

Lecture 22.

Introduction to classical oscillation and resonance

(Ch. 1 of Unit 4 11.08.12)

1D forced-damped-harmonic oscillator equations and Green's function solutions

Linear harmonic oscillator equation of motion.

Linear damped-harmonic oscillator equation of motion.

Frequency retardation and amplitude damping

Figure of oscillator merit (the 5% solution $3/\Gamma$ and other numbers)

Linear forced-damped-harmonic oscillator equation of motion.

Phase lag and amplitude resonance amplification

Figure of resonance merit: Quality factor $q = \omega_0/2\Gamma$

Properties of Green's function solutions and their mathematical/physical behavior

Transient solutions vs. Steady State solutions

Complete Green's Solution for the FDHO (Forced-Damped-Harmonic Oscillator)

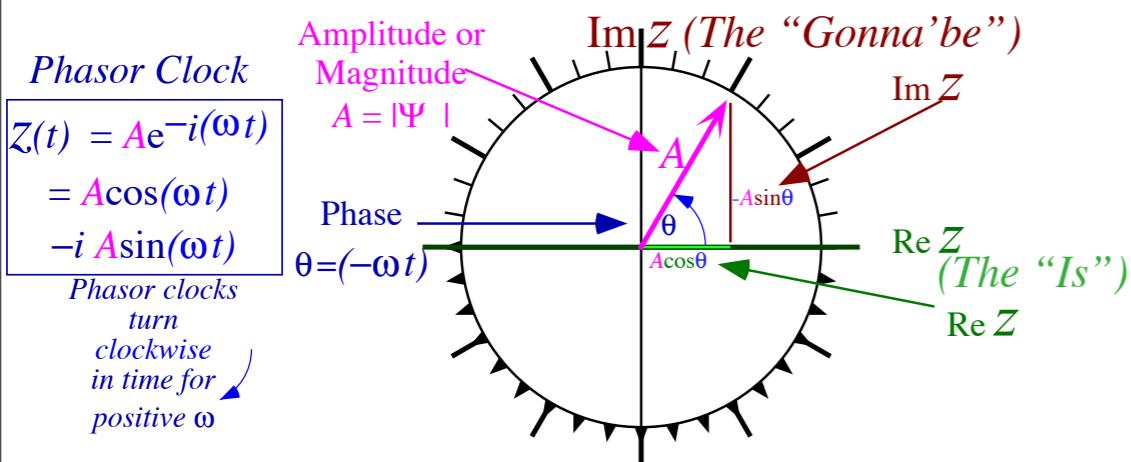
Quality factors: Beat, lifetimes, and uncertainty

Approximate Lorentz-Green's Function for high quality FDHO (Quantum propagator)

Common Lorentzian (a.k.a. Witch of Agnesi)

Linear forced-damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore} + F_{stimulus}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m} + \frac{F_{stimulus}}{m}$$

Stimulating acceleration
 $a_{stimulus} = a(t)$ due to
 stimulating force $F_{stimulus}(t)$
 (Typically E-field)

$$= \frac{e}{m} E(t)$$

$$\frac{d^2 z}{dt^2} + 2\Gamma \frac{dz}{dt} + \omega_0^2 z = a_{stimulus}$$

↑ ↑ ↑

$$F_{stimulus}(t) = eE(t)$$

$$F_{restore} = -kz, \quad (k = \omega_0^2 m),$$

$$F_{damping} = -b \frac{dz}{dt}, \quad (b = 2\Gamma m)$$

Coordinate $z=z(t)$ is the response coordinate
 for a particle of mass m and charge e

driven by external **stimulating force**

held back by a **harmonic (linear) restoring force**

retarded by **frictional damping force**

Linear

harmonic oscillator equation of motion.

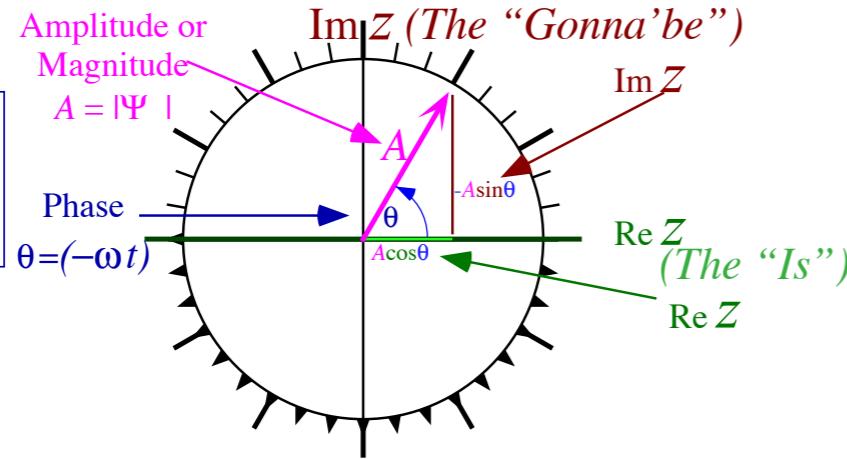
Phasor Clock

$$Z(t) = A e^{-i(\omega t)}$$

$$= A \cos(\omega t)$$

$$-i A \sin(\omega t)$$

Phasor clocks
turn
clockwise
in time for
positive ω



$$F_{total}(t) = m \frac{d^2 z}{dt^2} =$$

$$\frac{d^2 z}{dt^2} =$$

$F_{restore}$

$$\frac{F_{restore}}{m}$$

$$\frac{d^2 z}{dt^2}$$

$$+ \omega_0^2 z = 0$$

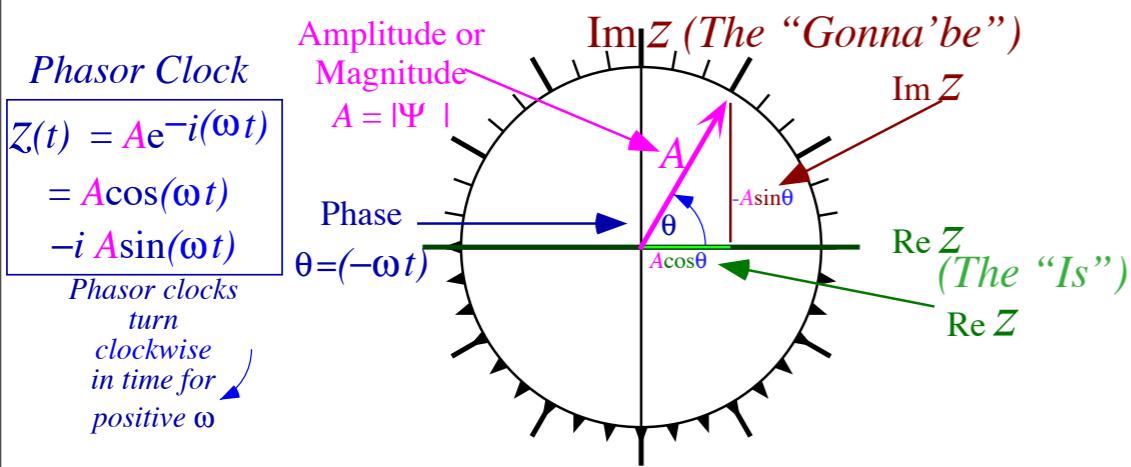
Coordinate $z=z(t)$ is the response coordinate
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held back by a harmonic (linear) restoring force $\rightarrow F_{restore} = -kz, \quad (k = \omega_0^2 m),$

Linear

harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{restore}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{restore}}{m}$$

$$+ \omega_0^2 z = 0$$

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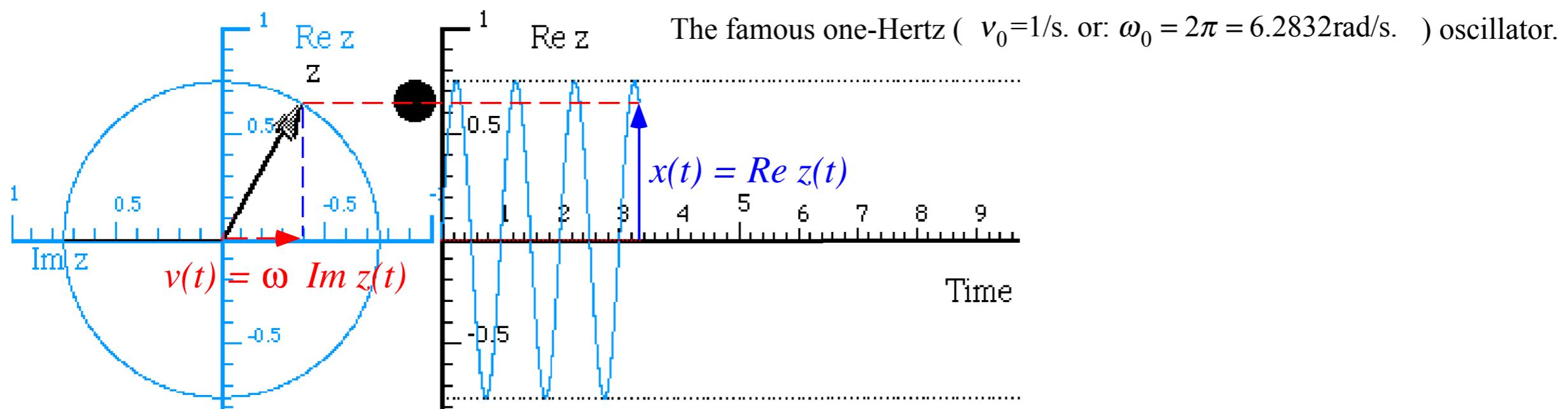
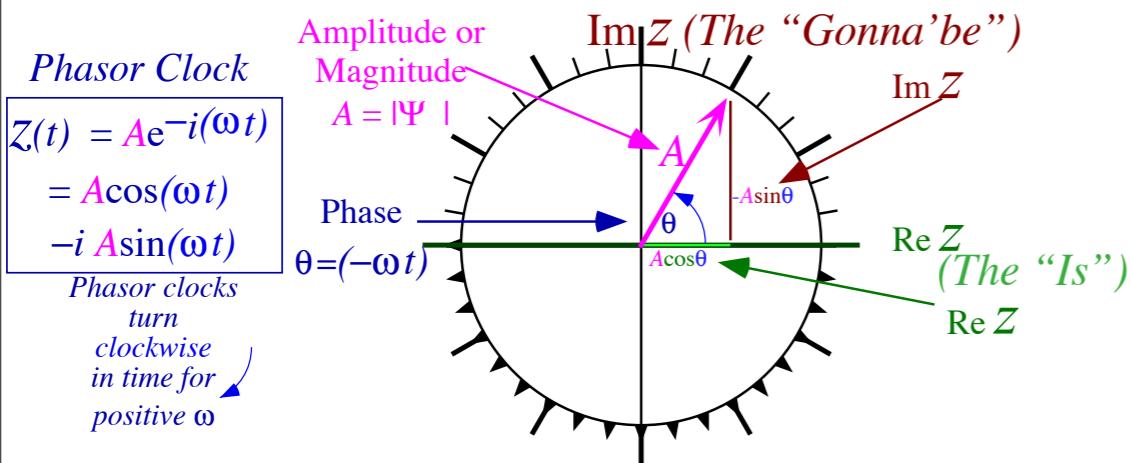


Fig. 3.2.2 Phasor z and corresponding coordinate versus time plot for $\omega_0 = 2\pi$ and $\Gamma = 0$

Linear damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m}$$

$$\frac{d^2 z}{dt^2} + 2\Gamma \frac{dz}{dt} + \omega_0^2 z = 0$$

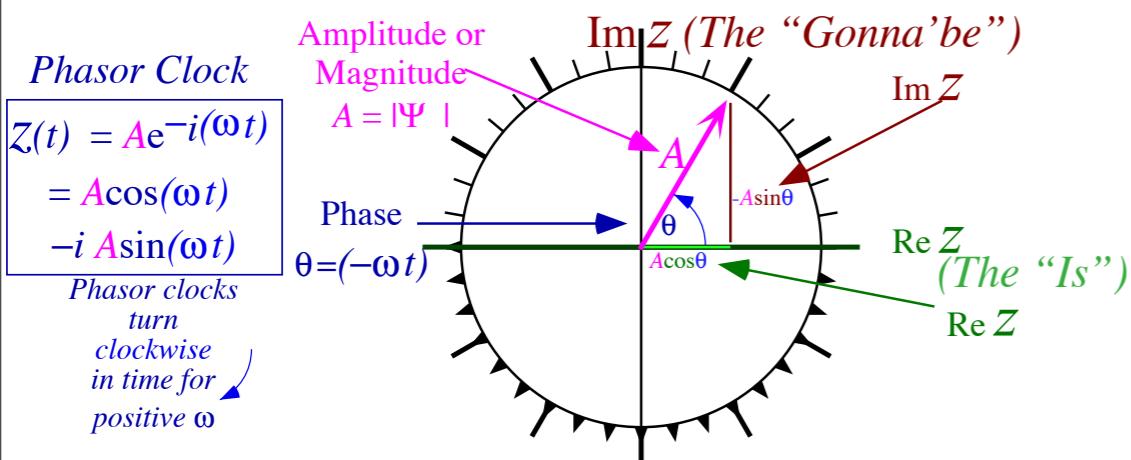
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retarded by frictional damping force $\rightarrow F_{damping} = -b \frac{dz}{dt}, \quad (b = 2\Gamma m)$

Linear damped-harmonic oscillator equation of motion.

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$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m}$$

Trick:
Set: $z = z(t) = A e^{-i\omega t}$

$$\frac{d^2 z}{dt^2} + 2\Gamma \frac{dz}{dt} + \omega_0^2 z = 0$$

$$[(-i\omega)^2 + 2\Gamma(-i\omega) + \omega_0^2] e^{-i\omega t} = 0$$

$$\omega^2 + 2i\Gamma\omega - \omega_0^2 = 0$$

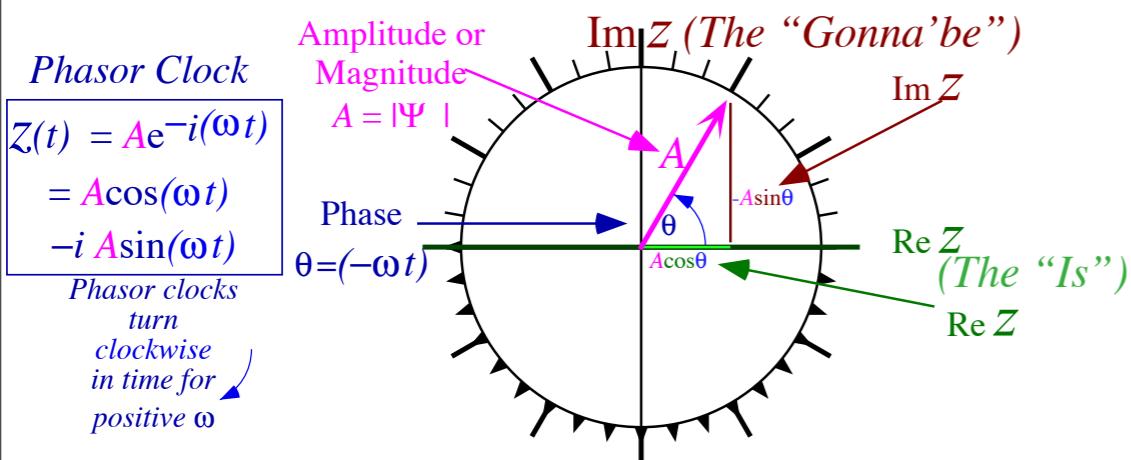
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$$[(-i\omega)^2 + 2\Gamma(-i\omega) + \omega_0^2] e^{-i\omega t} = 0$$

$$\omega^2 + 2i\Gamma\omega - \omega_0^2 = 0$$

Solve for: $\omega = \omega_{\pm}$

$$\omega_{\pm} = \frac{-2i\Gamma \pm \sqrt{-4\Gamma^2 + 4\omega_0^2}}{2}$$

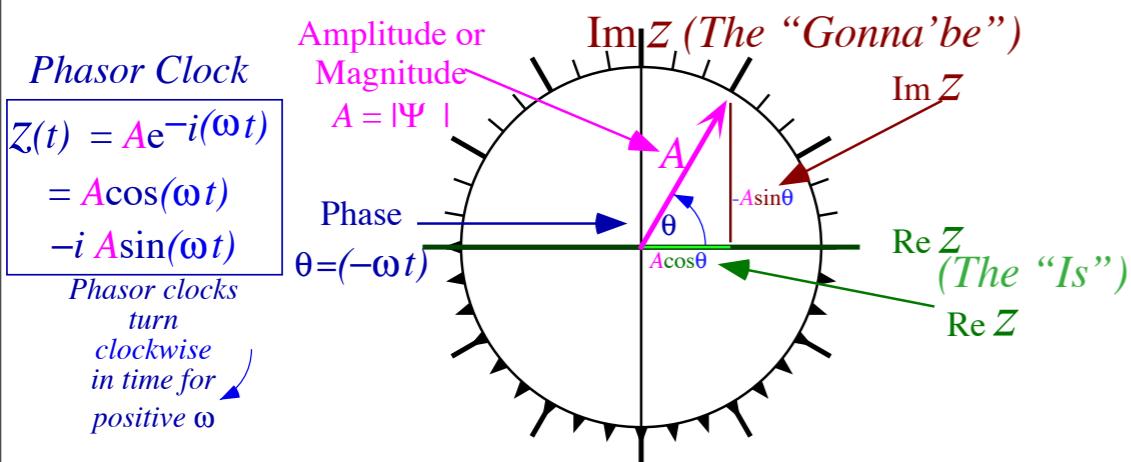
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$$= -i\Gamma \pm \sqrt{\omega_0^2 - \Gamma^2}$$

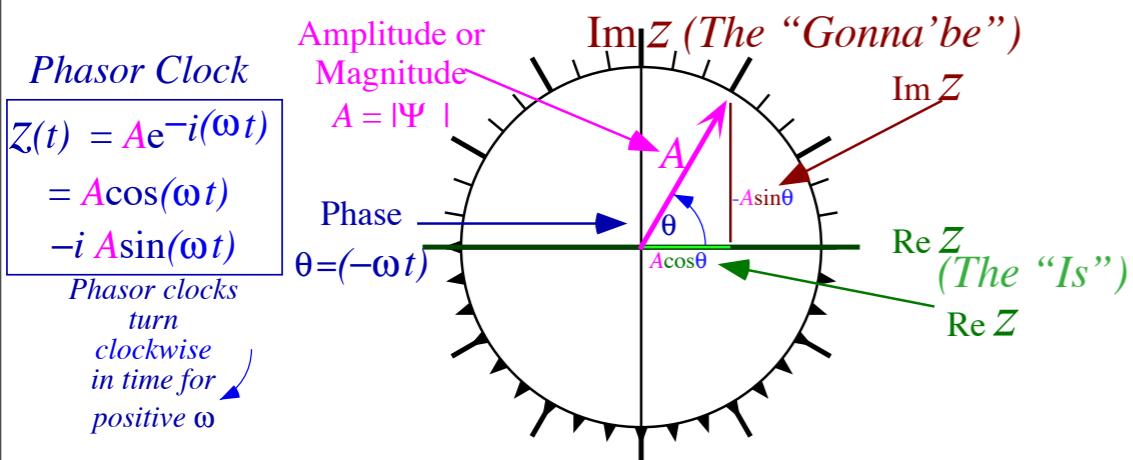
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Solve for: $\omega = \omega_{\pm}$

$$\omega_{\pm} = \frac{-2i\Gamma \pm \sqrt{-4\Gamma^2 + 4\omega_0^2}}{2}$$

$$= -i\Gamma \pm \sqrt{\omega_0^2 - \Gamma^2}$$

Solution:

$$z(t) = e^{-i\left(-i\Gamma \pm \sqrt{\omega_0^2 - \Gamma^2}\right)t}$$

$$= e^{\left(-\Gamma \pm i\sqrt{\omega_0^2 - \Gamma^2}\right)t}$$

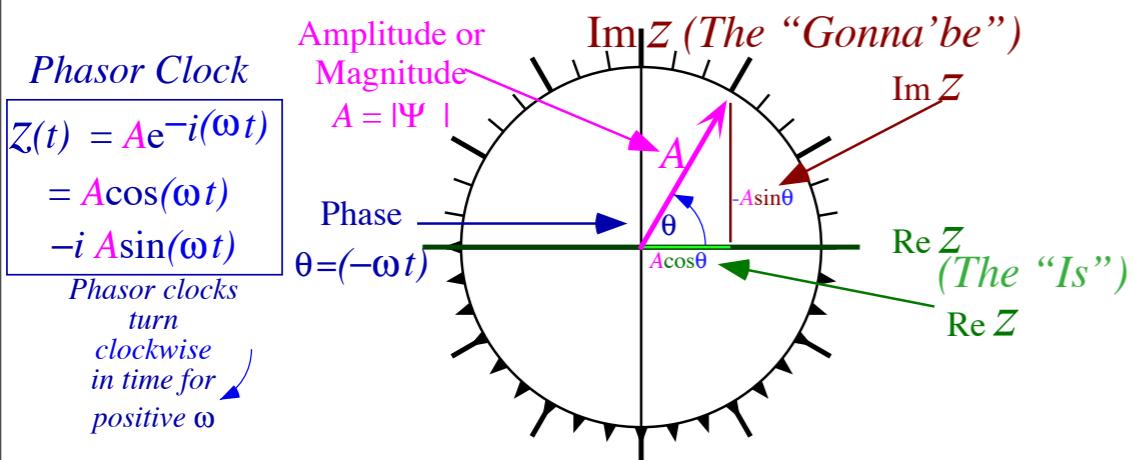
$$= e^{-\Gamma t} e^{\pm i\sqrt{\omega_0^2 - \Gamma^2}t}$$

Coordinate $z = z(t)$ is the response coordinate
for a particle of mass m and charge e

held back by a harmonic (linear) restoring force $\rightarrow F_{restore} = -kz$
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Linear damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m}$$

Trick:
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$$\frac{d^2 z}{dt^2} + 2\Gamma \frac{dz}{dt} + \omega_0^2 z = 0$$

$$[(-i\omega)^2 + 2\Gamma(-i\omega) + \omega_0^2] e^{-i\omega t} = 0$$

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Solve for: $\omega = \omega_{\pm}$

$$\omega_{\pm} = \frac{-2i\Gamma \pm \sqrt{-4\Gamma^2 + 4\omega_0^2}}{2}$$

$$= -i\Gamma \pm \sqrt{\omega_0^2 - \Gamma^2}$$

Solution:

$$z(t) = e^{-i\left(-i\Gamma \pm \sqrt{\omega_0^2 - \Gamma^2}\right)t}$$

$$= e^{\left(-\Gamma \pm i\sqrt{\omega_0^2 - \Gamma^2}\right)t}$$

$$= e^{-\Gamma t} e^{\pm i\sqrt{\omega_0^2 - \Gamma^2}t}$$

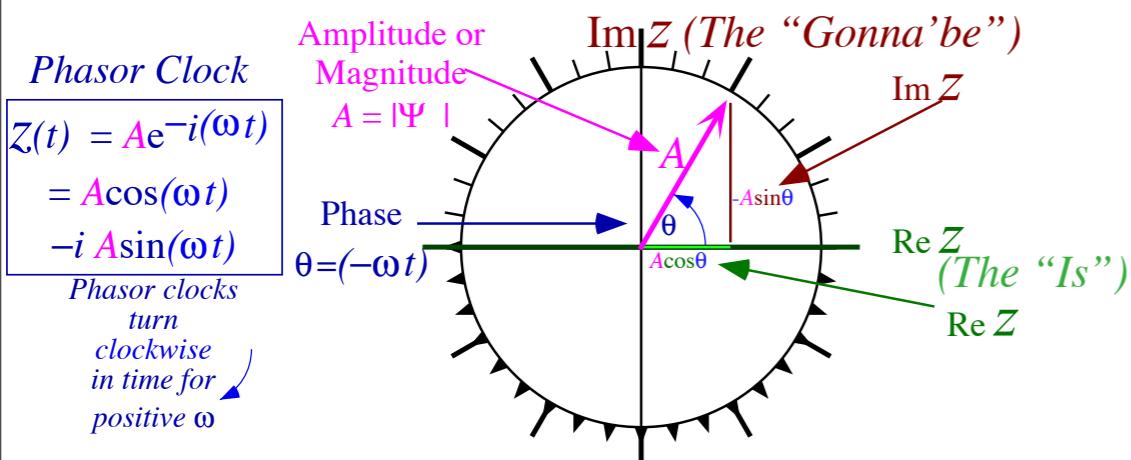
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Coordinate $z = z(t)$ is the response coordinate for a particle of mass m and charge e

held back by a harmonic (linear) restoring force $\rightarrow F_{restore} = -kz$
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Linear damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore}$$



Coordinate $z=z(t)$ is the response coordinate for a particle of mass m and charge e

$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m}$$

Trick:
Set: $z=z(t)=Ae^{-i\omega t}$

$$\frac{d^2 z}{dt^2} + 2\Gamma \frac{dz}{dt} + \omega_0^2 z = 0$$

$$[(-i\omega)^2 + 2\Gamma(-i\omega) + \omega_0^2]e^{-i\omega t} = 0$$

$$\omega^2 + 2i\Gamma\omega - \omega_0^2 = 0$$

Solve for: $\omega = \omega_{\pm}$

$$\omega_{\pm} = \frac{-2i\Gamma \pm \sqrt{-4\Gamma^2 + 4\omega_0^2}}{2}$$

$$= -i\Gamma \pm \sqrt{\omega_0^2 - \Gamma^2}$$

Solution:

$$z(t) = e^{-i(-i\Gamma \pm \sqrt{\omega_0^2 - \Gamma^2})t}$$

$$= e^{(-\Gamma \pm i\sqrt{\omega_0^2 - \Gamma^2})t}$$

$$= e^{-\Gamma t} e^{\pm i\sqrt{\omega_0^2 - \Gamma^2}t}$$

$$= e^{-\Gamma t} e^{\pm i\omega \Gamma t}$$

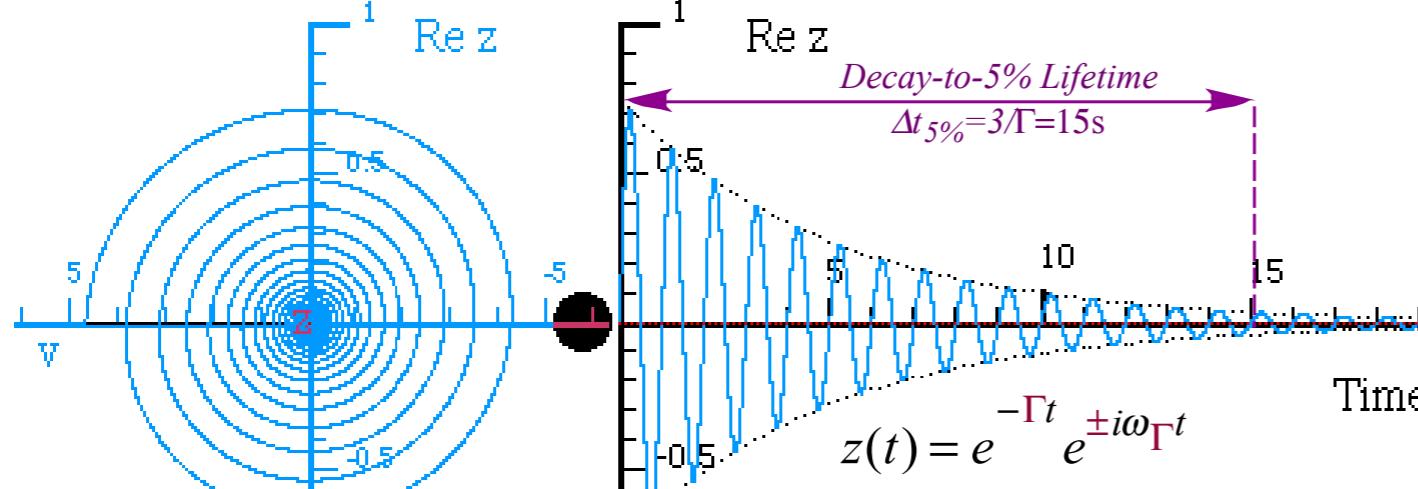
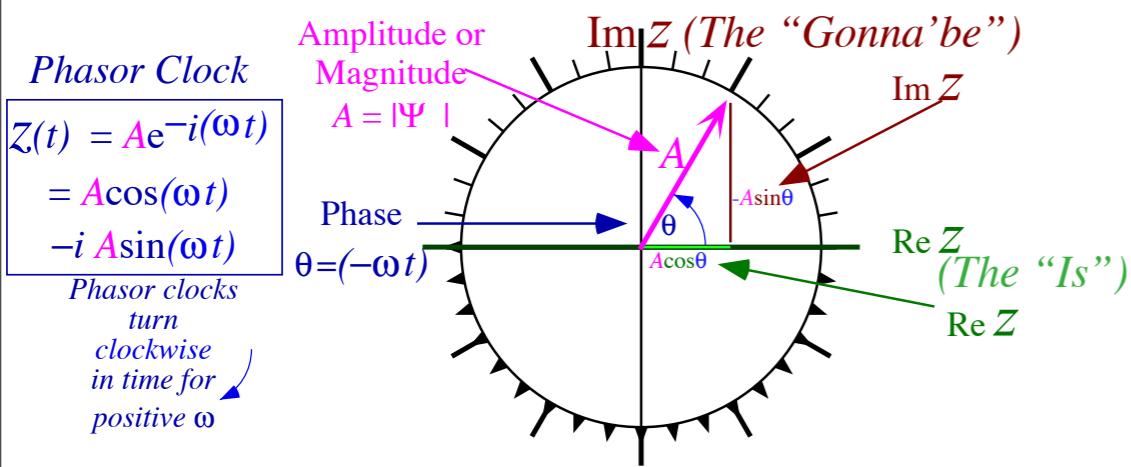


Fig. 3.2.3 Phasor z and corresponding coordinate versus time plot for $\omega_0=2\pi$ and $\Gamma=0.2$

Linear damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m}$$

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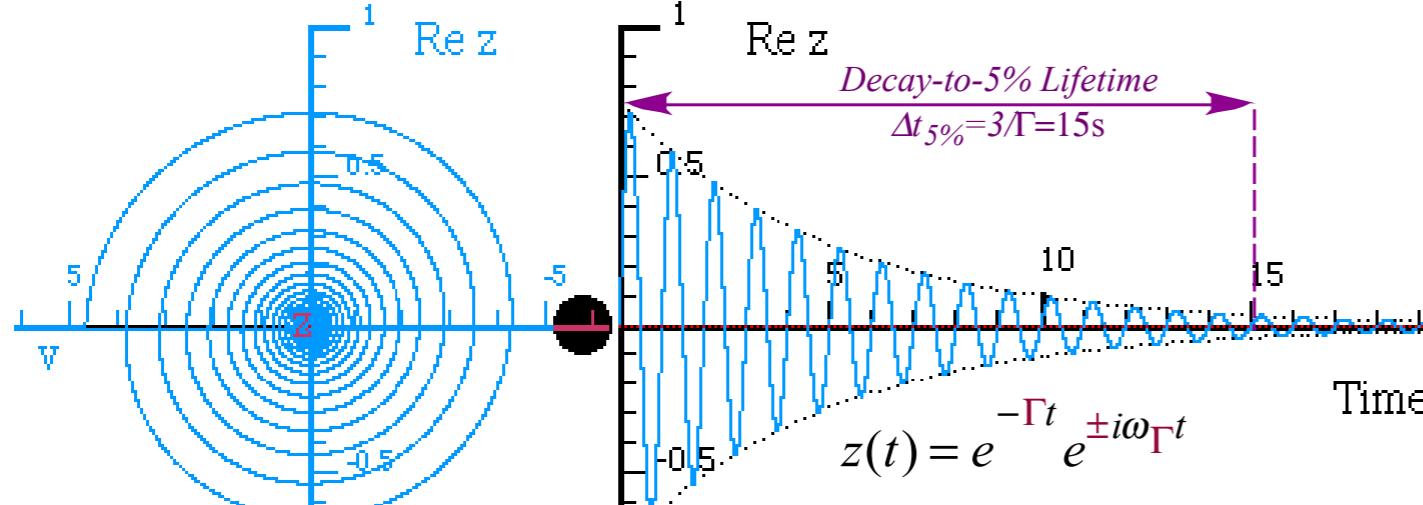
Coordinate $z=z(t)$ is the response coordinate for a particle of mass m and charge e

held back by a harmonic (linear) restoring force $\rightarrow F_{restore} = -kz$

retarded by frictional damping force $\rightarrow F_{damping} = -b \frac{dz}{dt}$

Oscillator Figures of Merit:

Time required to reduce amplitude to 5%



Easy-to-recall 5% approximation:

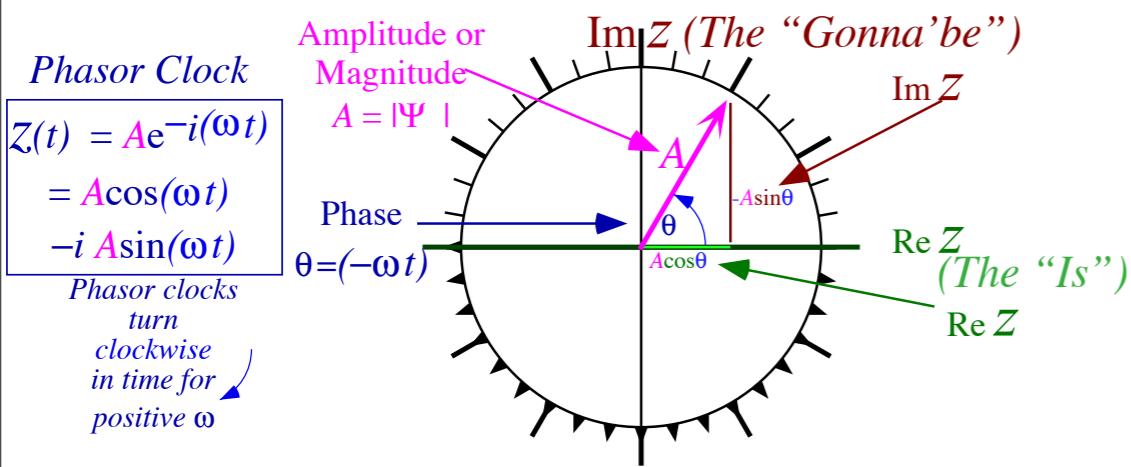
$$e^{-3} \approx 0.05$$

$$t_{5\%} = \frac{3}{\Gamma} = \frac{3}{0.2} = 15$$

Fig. 3.2.3 Phasor z and corresponding coordinate versus time plot for $\omega_0=2\pi$ and $\Gamma=0.2$

Linear damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m}$$

$$\frac{d^2 z}{dt^2} + 2\Gamma \frac{dz}{dt} + \omega_0^2 z = 0$$

Coordinate $z=z(t)$ is the response coordinate for a particle of mass m and charge e

held back by a harmonic (linear) restoring force

$$F_{restore} = -kz$$

retarded by frictional damping force

$$F_{damping} = -b \frac{dz}{dt}$$

Oscillator Figures of Merit:

Time required to reduce amplitude to 5% (or 4.321%)

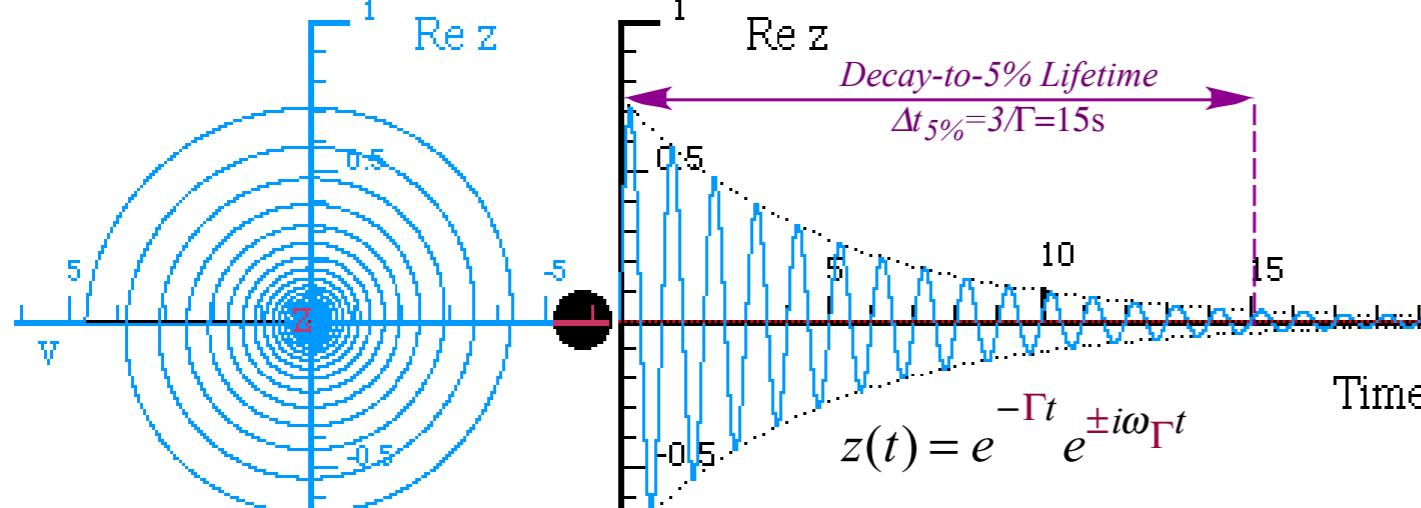


Fig. 3.2.3 Phasor z and corresponding coordinate versus time plot for $\omega_0=2\pi$ and $\Gamma=0.2$

Easy-to-recall 5% approximation: More precise one:

$$e^{-3} \approx 0.05$$

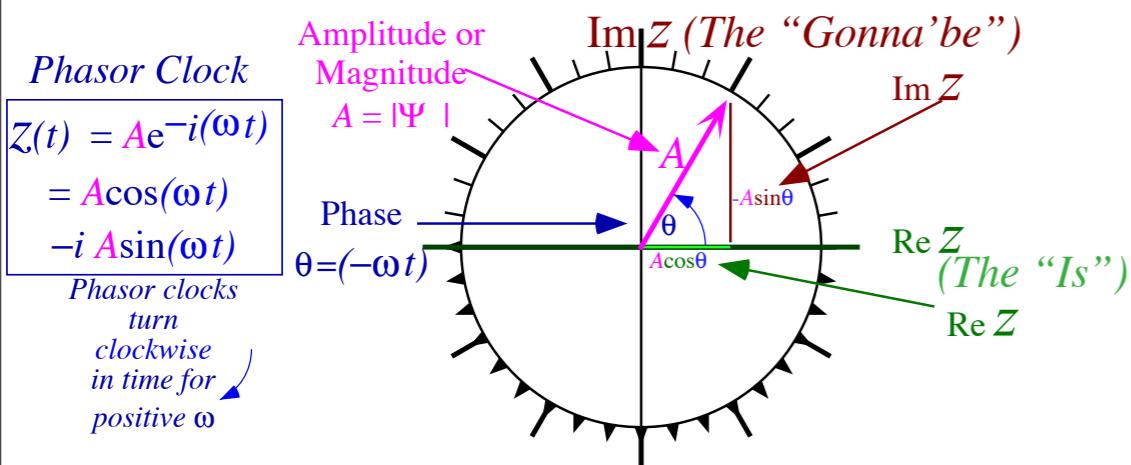
$$e^{-\pi} \approx 0.04321$$

$$t_{5\%} = \frac{3}{\Gamma} = \frac{3}{0.2} = 15$$

$$t_{4.321\%} = \frac{\pi}{\Gamma} = \frac{\pi}{0.2} = 15.708$$

Linear damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m}$$

$$\frac{d^2 z}{dt^2} + 2\Gamma \frac{dz}{dt} + \omega_0^2 z = 0$$

Coordinate $z=z(t)$ is the response coordinate for a particle of mass m and charge e

held back by a harmonic (linear) restoring force $\rightarrow F_{restore} = -kz$

retarded by frictional damping force $\rightarrow F_{damping} = -b \frac{dz}{dt}$

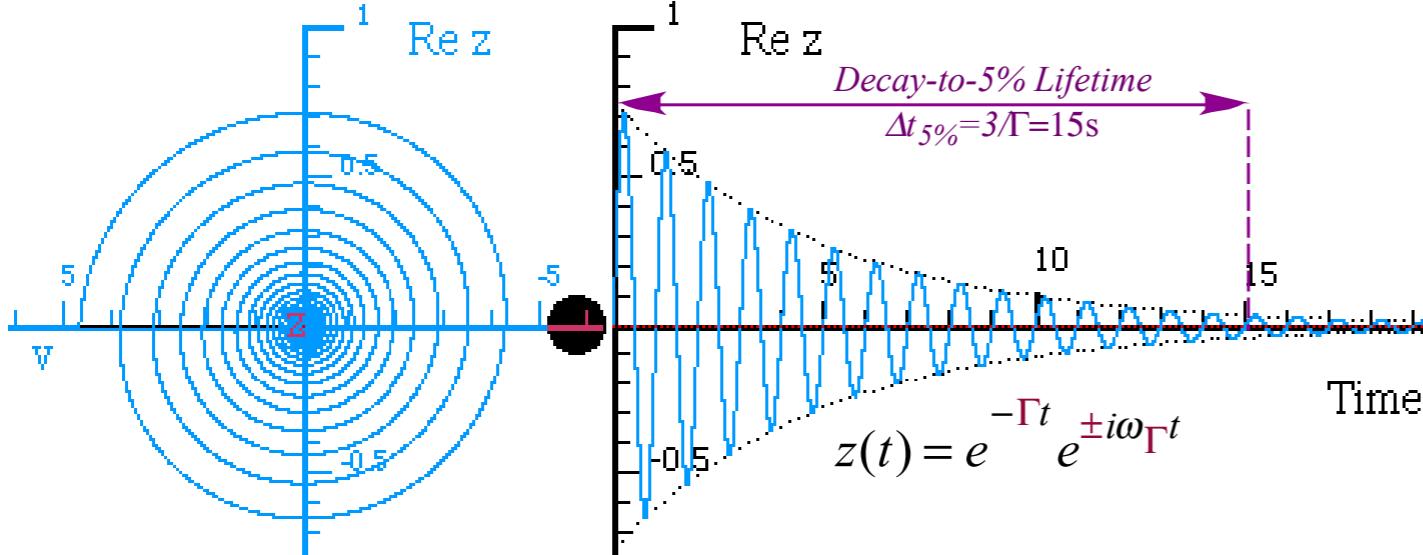


Fig. 3.2.3 Phasor z and corresponding coordinate versus time plot for $\omega_0=2\pi$ and $\Gamma=0.2$

Oscillator Figures of Merit:

Number N of oscillations to reduce amplitude to 5% (or 4.321%)

Easy-to-recall 5% approximation: More precise one:

$$e^{-3} \approx 0.05$$

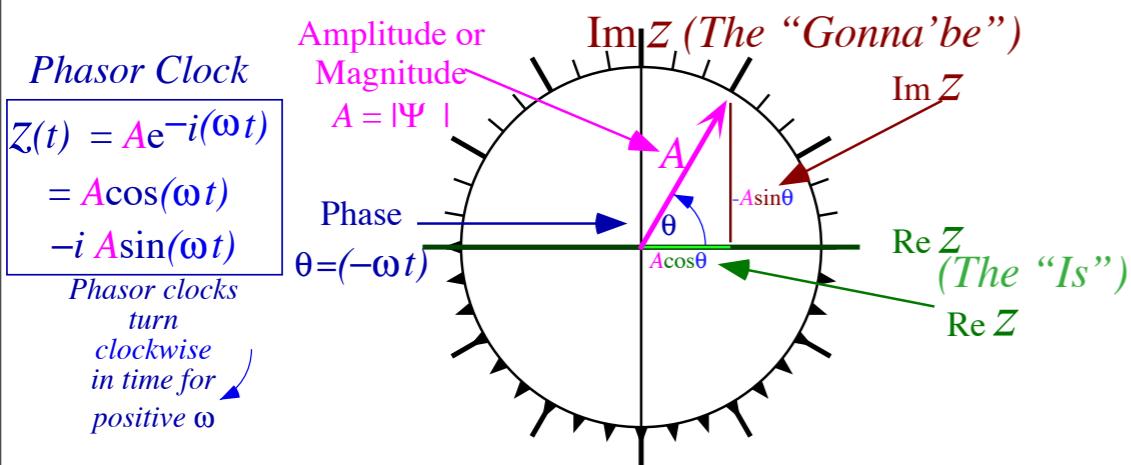
$$e^{-\pi} \approx 0.04321$$

$$N_{5\%} = \frac{\omega_\Gamma \cdot t_{5\%}}{2\pi} = \frac{3\omega_\Gamma}{2\pi\Gamma} \sim \frac{\omega_\Gamma}{2\Gamma}$$

$$t_{4.321\%} = \frac{\pi}{\Gamma} = \frac{\pi}{0.2} = 15.708$$

Linear forced-damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore} + F_{stimulus}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m} + \frac{F_{stimulus}}{m}$$

Stimulating acceleration
 $a_{stimulus} = a(t)$ due to
 stimulating force $F_{stimulus}(t)$
 (Typically **E**-field)

$$= \frac{e}{m} E(t)$$

$$\frac{d^2 z}{dt^2} + 2\Gamma \frac{dz}{dt} + \omega_0^2 z = a_{stimulus}$$

Coordinate $z=z(t)$ is the response coordinate
 for a particle of mass m and charge e

driven by external **stimulating force**

$$\xrightarrow{\hspace{1cm}} F_{stimulus}(t) = eE(t)$$

held back by a **harmonic (linear) restoring force**

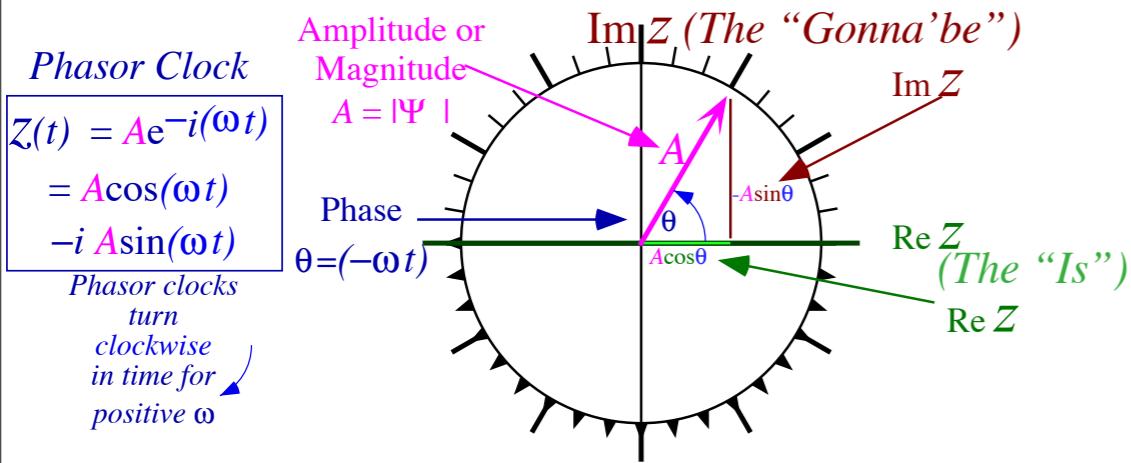
$$\xrightarrow{\hspace{1cm}} F_{restore} = -kz, \quad (k = \omega_0^2 m),$$

retarded by **frictional damping force**

$$\xrightarrow{\hspace{1cm}} F_{damping} = -b \frac{dz}{dt}, \quad (b = 2\Gamma m)$$

Linear forced-damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore} + F_{stimulus}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m} + \frac{F_{stimulus}}{m}$$

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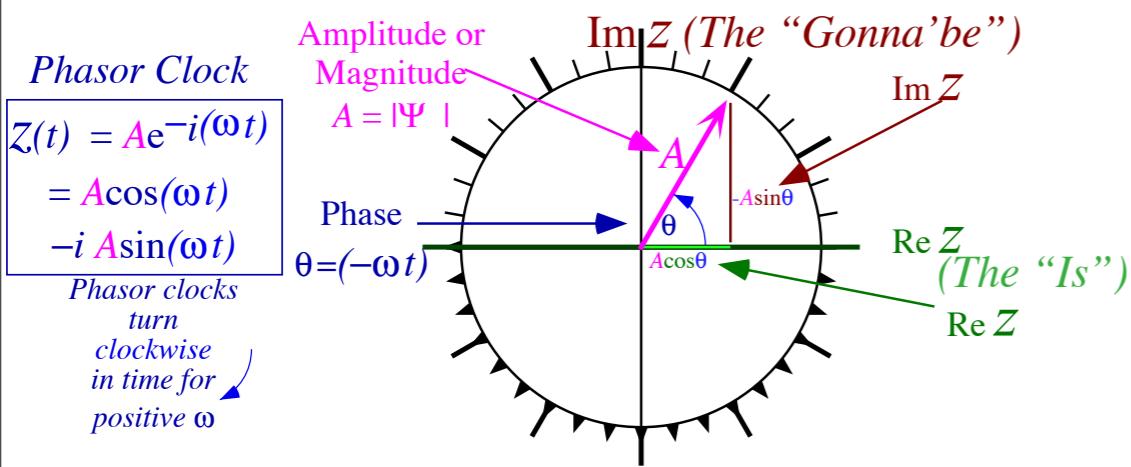
$$\frac{d^2 z}{dt^2} + 2\Gamma \frac{dz}{dt} + \omega_0^2 z = a_{stimulus}$$

$$= \frac{e}{m} E(t)$$

Solving for $z_{stimulus}(t)$ given $a_{stimulus}$:

Linear forced-damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore} + F_{stimulus}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m} + \frac{F_{stimulus}}{m}$$

Stimulating acceleration
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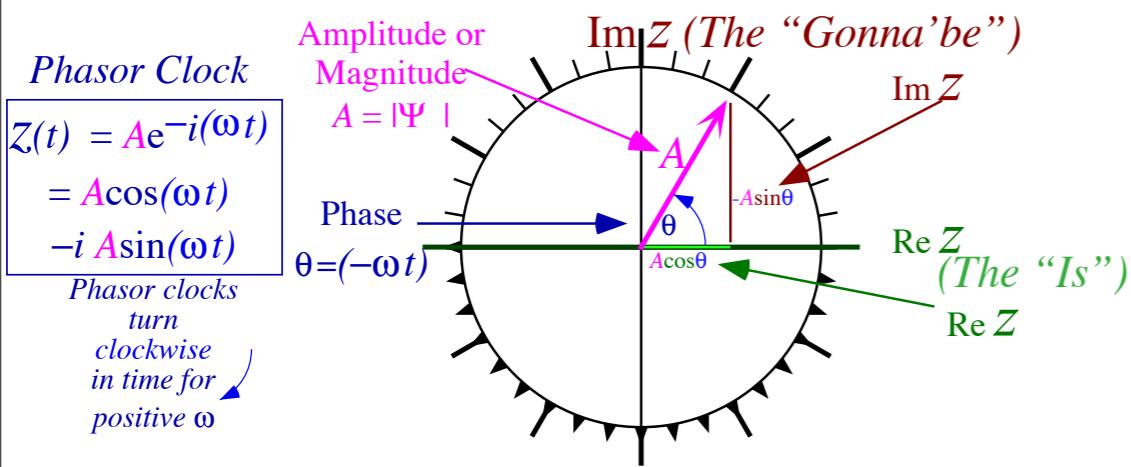
$$\left(\frac{d^2}{dt^2} + 2\Gamma \frac{d}{dt} + \omega_0^2 \right) z = a_{stimulus}$$

$$z = \frac{1}{\frac{d^2}{dt^2} + 2\Gamma \frac{d}{dt} + \omega_0^2} a_{stimulus}$$

Solving for $z_{stimulus}(t)$ given $a_{stimulus}$:

Linear forced-damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore} + F_{stimulus}$$



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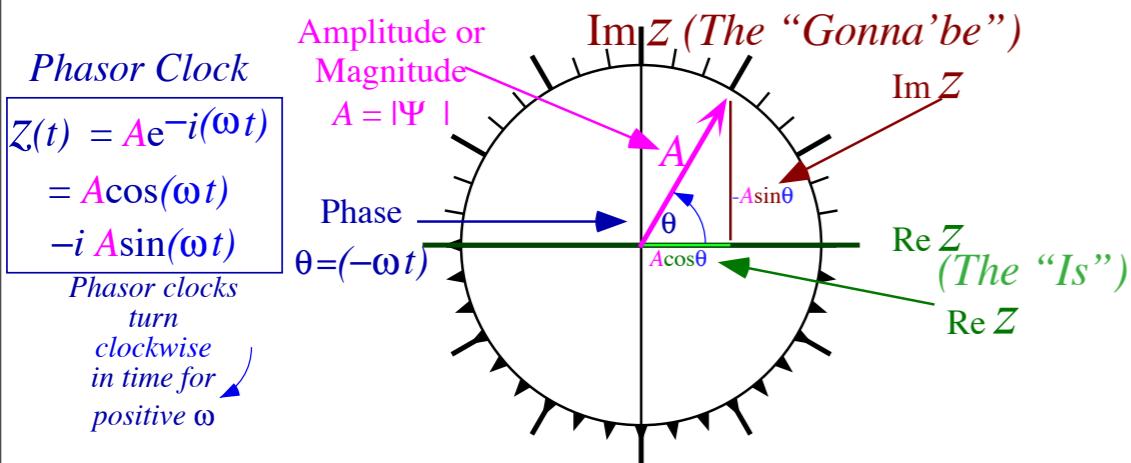
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$$z = \frac{1}{\frac{d^2}{dt^2} + 2\Gamma \frac{d}{dt} + \omega_0^2} a_{stimulus}$$

Pretty crazy?

Linear forced-damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore} + F_{stimulus}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m} + \frac{F_{stimulus}}{m}$$

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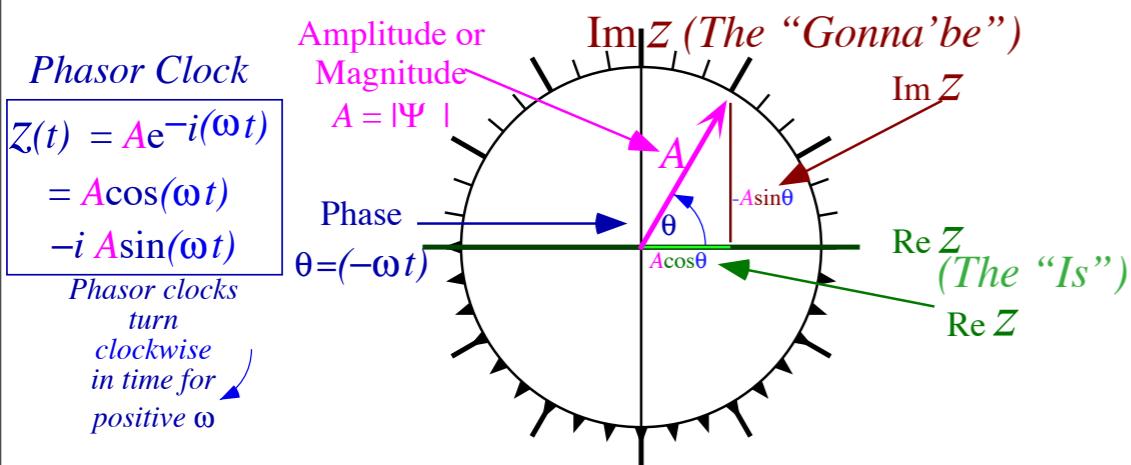
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$$z = \frac{1}{\frac{d^2}{dt^2} + 2\Gamma \frac{d}{dt} + \omega_0^2} a_{stimulus}$$

Pretty crazy? But not so crazy if
 $a_{stimulus}(t) = |a_{stimulus}| e^{-i\omega_{stimulus}t} = |a_s| e^{-i\omega_s t}$

Linear forced-damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore} + F_{stimulus}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m} + \frac{F_{stimulus}}{m}$$

Stimulating acceleration
 $a_{stimulus} = a(t)$ due to
 stimulating force $F_{stimulus}(t)$
 (Typically **E**-field)

$$= \frac{e}{m} E(t)$$

$$\left(\frac{d^2}{dt^2} + 2\Gamma \frac{d}{dt} + \omega_0^2 \right) z = a_{stimulus}$$

$$z_{stimulus} = \frac{1}{-\omega_s^2 - i2\Gamma\omega_s + \omega_0^2} a_s e^{-i\omega_s t}$$

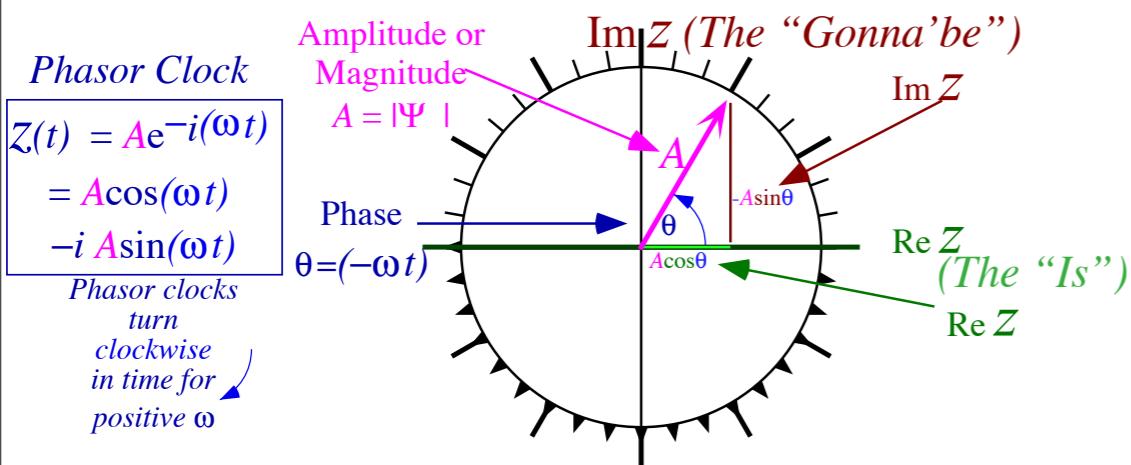
$$z_s e^{-i\omega_s t} = \frac{1}{\omega_0^2 - \omega_s^2 - i2\Gamma\omega_s} a_s e^{-i\omega_s t}$$

Solving for $z_{stimulus}(t)$ given $a_{stimulus}$:

Pretty crazy? But not so crazy if
 $a_{stimulus}(t) = |a_{stimulus}| e^{-i\omega_{stimulus} t} = |a_s| e^{-i\omega_s t}$

Linear forced-damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore} + F_{stimulus}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m} + \frac{F_{stimulus}}{m}$$

Stimulating acceleration
 $a_{stimulus} = a(t)$ due to
 stimulating force $F_{stimulus}(t)$
 (Typically **E**-field)

$$= \frac{e}{m} E(t)$$

$$\frac{d^2 z}{dt^2} + 2\Gamma \frac{dz}{dt} + \omega_0^2 z = a_{stimulus}$$

$$\left(\frac{d^2}{dt^2} + 2\Gamma \frac{d}{dt} + \omega_0^2 \right) z = a_{stimulus}$$

$$z_{stimulus} = \frac{1}{-\omega_s^2 - i2\Gamma\omega_s + \omega_0^2} a_s e^{-i\omega_s t}$$

$$z_s e^{-i\omega_s t} = \frac{1}{\omega_0^2 - \omega_s^2 - i2\Gamma\omega_s} a_s e^{-i\omega_s t}$$

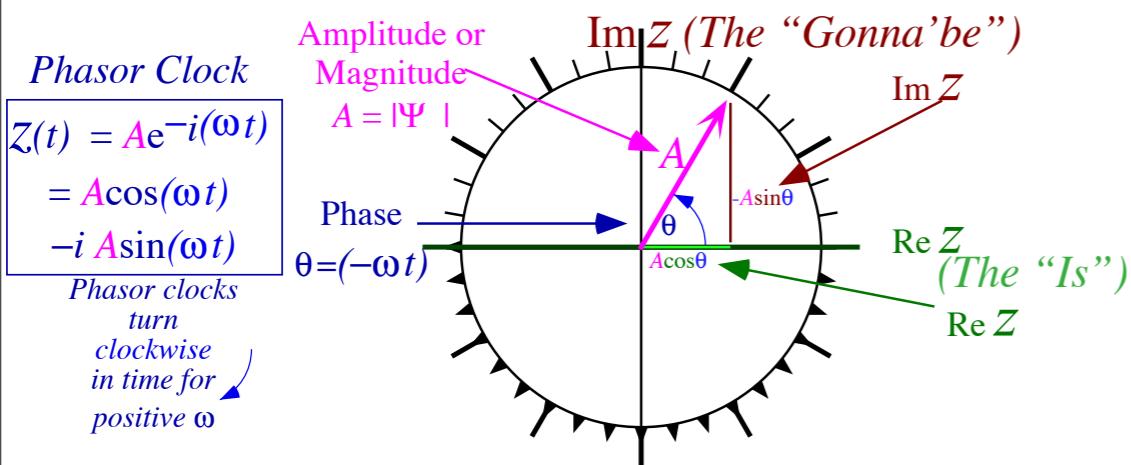
$$z_s = G_{\omega_0}(\omega_s) \cdot a_s$$

Solving for $z_{stimulus}(t)$ given $a_{stimulus}$:

Pretty crazy? But not so crazy if
 $a_{stimulus}(t) = |a_{stimulus}| e^{-i\omega_{stimulus} t} = |a_s| e^{-i\omega_s t}$

Linear forced-damped-harmonic oscillator equation of motion.

$$F_{total}(t) = m \frac{d^2 z}{dt^2} = F_{damping} + F_{restore} + F_{stimulus}$$



$$\frac{d^2 z}{dt^2} = \frac{F_{damping}}{m} + \frac{F_{restore}}{m} + \frac{F_{stimulus}}{m}$$

Stimulating acceleration
 $a_{stimulus} = a(t)$ due to
 stimulating force $F_{stimulus}(t)$
 (Typically **E**-field)

$$\frac{d^2 z}{dt^2} + 2\Gamma \frac{dz}{dt} + \omega_0^2 z = a_{stimulus}$$

$$= \frac{e}{m} E(t)$$

$$\left(\frac{d^2}{dt^2} + 2\Gamma \frac{d}{dt} + \omega_0^2 \right) z = a_{stimulus}$$

$$z_{stimulus} = \frac{1}{-\omega_s^2 - i2\Gamma\omega_s + \omega_0^2} a_s e^{-i\omega_s t}$$

$$z_s e^{-i\omega_s t} = \boxed{\frac{1}{\omega_0^2 - \omega_s^2 - i2\Gamma\omega_s}}$$

$$z_s = G_{\omega_0}(\omega_s) \cdot a_s$$

Green's Function for the F-D-H Oscillator (FDHO)

George Green (14 July 1793 – 31 May 1841)

Green's Function for the FDHO (Forced-Damped-Harmonic Oscillator)

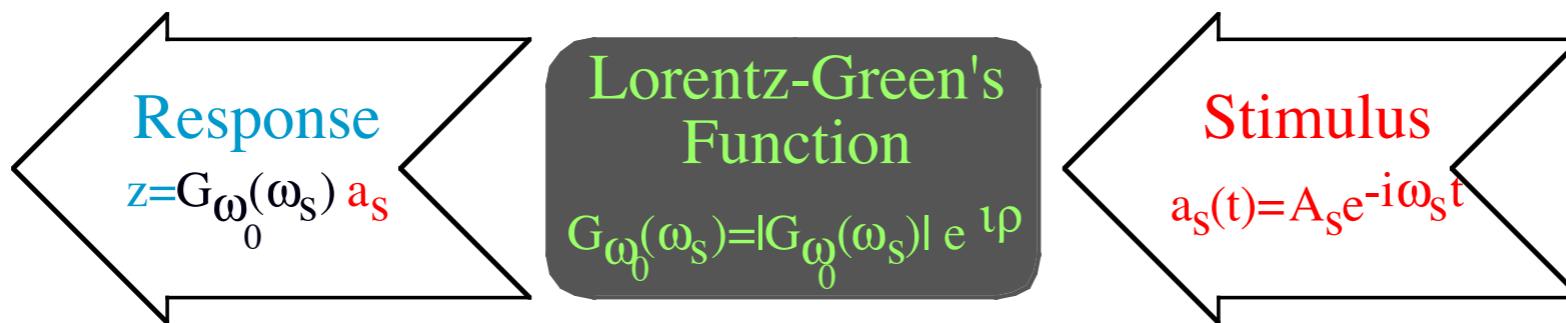


Fig. 3.2.4 Black-box diagram of oscillator response to monochromatic stimulus

$$G_{\omega_0}(\omega_s) = \frac{1}{\omega_0^2 - \omega_s^2 - i2\Gamma\omega_s} = \operatorname{Re} G_{\omega_0}(\omega_s) + i \operatorname{Im} G_{\omega_0}(\omega_s)$$

Real and imaginary parts of the *rectangular form* of G :

Green's Function for the FDHO (Forced-Damped-Harmonic Oscillator)

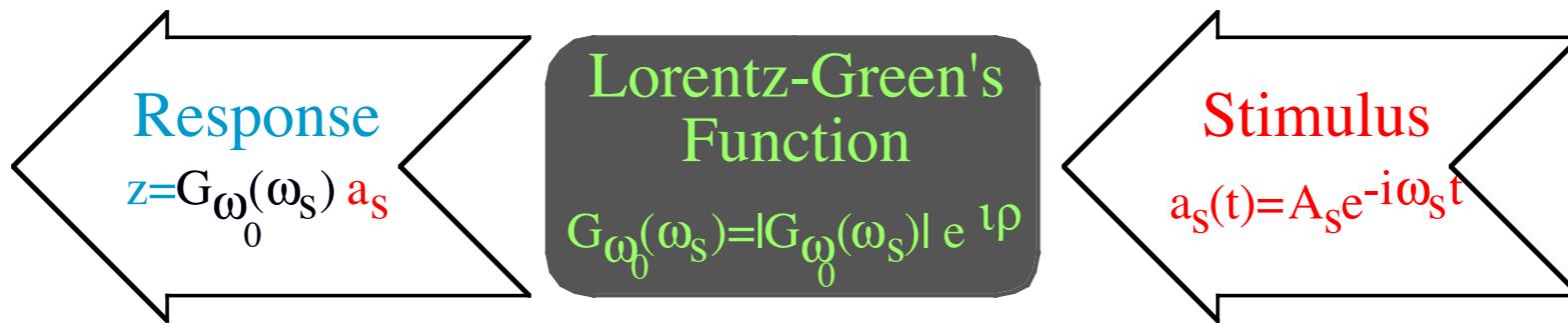


Fig. 3.2.4 Black-box diagram of oscillator response to monochromatic stimulus

$$G_{\omega_0}(\omega_s) = \frac{1}{\omega_0^2 - \omega_s^2 - i2\Gamma\omega_s} = \operatorname{Re} G_{\omega_0}(\omega_s) + i \operatorname{Im} G_{\omega_0}(\omega_s)$$

Real and imaginary parts of the *rectangular form* of G :

$$\frac{1}{x - iy} = \frac{1}{x - iy} \frac{x + iy}{x + iy} = \frac{x + iy}{x^2 + y^2}$$

Green's Function for the FDHO (Forced-Damped-Harmonic Oscillator)

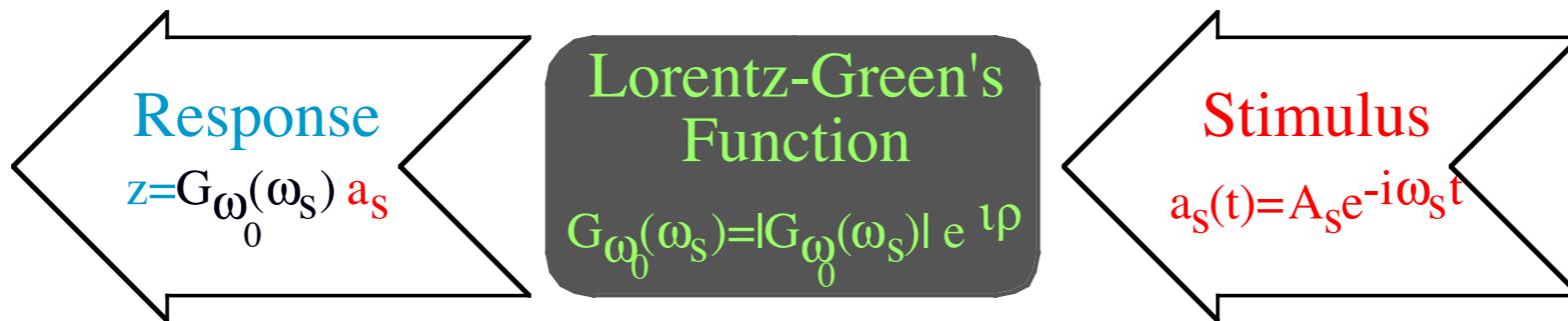


Fig. 3.2.4 Black-box diagram of oscillator response to monochromatic stimulus

$$G_{\omega_0}(\omega_s) = \frac{1}{\omega_0^2 - \omega_s^2 - i2\Gamma\omega_s} = \operatorname{Re} G_{\omega_0}(\omega_s) + i \operatorname{Im} G_{\omega_0}(\omega_s)$$

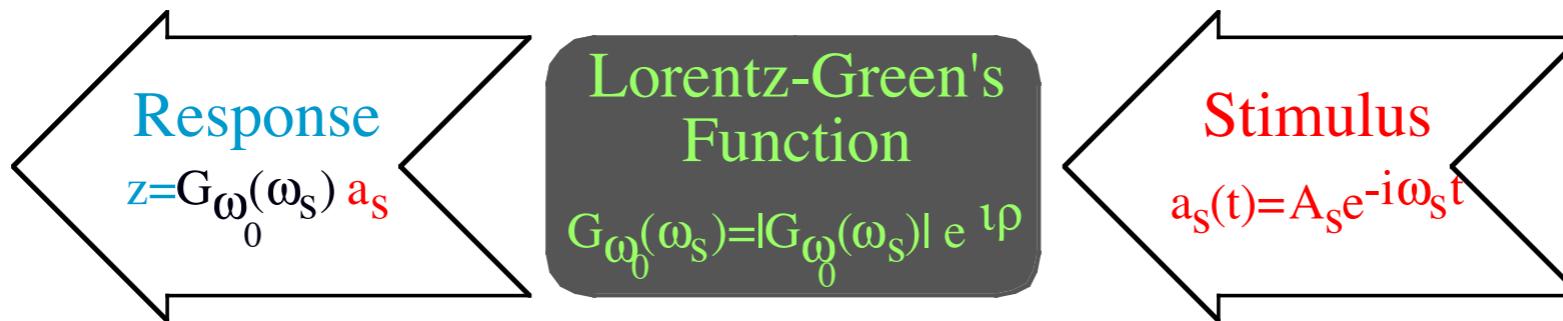
Real and imaginary parts of the *rectangular form* of G :

$$\frac{1}{x - iy} = \frac{1}{x - iy} \frac{x + iy}{x + iy} = \frac{x + iy}{x^2 + y^2} = \frac{x}{x^2 + y^2} + i \frac{y}{x^2 + y^2}$$

$$\operatorname{Re} G_{\omega_0}(\omega_s) = \frac{\omega_0^2 - \omega_s^2}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

$$\operatorname{Im} G_{\omega_0}(\omega_s) = \frac{2\Gamma\omega_s}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

Green's Function for the FDHO (Forced-Damped-Harmonic Oscillator)



$$G_{\omega_0}(\omega_s) = \frac{1}{\omega_0^2 - \omega_s^2 - i2\Gamma\omega_s} = \operatorname{Re} G_{\omega_0}(\omega_s) + i \operatorname{Im} G_{\omega_0}(\omega_s) = |G_{\omega_0}(\omega_s)| e^{i\rho}$$

Real and imaginary parts of the *rectangular form* of G :

$$\operatorname{Re} G_{\omega_0}(\omega_s) = \frac{\omega_0^2 - \omega_s^2}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

$$\operatorname{Im} G_{\omega_0}(\omega_s) = \frac{2\Gamma\omega_s}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

Magnitude $|G_{\omega_0}(\omega_s)|$ and polar angle ρ of the *polar form* of G :

$$|G_{\omega_0}(\omega_s)| = \sqrt{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

$$\rho = \tan^{-1} \left(\frac{2\Gamma\omega_s}{\omega_0^2 - \omega_s^2} \right)$$

Green's Function for the FDHO (Forced-Damped-Harmonic Oscillator)

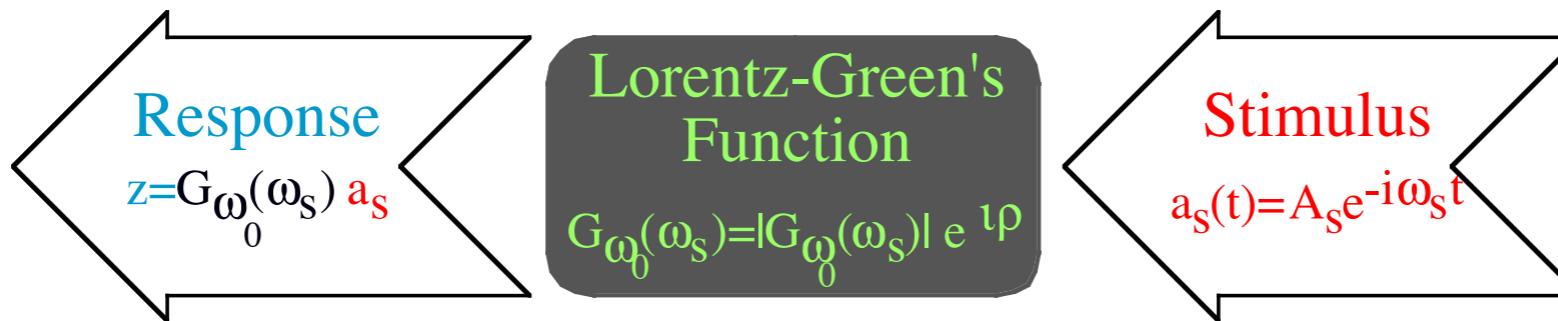


Fig. 3.2.4 Black-box diagram of oscillator response to monochromatic stimulus

$$G_{\omega_0}(\omega_s) = \frac{1}{\omega_0^2 - \omega_s^2 - i2\Gamma\omega_s} = \operatorname{Re} G_{\omega_0}(\omega_s) + i \operatorname{Im} G_{\omega_0}(\omega_s) = |G_{\omega_0}(\omega_s)| e^{i\rho}$$

Real and imaginary parts of the *rectangular form* of G :

$$\operatorname{Re} G_{\omega_0}(\omega_s) = \frac{\omega_0^2 - \omega_s^2}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

$$\operatorname{Im} G_{\omega_0}(\omega_s) = \frac{2\Gamma\omega_s}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

Magnitude $|G_{\omega_0}(\omega_s)|$ and *polar angle* ρ of the *polar form* of G :

$$|G_{\omega_0}(\omega_s)| = \frac{1}{\sqrt{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}}$$

$$\rho = \tan^{-1} \left(\frac{2\Gamma\omega_s}{\omega_0^2 - \omega_s^2} \right)$$

polar angle ρ is the
phase lag angle ρ

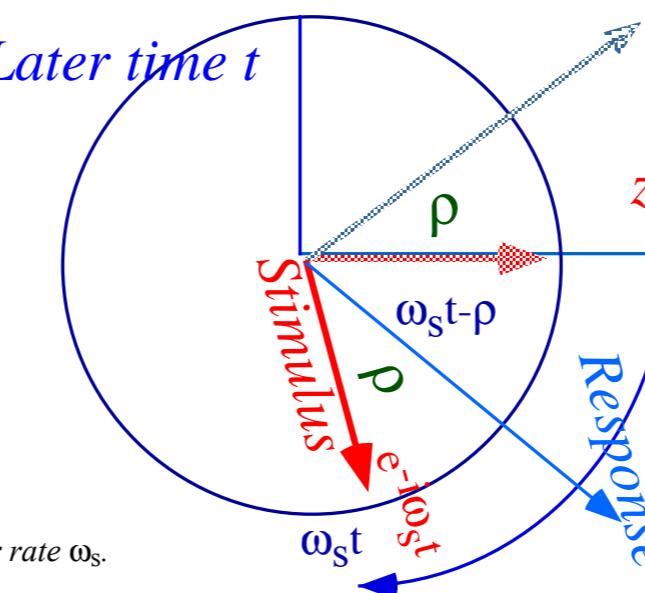
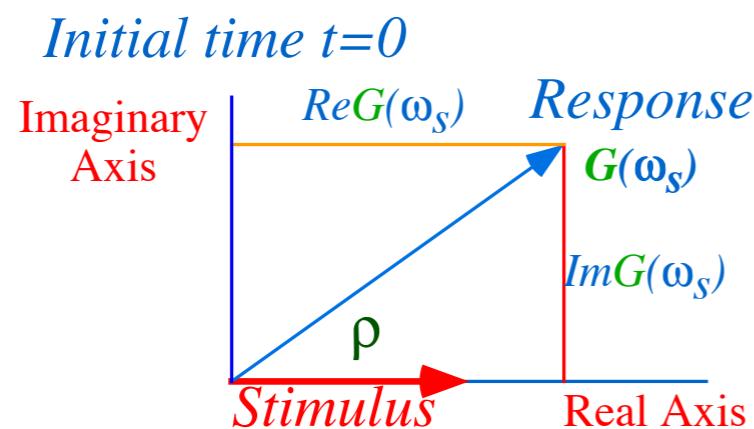


Fig. 3.2.5 Oscillator response and stimulus phasors rotate rigidly at angular rate ω_s .

Green's Function for the FDHO (Forced-Damped-Harmonic Oscillator)

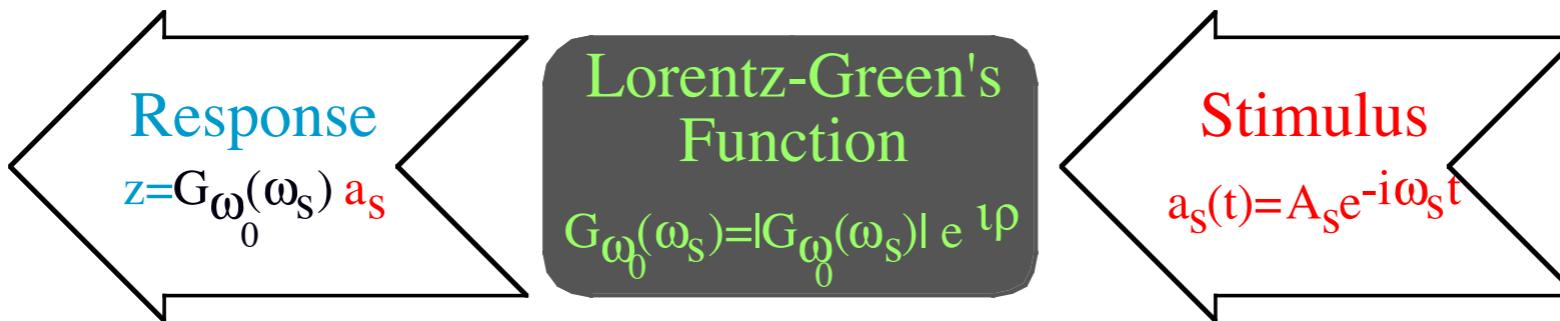


Fig. 3.2.4 Black-box diagram of oscillator response to monochromatic stimulus

$$G_{\omega_0}(\omega_s) = \frac{1}{\omega_0^2 - \omega_s^2 - i2\Gamma\omega_s} = \operatorname{Re} G_{\omega_0}(\omega_s) + i \operatorname{Im} G_{\omega_0}(\omega_s) = |G_{\omega_0}(\omega_s)| e^{i\rho}$$

Real and imaginary parts of the *rectangular form* of G :

$$\operatorname{Re} G_{\omega_0}(\omega_s) = \frac{\omega_0^2 - \omega_s^2}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

$$\operatorname{Im} G_{\omega_0}(\omega_s) = \frac{2\Gamma\omega_s}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

Magnitude $|G_{\omega_0}(\omega_s)|$ and *polar angle* ρ of the *polar form* of G :

$$|G_{\omega_0}(\omega_s)| = \sqrt{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

$$\rho = \tan^{-1} \left(\frac{2\Gamma\omega_s}{\omega_0^2 - \omega_s^2} \right)$$

polar angle ρ is the *phase lag angle* ρ

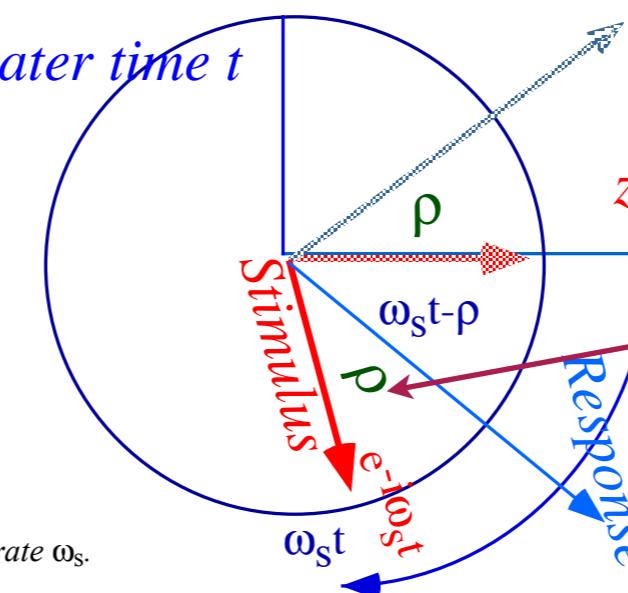
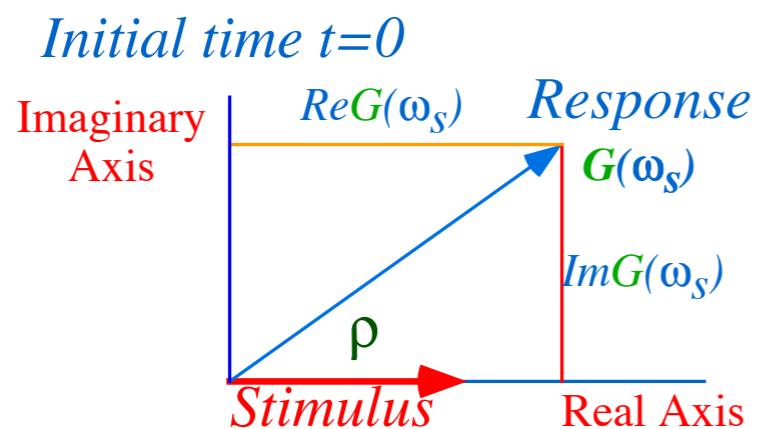


Fig. 3.2.5 Oscillator response and stimulus phasors rotate rigidly at angular rate ω_s .

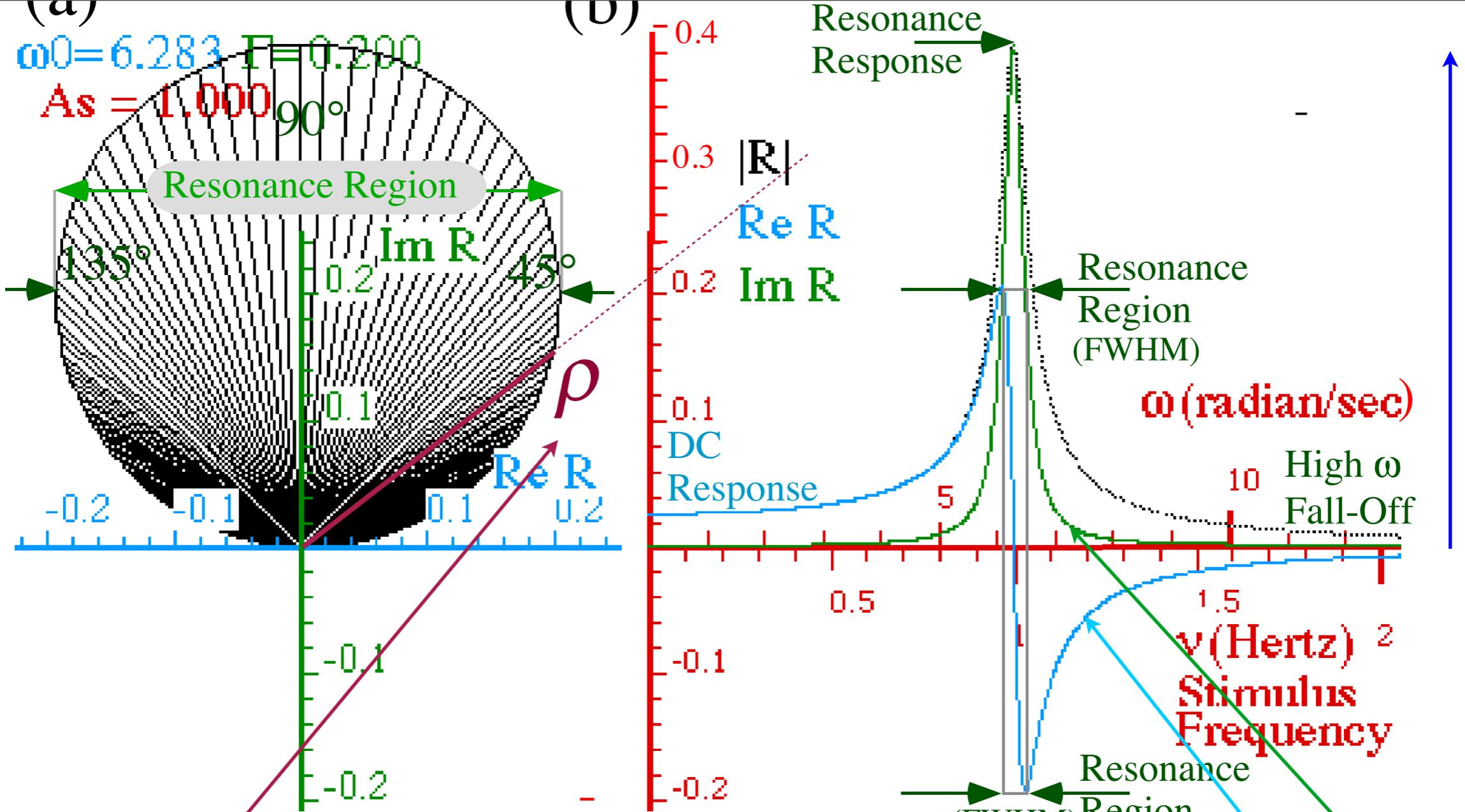


Fig. 3.2.6 Anatomy of oscillator Green-Lorentz response function plots

Phase lag angle

$$\rho = \tan^{-1} \left(\frac{2\Gamma\omega_s}{\omega_0^2 - \omega_s^2} \right)$$

$$\text{Real part}$$

$$\text{Imaginary part}$$

$$\text{Re } G_{\omega_0}(\omega_s) = \frac{\omega_0^2 - \omega_s^2}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

$$\text{Im } G_{\omega_0}(\omega_s) = \frac{2\Gamma\omega_s}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2}$$

$$AAF = \frac{\text{Resonant response}}{\text{DC response}} = \frac{|G_{\omega_0}(\omega_s = \omega_0)|}{|G_{\omega_0}(0)|} = \frac{1/(2\Gamma\omega_0)}{1/\omega_0^2} = \frac{\omega_0}{2\Gamma} = q \quad (\text{angular quality factor})$$

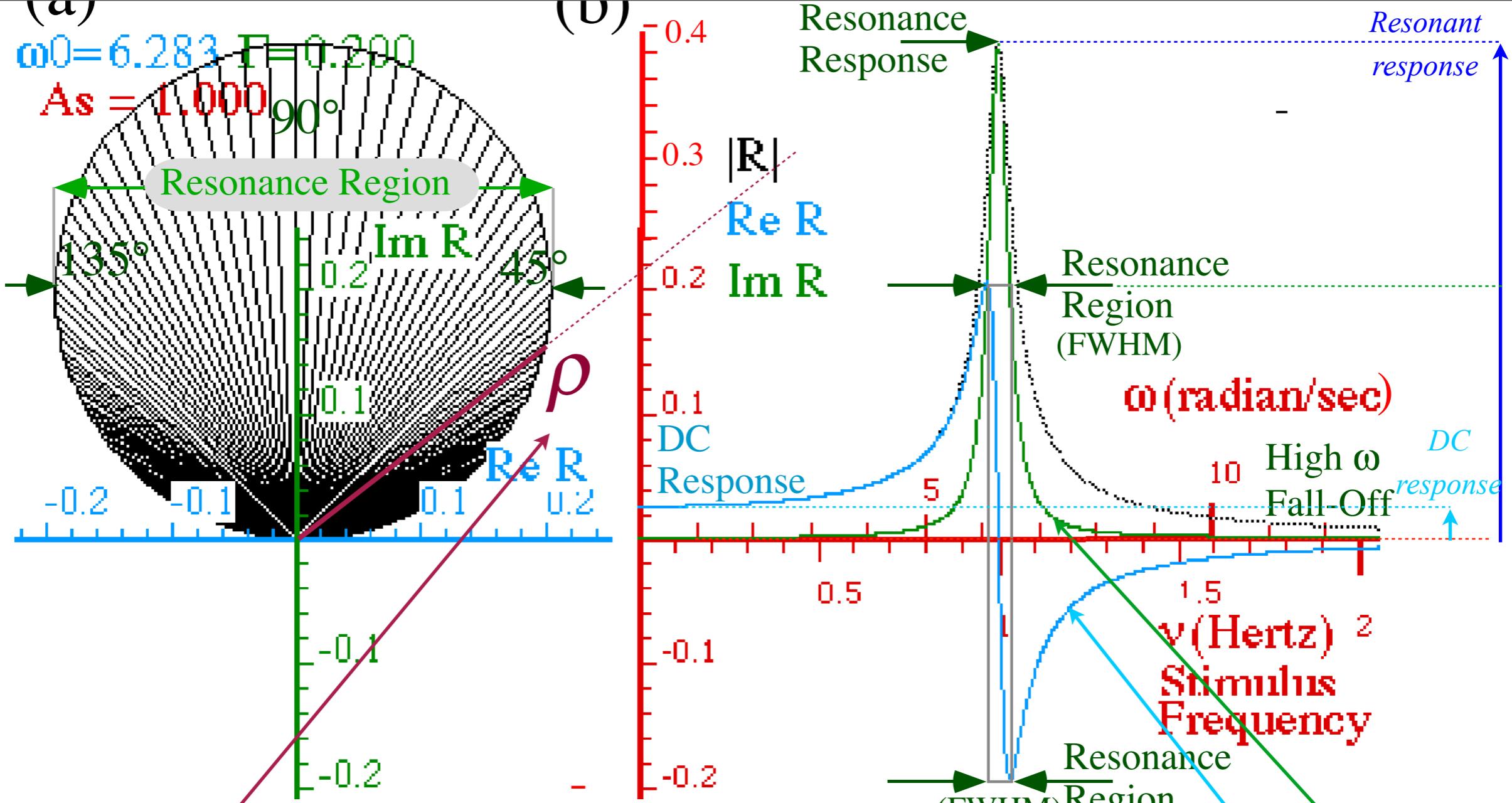


Fig. 3.2.6 Anatomy of oscillator Green-Lorentz response function plots

Phase lag angle

$$\rho = \tan^{-1} \left(\frac{2\Gamma\omega_s}{\omega_0^2 - \omega_s^2} \right)$$

$$\begin{aligned} \text{Real part: } Re G_{\omega_0}(\omega_s) &= \frac{\omega_0^2 - \omega_s^2}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2} \\ \text{Imaginary part: } Im G_{\omega_0}(\omega_s) &= \frac{2\Gamma\omega_s}{(\omega_0^2 - \omega_s^2)^2 + (2\Gamma\omega_s)^2} \end{aligned}$$

$$AAF = \frac{\text{Resonant response}}{\text{DC response}} = \frac{|G_{\omega_0}(\omega_s = \omega_0)|}{|G_{\omega_0}(0)|} = \frac{1/(2\Gamma\omega_0)}{1/\omega_0^2} = \frac{\omega_0}{2\Gamma} = q \quad (\text{angular quality factor})$$

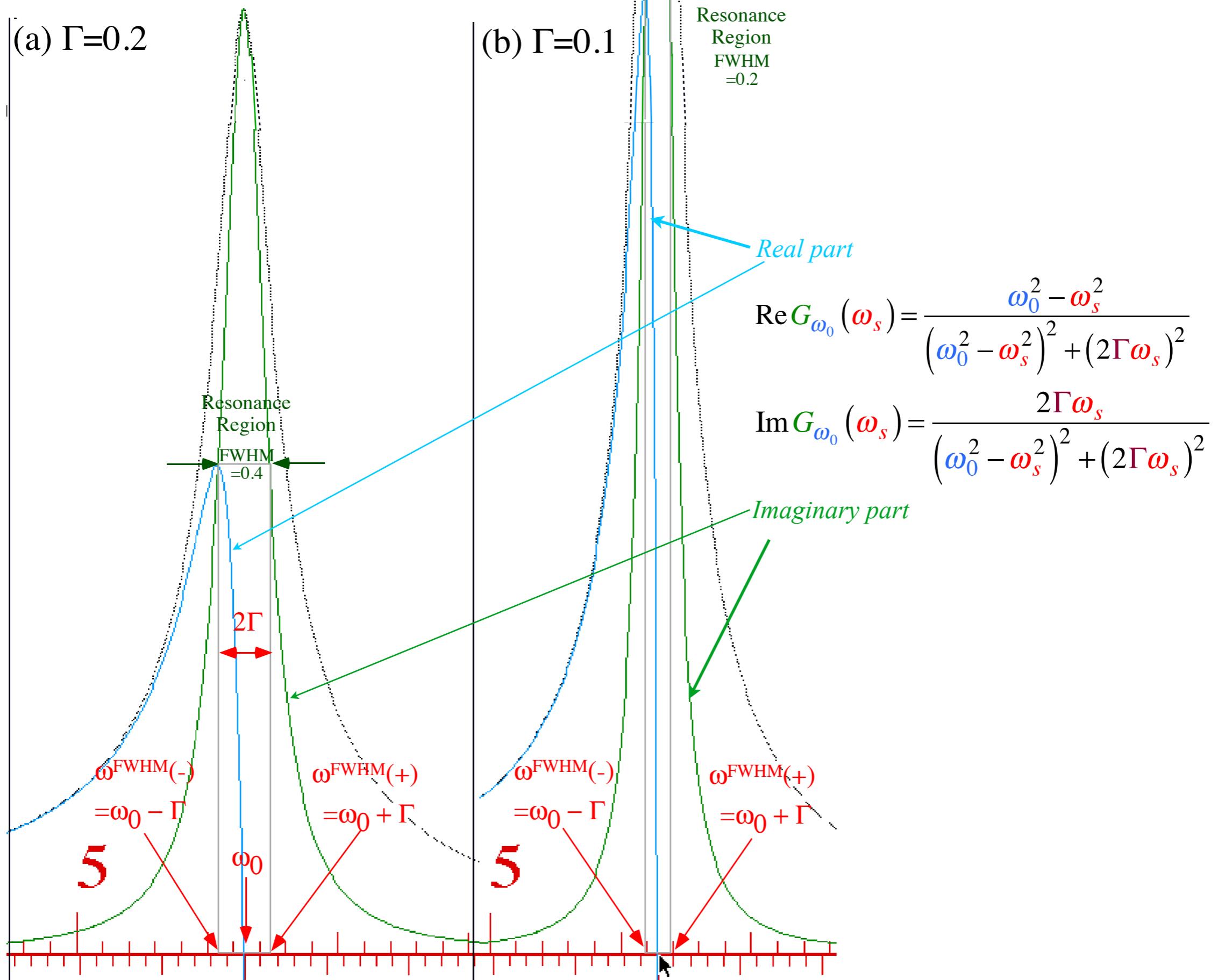


Fig. 3.2.7 Comparing Lorentz-Green resonance region for (a) $\Gamma=0.2$ and (b) $\Gamma=0.1$.

Maximum and minimum points of $\text{Re } G(\omega)$ and inflection points of $\text{Im } G(\omega)$ are near region boundaries $\omega^{FWHM}(\pm) = \omega_0 \pm \Gamma$.

Complete Green's Solution for the FDHO (Forced-Damped-Harmonic Oscillator)

$$\begin{aligned}
 z(t) &= z_{\text{transient}}(t) + z_{\text{response}}(t) \equiv z_{\text{decaying}}(t) + z_{\text{steady state}}(t) \\
 &= Ae^{-\Gamma t} e^{-i\omega_\Gamma t} + G_{\omega_0}(\omega_s) a(0) e^{-i\omega_s t} \\
 &= Ae^{-\Gamma t} e^{-i\omega_\Gamma t} + |G_{\omega_0}(\omega_s)| a(0) e^{-i(\omega_s t - \rho)}
 \end{aligned}$$

Known as “homogeneous” solution (no force)

Let’s you set initial values or boundary conditions

Known as “inhomogeneous” solution

Not function of initial values. Marches to stimulus only.

Complete Green's Solution for the FDHO (Forced-Damped-Harmonic Oscillator)

$$\begin{aligned}
 z(t) &= z_{\text{transient}}(t) + z_{\text{response}}(t) \equiv z_{\text{decaying}}(t) + z_{\text{steady state}}(t) \\
 &= Ae^{-\Gamma t} e^{-i\omega_\Gamma t} + G_{\omega_0}(\omega_s) a(0) e^{-i\omega_s t} \\
 &= Ae^{-\Gamma t} e^{-i\omega_\Gamma t} + |G_{\omega_0}(\omega_s)| a(0) e^{-i(\omega_s t - \rho)}
 \end{aligned}$$

Known as “homogeneous” solution (no force)

Let’s you set initial values or boundary conditions

Known as *Transient* solution since it dies-off as time advances past initial conditions

Known as “inhomogeneous” solution

Not function of initial values. Marches to stimulus only.

Known as *Steady State* solution since it is present as long as stimulus is.

Complete Green's Solution for the FDHO (Forced-Damped-Harmonic Oscillator)

$$\begin{aligned}
 z(t) &= z_{\text{transient}}(t) + z_{\text{response}}(t) \equiv z_{\text{decaying}}(t) + z_{\text{steady state}}(t) \\
 &= Ae^{-\Gamma t} e^{-i\omega_\Gamma t} + G_{\omega_0}(\omega_s) a(0) e^{-i\omega_s t} \\
 &= Ae^{-\Gamma t} e^{-i\omega_\Gamma t} + |G_{\omega_0}(\omega_s)| a(0) e^{-i(\omega_s t - \rho)}
 \end{aligned}$$

Known as “homogeneous” solution (no force)

Let’s you set initial values or boundary conditions

Known as *Transient* solution since it dies-off as time advances past initial conditions

Known as “inhomogeneous” solution

Not function of initial values. Marches to stimulus only.

Known as *Steady State* solution since it is present as long as stimulus is.

Stimulus: $A_s = 0.5000$ $\omega = 6.2832$

Response: $R = 0.1989$ $\rho = 1.5708$

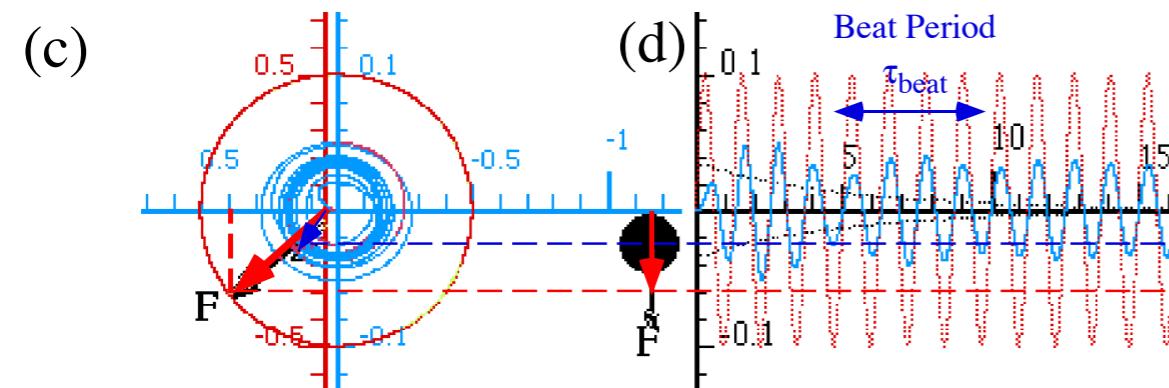
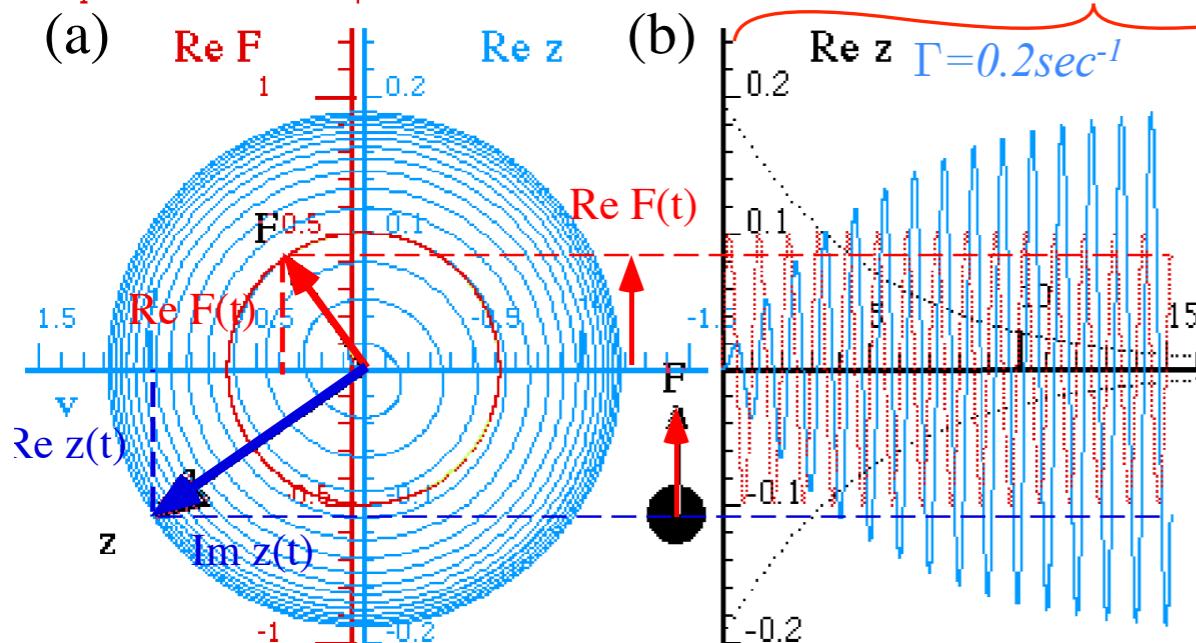
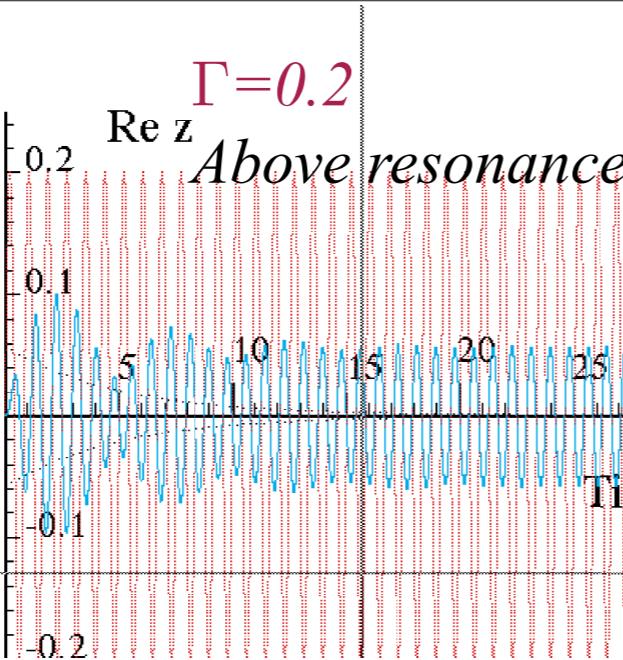
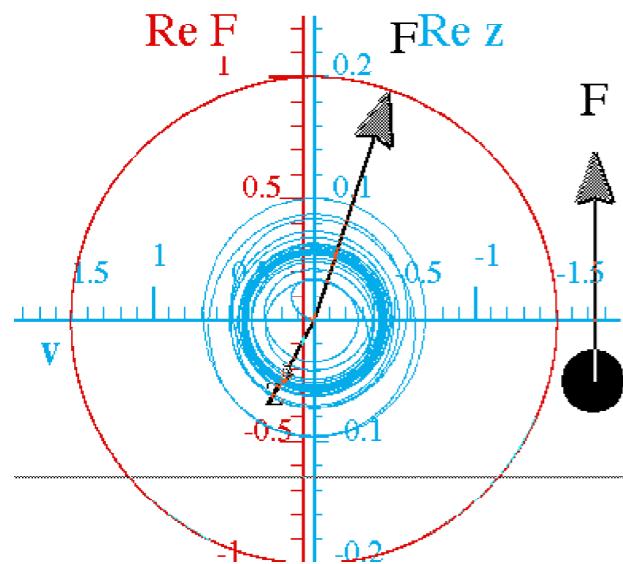


Fig. 3.2.8 On Resonance (a) Response z -phasor lags $\rho = 90^\circ$ behind stimulus F -phasor. ($\omega_s = \omega_0 = 2\pi$, $\omega_0 = 2\pi$, and $\Gamma = 0.2$). (b) Time plots of $\text{Re } z(t)$ and $\text{Re } F(t)$

Fig. 3.2.8 Below Resonance (c) Response z -phasor lags $\rho = 8.05^\circ$ behind stimulus F -phasor. ($\omega_s = 5.03$, $\omega_0 = 2\pi$, and $\Gamma = 0.2$). (d) Time plots of $\text{Re } z(t)$ and $\text{Re } F(t)$. Beats are barely visible.

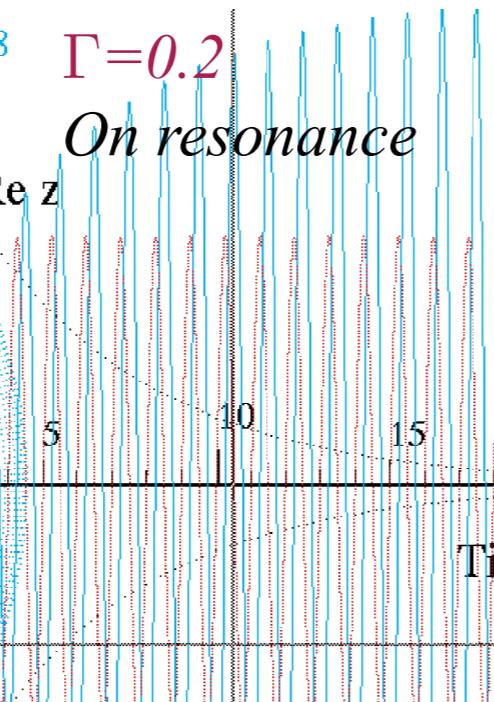
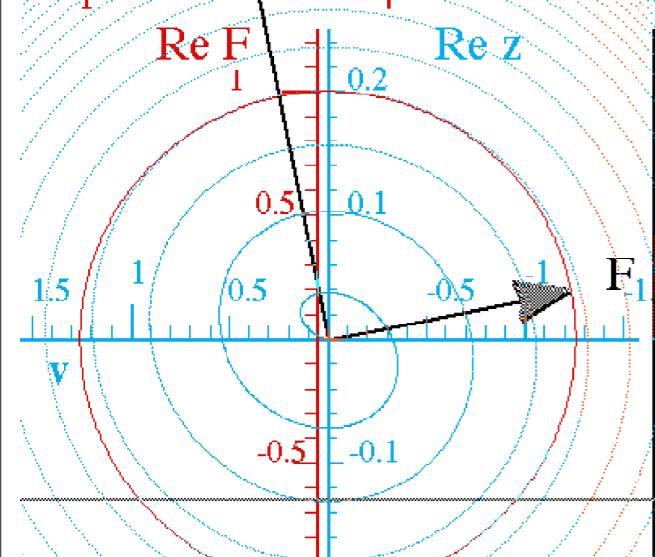
Stimulus: $A_s = 1.0000$ $\omega = 7.5265$
Response: $R = 0.0574$ $\rho = 2.9680$



Initial Amplitude & Phase: $A = 0.3981$ $\alpha = -1.5708$

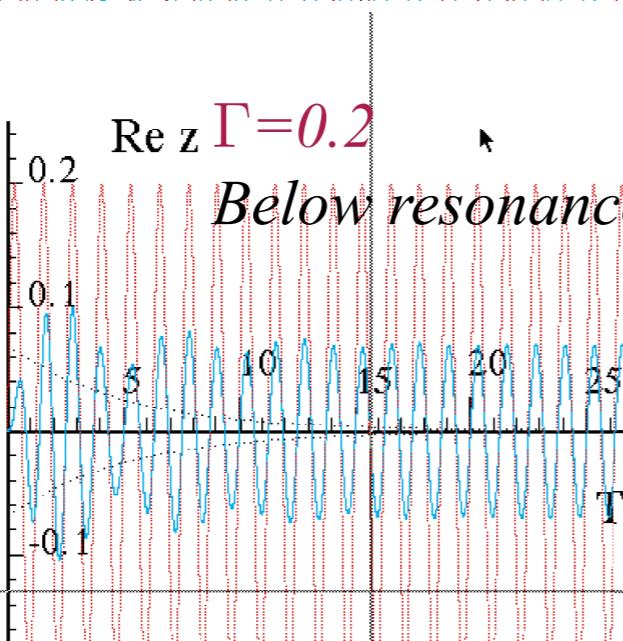
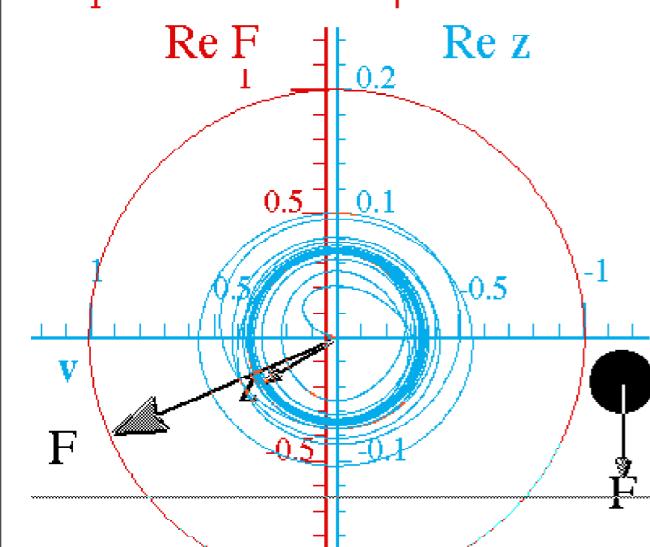
Stimulus: $A_s = 1.0000$ $\omega = 6.2832$

Response: $R = 0.3979$ $\rho = 1.5708$

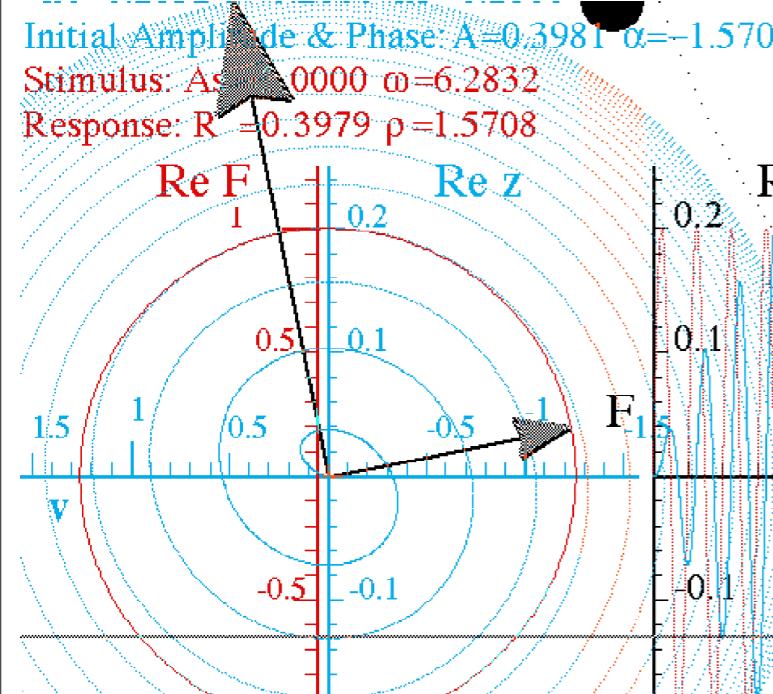
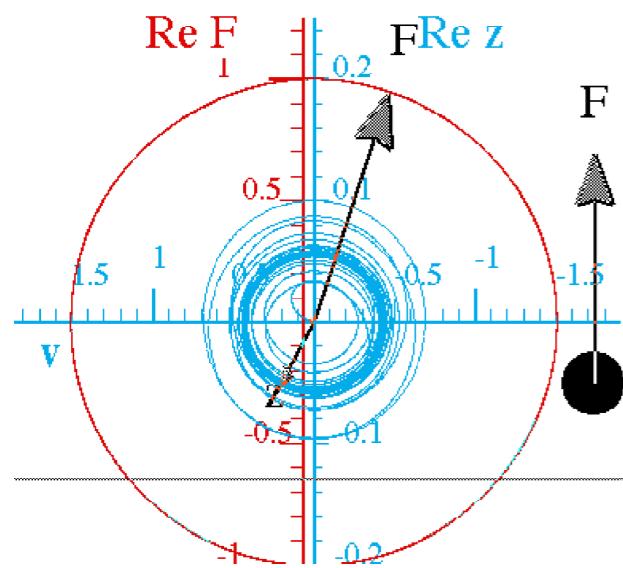


Stimulus: $A_s = 1.0000$ $\omega = 5.0265$

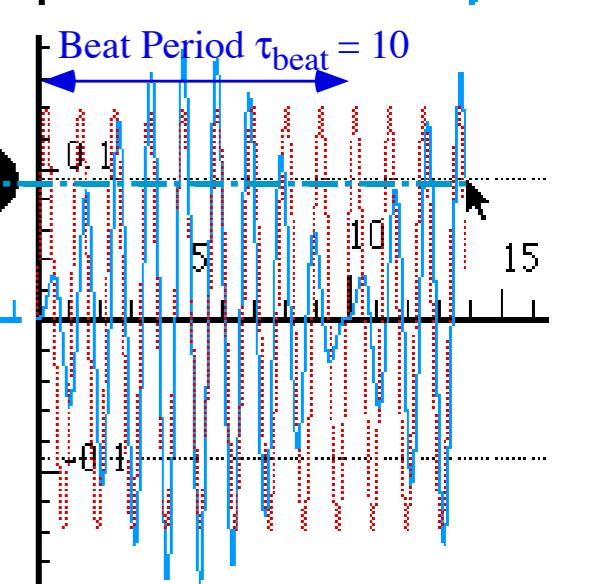
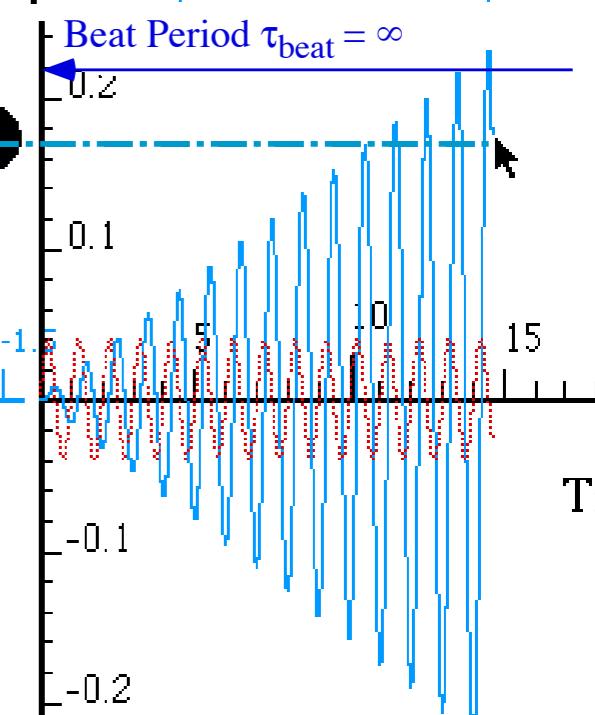
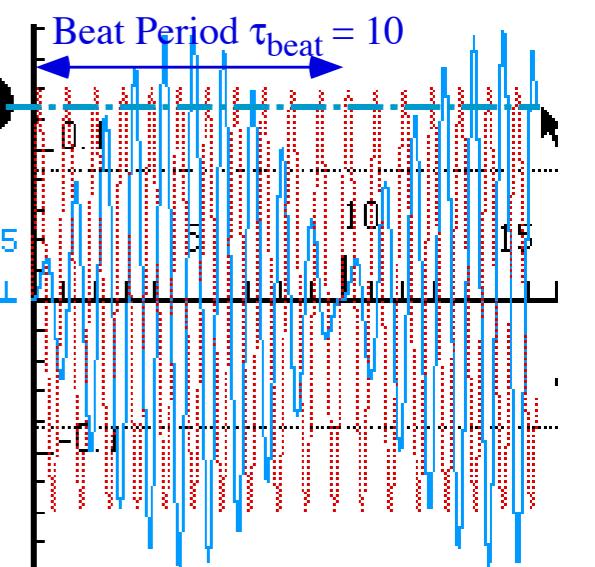
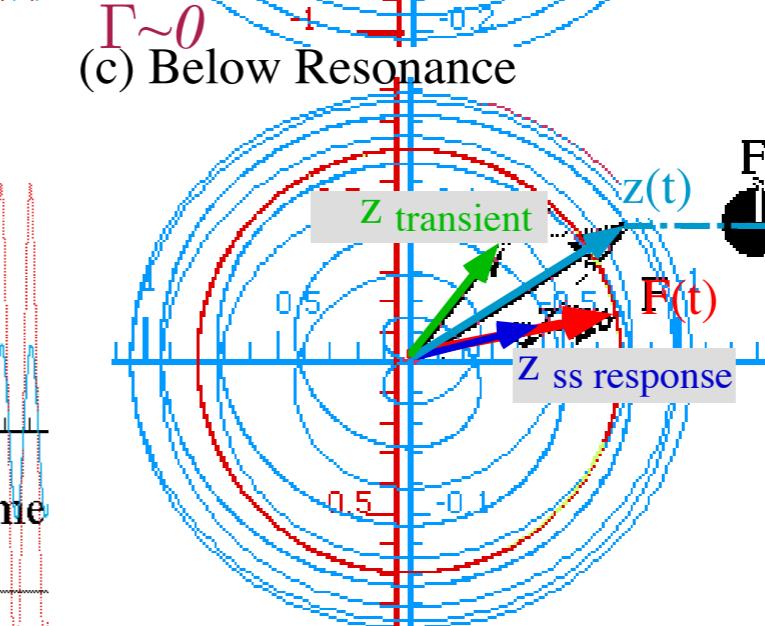
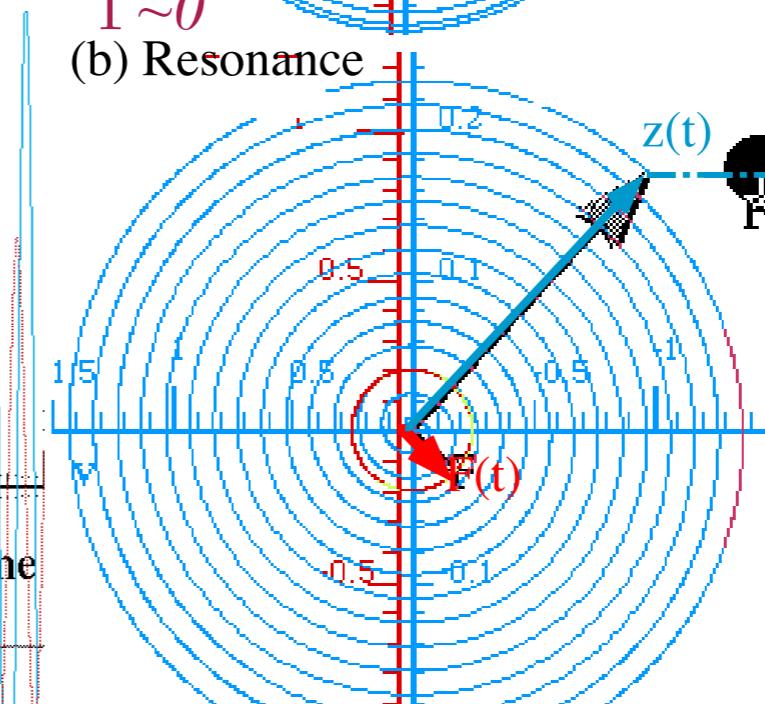
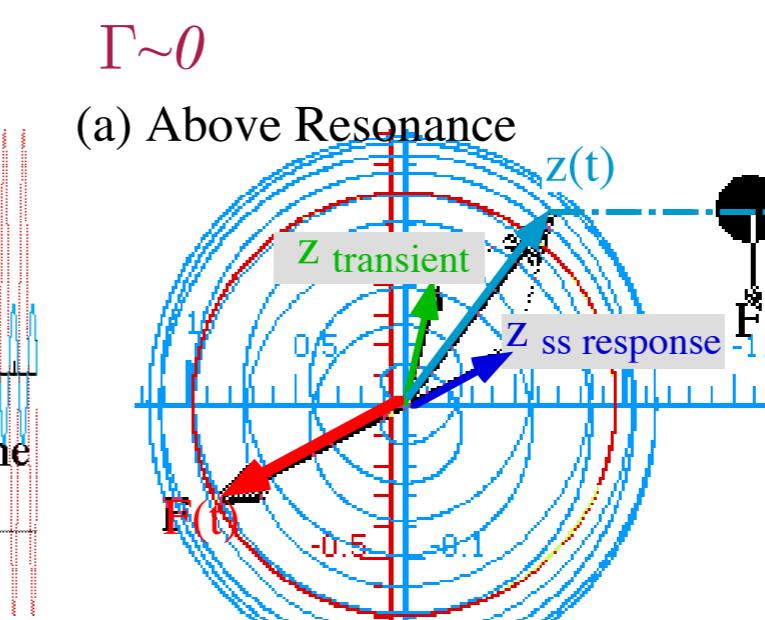
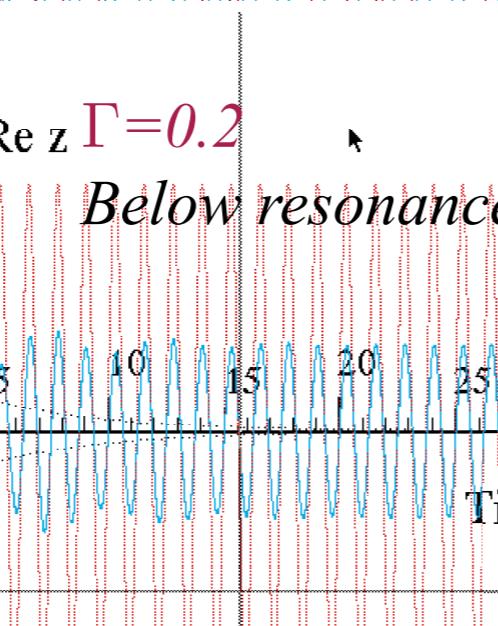
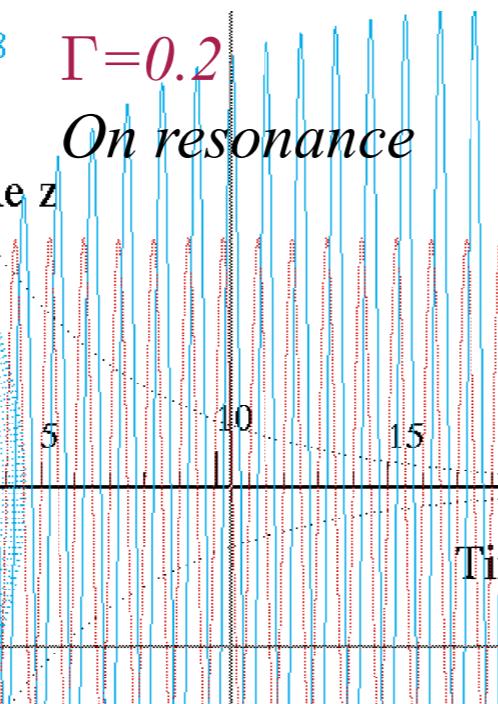
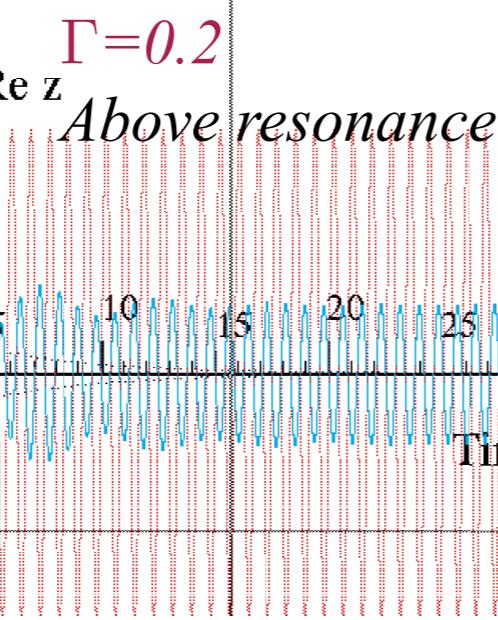
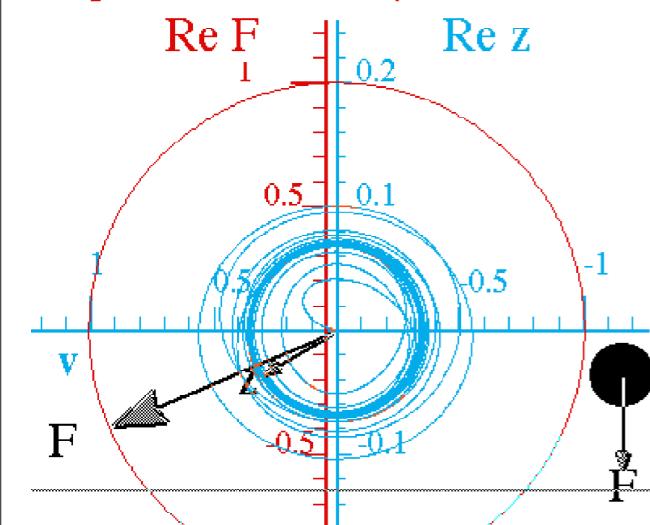
Response: $R = 0.0697$ $\rho = 0.1405$



Stimulus: $A_s = 1.0000 \omega = 7.5265$
Response: $R = 0.0574 \rho = 2.9680$



Stimulus: $A_s = 1.0000 \omega = 5.0265$
Response: $R = 0.0697 \rho = 0.1405$



Lorentz-Green's Function for high quality FDHO

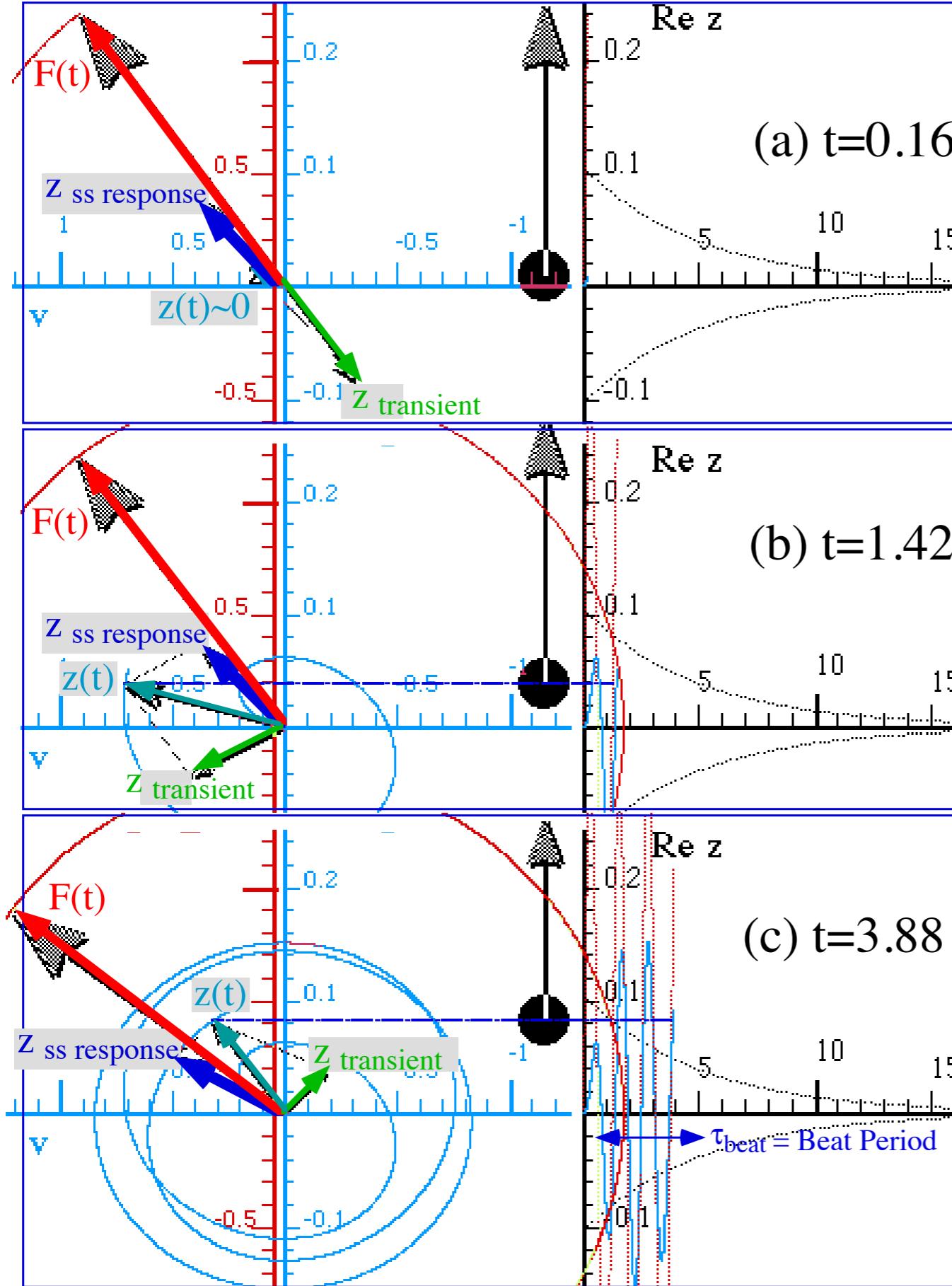


Fig. 4.2.9 Beat formation.

Transient phasor $z_{\text{transient}}$ catches up with F -phasor and passes it.

Oscillator figures of merit: quality factors Q and $q=2\pi Q$

$$AAF = \frac{\text{Resonant response}}{\text{DC response}} = \frac{\left| G_{\omega_0}(\omega_s = \omega_0) \right|}{\left| G_{\omega_0}(0) \right|} = \frac{1/(2\Gamma\omega_0)}{1/\omega_0^2} = \frac{\omega_0}{2\Gamma} \equiv q \quad (\text{angular quality factor})$$

Amplification factor $q = \omega_0/2\Gamma$

Natural oscillation frequency is approximately $v_0 = \omega_0/2\pi$ (for $\omega_0 \gg \Gamma$ we have $\omega_0 \sim \omega_\Gamma$).

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$t_{5\%} = 3/\Gamma = \text{Lifetime}$
(for decaying oscillator)
to lose 95% of
amplitude

$times \left(v_0 = \frac{\omega_0}{2\pi} \right) =$ number $n_{5\%}$
of oscillations
in a $t_{5\%}$ Lifetime

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$$\text{times} \left(v_0 = \frac{\omega_0}{2\pi} \right) = \begin{array}{l} \text{number } n_{5\%} \\ \text{of oscillations} \\ \text{in a } t_{5\%} \text{ Lifetime} \end{array}$$

The “Heartbeat Count”
 measure of lifetime

$$n_{5\%} = t_{5\%} v_0 = \frac{3}{\Gamma} \cdot \frac{\omega_0}{2\pi} \approx \frac{\omega_0}{2\Gamma} = q$$

Oscillator figures of merit: quality factors Q and $q=2\pi Q$

$$AAF = \frac{\text{Resonant response}}{\text{DC response}} = \frac{\left| G_{\omega_0}(\omega_s = \omega_0) \right|}{\left| G_{\omega_0}(0) \right|} = \frac{1/(2\Gamma\omega_0)}{1/\omega_0^2} = \frac{\omega_0}{2\Gamma} \equiv q \quad (\text{angular quality factor})$$

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The “Heartbeat Count”
 measure of lifetime

Energy decay

(proportional to the square of oscillator amplitude): $(e^{\Gamma t})^2 = e^{-2\Gamma t}$

$$dE = -2\Gamma E$$

Oscillator figures of merit: quality factors Q and $q=2\pi Q$

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The “Heartbeat Count”
 measure of lifetime

Energy decay

(proportional to the square of oscillator amplitude): $(e^{\Gamma t})^2 = e^{-2\Gamma t}$

$$dE = -2\Gamma E$$

Relative amount

of energy lost

$$\text{each cycle period} = \tau_0 \left(\frac{-dE}{E} \right) = \frac{2\Gamma}{v_0} \equiv \frac{1}{Q} = \frac{2\pi}{q}$$

$\left(\tau_0 = \frac{1}{v_0} \right)$

$$Q = (\text{Standard angular quality factor}) = \frac{q}{2\pi}$$

Oscillator figures of merit: Uncertainty 1/q

To see a beat we need $\tau_{\text{half-beat}}$ to be less than $\tau_{5\%}$ or $3/\Gamma$. (Here we approximate $\pi \sim 3.0$, again.)

$$\pi / |\omega_s - \omega_0| < 3 / \Gamma \quad |\omega_s - \omega_0| > \Gamma$$

This means ω -detuning error is greater than or equal to the decay rate Γ .

Any detuning less than Γ is virtually undetectable.

Total ω uncertainty is $\pm \Gamma$ or twice Γ (that is: FWHM $\Delta\omega = 2\Gamma$). Linear frequency uncertainty is:

The *relative frequency uncertainty* $\frac{2\Gamma}{\omega_0} = \frac{\Delta\omega}{\omega_0} = \frac{1}{q} = \frac{\Delta\nu}{\nu_0}$ $\Delta\nu = \Delta\omega / 2\pi = \Gamma / \pi$

is the *inverse* of the *angular quality factor* q .

If we think of the 5% or 4.321% lifetime of a musical note as its time uncertainty Δt , then:

$$\Delta t \Delta \nu = 3 / \pi \approx 1$$

$$\Delta t = t_{5\%} = 3 / \Gamma$$

$$\Delta t = t_{4.321\%} = \pi / \Gamma$$

Very precise measures of imprecision

Approximate Lorentz-Green's Function for high quality FDHO (Quantum propagator)

$$G_{\omega_0}(\omega_s) = \frac{1}{\omega_0^2 - \omega_s^2 - i2\Gamma\omega_s} \xrightarrow{\omega_s \rightarrow \omega_0} \frac{1}{2\omega_s} \frac{1}{\omega_0 - \omega_s - i\Gamma} \approx \frac{1}{2\omega_0} \frac{1}{\Delta - i\Gamma} = \frac{1}{2\omega_0} L(\Delta - i\Gamma)$$

Complex detuning-decay $\delta = \Delta - i\Gamma$ variable δ is defined with the *real detuning* $\Delta = \omega_0 - \omega_s$

Approximate Lorentz-Green's Function for high quality FDHO (Quantum propagator)

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$$L(\Delta - i\Gamma) = \frac{1}{\Delta - i\Gamma} = \operatorname{Re} L + i \operatorname{Im} L = \frac{\Delta}{\Delta^2 + \Gamma^2} + i \frac{\Gamma}{\Delta^2 + \Gamma^2} = |L|^2 \Delta + i |L|^2 \Gamma$$

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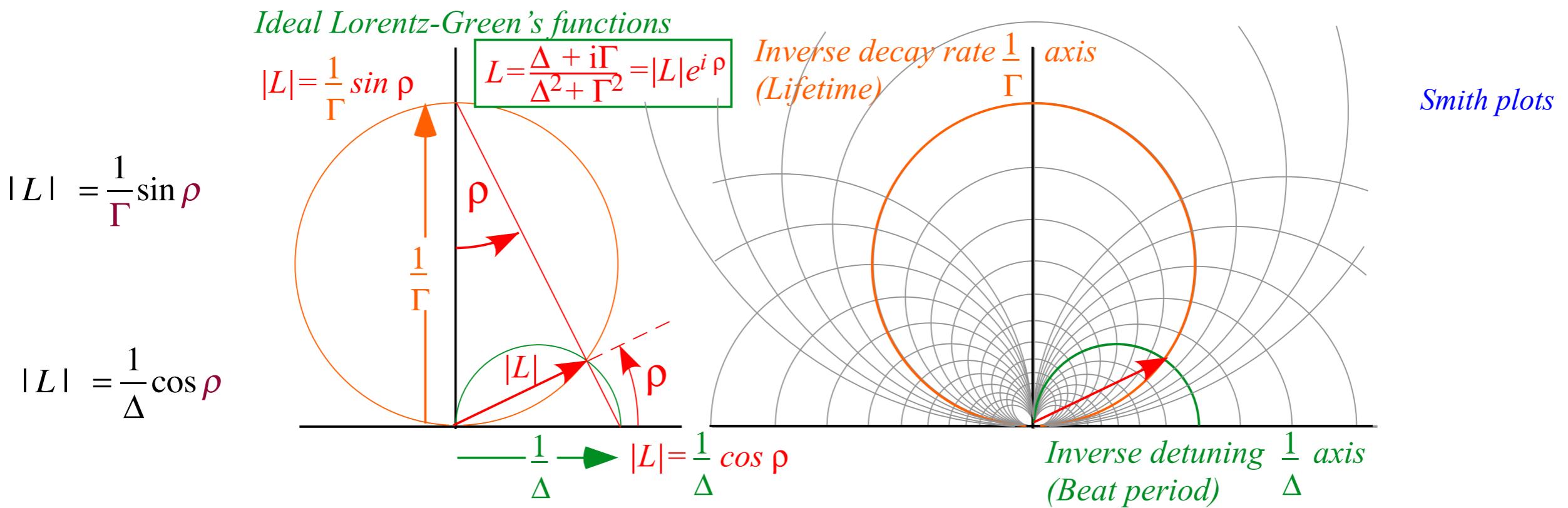
$$\begin{aligned} L(\Delta - i\Gamma) &= \frac{1}{\Delta - i\Gamma} = \operatorname{Re} L + i \operatorname{Im} L = \frac{\Delta}{\Delta^2 + \Gamma^2} + i \frac{\Gamma}{\Delta^2 + \Gamma^2} = |L|^2 \Delta + i |L|^2 \Gamma \\ &= |L| e^{i\rho} = |L| \cos \rho + i |L| \sin \rho = \frac{\cos \rho}{\sqrt{\Delta^2 + \Gamma^2}} + i \frac{\sin \rho}{\sqrt{\Delta^2 + \Gamma^2}} \text{ where: } |L| = \frac{1}{\sqrt{\Delta^2 + \Gamma^2}} \end{aligned}$$

Approximate Lorentz-Green's Function for high quality FDHO (Quantum propagator)

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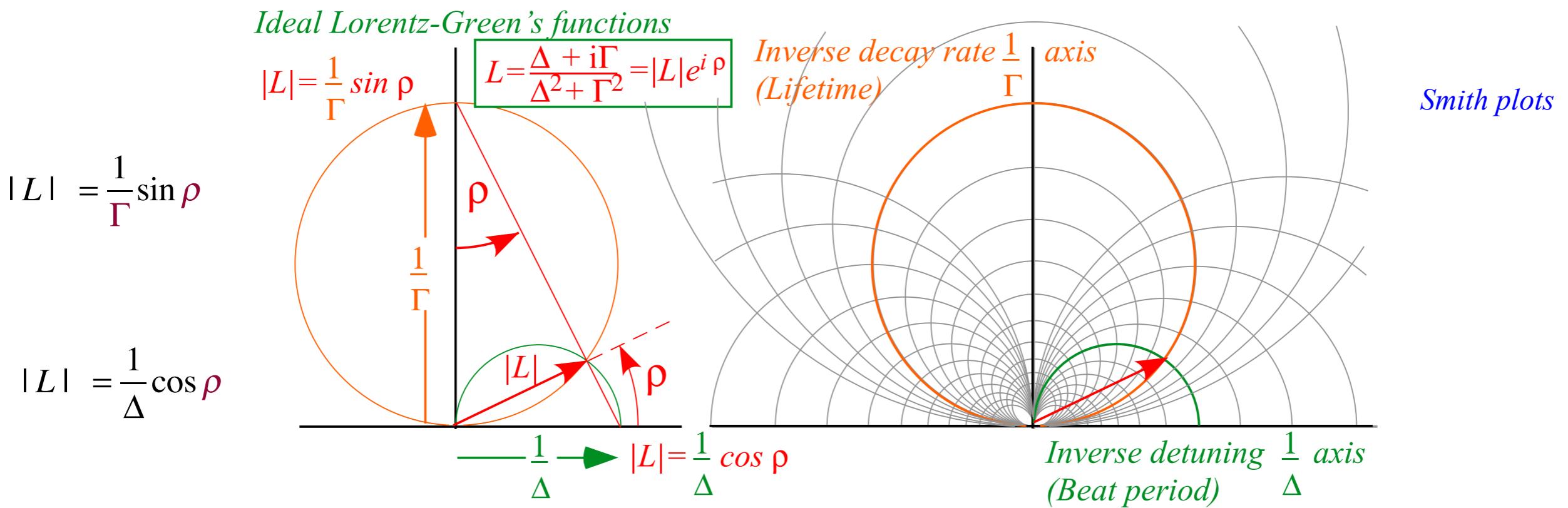
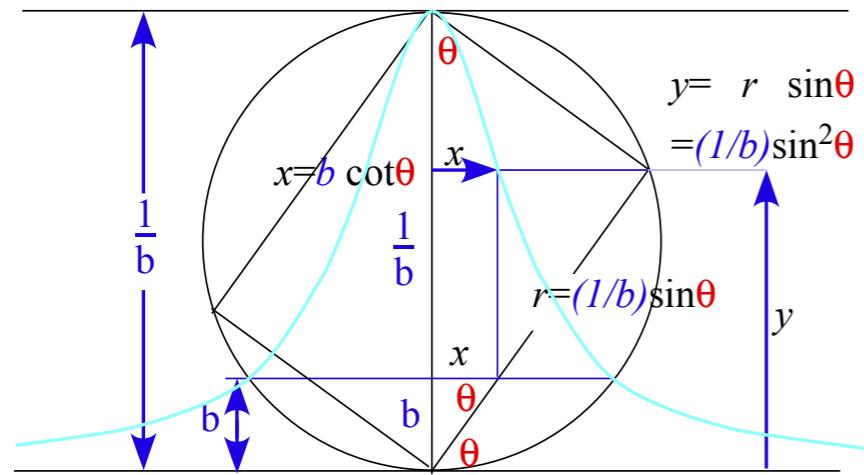


Fig. 3.2.13 Ideal Lorentzian in inverse rate space. (Smith life-time $1/\Gamma$ vs. beat-period $1/\Delta$ coordinates)

Constant Δ and Γ curves in Fig. 3.2.13 are orthogonal circles of $1/z$ -dipolar coordinates. Recall Fig. 1.10.11.

The Common Lorentzian (a.k.a. The Witch of Agnesi)



$$x^2 = b^2 \cot^2 \theta = b^2 \frac{\cos^2 \theta}{\sin^2 \theta} = b^2 \frac{1 - \sin^2 \theta}{\sin^2 \theta} = \frac{b^2}{\sin^2 \theta}$$

$$x^2 + b^2 = \frac{b^2}{\sin^2 \theta} = \frac{b}{y}$$

$y = \frac{b}{x^2 + b^2}$

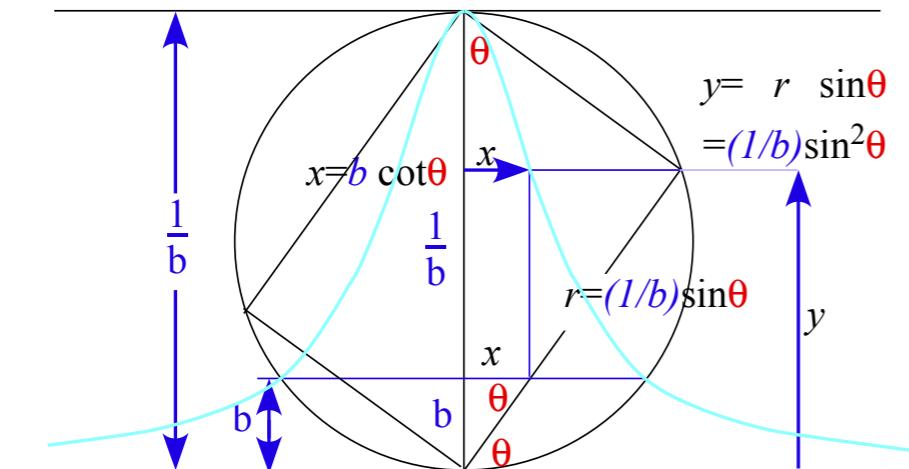
*Common Lorentzian function I.
(imaginary "absorptive" part)*

Maria Gaetana Agnesi



Born	May 16, 1718
Died	January 9, 1799 (aged 80)
Residence	Italy
Nationality	Italy
Fields	Mathematics

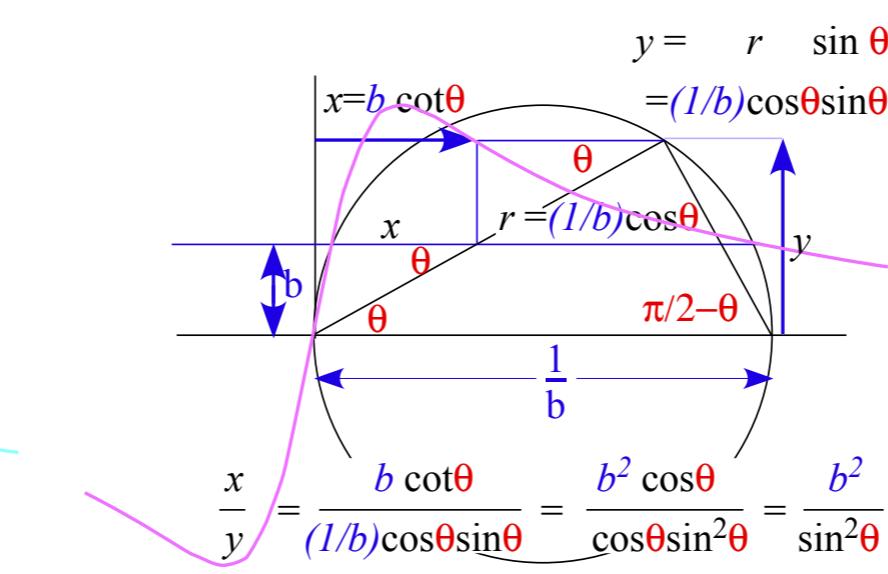
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Common Lorentzian function II.
(real "refractory" part)

Maria Gaetana Agnesi



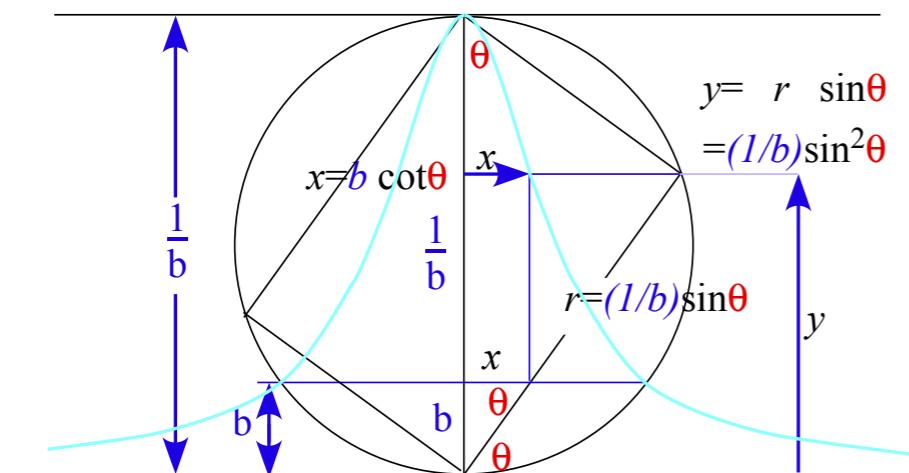
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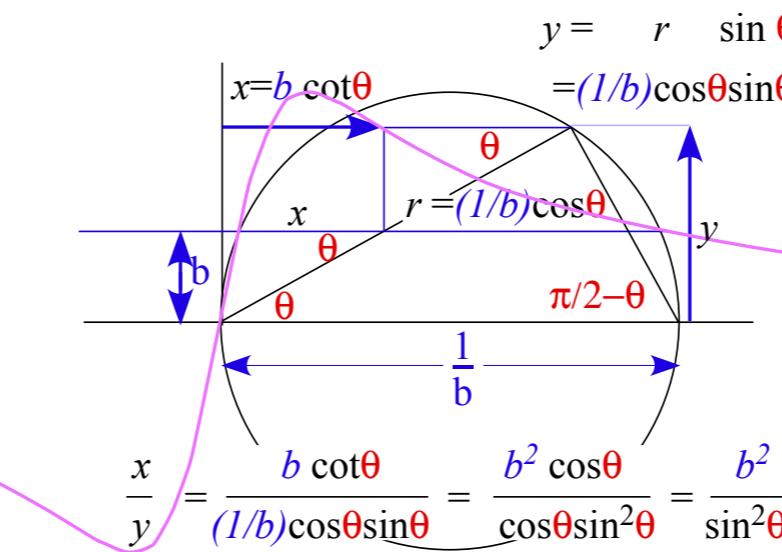
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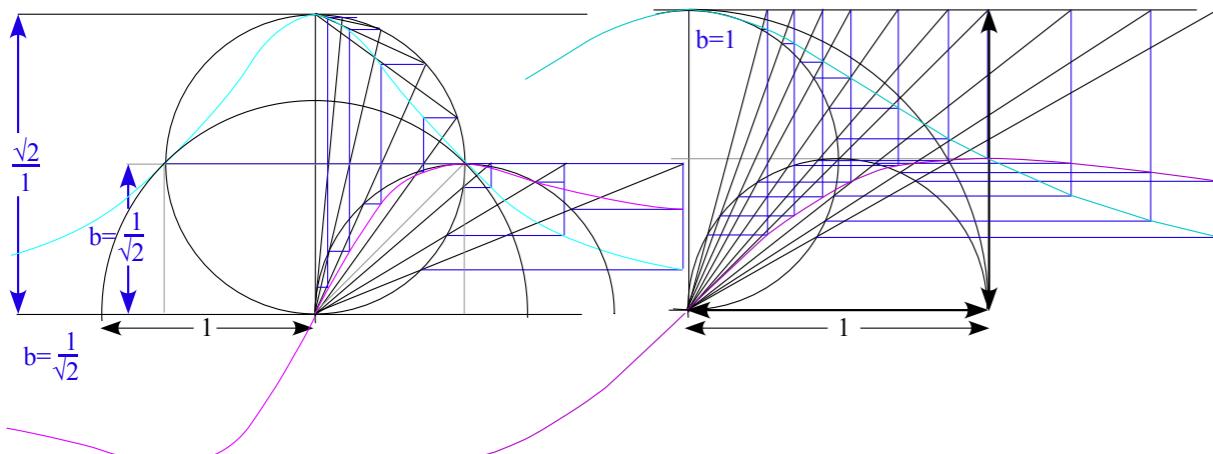
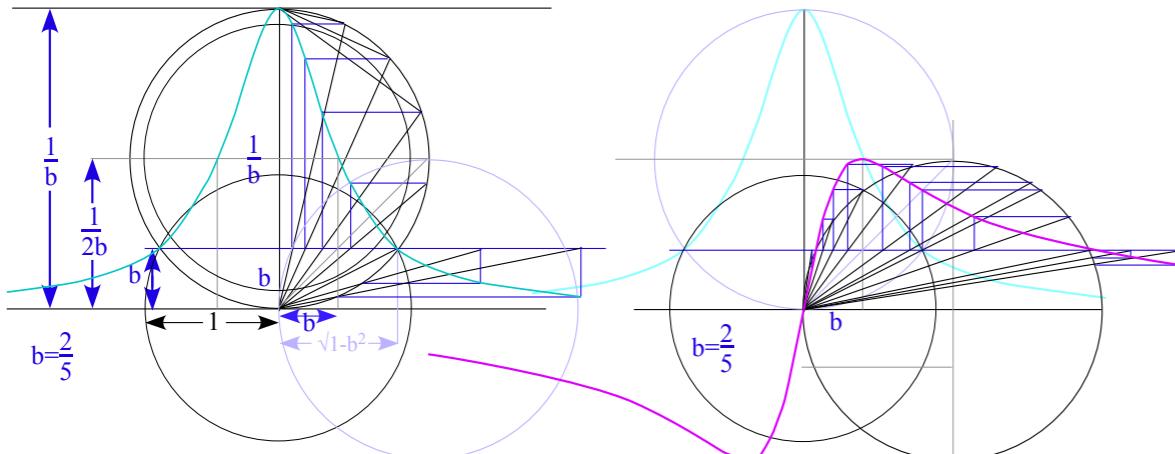
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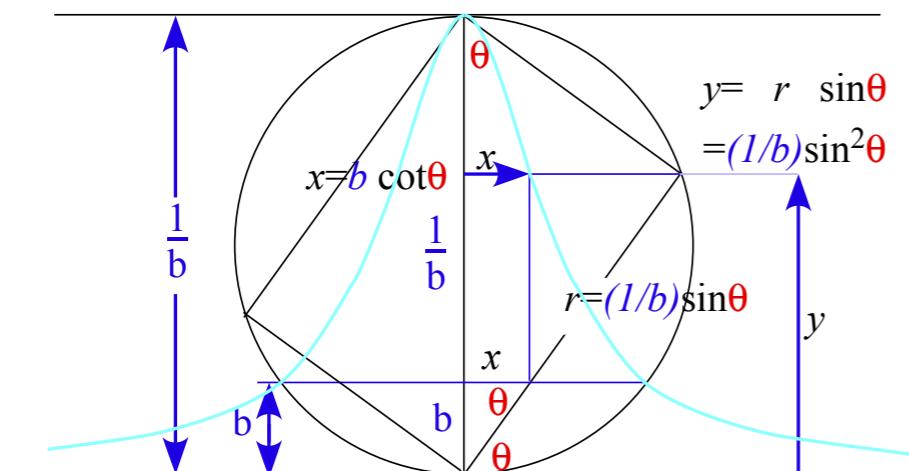


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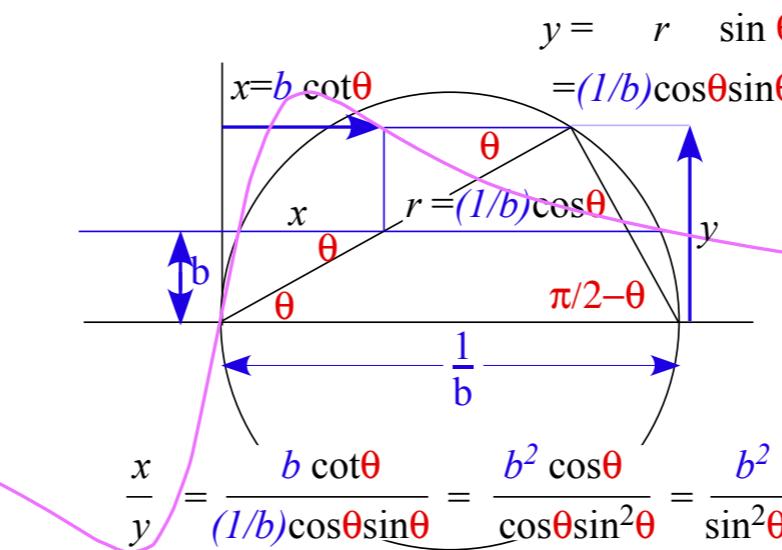
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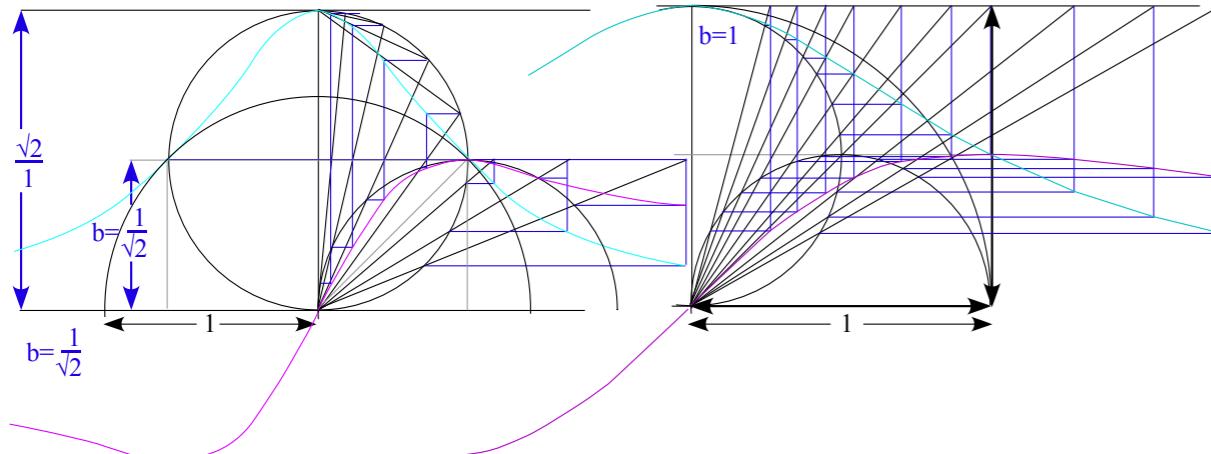
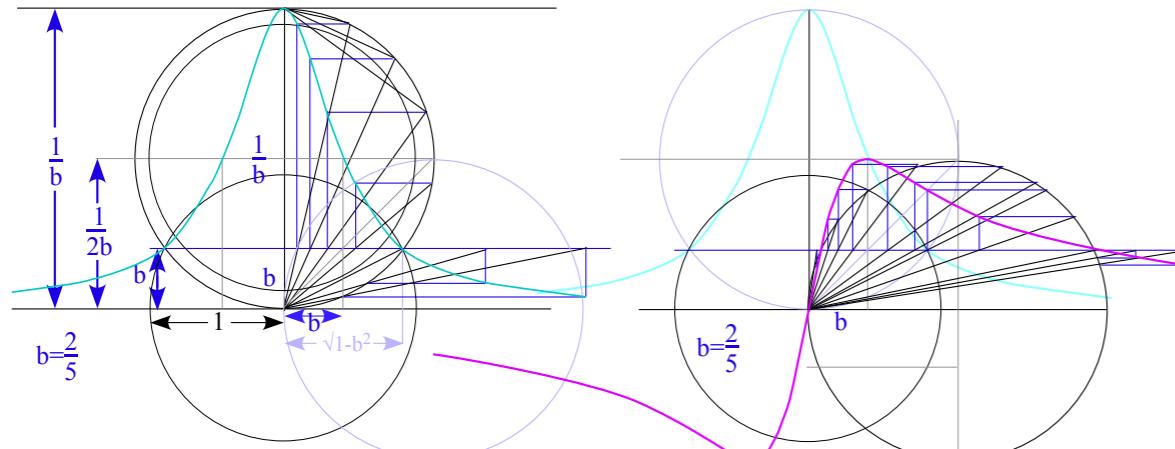
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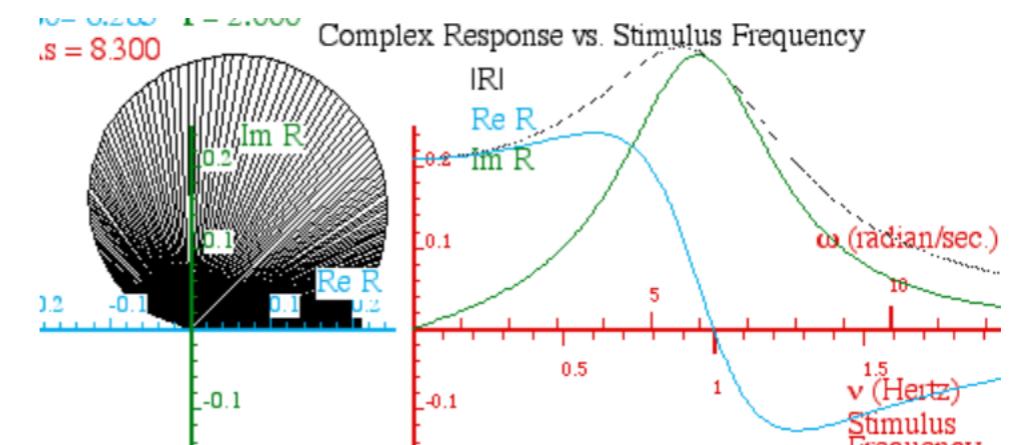


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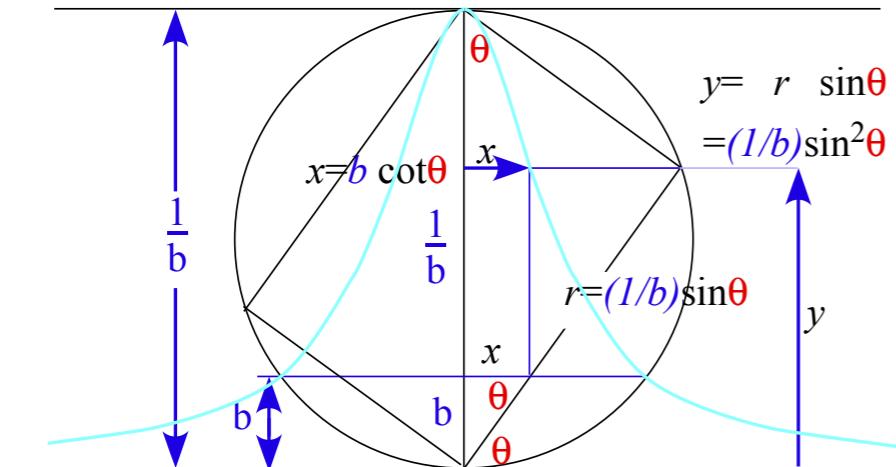
$y = \frac{x}{x^2 + b^2}$
*Common Lorentzian function II.
(real "refractory" part)*



Compare ideal Lorentzians ($\Gamma=0.2$)
with a very non-ideal one ($\Gamma=2$)



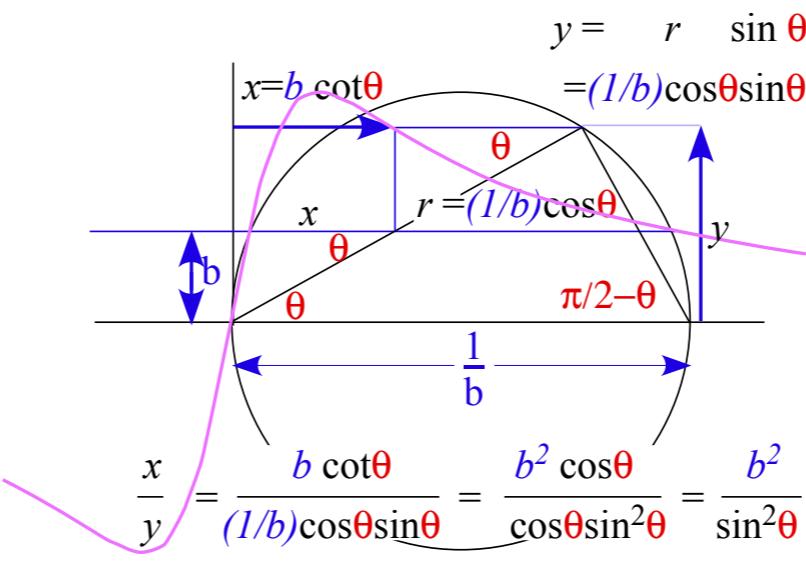
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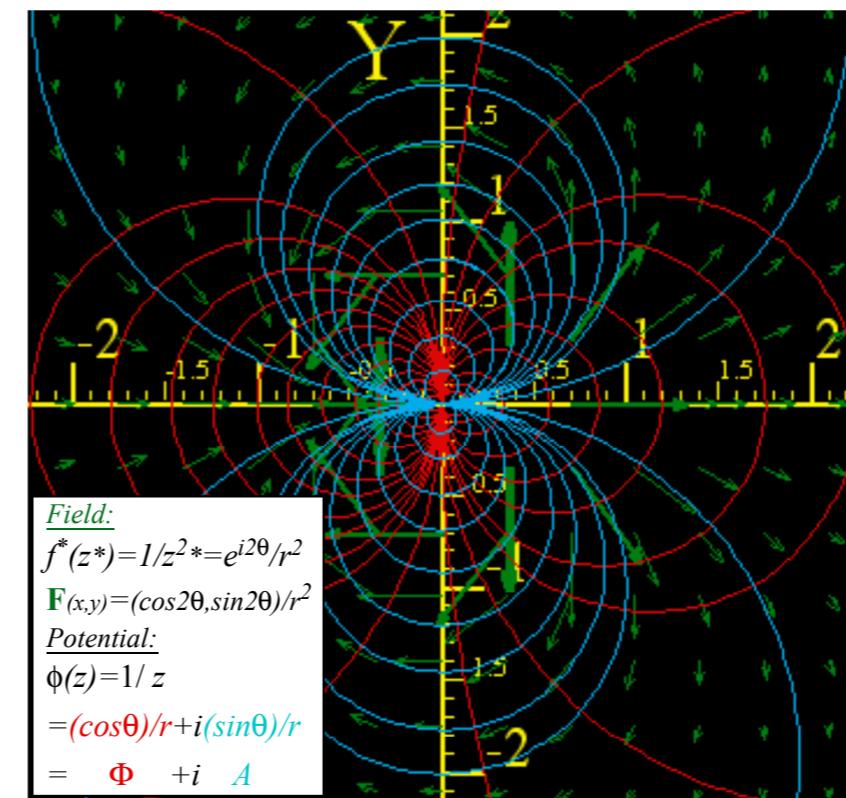
$$\frac{x}{y} = \frac{b \cot \theta}{(1/b) \cos \theta \sin \theta} = \frac{b^2 \cos \theta}{\cos \theta \sin^2 \theta} = \frac{b^2}{\sin^2 \theta}$$

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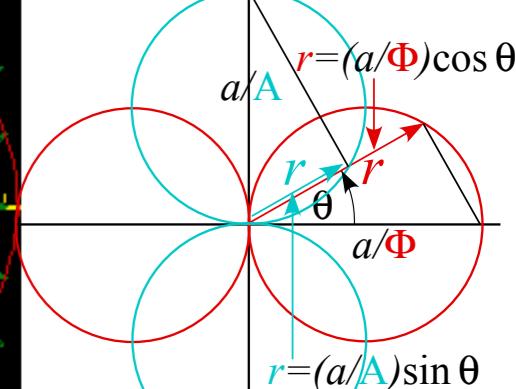
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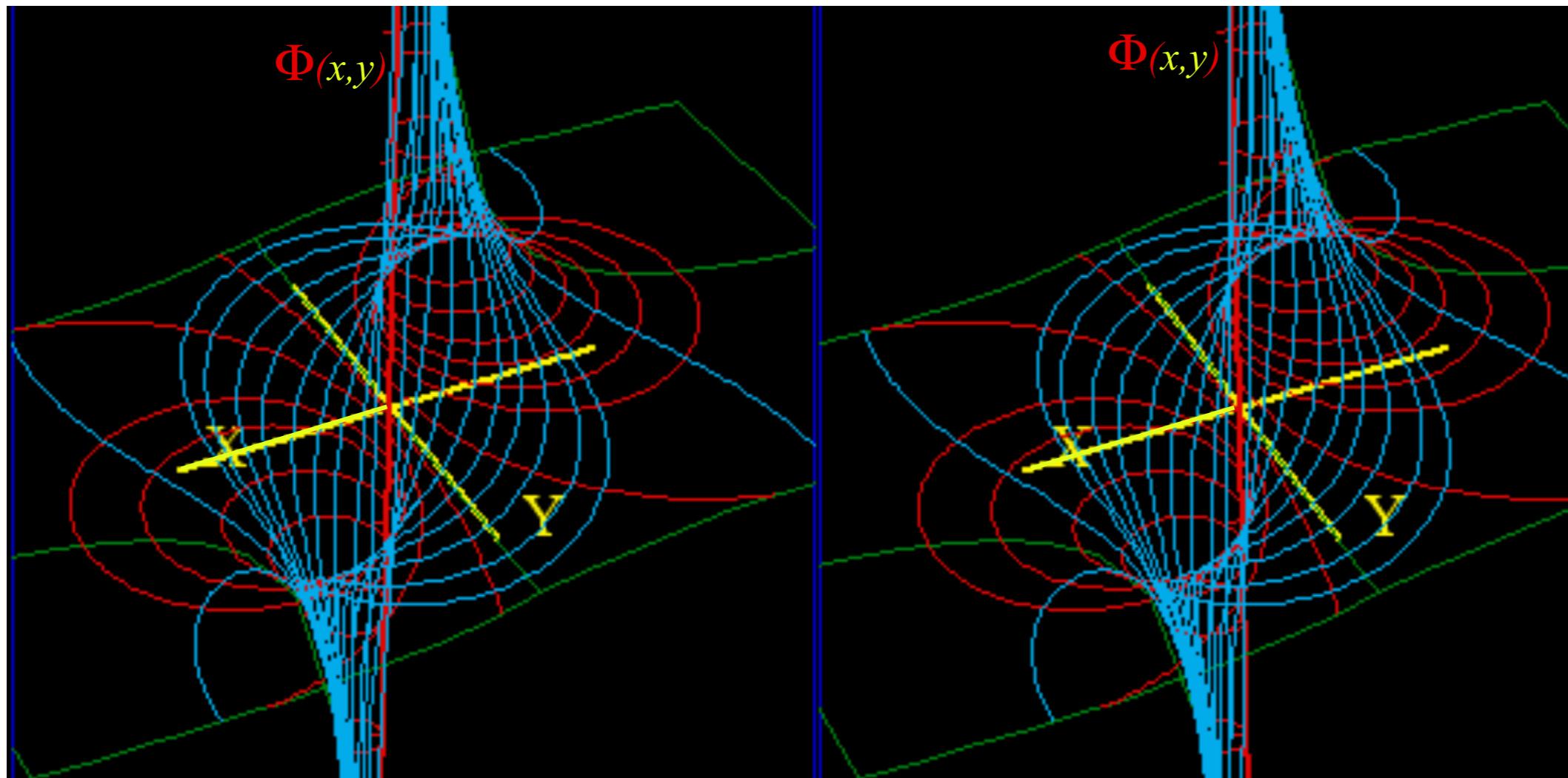


Scalar potentials
 $\Phi = (a/r) \cos \theta = \text{const.}$

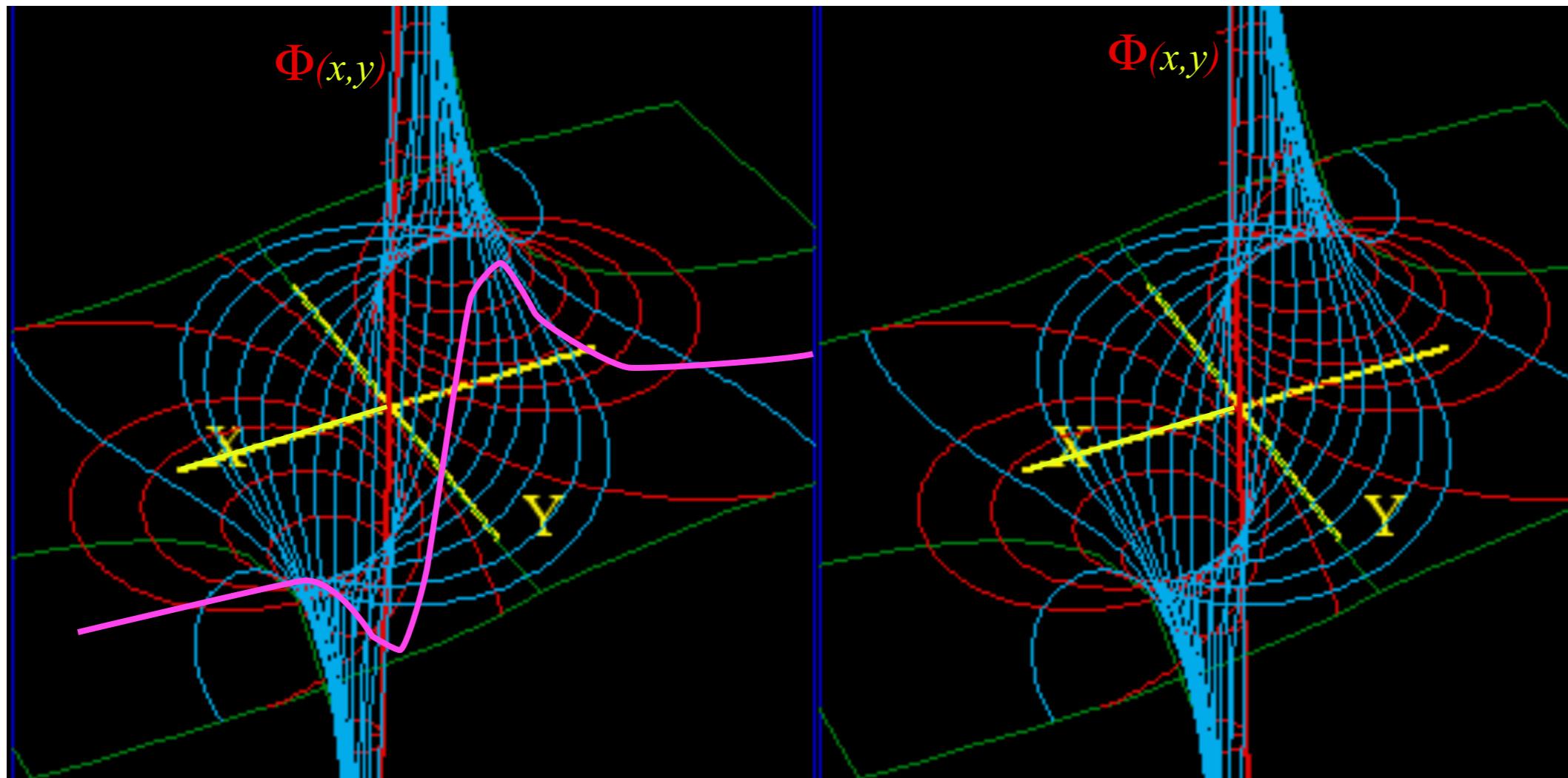


Vector potentials
 $A = (a/r) \sin \theta = \text{const.}$

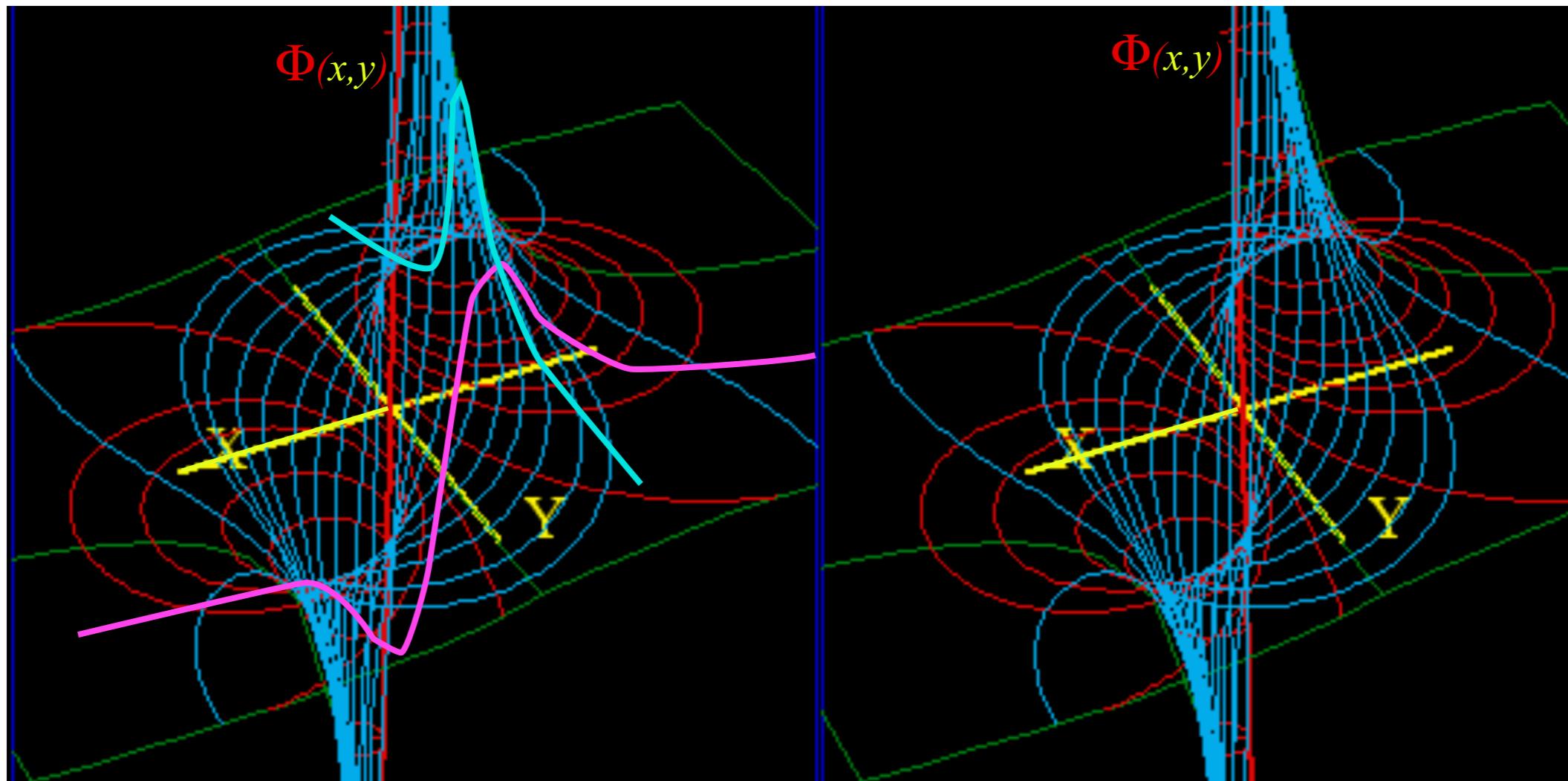
Fig. 10.11 Dipole \mathbf{F} -field $f(z) = 1/z^2$ and scalar potential ($\Phi = \text{const.}$)-circles orthogonal to ($\mathbf{A} = \text{const.}$)-circles.



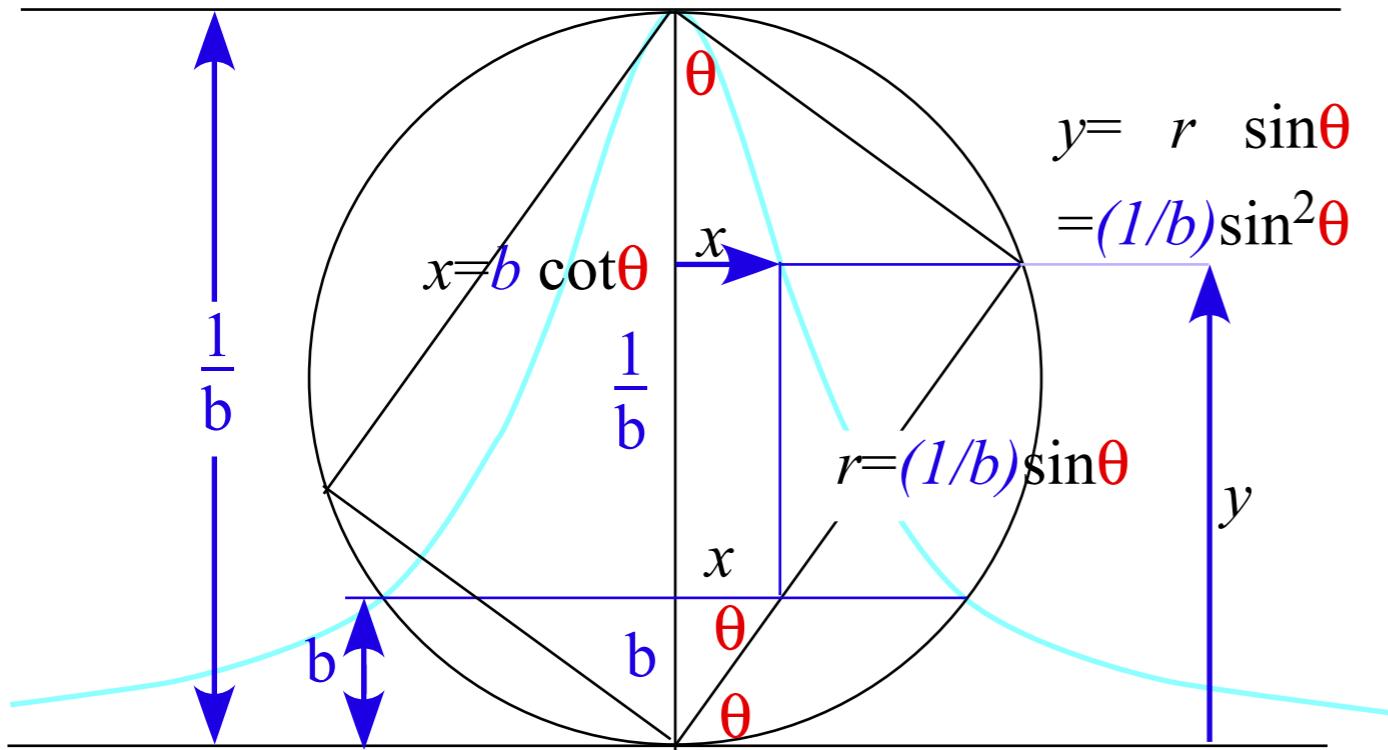
From: Fig. 1.10.12



From: Fig. 1.10.12



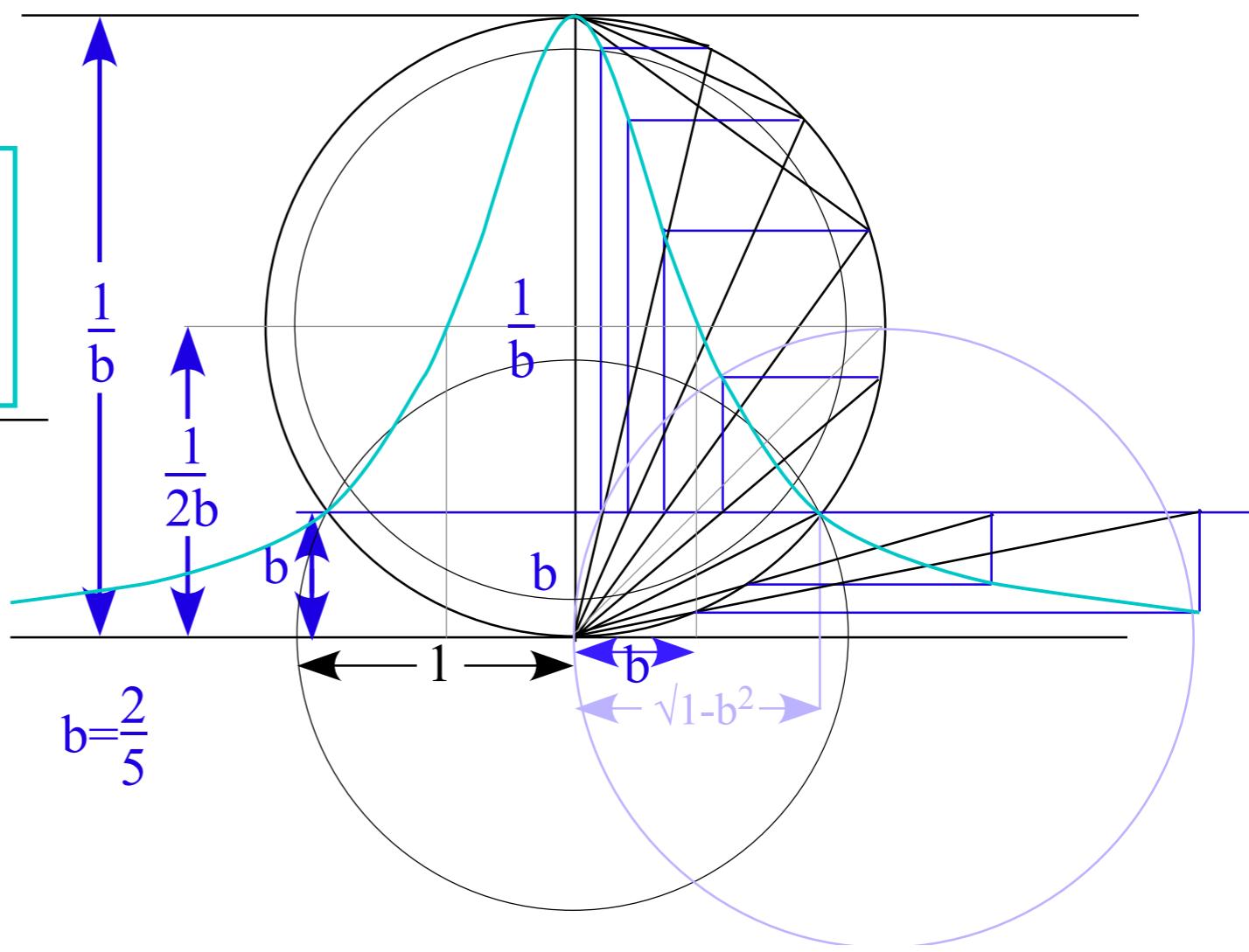
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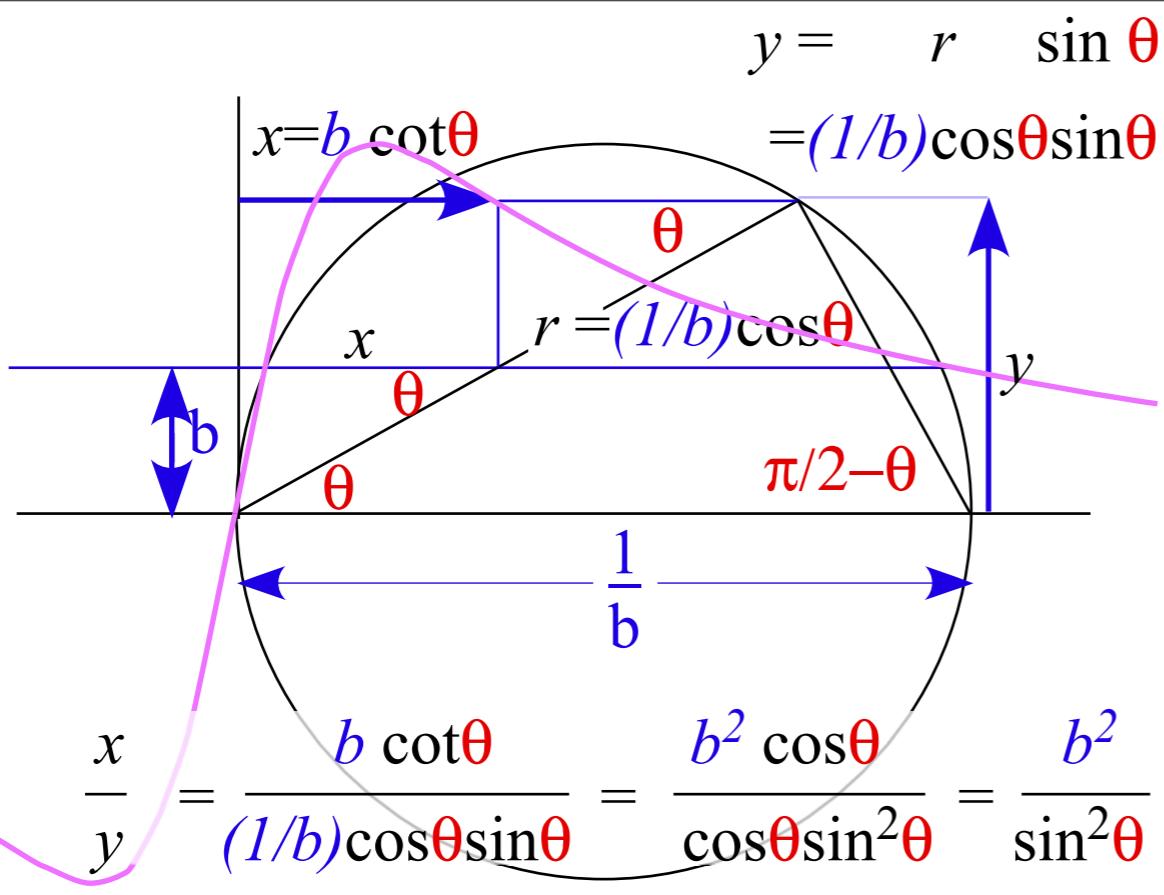
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$$x^2 + b^2 = \frac{b^2}{\sin^2\theta} + b^2 = \frac{b^2}{y^2} + b^2 = \frac{b^2}{x^2 + b^2}$$

*Common Lorentzian function I.
(imaginary "absorptive" part)*



$$b = \frac{2}{5}$$



$$x^2 + b^2 = \frac{b^2}{\sin^2 \theta} = \frac{x}{y}$$

$y = \frac{x}{x^2 + b^2}$

*Common Lorentzian function II.
(real “refractory” part)*

