos\phi + i\sin\phi) \cdot (x + iy) = x\cos\phi - y\sin\phi + i \quad (x\sin\phi + y\cos\phi)$$
$$\mathbf{R}_{+\phi} \cdot \mathbf{r} = (x\cos\phi - y\sin\phi) \hat{\mathbf{e}}_x + (x\sin\phi + y\cos\phi) \hat{\mathbf{e}}_y$$
$$\begin{pmatrix} \cos\phi & -\sin\phi\\ \sin\phi & \cos\phi \end{pmatrix} \cdot \begin{pmatrix} x\\ y \end{pmatrix} = \begin{pmatrix} x\cos\phi - y\sin\phi\\ x\sin\phi + y\cos\phi \end{pmatrix}$$

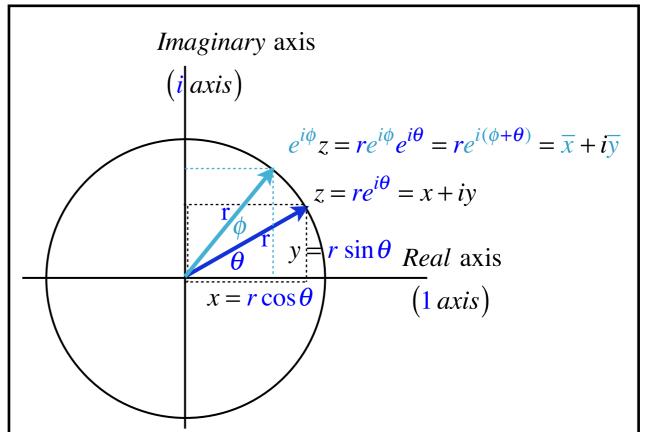
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 $e^{i\phi}$  acts on this:  $z = re^{i\theta}$ 

to give this:  $e^{i\phi} e^{i\phi} z = r e^{i\phi} e^{i\theta}$ 





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5. Complex products provide 2D "dot"(•) and "cross"(x) products.

Two complex numbers  $A = A_x + iA_y$  and  $B = B_x + iB_y$  and their "star" (\*)-product A \* B.

$$A * B = (A_x + iA_y)^* (B_x + iB_y) = (A_x - iA_y)(B_x + iB_y)$$
  
=  $(A_x B_x + A_y B_y) + i(A_x B_y - A_y B_x) = \mathbf{A} \cdot \mathbf{B} + i | \mathbf{A} \times \mathbf{B} |_{Z \perp (x,y)}$   
Real part is scalar or "dot"(•) product  $\mathbf{A} \cdot \mathbf{B}$ .  
Imaginary part is vector or "cross"(×) product, but just the Z-component normal to xy-plane.

Rewrite *A*\**B* in polar form.

$$A * B = (|A|e^{i\theta_A})^* (|B|e^{i\theta_B}) = |A|e^{-i\theta_A}|B|e^{i\theta_B} = |A||B|e^{i(\theta_B - \theta_A)}$$
$$= |A||B|\cos(\theta_B - \theta_A) + i|A||B|\sin(\theta_B - \theta_A) = \mathbf{A} \cdot \mathbf{B} + i|\mathbf{A} \times \mathbf{B}|_{Z\perp(x,y)}$$

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$$\mathbf{A} \cdot \mathbf{B} = |A||B|\cos(\theta_B - \theta_A)$$
$$|\mathbf{A} \times \mathbf{B}| = |A||B|\sin(\theta_B - \theta_A)$$
$$|A|\cos\theta_A|B|\cos\theta_B + |A|\sin\theta_A|B|\sin\theta_B$$
$$= |A|\cos\theta_A|B|\sin\theta_B - |A|\sin\theta_A|B|\cos\theta_B$$
$$= A_x B_y - A_y B_x$$

\_

\_

Real part

### What Good are complex variables?

Easy 2D vector calculus Easy 2D vector derivatives Easy 2D source-free field theory Easy 2D vector field-potential theory

6. Complex derivative contains "divergence" ( $\nabla \cdot \mathbf{F}$ ) and "curl" ( $\nabla \mathbf{xF}$ ) of 2D vector field Relation of  $(z,z^*)$  to  $(x=\operatorname{Re}z,y=\operatorname{Im}z)$  defines a z-derivative  $\frac{df}{dz}$  and "star"  $z^*$ -derivative.  $\frac{df}{dz^*}$  z = x + iy  $x = \frac{1}{2}(z + z^*)$   $z^* = x - iy$   $y = \frac{1}{2i}(z - z^*)$ Applying  $\frac{df}{dz} = \frac{\partial x}{\partial z} \frac{\partial f}{\partial x} + \frac{\partial y}{\partial z} \frac{\partial f}{\partial y} = \frac{1}{2} \frac{\partial f}{\partial x} - \frac{i}{2} \frac{\partial f}{\partial y}$  $\frac{df}{dz^*} = \frac{\partial x}{\partial z} \frac{\partial f}{\partial x} + \frac{\partial y}{\partial z} \frac{\partial f}{\partial y} = \frac{1}{2} \frac{\partial f}{\partial x} + \frac{i}{2} \frac{\partial f}{\partial y}$ 

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$$z^* = x - iy \qquad y = \frac{1}{2i} (z - z^*) \qquad \frac{df}{dz^*} = \frac{\partial x}{\partial z^* \partial x} + \frac{\partial y}{\partial z} \frac{\partial f}{\partial y} = \frac{1}{2} \frac{\partial f}{\partial x} + \frac{i}{2} \frac{\partial f}{\partial y}$$

Derivative chain-rule shows real part of  $\frac{df}{dz}$  has 2D divergence  $\nabla \cdot \mathbf{f}$  and imaginary part has curl  $\nabla \times \mathbf{f}$ .

$$\frac{df}{dz} = \frac{d}{dz} \left( f_x + i f_y \right) = \frac{1}{2} \left( \frac{\partial f}{\partial x} - i \frac{\partial f}{\partial y} \right) \left( f_x + i f_y \right) = \frac{1}{2} \left( \frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} \right) + \frac{i}{2} \left( \frac{\partial f_y}{\partial x} - \frac{\partial f_x}{\partial y} \right) = \frac{1}{2} \nabla \bullet \mathbf{f} + \frac{i}{2} |\nabla \times \mathbf{f}|_{Z \perp (x, y)}$$

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7. Invent source-free 2D vector fields  $[\nabla \cdot \mathbf{F}=0 \text{ and } \nabla \mathbf{x}\mathbf{F}=0]$ 

We can invent *source-free 2D vector fields* that are both *zero-divergence* and *zero-curl*. Take any function f(z), conjugate it (change all *i*'s to -i) to give  $f^*(z^*)$  for which  $\frac{df^*}{dz} = 0$ .

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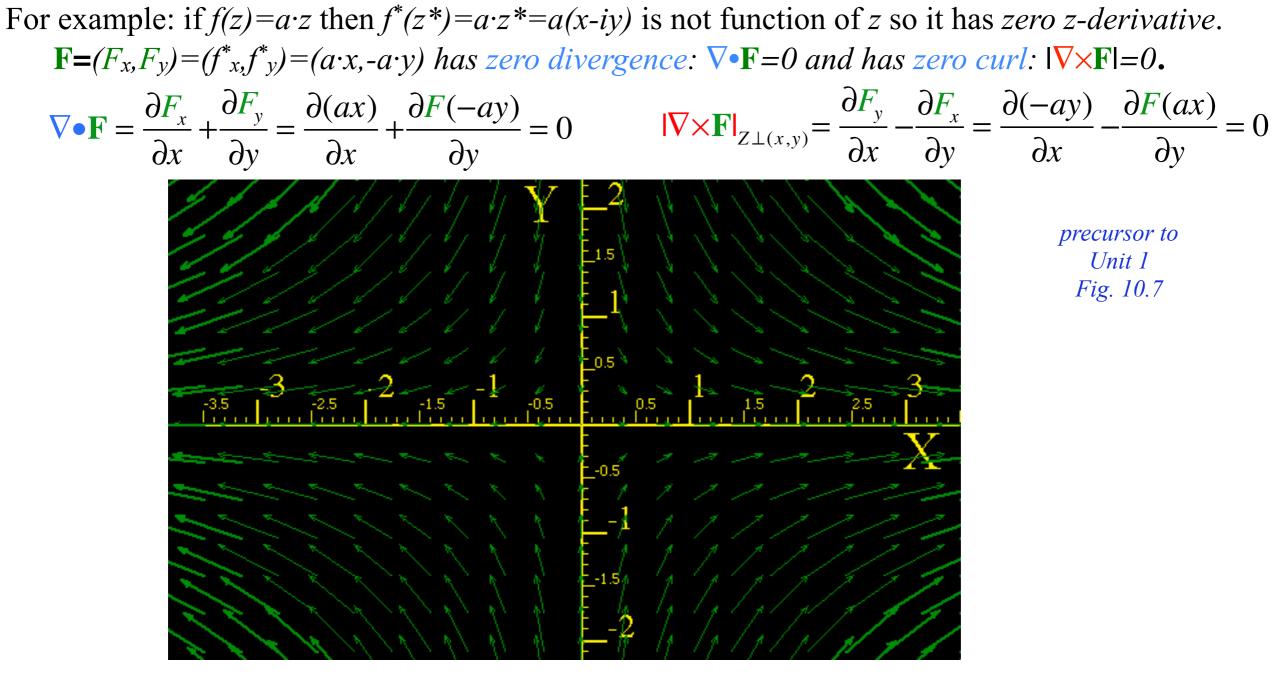
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For example: if  $f(z) = a \cdot z$  then  $f^*(z^*) = a \cdot z^* = a(x - iy)$  is not function of z so it has zero z-derivative.  $\mathbf{F} = (F_x, F_y) = (f^*_x, f^*_y) = (a \cdot x, -a \cdot y)$  has zero divergence:  $\nabla \cdot \mathbf{F} = 0$  and has zero curl:  $|\nabla \times \mathbf{F}| = 0$ .  $\nabla \cdot \mathbf{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} = \frac{\partial (ax)}{\partial x} + \frac{\partial F(-ay)}{\partial y} = 0$   $|\nabla \times \mathbf{F}|_{Z \perp (x, y)} = \frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} = \frac{\partial (-ay)}{\partial x} - \frac{\partial F(ax)}{\partial y} = 0$ A DFL field  $\mathbf{F}$  (Divergence-Free-Laminar)

7. Invent source-free 2D vector fields [ $\nabla \cdot \mathbf{F} = 0$  and  $\nabla \mathbf{x} \mathbf{F} = 0$ ]

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 $\mathbf{F}=(f_{x}^{*},f_{y}^{*})=(a\cdot x,-a\cdot y)$  is a *divergence-free laminar (DFL)* field.

## What Good are complex variables?

Easy 2D vector calculus Easy 2D vector derivatives Easy 2D source-free field theory Easy 2D vector field-potential theory

8. Complex potential  $\phi$  contains "scalar" (F= $\nabla \Phi$ ) and "vector" (F= $\nabla xA$ ) potentials

Any *DFL* field **F** is a gradient of a *scalar potential field*  $\Phi$  or a curl of a *vector potential field* **A**. **F**= $\nabla \Phi$  **F**= $\nabla \times \mathbf{A}$ 

A *complex potential*  $\phi(z) = \Phi(x,y) + iA(x,y)$  exists whose *z*-derivative is  $f(z) = d \phi/dz$ .

Its complex conjugate  $\phi^*(z^*) = \Phi(x,y) - iA(x,y)$  has  $z^*$ -derivative  $f^*(z^*) = d\phi^*/dz^*$  giving *DFL* field **F**.

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To find  $\phi = \Phi + i\mathbf{A}$  integrate  $f(z) = a \cdot z$  to get  $\phi$  and isolate real (Re  $\phi = \Phi$ ) and imaginary (Im  $\phi = \mathbf{A}$ ) parts.  $f(z) = \frac{d\phi}{dz} \Rightarrow \phi = \Phi + i \mathbf{A} = \int f \cdot dz = \int az \cdot dz = \frac{1}{2} az^2$ 

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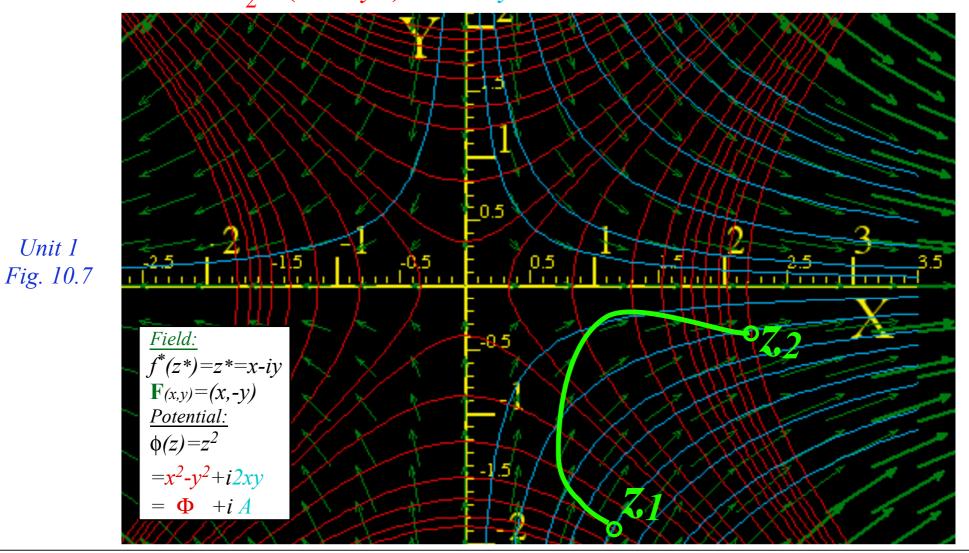
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Tuesday, October 9, 2012

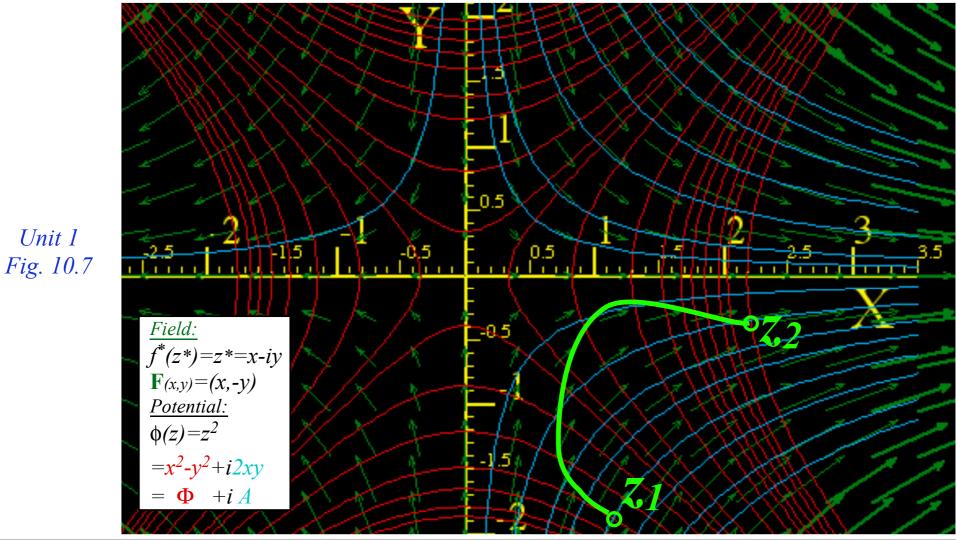
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$$f(z) = \frac{d\phi}{dz} \implies \phi = \underbrace{\phi}_{z} + i \quad A = \int f \cdot dz = \int az \cdot dz = \frac{1}{2} az^{2} = \frac{1}{2} a(x + iy)^{2}$$
$$= \frac{1}{2} a(x^{2} - y^{2}) + i \quad axy$$



BONUS! Get a free coordinate system!

The  $(\Phi, A)$  grid is a GCC coordinate system\*:  $q^{l} = \Phi = (x^{2}-y^{2})/2 = const.$  $q^{2} = A = (xy) = const.$ 

\*Actually it's OCC.

# What Good are complex variables?

Easy 2D vector calculus Easy 2D vector derivatives Easy 2D source-free field theory Easy 2D vector field-potential theory

The half-n'-half results: (Riemann-Cauchy Derivative Relations)

8. (contd.) Complex potential  $\phi$  contains "scalar"( $F=\nabla \Phi$ ) and "vector"( $F=\nabla xA$ ) potentials ...and either one (or half-n'-half!) works just as well.

Derivative  $\frac{d\phi^*}{dz^*}$  has 2D gradient  $\nabla \Phi = \begin{pmatrix} \frac{\partial \Phi}{\partial x} \\ \frac{\partial \Phi}{\partial y} \end{pmatrix}$  of scalar  $\Phi$  and curl  $\nabla \times \mathbf{A} = \begin{pmatrix} \frac{\partial \mathbf{A}}{\partial y} \\ -\frac{\partial \mathbf{A}}{\partial y} \end{pmatrix}$  of vector  $\mathbf{A}$  (and they're equal!)  $f(z) = \frac{d\phi}{dz} \Rightarrow$  $\frac{d}{dz^*} \phi^* = \frac{d}{dz^*} (\Phi - i\mathbf{A}) = \frac{1}{2} (\frac{\partial}{\partial x} + i\frac{\partial}{\partial y}) (\Phi - i\mathbf{A}) = \frac{1}{2} (\frac{\partial \Phi}{\partial x} + i\frac{\partial \Phi}{\partial y}) + \frac{1}{2} (\frac{\partial \mathbf{A}}{\partial y} - i\frac{\partial \mathbf{A}}{\partial x}) = \frac{1}{2} \nabla \Phi + \frac{1}{2} \nabla \times \mathbf{A}$ 

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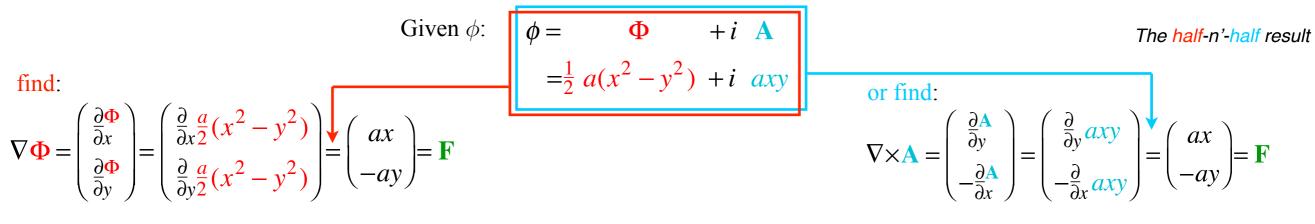
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Note, *mathematician definition* of force field  $\mathbf{F} = +\nabla \Phi$  replaces usual physicist's definition  $\mathbf{F} = -\nabla \Phi$ 

8. (contd.) Complex potential  $\phi$  contains "scalar"( $F=\nabla \Phi$ ) and "vector"( $F=\nabla xA$ ) potentials ...and either one (or half-n'-half!) works just as well.

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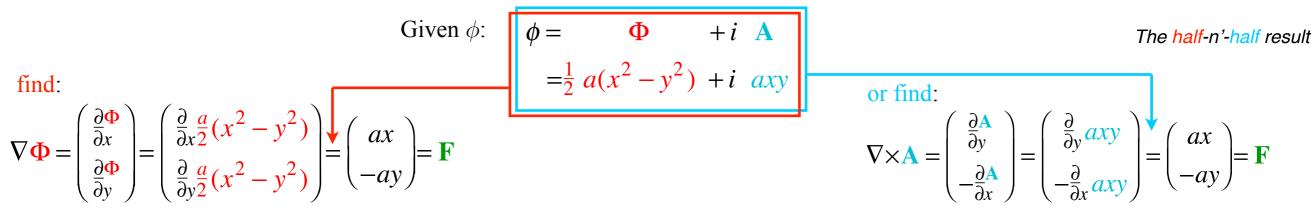


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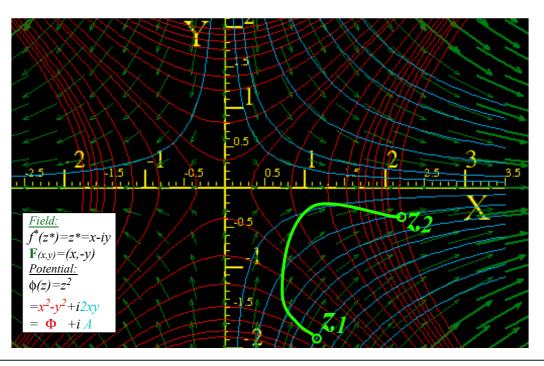
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 $f(z) = \frac{d\phi}{dz} \Rightarrow$   
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 $\langle \cdot \cdot \rangle$ 

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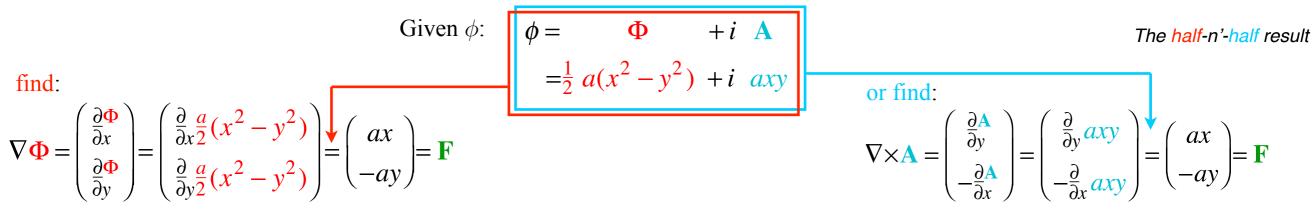
Scalar *static potential lines*  $\Phi$ =*const.* and vector *flux potential lines* A=*const.* define *DFL field-net.* 



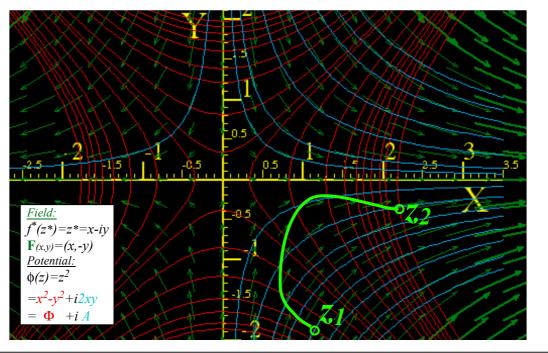
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 $\begin{array}{l} \text{...and entries one (or nan-respective for equal) result} \\ \text{Derivative } \frac{d\phi^*}{dz^*} \text{ has 2D gradient } \nabla \Phi = \begin{pmatrix} \frac{\partial \Phi}{\partial x} \\ \frac{\partial \Phi}{\partial y} \end{pmatrix} \text{ of scalar } \Phi \text{ and curl } \nabla \times \mathbf{A} = \begin{pmatrix} \frac{\partial A}{\partial y} \\ -\frac{\partial A}{\partial y} \end{pmatrix} \text{ of vector } \mathbf{A} \text{ (and they 're equal!)} \\ \text{The half-n'-half result} \\ \frac{d}{dz^*} \phi^* = \frac{d}{dz^*} \left( \Phi - i\mathbf{A} \right) = \frac{1}{2} \left( \frac{\partial}{\partial x} + i\frac{\partial}{\partial y} \right) (\Phi - i\mathbf{A}) = \frac{1}{2} \left( \frac{\partial \Phi}{\partial x} + i\frac{\partial}{\partial y} \right) + \frac{1}{2} \left( \frac{\partial A}{\partial y} - i\frac{\partial A}{\partial x} \right) = \frac{1}{2} \nabla \Phi + \frac{1}{2} \nabla \times \mathbf{A} \end{array}$ 

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Scalar *static potential lines*  $\Phi$ =*const.* and vector *flux potential lines* A=*const.* define *DFL field-net.* 



The half-n'-half results are called Riemann-Cauchy Derivative Relations

$$\frac{\partial \Phi}{\partial x} = \frac{\partial A}{\partial y} \quad \text{is:} \quad \frac{\partial \text{Re}f(z)}{\partial x} = \quad \frac{\partial \text{Im}f(z)}{\partial y}$$
$$\frac{\partial \Phi}{\partial y} = -\frac{\partial A}{\partial x} \quad \text{is:} \quad \frac{\partial \text{Re}f(z)}{\partial y} = -\frac{\partial \text{Im}f(z)}{\partial x}$$

→ 4. Riemann-Cauchy conditions What's analytic? (...and what's <u>not</u>?)

*Review* (*z*,*z*\*) *to* (*x*,*y*) *transformation relations* 

$$z = x + iy \qquad x = \frac{1}{2} (z + z^*) \qquad \frac{df}{dz} = \frac{\partial x}{\partial z} \frac{\partial f}{\partial x} + \frac{\partial y}{\partial z} \frac{\partial f}{\partial y} = \frac{1}{2} \frac{\partial f}{\partial x} + \frac{1}{2i} \frac{\partial f}{\partial y} = \frac{1}{2} \left(\frac{\partial}{\partial x} - i\frac{\partial}{\partial y}\right) f$$

$$z^* = x - iy \qquad y = \frac{1}{2i} (z - z^*) \qquad \frac{df}{dz^*} = \frac{\partial x}{\partial z^*} \frac{\partial f}{\partial x} + \frac{\partial y}{\partial z^*} \frac{\partial f}{\partial y} = \frac{1}{2} \frac{\partial f}{\partial x} - \frac{1}{2i} \frac{\partial f}{\partial y} = \frac{1}{2} \left(\frac{\partial}{\partial x} + i\frac{\partial}{\partial y}\right) f$$

Criteria for a field function  $f = f_x(x,y) + i f_y(x,y)$  to be an **analytic function** f(z) of z=x+iy: First, f(z) must <u>not</u> be a function of  $z^*=x-iy$ , that is:  $\frac{df}{dz^*}=0$ This implies f(z) satisfies differential equations known as the **Riemann-Cauchy conditions**  $df = 1(\partial_{x} + \partial_{y}) + 1(\partial_{x} + \partial_{y}) + i(\partial_{y} + \partial_{y}) + i(\partial_{y}$ 

*Review* (*z*,*z*\*) *to* (*x*,*y*) *transformation relations* 

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Criteria for a field function  $f = f_x(x,y) + i f_y(x,y)$  to be an **analytic function**  $f(z^*)$  of  $z^*=x-iy$ : First,  $f(z^*)$  must <u>not</u> be a function of z=x+iy, that is: $\frac{df}{dz}=0$ This implies  $f(z^*)$  satisfies differential equations we call Anti-Riemann-Cauchy conditions  $\frac{df}{dz} = 0 = \frac{1}{2} \left( \frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right) (f_x + i f_y) = \frac{1}{2} \left( \frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} \right) + \frac{i}{2} \left( \frac{\partial f_y}{\partial x} - \frac{\partial f_x}{\partial y} \right) = implies: \frac{\partial f_x}{\partial x} = -\frac{\partial f_y}{\partial y} \quad and: \quad \frac{\partial f_y}{\partial x} = \frac{\partial f_x}{\partial y}$ 

$$\frac{df}{dz^*} = \frac{1}{2} \left( \frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right) (f_x + i f_y) = \frac{1}{2} \left( \frac{\partial f_x}{\partial x} - \frac{\partial f_y}{\partial y} \right) + \frac{i}{2} \left( \frac{\partial f_y}{\partial x} + \frac{\partial f_x}{\partial y} \right) = \frac{\partial f_x}{\partial x} + i \frac{\partial f_y}{\partial x} = -\frac{\partial f_y}{\partial y} + i \frac{\partial f_x}{\partial y} = \frac{\partial}{\partial x} (f_x + i f_y) = -\frac{\partial}{\partial i y} (f_x + i f_y)$$

Example: Is f(x,y) = 2x + iy an analytic function of z=z+iy?

Example: Q: Is f(x,y) = 2x + i4y an analytic function of z=z+iy?

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= z+z^\* + (2z-2z^\*)

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$$f(x,y) = 2x + i4y = 2 (z+z^*)/2 + i4(-i(z-z^*)/2)$$
  
= z+z^\* + (2z-2z^\*)  
= 3z-z^\*

Example: Q: Is f(x,y) = 2x + i4y an analytic function of z=z+iy?

Well, test it using definitions: z = x + iy and:  $z^* = x - iy$ or:  $x = (z+z^*)/2$  and:  $y = -i(z-z^*)/2$ 

$$f(x,y) = 2x + i4y = 2 (z+z^*)/2 + i4(-i(z-z^*)/2) = z+z^* + (2z-2z^*) = 3z-z^*$$

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Example 2: Q: Is  $r(x,y) = x^2 + y^2$  an analytic function of z=z+iy?

A: NO! r(xy)=z\*z is a function of z and z\* so not analytic for <u>either</u>.

Example: Q: Is f(x,y) = 2x + i4y an analytic function of z=z+iy?

Well, test it using definitions: z = x + iy and:  $z^* = x - iy$ or:  $x = (z+z^*)/2$  and:  $y = -i(z-z^*)/2$ 

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Example 2: Q: Is  $r(x,y) = x^2 + y^2$  an analytic function of z=z+iy?

A: NO!  $r(xy)=z^*z$  is a function of  $z \text{ and } z^*$  so not analytic for <u>either</u>.

Example 3: Q: Is  $s(x,y) = x^2 - y^2 + 2ixy$  an analytic function of z=z+iy?

A: YES!  $s(xy) = (x+iy)^2 = z^2$  is analytic function of z. (Yay!)

### 4. Riemann-Cauchy conditions What's analytic? (...and what's not?)

Easy 2D circulation and flux integrals Easy 2D curvilinear coordinate discovery Easy 2D monopole, dipole, and 2<sup>n</sup>-pole analysis Easy 2<sup>n</sup>-multipole field and potential expansion Easy stereo-projection visualization

### 9. Complex integrals f (z)dz count 2D "circulation" ( **F**•dr) and "flux" (**F**xdr)

Integral of f(z) between point  $z_1$  and point  $z_2$  is potential difference  $\Delta \phi = \phi(z_2) - \phi(z_1)$  $\Delta \phi = \phi(z_2) - \phi(z_1) = \int_{z_1}^{z_2} f(z) dz = \Phi(x_2, y_2) - \Phi(x_1, y_1) + i[A(x_2, y_2) - A(x_1, y_1)]$   $\Delta \phi = \Delta \Phi + i \Delta A$ 

In *DFL*-field **F**,  $\Delta \phi$  is independent of the integration path z(t) connecting  $z_1$  and  $z_2$ .

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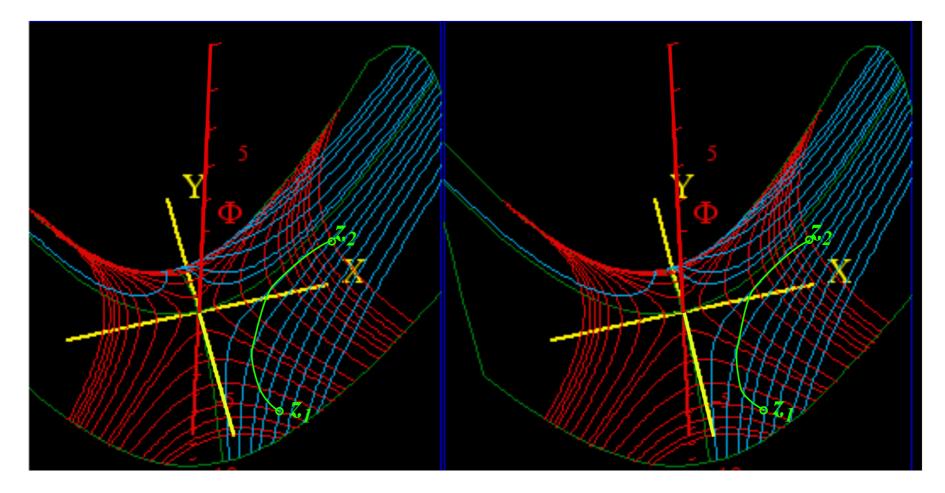
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$$\int f(z)dz = \int \left(f^*(z^*)\right)^* dz = \int \left(f^*(z^*)\right)^* \left(dx + i\,dy\right) = \int \left(f^*_x + i\,f^*_y\right)^* \left(dx + i\,dy\right) = \int \left(f^*_x - i\,f^*_y\right) \left(dx + i\,dy\right)$$
$$= \int \left(f^*_x dx + f^*_y dy\right) + i \int \left(f^*_x dy - f^*_y dx\right)$$
$$= \int \mathbf{F} \cdot d\mathbf{r} + i \int \mathbf{F} \times d\mathbf{r} \cdot \hat{\mathbf{e}}_Z$$
$$= \int \mathbf{F} \cdot d\mathbf{r} + i \int \mathbf{F} \cdot d\mathbf{r} \times \hat{\mathbf{e}}_Z$$
$$= \int \mathbf{F} \cdot d\mathbf{r} + i \int \mathbf{F} \cdot d\mathbf{s} \quad \text{where:} \quad d\mathbf{S} = d\mathbf{r} \times \hat{\mathbf{e}}_Z$$

### 9. Complex integrals f (z)dz count 2D "circulation" ( **F**•dr) and "flux" (**F**xdr)

Integral of f(z) between point  $z_1$  and point  $z_2$  is potential difference  $\Delta \phi = \phi(z_2) - \phi(z_1)$  $\Delta \phi = \phi(z_2) - \phi(z_1) = \int_{z_1}^{z_2} f(z) dz = \Phi(x_2, y_2) - \Phi(x_1, y_1) + i[\mathbf{A}(x_2, y_2) - \mathbf{A}(x_1, y_1)]$  $\Delta \phi = \Delta \Phi + i \Delta \mathbf{A}$ In *DFL*-field **F**,  $\Delta \phi$  is independent of the integration path z(t) connecting  $z_1$  and  $z_2$ .  $\int f(z)dz = \int \left( f^*(z^*) \right)^* dz = \int \left( f^*(z^*) \right)^* \left( dx + i \, dy \right) = \int \left( f^*_x + i \, f^*_y \right)^* \left( dx + i \, dy \right) = \int \left( f^*_x - i \, f^*_y \right) \left( dx + i \, dy \right)$  $= \int (f_x^* dx + f_v^* dy) + i \int (f_x^* dy - f_v^* dx)$  $= \int \mathbf{F} \cdot d\mathbf{r} + i \int \mathbf{F} \times d\mathbf{r} \cdot \hat{\mathbf{e}}_{Z}$  $= \int \mathbf{F} \cdot d\mathbf{r} + i \int \mathbf{F} \cdot d\mathbf{r} \times \hat{\mathbf{e}}_{7}$  $d\mathbf{S}$  $= \int \mathbf{F} \cdot d\mathbf{r} + i \int \mathbf{F} \cdot d\mathbf{S}$ where:  $d\mathbf{S} = d\mathbf{r} \times \hat{\mathbf{e}}_Z$ drBig F•dr Imaginary part  $\int_{1}^{2} \mathbf{F} \cdot d\mathbf{S} = \Delta \mathbf{A}$ Real part  $\int_{1}^{2} \mathbf{F} \cdot d\mathbf{r} = \Delta \Phi$ sums **F** projection *across* path *d***r** sums F projections *along* path that is, *flux* thru surface dr that is, *circulation* on path elements  $d\mathbf{S} = d\mathbf{r} \times \mathbf{e}_{\mathbf{Z}}$  normal to  $d\mathbf{r}$ to get  $\Delta \Phi$ . to get  $\Delta A$ .

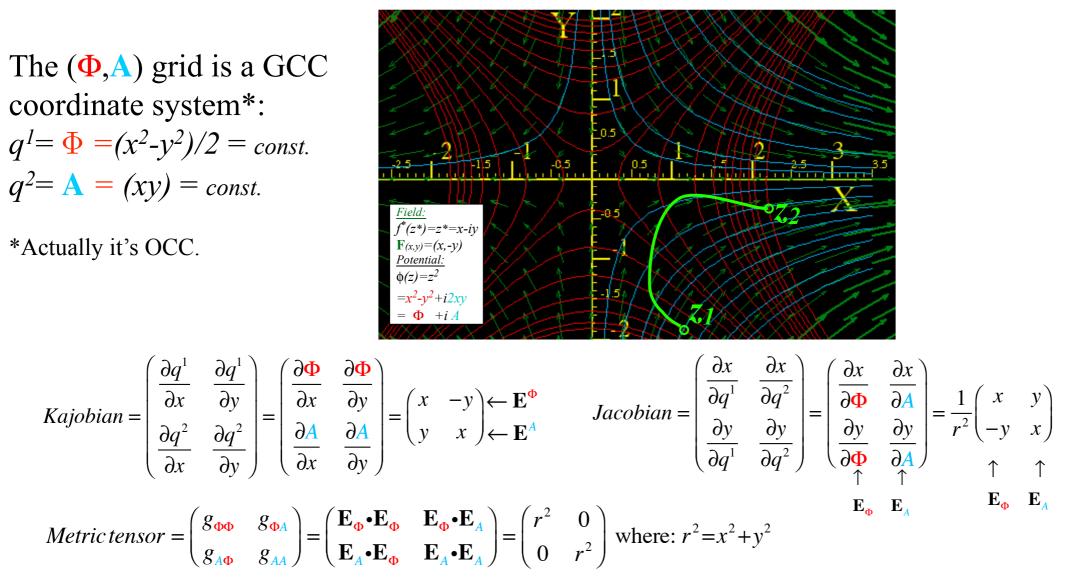
Here the scalar potential  $\Phi = (x^2 - y^2)/2$  is stereo-plotted vs. (x,y)The  $\Phi = (x^2 - y^2)/2 = const$ . curves are topography lines The A = (xy) = const. curves are streamlines normal to topography lines



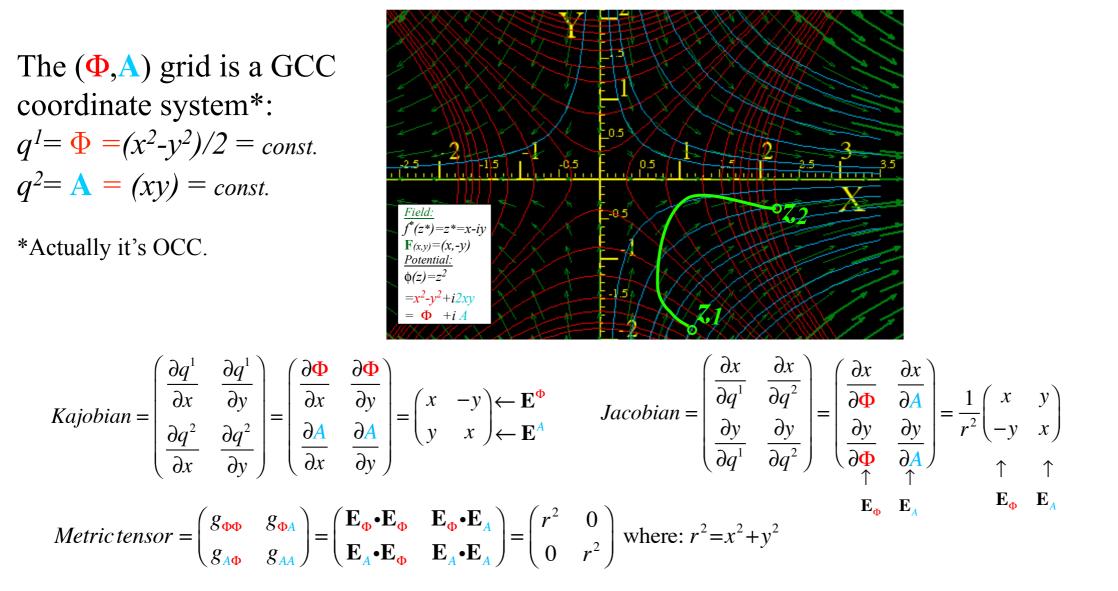
# **4.** Riemann-Cauchy conditions What's analytic? (...and what's <u>not</u>?) Easy 2D circulation and flux integrals

Easy 2D curvilinear coordinate discovery Easy 2D monopole, dipole, and 2<sup>n</sup>-pole analysis Easy 2<sup>n</sup>-multipole field and potential expansion Easy stereo-projection visualization

10. Complex potentials define 2D Orthogonal Curvilinear Coordinates (OCC) of field



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Riemann-Cauchy Derivative Relations make coordinates orthogonal

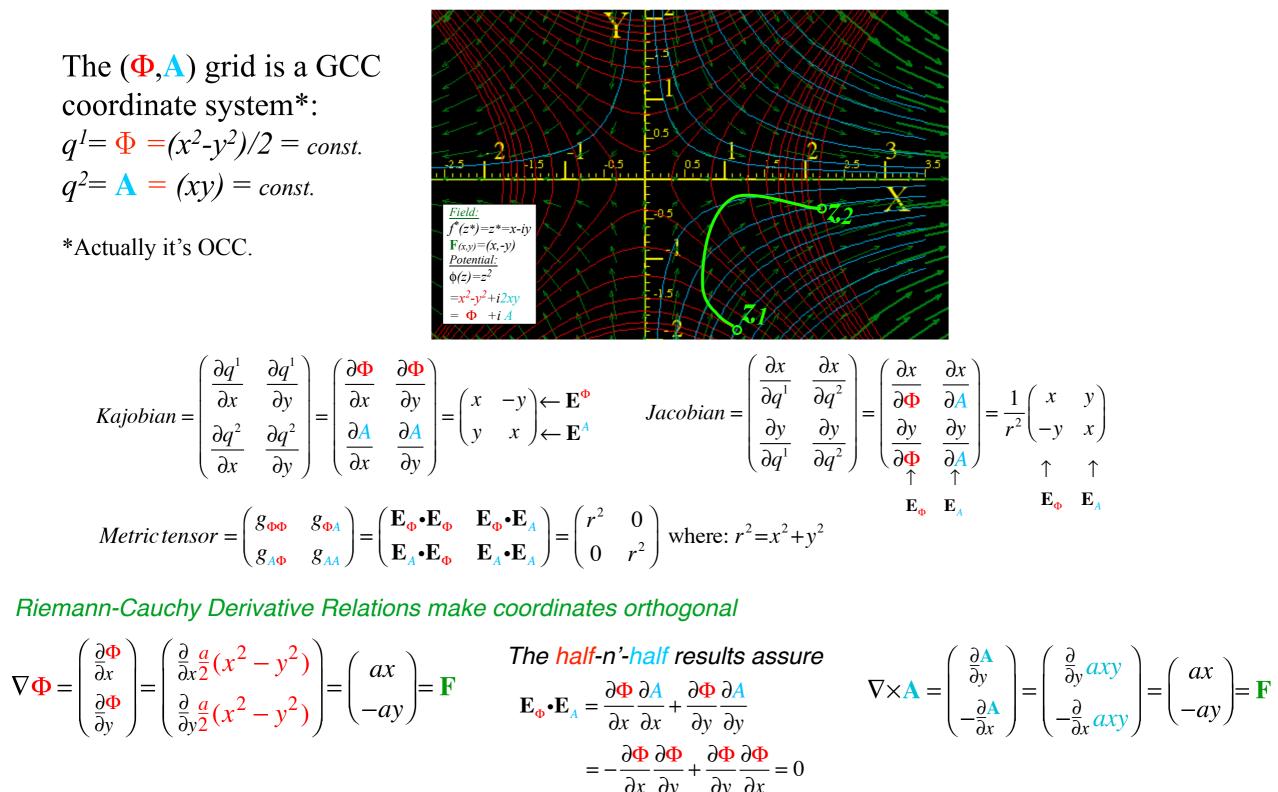
$$\nabla \Phi = \begin{pmatrix} \frac{\partial \Phi}{\partial x} \\ \frac{\partial \Phi}{\partial y} \end{pmatrix} = \begin{pmatrix} \frac{\partial}{\partial x} \frac{a}{2} (x^2 - y^2) \\ \frac{\partial}{\partial y} \frac{a}{2} (x^2 - y^2) \end{pmatrix} = \begin{pmatrix} ax \\ -ay \end{pmatrix} = \mathbf{F}$$

$$\mathbf{E}_{\Phi} \cdot \mathbf{E}_{A} = \frac{\partial \Phi}{\partial x} \frac{\partial A}{\partial x} + \frac{\partial \Phi}{\partial y} \frac{\partial A}{\partial y}$$

$$= -\frac{\partial \Phi}{\partial x} \frac{\partial \Phi}{\partial y} + \frac{\partial \Phi}{\partial y} \frac{\partial \Phi}{\partial x} = 0$$

$$\nabla \times \mathbf{A} = \begin{pmatrix} \frac{\partial \mathbf{A}}{\partial y} \\ -\frac{\partial \mathbf{A}}{\partial x} \end{pmatrix} = \begin{pmatrix} \frac{\partial}{\partial y} axy \\ -\frac{\partial}{\partial x} axy \end{pmatrix} = \begin{pmatrix} ax \\ -ay \end{pmatrix} = \mathbf{F}$$

10. Complex potentials define 2D Orthogonal Curvilinear Coordinates (OCC) of field



or Riemann-Cauchy Zero divergence requirement:  $0 = \frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} = \frac{\partial}{\partial x} \frac{\partial \Phi}{\partial x} + \frac{\partial}{\partial y} \frac{\partial \Phi}{\partial y} = \frac{\partial^2 \Phi}{\partial x^2} + \frac{\partial^2 \Phi}{\partial y^2} = 0$  potential  $\Phi$  obeys Laplace equation

Tuesday, October 9, 2012

# 4. Riemann-Cauchy conditions What's analytic? (...and what's not?)

Easy 2D circulation and flux integrals
 Easy 2D curvilinear coordinate discovery
 Easy 2D monopole, dipole, and 2<sup>n</sup>-pole analysis
 Easy 2<sup>n</sup>-multipole field and potential expansion
 Easy stereo-projection visualization

11. Complex integrals define 2D monopole fields and potentials Of all power-law fields  $f(z)=az^n$  one lacks a power-law potential  $\phi(z)=\frac{a}{n+1}z^{n+1}$ . It is the n=-1 case.

Unit monopole field:  $f(z) = \frac{1}{z} = z^{-1}$   $f(z) = \frac{a}{z} = az^{-1}$  Source-*a* monopole

It has a *logarithmic potential*  $\phi(z) = a \cdot \ln(z) = a \cdot \ln(x+iy)$ .

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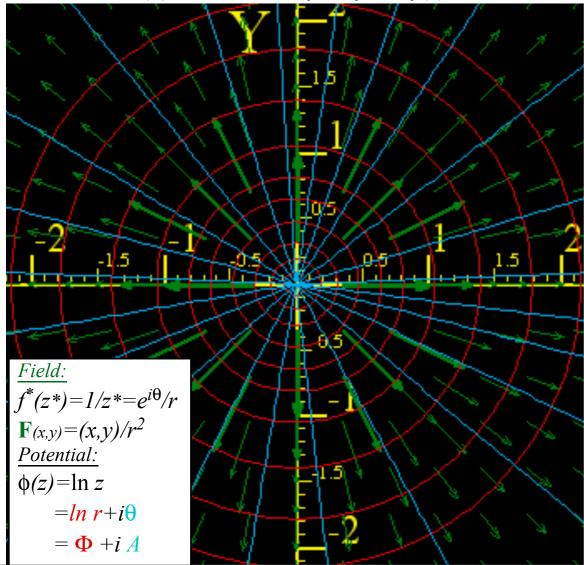
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(a) Unit Z-line-flux field f(z)=1/z



Lecture 14 Thur. 10.9 ends here

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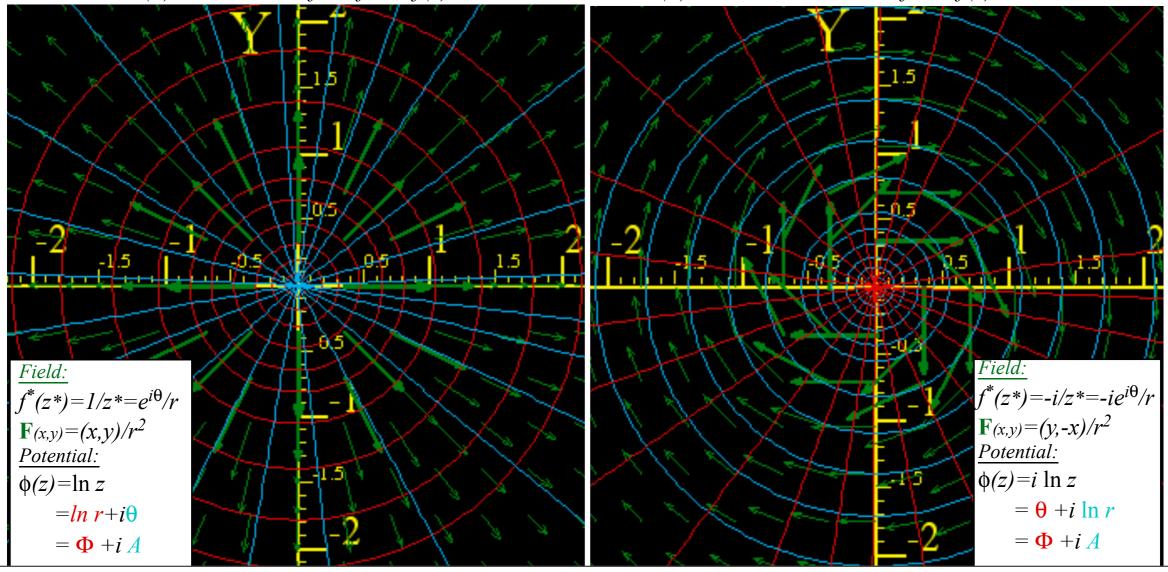
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(a) Unit Z-line-flux field f(z)=1/z

(b) Unit Z-line-vortex field f(z)=i/z



Tuesday, October 9, 2012

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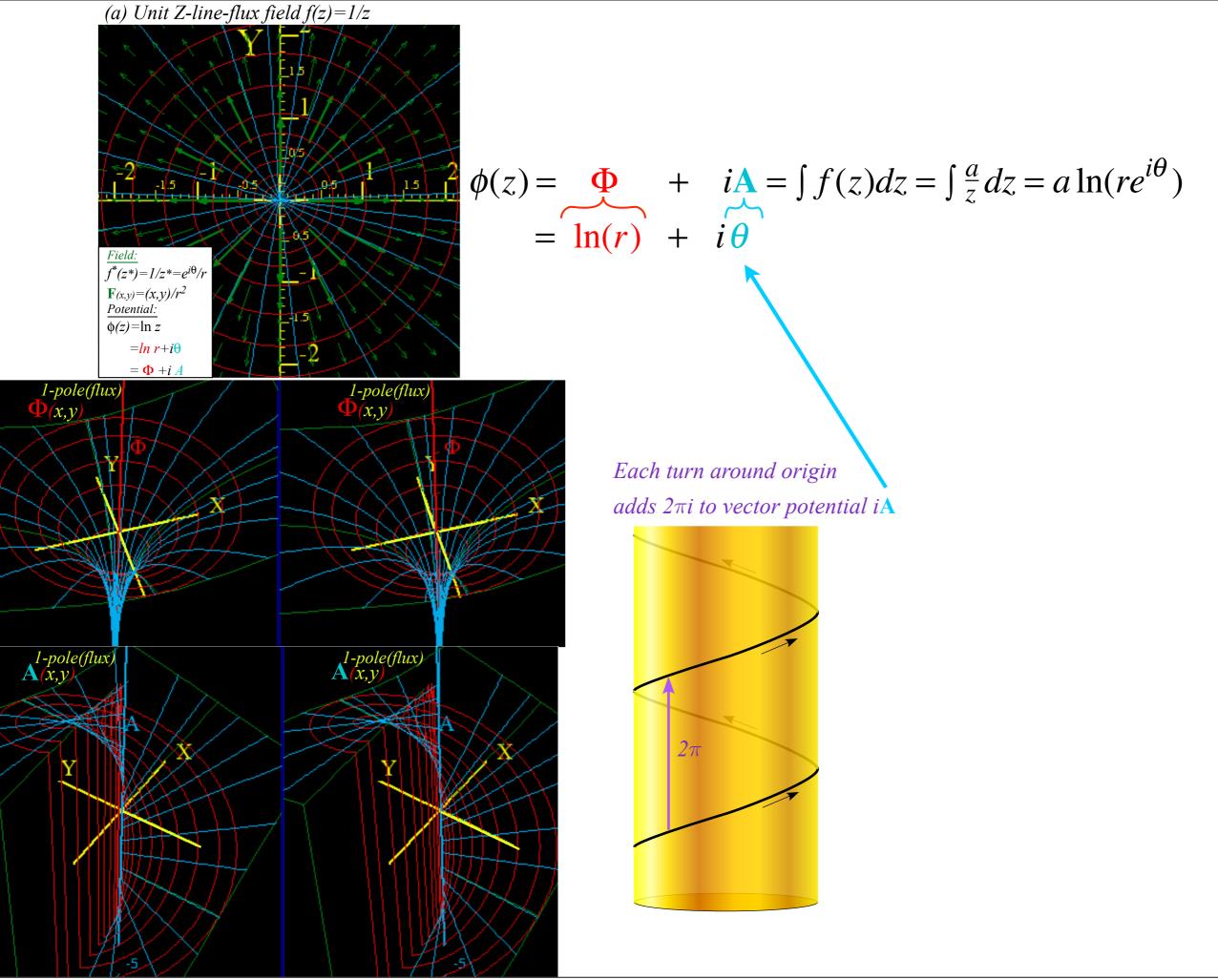
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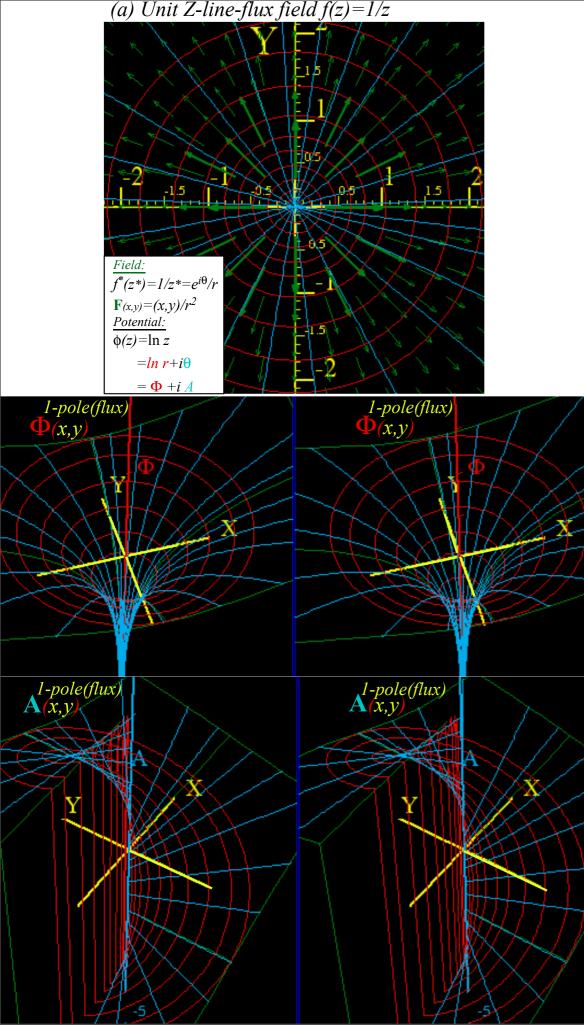
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A monopole field is the only power-law field whose integral (potential) depends on path of integration.

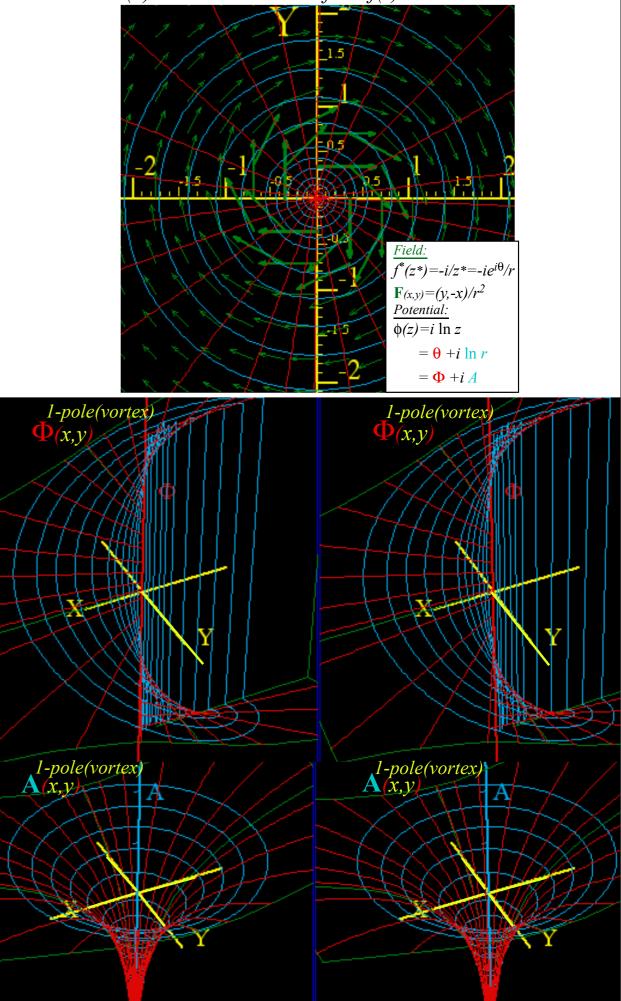
$$\Delta \phi = \oint f(z)dz = a \oint \frac{dz}{z} = a \oint_{\theta=0}^{\theta=2\pi N} \frac{d(Re^{i\theta})}{Re^{i\theta}} = a \oint_{\theta=0}^{\theta=2\pi N} \frac{d\theta}{d\theta} = a i \theta \Big|_{0}^{2\pi N} = 2a\pi i N$$



Tuesday, October 9, 2012



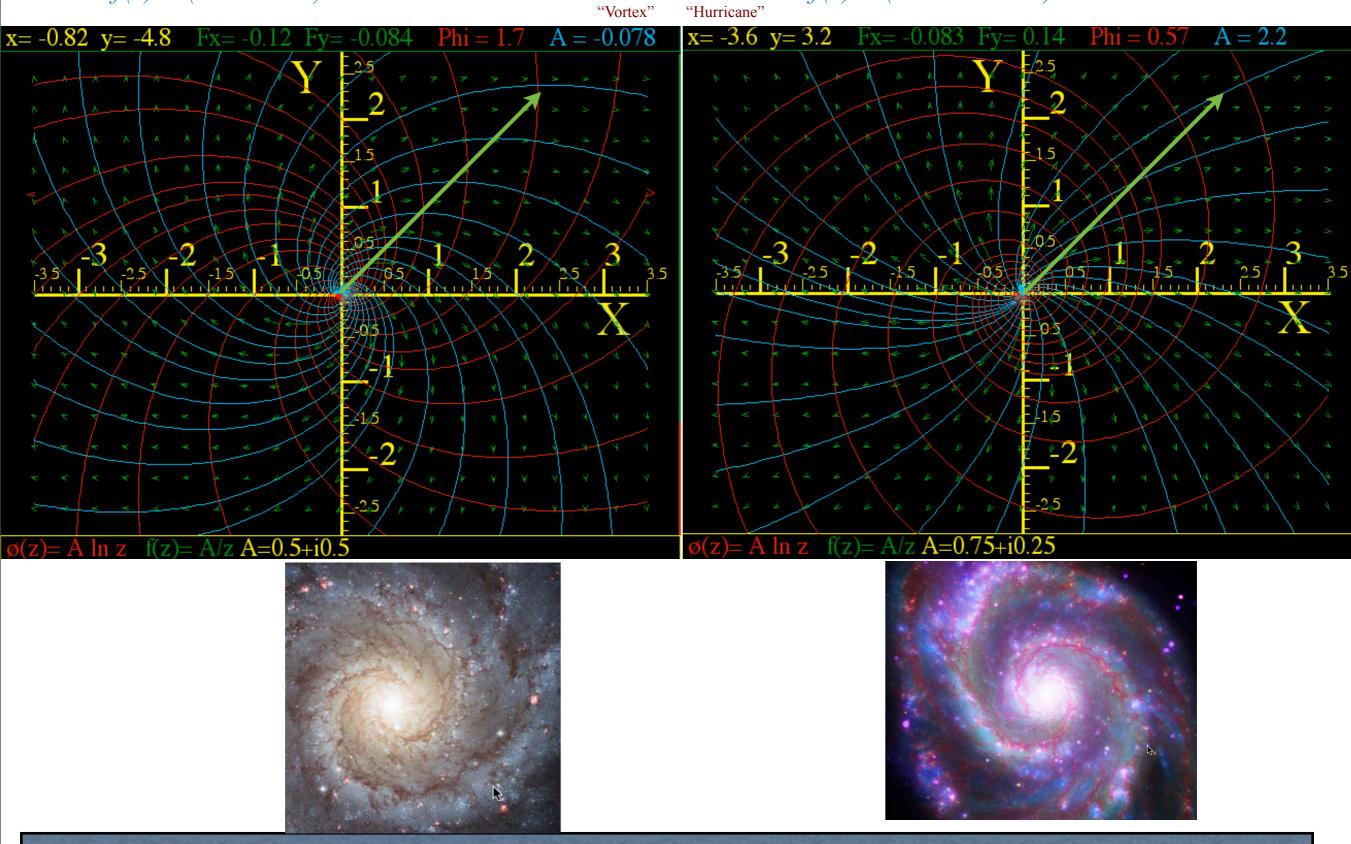
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What Good Are Complex Exponentials? (contd.)

 $f(z) = (0.5 + i0.5)/z = e^{i\pi/4}/z\sqrt{2}$ 





# 4. Riemann-Cauchy conditions What's analytic? (...and what's not?)

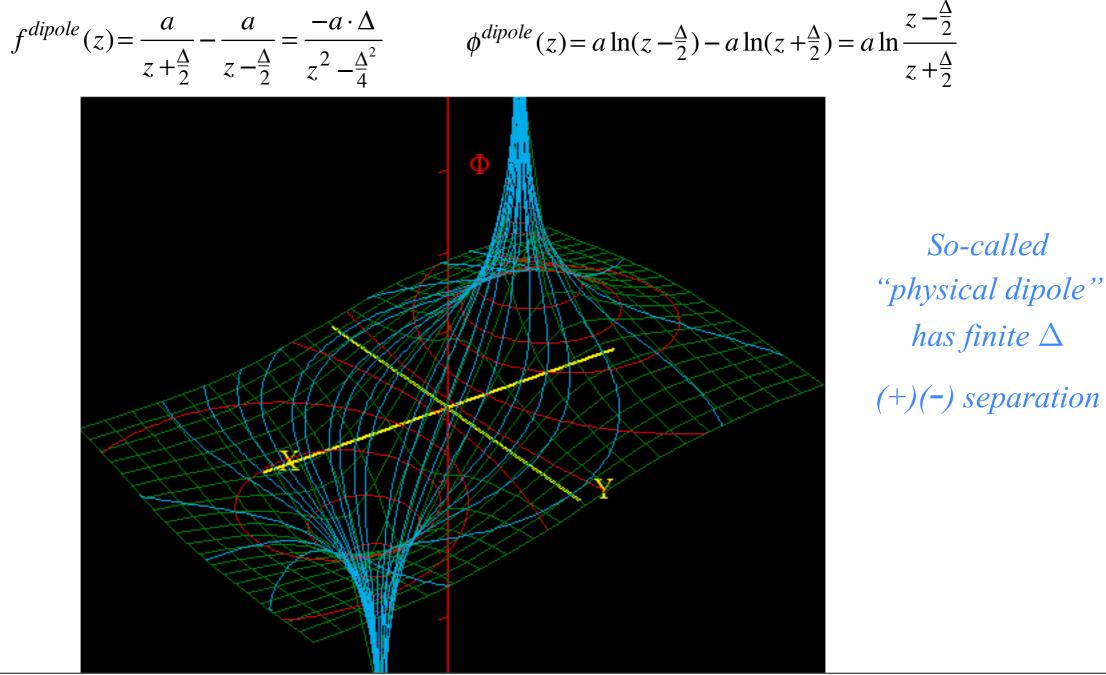
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#### What Good Are Complex Exponentials? (2D monopole, dipole, and 2<sup>n</sup>-pole analysis)

12. Complex derivatives give 2D dipole fields

Start with  $f(z) = az^{-1}$ : 2D line *monopole field* and is its *monopole potential* $\phi(z) = a \ln z$  of source strength a.  $f^{1-pole}(z) = \frac{a}{z} = \frac{d\phi^{1-pole}}{dz}$   $\phi^{1-pole}(z) = a \ln z$ 

Now let these two line-sources of equal but opposite source constants +a and -a be located at  $z=\pm\Delta/2$  separated by a small interval  $\Delta$ . This sum (actually difference) of  $f^{1-pole}$ -fields is called a *dipole field*.



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$$f^{dipole}(z) = \frac{a}{z + \frac{\Delta}{2}} - \frac{a}{z - \frac{\Delta}{2}} = \frac{-a \cdot \Delta}{z^2 - \frac{\Delta^2}{4}} \qquad \phi^{dipole}(z) = a \ln(z - \frac{\Delta}{2}) - a \ln(z + \frac{\Delta}{2}) = a \ln \frac{z - \frac{\Delta}{2}}{z + \frac{\Delta}{2}}$$

If interval  $\Delta$  is *tiny* and is divided out we get a *point-dipole field*  $f^{2-pole}$  that is the *z*-derivative of  $f^{1-pole}$ .

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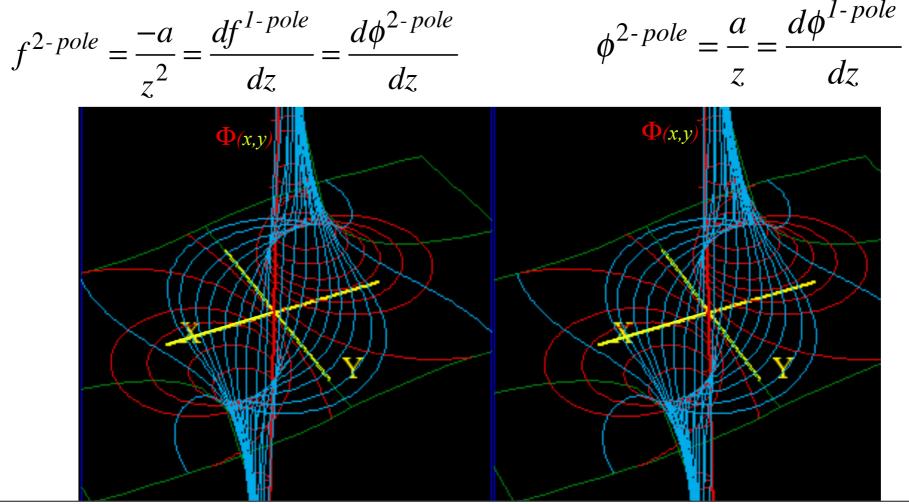
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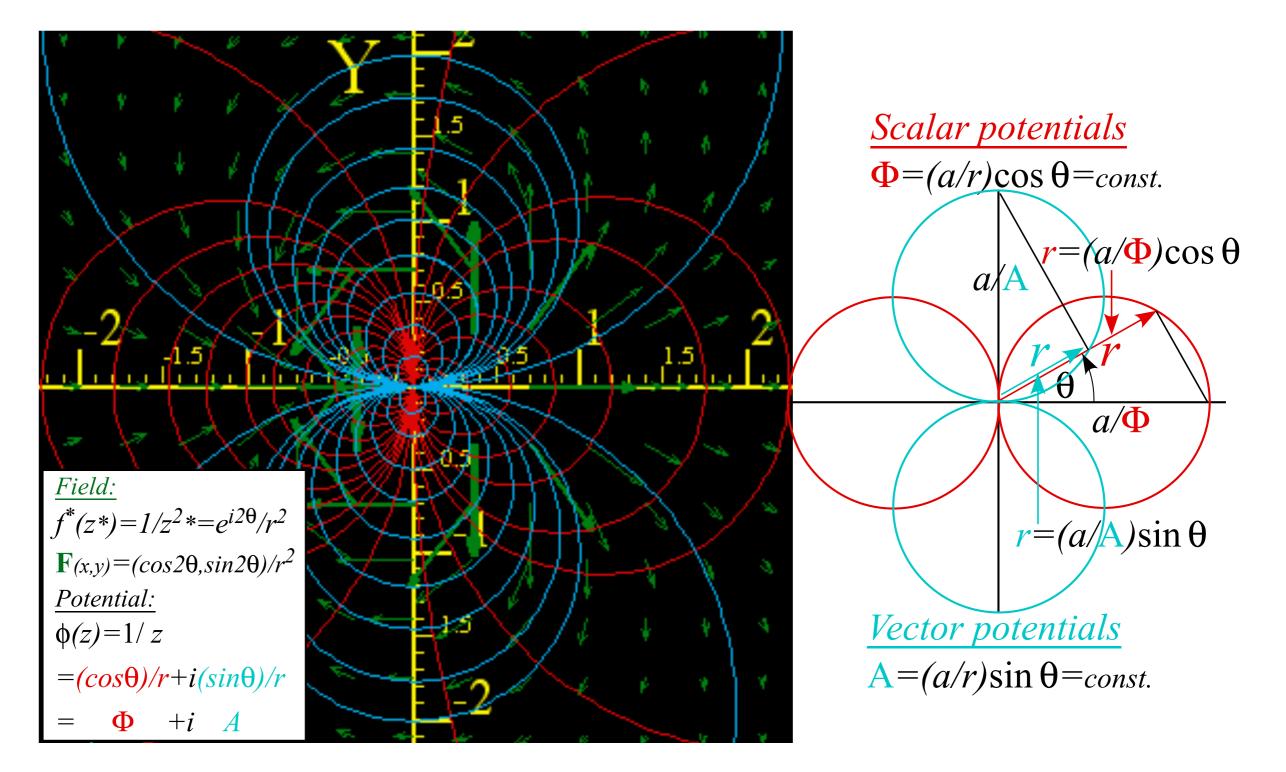
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## 2<sup>n</sup>-pole analysis (quadrupole:2<sup>2</sup>=4-pole, octapole:2<sup>3</sup>=8-pole,..., pole dancer,

What if we put a (-)copy of a 2-pole near its original?

Well, the result is 4-pole or quadrupole field  $f^{4-pole}$  and potential  $\phi^{4-pole}$ .

Each a *z*-derivative of  $f^{2-pole}$  and  $\phi^{2-pole}$ .

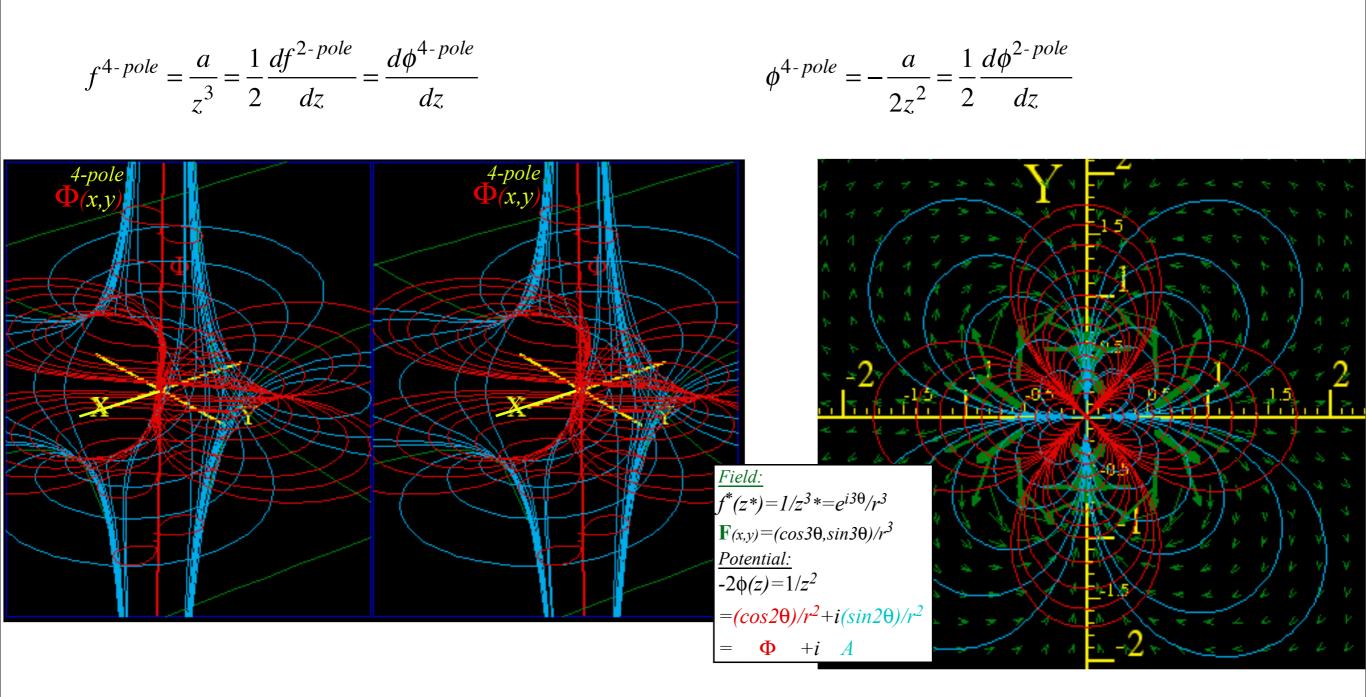
$$f^{4-pole} = \frac{a}{z^3} = \frac{1}{2} \frac{df^{2-pole}}{dz} = \frac{d\phi^{4-pole}}{dz} \qquad \qquad \phi^{4-pole} = -\frac{a}{2z^2} = \frac{1}{2} \frac{d\phi^{2-pole}}{dz}$$

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# 2<sup>n</sup>-pole analysis: Laurent series (Generalization of Maclaurin-Taylor series)

*Laurent series* or *multipole expansion* of a given complex field function f(z) around z=0.

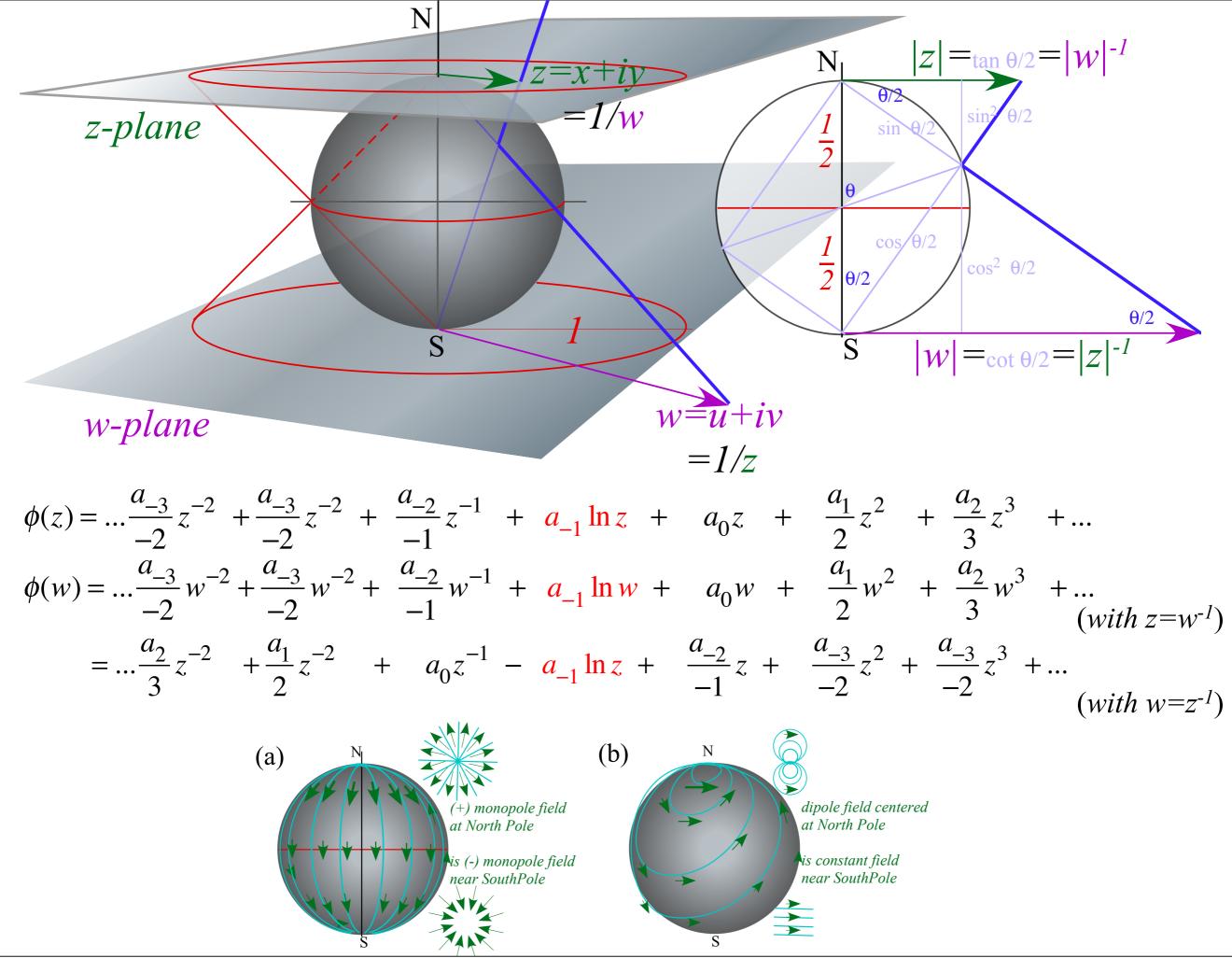
 $f(z) = \dots a_{-3}z^{-3} + a_{-2}z^{-2} + a_{-1}z^{-1} + a_0 + a_1z + a_2z^2 + a_3z^3 + a_4z^4 + a_5z^5 + \dots$   $\dots 2^2 \text{-pole} \quad 2^1 \text{-pole} \quad 2^0 \text{-pole} \quad 2^1 \text{-pole} \quad 2^2 \text{-pole} \quad 2^3 \text{-pole} \quad 2^4 \text{-pole} \quad 2^5 \text{-pole} \quad 2^6 \text{-pole} \dots$  $\text{at } z = 0 \quad \text{at } z = 0 \quad \text{at } z = \infty \quad \text{at } z =$ 

All field terms  $a_{m-1}z^{m-1}$  except 1-pole  $\frac{a}{z}$  have potential term  $a_{m-1}z^m/m$  of a 2<sup>m</sup>-pole. These are located at z=0 for m<0 and at  $z=\infty$  for m>0.

$$\phi(z) = \dots \frac{a_{-3}}{-2} z^{-2} + \frac{a_{-3}}{-2} z^{-2} + \frac{a_{-2}}{-1} z^{-1} + a_{-1} \ln z + a_0 z + \frac{a_1}{2} z^2 + \frac{a_2}{3} z^3 + \dots$$

$$\phi(w) = \dots \frac{a_{-3}}{-2} w^{-2} + \frac{a_{-3}}{-2} w^{-2} + \frac{a_{-2}}{-1} w^{-1} + a_{-1} \ln w + a_0 w + \frac{a_1}{2} w^2 + \frac{a_2}{3} w^3 + \dots$$
(with  $z = w^{-1}$ )

$$= \dots \frac{a_2}{3} z^{-2} + \frac{a_1}{2} z^{-2} + a_0 z^{-1} - a_{-1} \ln z + \frac{a_{-2}}{-1} z + \frac{a_{-3}}{-2} z^2 + \frac{a_{-3}}{-2} z^3 + \dots$$
(with  $w = z^{-1}$ )



Of all 2<sup>*m*</sup>-pole field terms  $a_{m-1}z^{m-1}$ , only the m=0 monopole  $a_{-1}z^{-1}$  has a non-zero loop integral (10.39).

$$\oint f(z)dz = \oint a_{-1}z^{-1}dz = 2\pi i a_{-1} \qquad a_{-1} = \frac{1}{2\pi i} \oint f(z)dz$$

This m=1-pole constant- $a_{-1}$  formula is just the first in a series of Laurent coefficient expressions.

$$\cdots a_{-3} = \frac{1}{2\pi i} \oint z^2 f(z) dz \ , \ a_{-2} = \frac{1}{2\pi i} \oint z^1 f(z) dz \ , \ a_{-1} = \frac{1}{2\pi i} \oint f(z) dz \ , \ a_0 = \frac{1}{2\pi i} \oint \frac{f(z)}{z} dz \ , \ a_1 = \frac{1}{2\pi i} \oint \frac{f(z)}{z^2} dz \ , \ a_1 = \frac{1}{2\pi i} \oint \frac{f(z)}{z^2} dz \ , \ a_2 = \frac{1}{2\pi i} \oint \frac{f(z)}{z^2} dz \ , \ a_3 = \frac{1}{2\pi i} \oint \frac{f(z)}{z^2} dz \ , \ a_4 = \frac{1}{2\pi i} \oint \frac{f(z)}{z^2} dz \ , \ a_5 = \frac{1}{2\pi i} \oint \frac{f(z)}{z^2} dz \ , \ a_5 = \frac{1}{2\pi i} \oint \frac{f(z)}{z^2} dz \ , \ a_6 = \frac{1}{2\pi i} \oint \frac{f(z)}{z} dz \ , \ a_7 = \frac{1}{2\pi i} \oint \frac{f(z)}{z^2} dz \ , \ a_8$$

Source analysis starts with 1-pole loop integrals  $\oint z^{-1}dz = 2\pi i$  or, with origin shifted  $\oint (z-a)^{-1}dz = 2\pi i$ . They hold for any loop about point-*a*. Function f(z) is just f(a) on a *tiny* circle around point-*a*.

$$\oint \frac{f(z)}{z-a} dz = \oint \frac{f(a)}{z-a} dz = f(a) \oint \frac{1}{z-a} dz = 2\pi i f(a) \qquad \qquad f(a) = \frac{1}{2\pi i} \oint \frac{f(z)}{z-a} dz$$

The f(a) result is called a *Cauchy integral*. Then repeated *a*-derivatives gives a sequence of them.

$$\frac{df(a)}{da} = \frac{1}{2\pi i} \oint \frac{f(z)}{(z-a)^2} dz , \quad \frac{d^2 f(a)}{da^2} = \frac{2}{2\pi i} \oint \frac{f(z)}{(z-a)^3} dz , \quad \frac{d^3 f(a)}{da^3} = \frac{3!}{2\pi i} \oint \frac{f(z)}{(z-a)^4} dz , \quad \dots, \\ \frac{d^n f(a)}{da^n} = \frac{n!}{2\pi i} \oint \frac{f(z)}{(z-a)^{n+1}} dz$$

This leads to a general *Taylor-Laurent* power series expansion of function f(z) around point-*a*.

$$f(z) = \sum_{n=-\infty}^{\infty} a_n (z-a)^n \qquad \text{where : } a_n = \frac{1}{2\pi i} \oint \frac{f(z)}{(z-a)^{n+1}} dz \left( = \frac{1}{n!} \frac{d^n f(a)}{da^n} \quad \text{for : } n \ge 0 \right)$$