Assignment 11 Oct. 31,2018 Exercises due Wed. Nov. 7 Constrained motion theory in Unit 3 Ch. 9 and Lect. 19. Lecture 19 was not presented this year but last year's lecture is available online as is Unit 3 Ch. 9

## Parabolic Fly-off vs. Spherical Fly-Off



Ex.1. The frictionless constraint problem with mass $m$ trapped in a parabolic well is shown to be an anharmonic oscillator in Sec. 3.9. Consider how $m$ on a barrier might fall off under gravity $g=10 \mathrm{~m} \cdot \mathrm{~s}^{-2}$.
(a) Suppose an inverted parabolic road $y=-\frac{1}{2} k x^{2}$ with $m$ starting with near-zero $v(0)$ at $x=0$ on top. Show whether there are $x_{f l}, y_{f l y}$, and $v_{f l y}$ values where the mass $m$ would fly off the road. Analyze and discuss.
(b) Do a similar analysis for a particle on a sphere of radius $R$. Compare to parabolic result of (a).

"Easy as rolling off a log"
Ex.2. A ball of radius $r$ and mass $m=1 \mathrm{~kg}$ starting at the top of a fixed $\log$ of radius $R$ and begins rolling down it. Assuming the sphere rolls without slipping calculate the angle from vertical where it last contacts the log. Give algebraic answers first. Then try $R=20 \mathrm{~cm}$ and $r=1 \mathrm{~cm}$ with $g=10 \mathrm{~m} \cdot \mathrm{~s}^{-2}$, and then try $R=1 \mathrm{~cm}$ and $r=20 \mathrm{~cm}$. Compare these answers with each other and with those involving sliding particles in exercise $\mathbf{1 ( b )}$.

## Pendulum on turntable (Soft-mode resonance)



Ex. 3 Suppose a pendulum supported by a circular ball bearing may swing without friction in the vertical plane of the bearing. The bearing plane is secured to a turntable that rotates at a constant angular frequency $\omega_{r}$. The pendulum consists of a mass $m$ at the end of a rod of length $\ell=1 \mathrm{~m}$ and negligible mass with natural frequency of small $\theta$-angle motion at zero- $\omega_{r}$ in gravity acceleration (Say $g=10 \mathrm{~m} / \mathrm{s}^{2}$ ) given by $\omega_{0}\left(\omega_{r}=0\right)=$ $\qquad$ .
(a) Derive the Lagrangian and Hamiltonian using spherical coordinates in the rotating frame.
(b) Derive the $\theta$-equilibrium points and small-oscillation frequency as a function of the frequency $\omega_{r}$ and $\omega_{0}$.

Overlay plots of effective $\theta$-potential for several key values of $\omega_{r}$. What $\omega_{r}$ value makes $\theta=0$ angle unstable?

