Exercise Set 7 Due Wednesday Oct. 16: Based on Unit 1 Chapter 10 and 12 and Lectures 12-13 (2018).

"Professional" Parabolic and Hyperbolic Coordinates (Relates to Fig. 1.10.7)

1. Consider GCC definition: $q^{1}=\Phi = x^{2} - y^{2}$, $q^{2}=A = 2xy$. Both $(x^{1}=x,x^{2}=y)$ and $(q^{1}=u=\Phi,q^{2}=v=A)$ are Orthogonal Curvilinear Coordinates (OCC) related by an analytic function $w=z^{2}$ or $(u+iv)=(x+iy)^{2}$. You can treat *either one* as Cartesian. (This is based on the analytic function f(z)=2z whose complex potential is $\phi =$ _____)

(a) Plot $(q^1 = u, q^2 = v)$ coordinate curves in a Cartesian $(x^1 = x, x^2 = y)$ graph. Derive the Jacobian, Kajobian, unitary vectors \mathbf{E}_k and \mathbf{E}^k and metric tensors g_{mn} and g^{mn} for this GCC.

(b) Plot $(x^1=x,x^2=y)$ coordinate curves in a Cartesian $(q^1=u,q^2=v)$ graph. Derive the Jacobian, Kajobian, unitary vectors and metric tensors for this GCC.

Galaxy Grids

2. Consider the monopole field function $f(z) = e^{i\alpha}/z$ with complex source $e^{i\alpha}$ discussed in Lectures 12-13.

- (a) Derive its $(q^1 = \Phi, q^2 = A)$ scalar and vector potential coordinate functions.
- (b) Plot examples for angle α =30° and α =45°.

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3. Consider a sequence of functions, $f_1(z) = z^z$, $f_2(z) = z^{f_1(z)} = z^{z^z}$, $f_3(z) = z^{f_2(z)} = z^{z^{z^z}}$,.... The function $f_N(z)$ has a finite limit $f_{\infty}(z)$ for N approaching infinity if argument z is small enough. $(z=1 \text{ works}! \text{ But, so does } z=\sqrt{2}.)$

(a) Find $f_{\infty}(\sqrt{2}) =$

(b) Find analytic expression for limiting real z_{max} to give finite $f_{\infty}(z)$. It involves Euler constant. e=2.718281828...

Fun in the bathtub (This has a peculiar connection to "Sophomore-Physics-Earth" potential.) **4.** Derive surface shape of rotating fluid subject to constraints on curl function $\nabla \times \mathbf{v}$ for velocity field. From this you should be able to derive surface altitude S=S(r) as a function of radius *r* by relating balanced forces to differential slope. (Objects floating on these surfaces would not move up or down their S(r) surface.)

(a) $\nabla \times \mathbf{v} = 0$ (Whirlpool or Vortex) Complex vortex field $f(z^*) = v_x(x,y) + i v_y(x,y) = i/z^*$ has zero z-derivative and zero divergence (flux derivative $\nabla \cdot \mathbf{v} = 0$) and zero curl (circulation derivative $\nabla \times \mathbf{v} = \mathbf{0}$).

(b) $\nabla \times \mathbf{v} = const$. (Rigid rotation) Complex vortex field $f(z) = v_x(x,y) + i v_y(x,y) = i\omega z$ has constant imaginary z-derivative and therefore zero divergence (flux derivative $\nabla \cdot \mathbf{v} = 0$) and <u>constant</u> curl (circulation derivative $\nabla \times \mathbf{v} = \mathbf{\omega}$).



(c) How might the "Sophomore-Physics-Earth" potential be related to a surface whirlpool in deep water

Assignments for Physics 5103 - 2019 Reading in Classical Mechanics with a BANG! and Lectures

Solutions: Assignment 6 "Professional" Parabolic and Hyperbolic Coordinates

1 Consider the GCC(Cartesian) definition: $q^1 = (x^1)^2 - (x^2)^2$, $q^2 = 2(x^1)(x^2)$. Both $(x^1 = x, x^2 = y)$ and $(q^1 = u, q^2 = v)$ are Orthogonal Curvilinear Coordinates (OCC) related by an analytic function $w = z^2$ or $(u+iv) = (x+iy)^2$.

(a) Plot $(q^1 = u, q^2 = v)$ coordinate curves in a Cartesian $(x^1 = x, x^2 = y)$ graph. Derive the Jacobian, Kajobian, unitary vectors and metric tensors for this GCC. See below.

(b) Plot $(x^1 = x, x^2 = y)$ coordinate curves in a Cartesian $(q^1 = u, q^2 = v)$ graph. Derive the Jacobian, Kajobian, unitary vectors and metric tensors for this GCC.

 $w = (u + iv) = z^2 = (x + iy)^2$ is analytic function of z and w

Expansion: $u = x^2 - y^2$ and v = 2xy may be solved using $|w| = |z^2| = |z|^2$

Expansion: $|w| = \sqrt{u^2 + v^2} = x^2 + y^2 = |z|^2$ Solution: $x^2 = \frac{u + \sqrt{u^2 + v^2}}{2}$ $y^2 = \frac{-u + \sqrt{u^2 + v^2}}{2}$

Jacobian follows by inversion:

Easier to get Kajobian first:

$$\begin{pmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{u} \\ \mathbf{\bar{E}}^{v} \end{pmatrix} = \begin{pmatrix} 2x & -2y \\ +2y & 2x \end{pmatrix}$$

$$\begin{pmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial u} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{u} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{u} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{u} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial y} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial y} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial y} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial y} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial y} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial y} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} \mathbf{\bar{E}}^{v} \\ \frac{\partial v}{\partial y} & \frac{\partial v}{\partial y}$$

$$4\sqrt{u^2+v}$$



Note how parabolic covariant vectors grow with distance from origin while contravariant vectors shrink.

Galaxy Grids-Solutions:

- **2.** Consider the monopole field function $f(z) = e^{i\alpha}/z$ with complex source $e^{i\alpha}$ discussed in Lect. 12-13.
- (a) Derive its $(q^1 = \Phi, q^2 = A)$ scalar and vector potential coordinate functions.
- (b) Plot examples for angle α =30° and α =45°.



 $A=0.75 \text{ and } B=0.25 \text{ A}=e^{i\alpha}=0.75 + i \ 0.25 \text{ has } \alpha = atan(0.25/0.75) = 18^{\circ}.$

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3. Consider a sequence of functions, $f_1(z) = z^z$, $f_2(z) = z^{f_1(z)} = z^{z^z}$, $f_3(z) = z^{f_2(z)} = z^{z^{z^z}}$,.... The function $f_N(z)$ has a limit for N approaching infinity if argument z is small enough . (z=1 works! But, so does $z=\sqrt{2}$.) Find an analytic expression for the limiting real z that involves the Euler constant. e=2.718281828...

Solution: Assume limiting case can be reached. Then: $f(z) = z^{f(z)}$ or: $z = f^{\frac{1}{f}}$. Let's plot this function: $y(x) = x^{\frac{1}{x}}$ $1^{\frac{1}{1}} = 1.00, \quad 1.5^{\frac{1}{15}} = 1.30, \quad 2^{\frac{1}{2}} = 1.414, \quad 3^{\frac{1}{3}} = 1.442, \quad 4^{\frac{1}{4}} = 1.414, \dots$ Has max when: $\frac{dy}{dx} = 0$ with $: \ln y = \ln x^{\frac{1}{x}} = \frac{\ln x}{x}$ Take implicit derivative of $x \ln y = \ln x$: then set $\frac{dy}{dx} = 0$: $\frac{d}{dx} x \ln y = \frac{d}{dx} \ln x$ or: $\ln y + \frac{x}{y} \frac{dy}{dx} = \ln y = \frac{1}{x}$, so: $x^{\frac{1}{x}} = y = e^{\frac{1}{x}} = e^{\frac{1}{e}} = 1.44466786$

Fun in the bathtub (This has a peculiar connection to "Sophomore-Physics-Earth" potential.) Solution

4. Derive surface shape of rotating fluid subject to constraints on curl function $\nabla \times \mathbf{v}$ on velocity field.

(a) $\nabla \times \mathbf{v} = 0$ (Whirlpool or Vortex) Complex vortex field $f(z^*) = v_x(x,y) + i v_y(x,y) = i/z^*$ has zero z-derivative and therefore zero divergence (flux derivative $\nabla \cdot \mathbf{v} = 0$) and zero curl (circulation derivative $\nabla \times \mathbf{v} = \mathbf{0}$).

$$0 = \frac{dv(z^*)}{dz} = \frac{1}{2} \left(\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right) (v_x + iv_y) = \frac{1}{2} \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} \right) + \frac{i}{2} \left(\frac{\partial v_x}{\partial y} - \frac{\partial v_y}{\partial x} \right) = \frac{1}{2} \left(\nabla \cdot \mathbf{v} \right) + \frac{i}{2} \left| \nabla \times \mathbf{v} \right|_{\perp x, y}$$

$$for: v(z^*) = \frac{i}{z^*} = \frac{i}{x - iy} = \frac{i}{x - iy} \frac{x + iy}{x + iy} = i\left(\frac{x}{x^2 + y^2} + i\frac{y}{x^2 + y^2}\right) = v_x + iv_y \text{ where:} \quad \begin{cases} v_x = -\frac{y}{r^2} = -\frac{\sin\theta}{r} \\ v_y = +\frac{x}{r^2} = +\frac{\cos\theta}{r} \end{cases}$$

(b) $\nabla \times \mathbf{v} = const$. (Rigid rotation) Complex vortex field $f(z) = v_x(x,y) + i v_y(x,y) = i\omega z$ has constant imaginary z-derivative and therefore zero divergence (flux derivative $\nabla \cdot \mathbf{v} = 0$) and <u>constant</u> curl (circulation derivative $\nabla \times \mathbf{v} = \boldsymbol{\omega}$).

$$i\omega = \frac{d(i\omega z)}{dz} = \frac{1}{2} \left(\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right) (v_x + iv_y) = \frac{1}{2} (\nabla \cdot \mathbf{v}) + \frac{i}{2} |\nabla \times \mathbf{v}|_{\perp x, y} \quad \text{So: } \nabla \cdot \mathbf{v} = 0 \text{ and: } |\nabla \times \mathbf{v}|_{\perp x, y} = 2\omega$$
for : $v(z) = i\omega z = i\omega (x + iy) = v_x + iv_y$ where: $v_x = -\omega y = -\omega r \sin \theta$

for : $v(z) = i\omega z = i\omega(x + iy) = v_x + iv_y$ where: $v_y = +\omega x = +\omega r \cos\theta$



$$\tan \theta = \frac{dz}{dr} = \frac{|a|}{g} = \frac{v^2 / r}{g} = \begin{cases} (k^2 / g)r^{-3} \text{ for vortex } (v = k / r) \\ (\omega^2 / g)r^{+1} \text{ for rotor } (v = \omega r) \end{cases} \qquad z(r) = \begin{cases} -(k^2 / 2g)r^{-2} \text{ for vortex } (v = k / r) \\ (\omega^2 / 2g)r^{+2} \text{ for rotor } (v = \omega r) \end{cases}$$

(c) Ideal whirlpools have parabolic core-bottoms starting wherever viscosity wins over curl-free flow.

